

Report

Automatic Car Wiper

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1.Description

The car wipers that have been available in the present day market are manual systems that work on the principle of manual switching. Our proposed system proposes an automatic wiper system that automatically switches ON the wiper on detection of rain and stops the wiper action when rain stops.

This system eases the work of driver by eliminating the manual human intervention for initiating the wiper action, thereby contributing to the comfort driving.

Here, the rain sensor is used along with microcontroller (Arduino UNO) and driver IC to drive the wiper motor. The rain sensor detects rain and then the signal is then processed by microcontroller to take the desired wiper action.

Principle of sensor

The rain sensor works on the principle of using water for completing its circuit, so when rain falls on it its circuit gets completed and sends out a signal to the microcontroller.

The microcontroller now processes this data and drives the motor IC to perform the required wiper action. The motor driver IC now drives a servomotor to simulate as a car wiper.

1.2 Identifying features

- *Rain is identified with the help of the rain sensor.*
- *Automatic wiper action is initiated without manual intervention.*
- *Microcontroller programmed system to ensure the automatic instant wiper action.*
- *When it stops raining, the wiper action automatically gets terminated.*

1.3 State of art

The main objective of this system is to initiate the wiper action when it rains and to terminate the same when the rain gets stopped. To ease the work of driver by eliminating the manual intervention thereby contributing to comfortable driving.

1.4 5W's and 1 H

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1.5 SWOT Analysis

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2.Requirements

2.1High Level Requirements

ID | Description

HLR 1 |System shall automatically turn the wiper on when it starts raining

HLR 2 |System shall detect rain

2.2 Low Level Requirements

ID | Description

LLR 1.1 | Rain sensor shall detect the rain

LLR 1.2 | This signal shall be processed by microcontroller to turn on the wiper

LLR 2.1 | Rain shall be detected by using rain sensor

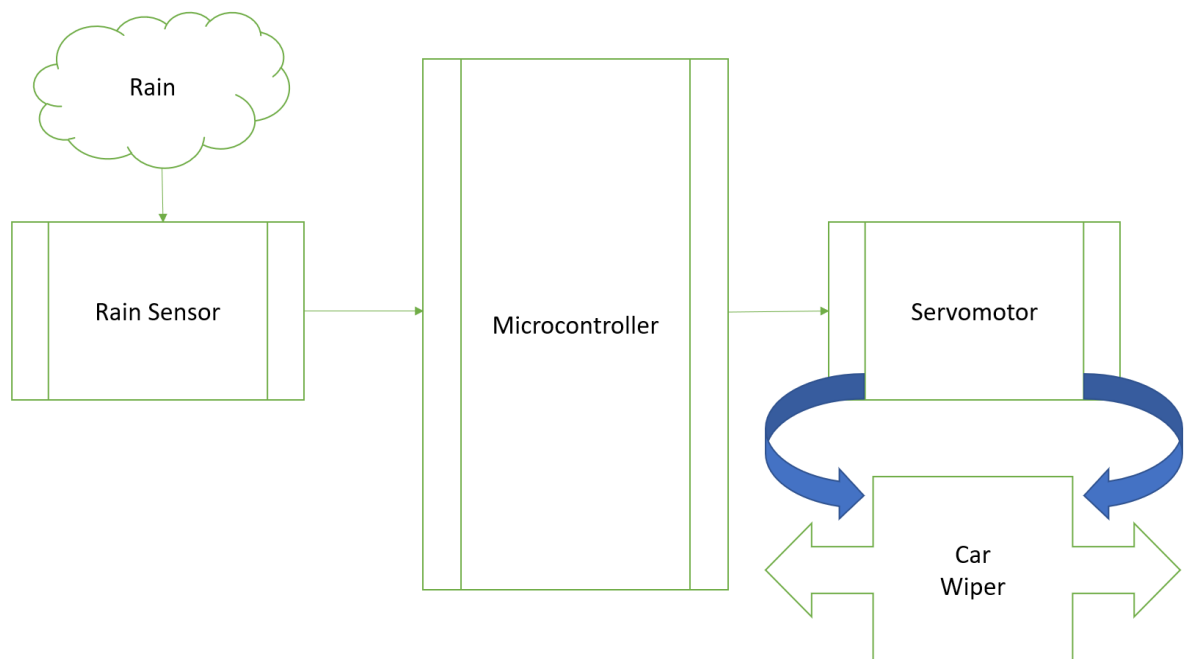
LLR 2.2 | Rain sensor shall work on the principle of using water for completing its circuit

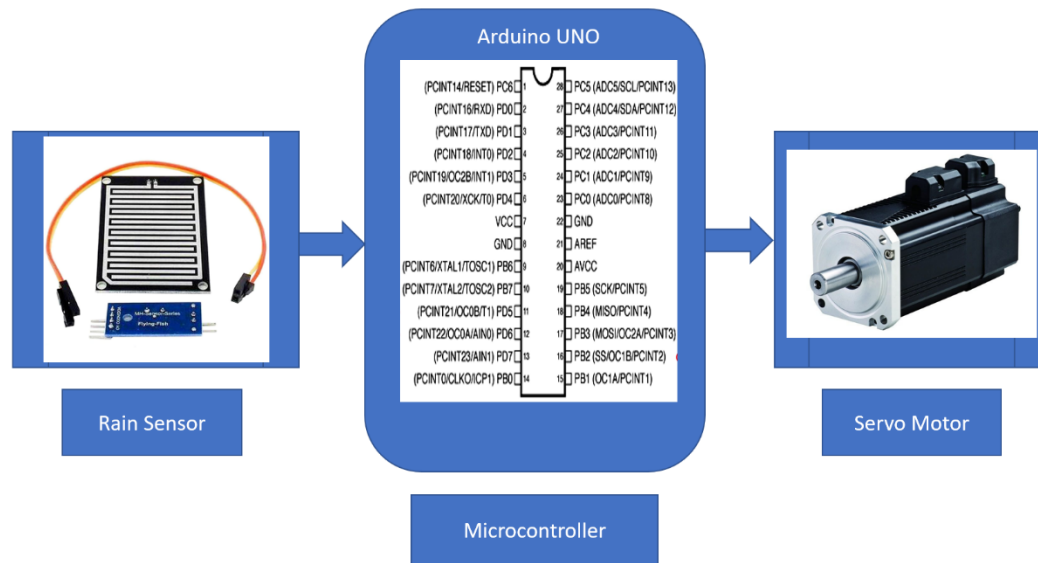
3. Applications

1. It can be used in cars to automatically control the wiper action when needed.

2. Using in cars thereby ease the work of driver and also contributes in comfortable driving by enabling the wiper action without manual intervention.

4. Block Diagram

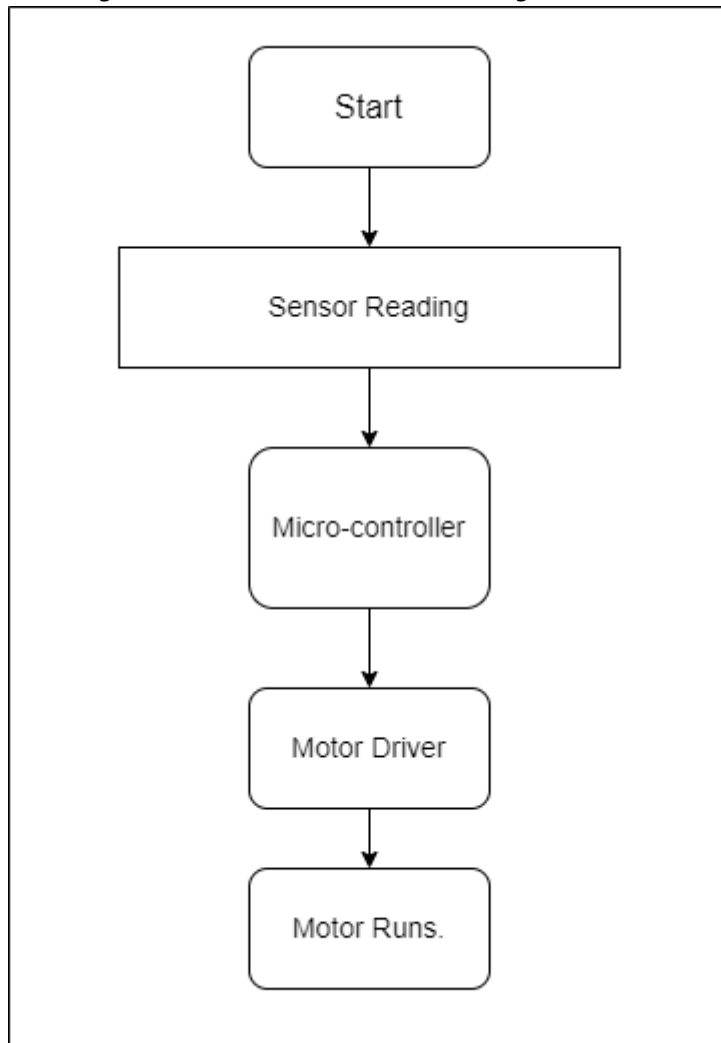


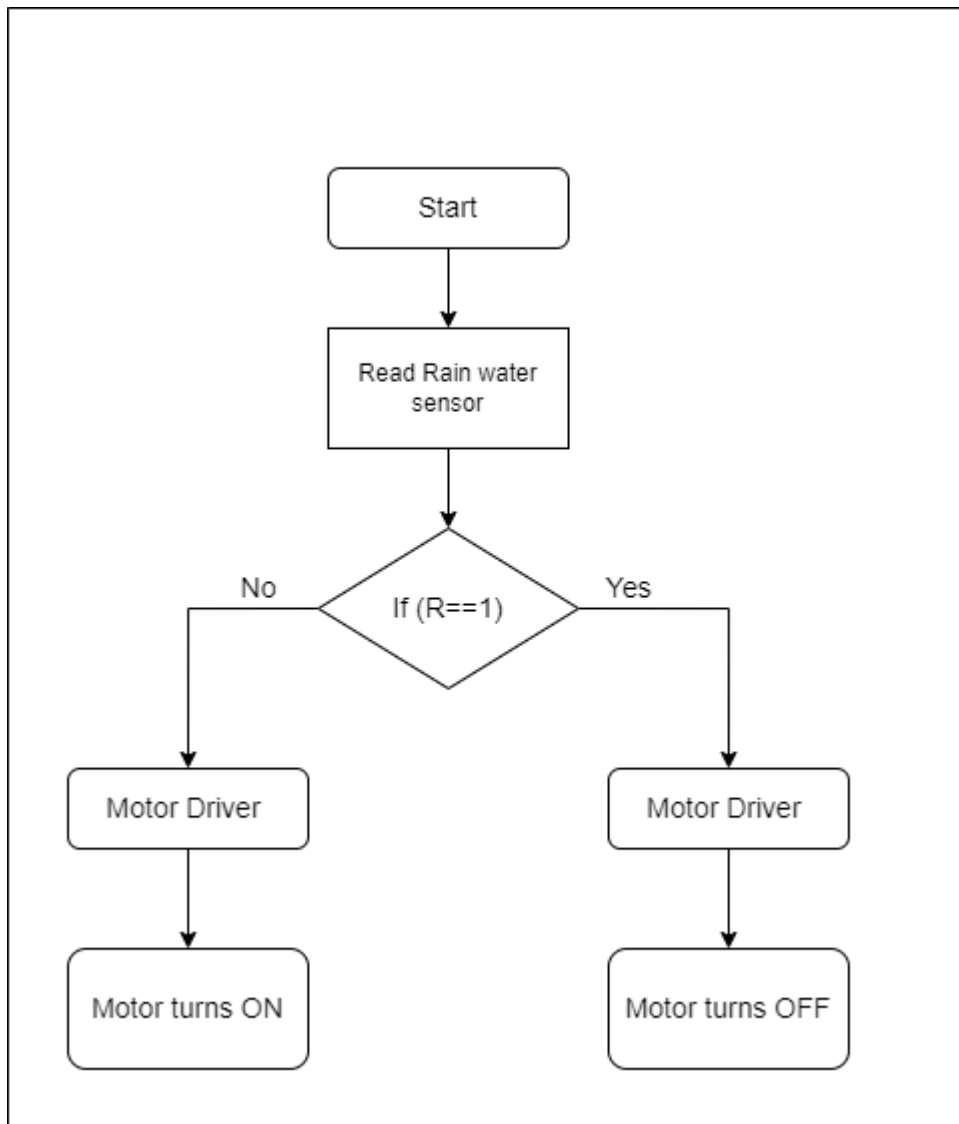


5. Architecture

5.1 Behavioural Diagram

5.1.1 High Level Flowchart Behavioural Diagram

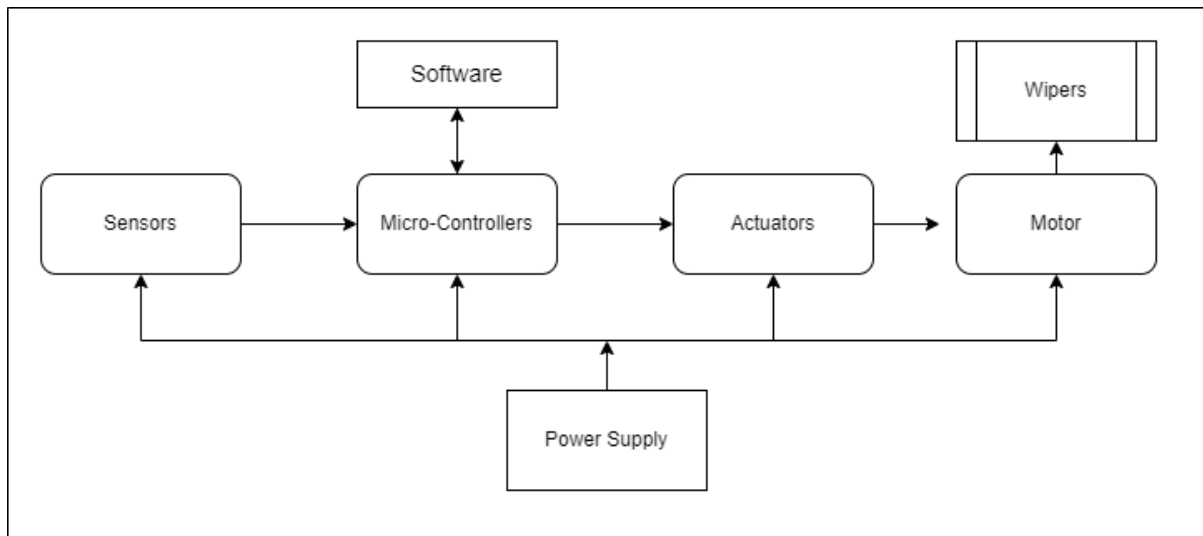




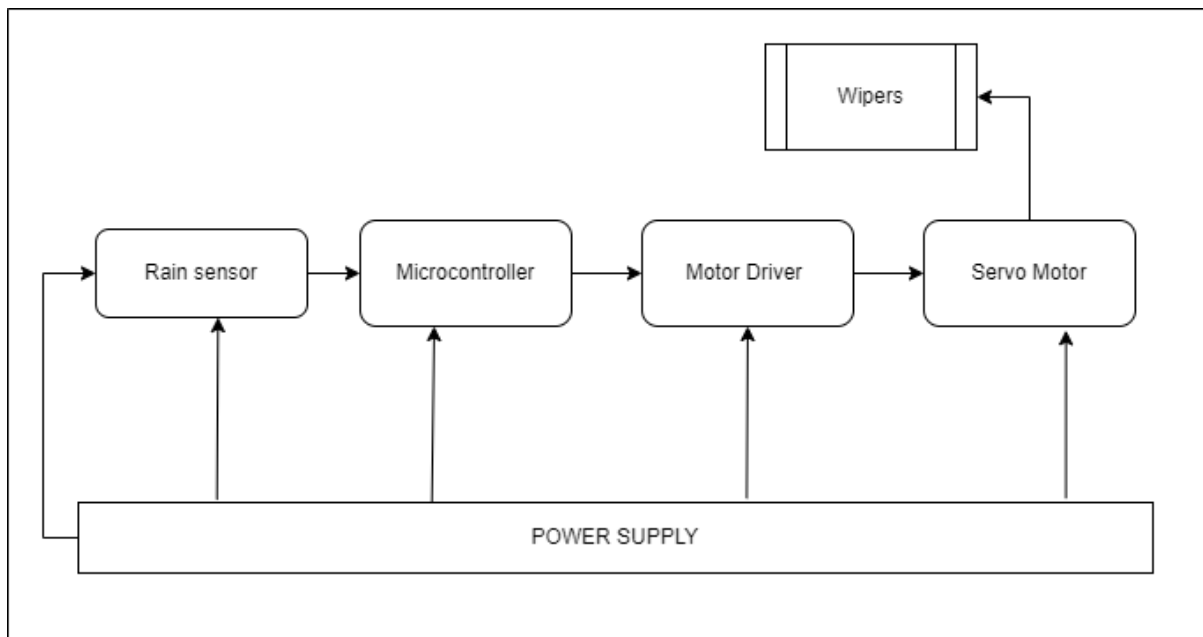
5.1.2 Low Level Flowchart Behavioural Diagram

5.2 Structural Diagram

5.2.1 High Level UML Usecase Structural Diagram



5.2.2 Low Level UML Usecase Structural Diagram



6.Badges

Badge of Codiga

Grade

Code Quality Score 100

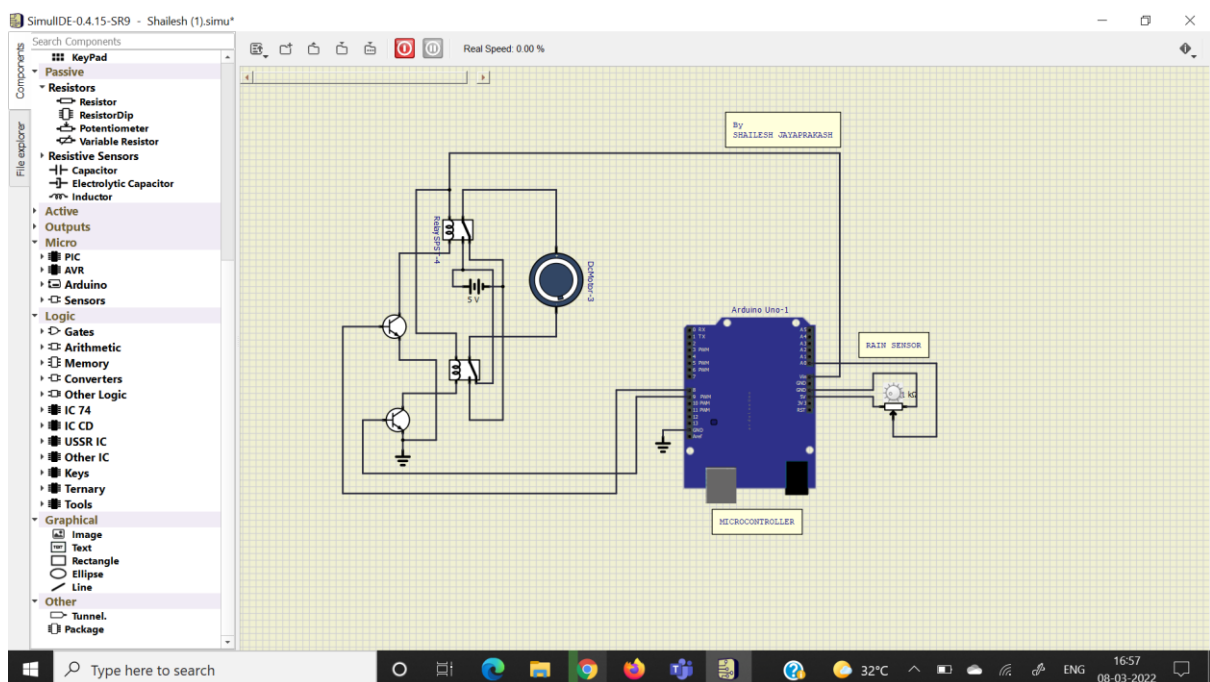
Code Grade A

Badge of codacy

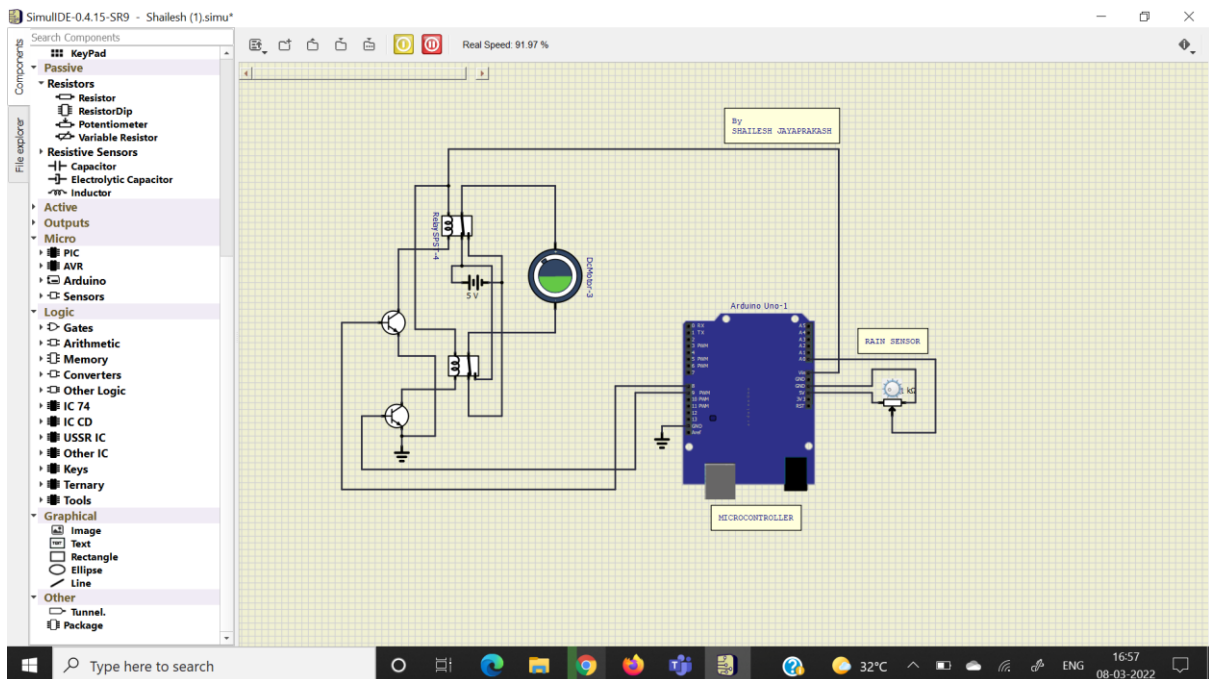
code quality B

7.Output

Schematic Diagram



Output When rain is detected



Output when Rain is not detected

