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1 Introduction

1.1 Objective

Rankings of government units derived from sample survey data are typically published without accompanying statistical statements that quantify uncertainty in estimated overall rankings (add here uncertainty is just expressed for each element being ranked). While the literature on quantifying overall uncertainty remains limited, existing methods overlook the potential correlation among ranks (Literature that this is possible). The objective of this study is to introduce a methodology that constructs joint confidence region for the true but unknown overall ranking while accounting for the correlation among them. In line with this, we also present ways to estimate correlation in a specific application—such as estimating the dependence structure among senatorial candidates' rankings.

1.2 Significance

True ranks are estimated based on sample-derived quantities. It follows that uncertainty in the estimators is carried over to the estimated ranking. As a result, a measure of this uncertainty should be reported alongside any resulting overall ranking. This approach accounts not only for the variability of individual estimators but also for the dependence introduced by the relative nature of ranking. It is also essential to consider correlations among ranked objects, which may stem from shared characteristics that predispose groups to occupy nearby ranks.

1.3 Scope and Limitations

2 Related Literature

2.1 Joint confidence region for an overall ranking

Klein et al. (2020) proposed an approach for quantifying overall rank uncertainty following the estimation of respondents' average travel time to work in each K sampled geographical area. In their paper, rank for the kth population is defined as

$$r_k = \sum_{j=1}^{K} I(\theta_j \le \theta_k) = 1 + \sum_{j:j \ne k} I(\theta_j \le \theta_k), \quad \text{for } k = 1, \dots, K$$
 (2.1)

As for the estimated overall ranking, it is computed from the estimates $\hat{\theta}_1, \dots, \hat{\theta}_K$, and expressed as $(\hat{r}_1, \dots, \hat{r}_K)$, where

$$\hat{r}_k = 1 + \sum_{j:j \neq k} I(\hat{\theta}_j \le \hat{\theta}_k), \quad \text{for } k = 1, \dots, K$$
(2.2)

True values, $\theta_1, \ldots, \theta_K$ are unknown; hence, it is assumed that for each $k \in \{1, 2, \ldots, K\}$, there exists L_k and U_k such that

$$\theta_k \in (L_k, U_k) \tag{2.3}$$

For each $k \in \{1, 2, ..., K\}$, they defined

$$I_{k} = \{1, 2, \dots, K\} - \{k\},$$

$$\Lambda_{Lk} = \{j \in I_{k} : U_{j} \leq L_{k}\},$$

$$\Lambda_{Rk} = \{j \in I_{k} : U_{k} \leq L_{j}\},$$

$$\Lambda_{Ok} = \{j \in I_{k} : U_{j} > L_{k} \text{ and } U_{k} > L_{j}\} = I_{k} - \{\Lambda_{Lk} \cup \Lambda_{Rk}\}$$

$$(2.4)$$

Equation 2.4 can likewise be expressed in words as follows:

- 1. $j \in \Lambda_{Lk} \leftrightarrow (L_j, U_j) \cap (L_k, U_k) = \emptyset$ and (L_j, U_j) lies to the left of (L_k, U_k) ;
- 2. $j \in \Lambda_{Rk} \leftrightarrow (L_j, U_j) \cap (L_k, U_k) = \emptyset$ and (L_j, U_j) lies to the right of (L_k, U_k) ;
- 3. $j \in \Lambda_{Ok} \leftrightarrow (L_j, U_j) \cap (L_k, U_k) \neq \emptyset$
- 4. Λ_{Lk} , Λ_{Rk} , and Λ_{Ok} are mutually exclusive, and $\Lambda_{Lk} \cup \Lambda_{Rk} \cup \Lambda_{Ok} = I_k$

and implies that for each $k \in \{1, 2, \dots, K\}$,

$$r_k \in \{ |\Lambda_{Lk}| + 1, |\Lambda_{Lk}| + 2, |\Lambda_{Lk}| + 3, \dots, |\Lambda_{Lk}| + |\Lambda_{Ok}| + 1 \}$$
 (2.5)

Equation 2.5 demonstrates that a smaller $|\Lambda_{Ok}|$ results in smaller difference between U_k and L_k . Collectively, for all k, this yields narrower confidence intervals for the overall ranks, which is desirable.

They also assumed a conservative confidence region whose joint coverage probability is at least as large as the nominal level, $1 - \alpha$, as shown in Equation 2.6.

$$P\left[\bigcap_{k=1}^{K} \left\{ \theta_k \in (L_k, U_k) \right\} \right] \ge 1 - \alpha \tag{2.6}$$

As a result, their joint confidence set, as presented in Equation 2.7, for the overall ranking (r_1, \ldots, r_K) has a joint probability of at least $1 - \alpha$.

$$\{(r_1, \dots, r_K) : r_k \in \{|\Lambda_{Lk}| + 1, |\Lambda_{Lk}| + 2, |\Lambda_{Lk}| + 3, \dots, |\Lambda_{Lk}| + | \text{ for } k = 1, 2, \dots, K\}\}$$
(2.7)

In line with this, they presented a proof demonstrating that if $(L_1, U_1), \ldots, (L_K, U_K)$ are constructed such that the estimator $\hat{\theta} \in (L_k, U_k) \ \forall k \in \{1, 2, \ldots, K\}$, then the estimated ranking $(\hat{r}_1, \hat{r}_2, \ldots, \hat{r}_K)$ lies within the joint confidence region defined in Equation 2.7 with probability 1.

They also noted that the joint confidence region in Equation 2.7 contains more than one possible overall ranking unless the values of θ_k differ from each other such that

 $(L_k, U_k) \cap (L_{k'}, U_{k'}) = \emptyset$, $\forall k \neq k'$. This implies that the unique overall ranking arises only from the narrowest attainable joint confidence region and it is the estimated ranking, $(\hat{r}_1, \hat{r}_2, \dots, \hat{r}_K)$.

2.1.1 Using Independence

2.1.2 Using Bonferroni Correction

2.2 T_1, T_2, T_3

https://mgimond.github.io/Spatial/spatial-autocorrelation.html https://cran.r-project.org/web/packages/simstudy/vignettes/corelationmat.html

3 Methodology

This section introduces the proposed methodologies to obtain confidence regions for the unknown overall true ranking. The following cases are tackled: case when items ranked are assumed to have zero and nonzero correlation. Both approaches are based on parametric bootstrap. Sections 3.1 and 3.2 discuss the algorithms for the cases mentioned. Section 3.3 shows the algorithms used to assess the performance of the proposed approaches. This makes use of coverage and metrics to measure the tightness of the estimated confidence regions.

For sections 3.1 and 3.2, let $\theta_1, \theta_2, \dots, \theta_K$ be the true parameter values and $\hat{\theta}_1, \hat{\theta}_2, \dots, \hat{\theta}_K$ be the corresponding estimates.

3.1 Joint confidence intervals for $\theta_1, \dots, \theta_K$ by using Parametric Bootstrap

The rank-based parametric bootstrap approach assumes $\hat{\theta}_1, \hat{\theta}_2, \dots, \hat{\theta}_K$ to be independent but not identically distributed estimates, where $\hat{\theta}_k \sim N(\theta_k, \sigma_k^2), k = 1, 2, \dots, K.$ σ_k^2 is assumed known. Denote the corresponding ordered values by $\hat{\theta}_{(1)}, \hat{\theta}_{(2)}, \dots, \hat{\theta}_{(K)}$.

Algorithm 1 Computation of Joint Confidence Region using Parametric Bootstrap

- 1: **for** $b = 1, 2, \dots, B$ **do**
- 2: Generate $\hat{\theta}_{bk}^* \sim N\left(\hat{\theta}_k, \sigma_k^2\right)$, $k = 1, 2, \dots, K$ and let $\hat{\theta}_{b(1)}, \hat{\theta}_{b(2)}, \dots, \hat{\theta}_{b(K)}$ be the corresponding ordered values

	k = 1	k=2	 k = K
b=1	$\hat{ heta}_{1(1)}^*$	$\hat{ heta}_{1(2)}^*$	 $\hat{ heta}_{1(K)}^*$
b=2	$\hat{ heta}_{2(1)}^*$	$\hat{\theta}_{2(2)}^*$	 $\hat{ heta}_{2(K)}^*$
:	•	•	 :
b = B	$\hat{\theta}_{B(1)}^*$	$\hat{ heta}_{B(2)}^*$	 $\hat{\theta}_{B(K)}^*$

3: Compute

$$\hat{\sigma}_{b(k)}^* = \sqrt{\text{kth ordered value among } \{\hat{\theta}_{b1}^{*2} + \sigma_1^2, \hat{\theta}_{b2}^{*2} + \sigma_2^2, \dots, \hat{\theta}_{bK}^{*2} + \sigma_K^2\} - \hat{\theta}_{(k)}^{*2}}$$

- 4: Compute $t_b^* = \max_{1 \le k \le K} \left| \frac{\hat{\theta}_{b(k)}^* \hat{\theta}_k^*}{\sigma_{b(k)}^*} \right|$
- 5: end for
- 6: Compute the (1α) -sample quantile of $t_1^*, t_2^*, \dots, t_B^*$, call this \hat{t} .
- 7: The joint confidence region of $\theta_{(1)}, \theta_{(2)}, \dots, \theta_{(K)}$ is given by

$$\mathfrak{R} = \left[\hat{\theta}_{(1)} \pm \hat{t} \times \hat{\sigma}_{(1)}\right] \times \left[\hat{\theta}_{(2)} \pm \hat{t} \times \hat{\sigma}_{(2)}\right] \times \cdots \times \left[\hat{\theta}_{(K)} \pm \hat{t} \times \hat{\sigma}_{(K)}\right]$$

where $\hat{\sigma}_{(k)}$ is computed as

$$\hat{\sigma}_{(k)} = \sqrt{\text{kth ordered value among } \left\{\hat{\theta}_1^2 + \sigma_1^2, \hat{\theta}_2^2 + \sigma_2^2, \dots, \hat{\theta}_K^2 + \sigma_K^2\right\} - \hat{\theta}_{(k)}^2}$$

3.2 Joint confidence intervals for $\theta_1, \dots, \theta_K$ by using Nonrank-based method

The nonrank-based method assumes that $\hat{\boldsymbol{\theta}} = (\hat{\theta}_1, \hat{\theta}_2, \dots, \hat{\theta}_K) \sim N(\boldsymbol{\theta}, \boldsymbol{\Sigma})$. It accounts for potential correlation among items being ranked. For this case, an exchangeable correlation, $\boldsymbol{\rho}$ (See Equation 3.1.), is assumed and used in the calculation of the variance covariance matrix (See Equation 3.2.).

$$\boldsymbol{\rho} = (1 - \rho) \mathbf{I}_K + \rho \mathbf{1}_K \mathbf{1}_K' \tag{3.1}$$

$$\Sigma = \Delta^{1/2} \rho \Delta^{1/2} \tag{3.2}$$

where $\Delta = \text{diag}\{\sigma_1^2, \sigma_2^2, \dots, \sigma_K^2\}$, with known σ_k 's and ρ is studied for 0.1, 0.5, 0.9.

Algorithm 2 Computation of Joint Confidence Region using Nonrank-based Method

Let the data consist of $\hat{\theta}_1, \dots, \hat{\theta}_K$ and suppose Σ is known

- 1: **for** $b = 1, 2, \dots, B$ **do**
- 2: Generate $\hat{\boldsymbol{\theta}}_b^* \sim N_K \left(\hat{\boldsymbol{\theta}}, \boldsymbol{\Sigma} \right)$ and write $\hat{\boldsymbol{\theta}}_b^* = \left(\hat{\theta}_{b1}^*, \hat{\theta}_{b2}^*, \dots, \hat{\theta}_{bK}^* \right)'$
- 3: Compute $t_b^* = \max_{1 \le k \le K} \left| \frac{\hat{\theta}_{bk}^* \hat{\theta}_k^*}{\sigma_k} \right|$
- 4: end for
- 5: Compute the (1α) -sample quantile of $t_1^*, t_2^*, \dots, t_B^*$, call this \hat{t} .
- 6: The joint confidence region of $\theta_1, \theta_2, \dots, \theta_K$ is given by

$$\mathfrak{R} = \left[\hat{\theta}_1 \pm \hat{t} \times \sigma_1\right] \times \left[\hat{\theta}_2 \pm \hat{t} \times \sigma_2\right] \times \dots \times \left[\hat{\theta}_K \pm \hat{t} \times \sigma_K\right]$$

3.3 Evaluation

Algorithm 3 is used to calculate the coverage which is defined as the proportion of times that the true parameter values fall within the confidence interval for all K simultaneously. Ideally, this should be equal to 0.90 since $\alpha = 0.1$. It also calculates the average T_1, T_2 , and T_3 . Higher values of T_1 and T_2 indicate wider confidence intervals and are therefore less desirable, whereas higher values of T_3 are preferable.

Algorithm 3 Computation of Coverage Probability for Parametric Bootstrap

For given values of $\theta_1, \theta_2, \dots, \theta_K$ and thus $\theta_{(1)}, \theta_{(2)}, \dots, \theta_{(K)}$

- 1: **for** replications = $1, 2, \dots, 5000$ **do**
- 2: Generate $\hat{\theta}_k \sim N(\theta_k, \sigma_k^2)$, for k = 1, 2, ..., K
- 3: Compute the rectangular confidence region \Re using Algorithm 1.
- 4: Check if $(\theta_{(1)}, \theta_{(2)}, \dots, \theta_{(K)}) \in \mathfrak{R}$ and compute

$$T_1 = \frac{1}{K} \sum_{k=1}^{K} \left| \Lambda_{Ok} \right|$$

$$T_2 = \prod_{k=1}^{K} \left| \Lambda_{Ok} \right|$$

$$T_3 = 1 - \frac{K + \sum_{k=1}^{K} \left| \Lambda_{Ok} \right|}{K^2}$$

- 5: end for
- 6: Compute the proportion of times that the condition in step 4 is satisfied and the average of T_1, T_2 , and T_3 .

Algorithm 4 is similar to Algorithm 3 but computes for the coverage and average T_1, T_2 , and T_3 for the nonrank-based method.

Algorithm 4 Computation of Coverage Probability for Nonrank-based Method

For given values of $\theta_1, \theta_2, \dots, \theta_K$ and Σ

- 1: for replications = $1, 2, \dots, 5000$ do
- 2: Generate $\hat{\boldsymbol{\theta}} \sim N_K(\boldsymbol{\theta}, \boldsymbol{\Sigma})$
- 3: Compute the rectangular confidence region \Re using Algorithm 2.
- 4: Check if $(\theta_1, \theta_2, \dots, \theta_K) \in \mathfrak{R}$ and compute T_1, T_2 , and T_3 .
- 5: end for
- 6: Compute the proportion of times that the condition in step 4 is satisfied and the average of T_1, T_2 , and T_3 .

Klein et al. (2020)

Bibliography

Klein, M., Wright, T., & Wieczorek, J. (2020). A joint confidence region for an overall ranking of populations.