#### **Statistical Methods**

Lecture 3 – Using statistics to summarise data

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### **Central Tendency**

Variability and Normality

**Sample Correlation Coefficient** 



#### Statistics are numerical quantities computed from data:

- These summarize certain features of the data
- Central tendency: mean, median and mode
- Variation/dispersion/spread: variance, standard deviation (and percentile ranges)
- Correlation: correlation coefficient
- There are others: skew, kurtosis...

We will look first at measures of central tendency.

### Sample mean



For n data-points  $x_1, x_2, \dots, x_n$  sample mean defined as:

$$\bar{x} = \frac{\sum_{i=1}^{n} x_i}{n}$$

- For data  $y_i = x_i + c$ , then  $\bar{y} = \bar{x} + c$
- For data  $y_i = cx_i$ , then  $\bar{y} = c\bar{x}$
- Weighted average:

$$ar{x} = \sum_{i=1}^n w_i x_i$$
 where  $\sum_i w_i = 1$ 

Calculate mean from frequency table using weighted average:

$$\bar{x} = \sum_{i=1}^{n} \frac{f_i}{n} x_i$$

### **Example usage: mean**



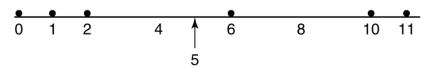
Compare severity of motorcycle accidents, for drivers with and without helmets [?] analysed in [?, Sec. 3.2].

Classification	with helmet	without helmet
0	248	227
1	58	135
2	11	33
3	3	14
4	2	3
5	8	21
6	1	6
Totals	331	439
Mean Severity	0.432	0.902



Deviations: differences between data values and mean:

- *i*th deviation is  $x_i \bar{x}$
- Deviations sum to 0:  $\sum_{i} x_i \bar{x} = 0$
- Physical analogy: n weights of equal mass placed on (weightless) rod at positions xi, i = 1, ..., n
  - $\circ$   $\bar{x}$  is centre of mass (point at which rod balances)
  - $(x_i \bar{x})$  is  $x_i$ 's signed distance from centre



Centre of mass for 0, 1, 2, 6, 10 and 11 [?, Sec. 3.2]



For *n* ordered data-points  $x_1, x_2, \ldots, x_n$  (such that  $x_i \leq x_{i+1}$ ), sample median defined as:

$$m = \begin{cases} x_i & \text{for } i = \frac{n+1}{2}, \text{ if } n \text{ is odd} \\ (x_i + x_{i+1})/2 & \text{for } i = \frac{n}{2}, \text{ if } n \text{ is even} \end{cases}$$

- If data is symmetric, mean  $\approx$  median
- Median less affected by extreme values
- Median may be more relevant for some questions

### Sample percentiles



Sample 100p percentile defined as data value such that at least: 100p% of data are less than or equal and 100(1-p)% are greater than or equal. If two data values satisfy condition, then it is the arithmetic average of these values.

For *n* ordered data-points  $x_1, x_2, \ldots, x_n$  (such that  $x_i \leq x_{i+1}$ ), then the sample 100p percentile

$$= \begin{cases} x_i & \text{for } i = \lceil np \rceil, \text{ if } np \text{ not integer} \\ (x_i + x_{i+1})/2 & \text{for } i = np, \text{ if } np \text{ is integer} \end{cases}$$

The  $25^{th}$ ,  $50^{th}$  and  $75^{th}$  percentiles respectively called the  $1^{st}$ ,  $2^{nd}$  and  $3^{rd}$  quartiles.

# Sample mode and Benford's law



Sample mode defined as the data value that occurs most frequently in the data set.

- If no single value occurs most frequently, then all highest frequency values are called modal values...
- ...and we say there is no unique sample mode.

Benford's law (First-Digit Law) is observation that first digits in many real-life data sets are biased towards the smaller numbers.

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### Sample Variance and Standard Deviation



For *n* data-points  $x_1, x_2, \dots, x_n$  sample variance defined as:

$$s^{2} = \frac{1}{n-1} \sum_{i=1}^{n} (x_{i} - \bar{x})^{2}$$

- A measure of the variability of data
- Almost, the average squared deviation (from the mean)
- Important algebraic identity:

$$\sum_{i=1}^{n} (x_i - \bar{x})^2 = \sum_{i=1}^{n} x_i^2 - n\bar{x}^2$$

• Sample standard deviation (SD) is square root of the variance.

$$s = \sqrt{s^2} = \sqrt{\frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x})^2}$$



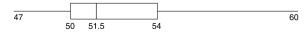
- Sample SD measured in same units as original data
- Sample variance measured in squared units of original data
- Variance (and SD) unaffected by constant shift, i.e. for data  $y_i = x_i + c$ , then  $s_v^2 = s_x^2$
- Scaling has squared influence on variance, i.e. for data  $y_i = cx_i$ , then  $s_v^2 = c^2 s_x^2$
- ... and for SD,  $s_y = |c| s_x$

# Other measures of variation/dispersion/s



Variance and SD are not the only statistical measures of dispersion. Of these, the most common is probably interquartile range:

- difference between sample 75<sup>th</sup> and 25<sup>th</sup> percentiles
- used for box-plots, e.g. starting salary data [?, p. 95]



Other measures are much rarer:

• Mean absolute deviation (about the mean):

$$MAD = \frac{1}{n} \sum_{i=1}^{n} |x_i - \bar{x}|$$

may be simpler to understand [?]

 Median absolute deviation about the median (also MAD) used in robust statistics (resistant to outliers) [?]

# Normality and the empirical rule



A data set is said to be normal if a histogram describing it has properties:

- 1. Highest at the middle interval.
- 2. Height decreases in both directions in a bell-shape
- 3. Symmetric about its middle interval
- From symmetry, mean and median approx. equal
- Empirical rule specifies approx. proportions of data within s, 2s, and 3s of  $\bar{x}$  as 68%, 95% and 99.7% respectively.

Bimodal data (with 2 peaks) is not normal, and may represent a mixture of sub-populations.

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# Sample Correlation Coefficient



The sample correlation coefficient for paired data:

$$\{(x_i,y_i)\}_{i=1}^n = \{(x_1,y_1),(x_2,y_2),\dots(x_n,y_n)\}$$

measures degree to which larger x values go with larger y values and smaller x values go with smaller y values. Given by:

$$r_{xy} = \frac{\sum_{i=1}^{n} (x_i - \bar{x})(y_i - \bar{y})}{(n-1)s_x s_y}$$

where  $\bar{x}$  and  $\bar{y}$  are means of x and y data respectively and  $s_x$  and  $s_y$  are their sample standard deviations.

Sometimes called Pearson's product-moment correlation coefficient OR Pearson's r OR just the r-value.



#### Some properties of Pearson's r:

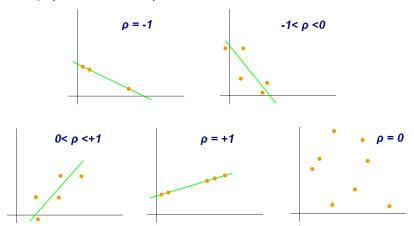
- 1.  $-1 \le r \le +1$
- 2. if  $y_i = a + bx_i$  for b > 0, i = 1, ..., n then  $r_{xy} = +1$  perfectly positively correlated
- 3. if  $y_i = a + bx_i$  for b < 0, i = 1, ..., n then  $r_{xy} = -1$  perfectly negatively correlated
- 4. For  $\{(u_i, v_i)\}_{i=1}^n$  where  $u_i = a + bx_i$  and  $v_i = c + dy_i$  for i = 1, ..., n and bd > 0 then

$$r_{uv} = r_{xy}$$

(r unaffected by rescaling.)



Here  $\rho$  (Greek letter rho) rather than r:

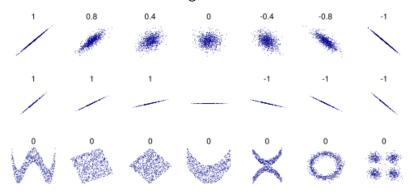


By Kiatdd - Own work, CC BY-SA 3.0 [link].

# More Examples



#### r values shown above each image:



By DenisBoigelot, original uploader was Imagecreator - Own work, original uploader was Imagecreator, CC0, [link].

# References I

