Preliminary Mechanical Design

1C03 - Milestone I

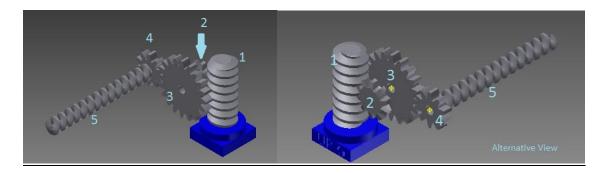
Group 41

400023762 - Shalmi Patel (patels19@mcmaster.ca)

400032887 - Kylee Schra(schrak1@mcmaster.ca)

400022825 - Ali Shah(shahs12@mcmaster.ca)

Mechanism Overview



This mechanism has a total of five gears. The blue section in the above diagrams depicts the motor which drives the first worm (1). Gear 1 and gear 2 in the above diagram worm a worm-drive pair, meaning the worm gear (2) is turned by the first worm (1). The worm gear (2) then reduces the output of the worm (1) by a factor of 10 and is mounted to the first spur gear (3) at a distance such that the worm's (1) motion is unaffected by the first spur gear (3). Both, the worm gear (2) and the first spur gear (3), rotate at the same speed. In order to increase the speed again for the final output, the second spur gear (4), meshed with the first spur gear (3), provides an increase by a factor of 2. This motion is then transferred to the final worm (5) from the second spur gear (4) along an axial mount. The final worm (5) and second spur gear (4) rotate at the same speed. As the final worm (5) rotates, the pin, attached to the read head, moves horizontally. This converts the rotational motion into linear motion.

Group Meetings

The group has planned to meet every week on Wednesday at 6:30pm. The group will also meet during printing times, and any other necessary times needed outside our regular time on Wednesdays.

Calculations

T 2 01) · (100 mm mm/6)
10/01/ 11/10/1 103/11/2/
Target Output: 105 mm m/s
Frank 110 x 41 = 8110 11.1/200
Emput 210 x 41 = 8610 12 / min
= 143.5 (er/s
· Final 10+0+ional output
· [Mad 10+0+10 Mar Outph)
105mm/s -> ACP constanil but 1 and 4
The Constitution of
ACP -ACP= 3.67
So, 105 mm/s
- 004
3.67 my/m = 28.61 /cv/s
Stage One: Reduction
Worm Drive A.V.
Diameter 6 mm
· W = 143.5 /10/5
(11.) (60)
10/00m/ 1 1 2
Worm Gear A.Z.
w, z toget by in he
- = = 10 /0 10 h
W Z
11.35 /a/e
m, = = 2 target we is with the target we is with the target we is with the target the ta
1435 /a/s
143.5 - 7 Module 1
143.5 = = = 2 Module 1
143.5 = == 22 Module 1 14.35 dianneter 10
14.35 = == 22 Module 1 14.35 diameter 10 teeth 10
14.35 = == 22 Module 1 14.35 diameter 10 teeth 10
143.5 = == 22 Module 1 14.35 dianneter 10
14.35 = == 22 Module 1 14.35 diameter 10 teeth 10
14.35 = == 22 Module 1 14.35 diameter 10 teeth 10
143.5 = == 22 Module 1 14.35 = dianuter 10 teeth 10
14.35 = == 22 Module 1 14.35 diameter 10 teeth 10
143.5 = == == Module 1 14.35 = == == diameter 10 10 = == == == == == == == == == == == ==
14.35 = == 2 Module 1 14.35 = == 2 diameter 10 10 = 7 Sipur Gear B Axial moint to A.2.
14.35 = == 2 Module 1 14.35 = == 2 diameter 10 10 = 7 Sipur Gear B Axial moint to A.2.
14.35 = == 22 Module 1 14.35 == == 22 Module 1 10 = 72 Spur Geor B Axial mont to A.2. -diameter 10 to sacrlidate inverse.
14.35 = == ? Module 1 14.35 = diameter 10 10 = ?, Spur Geor B Axial mont to A.2. -diameter 20 to sacretitate increase in each stage, so
14.35 = == ? Module 1 14.35 = diameter 10 10 = ?, Spur Geor B Axial mont to A.2. -diameter 20 to sacretitate increase in each stage, so
14.35 = 22 Module 1 14.35 diameter 10 10 = 7, Spur Gear B Axial mont to A.Z. -diameter 20 to sacritate increase in mat stage, So 20 teeth
14.35 = == 2 Module 1 14.35 diameter 10 10 = 72 Spur Gear B Axial mount to A.E. -diameter 20 to sacretitate increase in mext stage, so 20 tects madule 1
14.35 = == 2 Module 1 14.35 diameter 10 10 = 72 Spur Gear B Axial mount to A.E. -diameter 20 to sacretitate increase in mext stage, so 20 tects madule 1
14.35 = 22 Module 1 14.35 diameter 10 10 = 7, Spur Gear B Axial mont to A.Z. -diameter 20 to sacritate increase in mat stage, So 20 teeth

my = 2(14.33) = 70 = 28.7/ev/5 Feeth 10, mother 1 Spul gear D C · maridais W, mole distance So wz=w, Dz=D, diometer=10 seeth =10 module=1 Find norm V = w ACP 3.67 V = (3.67)(28.7) 105.32 mm/s