DIJKSTRAS

Greedy Algorithm Paradigm

- Characteristics of greedy algorithms:
 - Make a sequence of choices
 - Each choice is the one that seems best so far, only depends on what's been done so far
 - Choice produces a smaller problem to be solved
- Optimal solution to the big problem contains optimal solutions to subproblems

Designing a Greedy Algorithm

 Cast the problem so that we make a greedy (locally optimal) choice and are left with one subproblem

 Prove there is always a (globally) optimal solution to the original problem that makes the greedy choice

 Show that the choice together with an optimal solution to the subproblem gives an optimal solution to the original problem

Some Greedy Algorithms

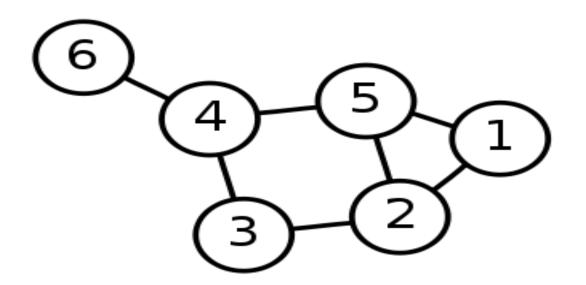
- Huffman codes
- Kruskal's MST algorithm
- Prim's MST algorithm
- Dijkstra's algorithm

DIJKSTRAS

From \rightarrow A	В	С	D	E	F
A	25	35	00	00	00
В	25	40	00	00	00
C	25	40	00	70	00
E	25	40	80	70	00
D	25	40	80	70	100

Single-Source Shortest Path Problem

Single-Source Shortest Path Problem - The problem of finding shortest paths from a source vertex *v* to all other vertices in the graph.



Dijkstra's algorithm

Dijkstra's algorithm - is a solution to the single-source shortest path problem in graph theory.

Works on both directed and undirected graphs. However, all edges must have nonnegative weights.

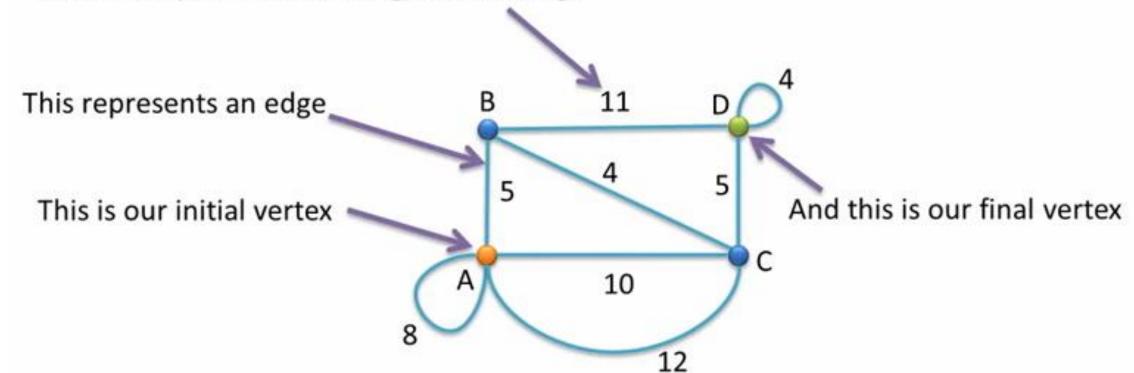
Approach: Greedy

Input: Weighted graph G={E,V} and source vertex *v*∈V, such that all edge weights are nonnegative

Output: Lengths of shortest paths from a given source vertex *v*∈V to all other vertices

Here is our graph

And this represents the weight of the edge



Step 1: Remove all the loops

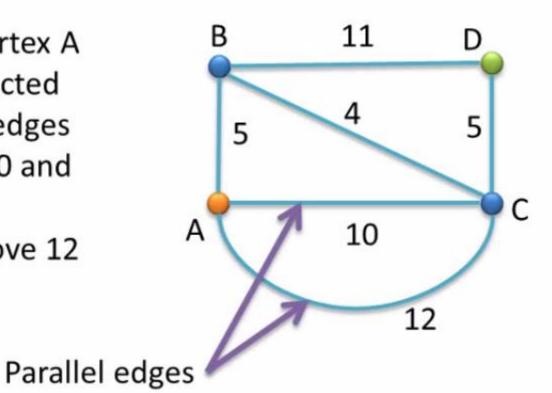
Note! Any edge that 11 starts and ends at the same Loop vertex is a loop. 10 Loop

Step 2: Remove all parallel edges between two vertex except the one with least weight

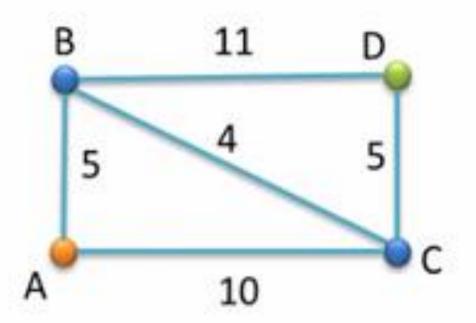
Note!

In this graph, vertex A and C are connected by two parallel edges having weight 10 and 12 respectively.

So, we will remove 12 and keep 10.

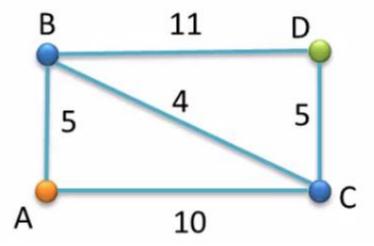


We are now ready to find the shortest path from vertex A to vertex D



Step 3: Create shortest path table

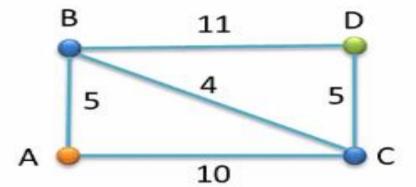
As our graph has 4 vertices, so our table will have 4 columns



Α	В	С	D

Note!

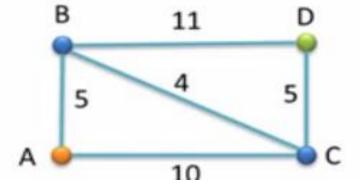
Column name is same as the name of the vertex.



А	В	С	D
0	∞	∞	

Note! We have written 0 in column A, as because vertex A is our source. Now in the 1st row write 0 in column A and ∞ in other columns.

∞ denotes Infinity



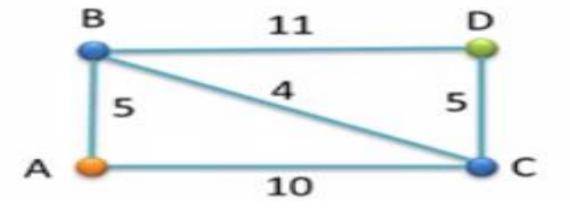
Value in the columns denote the weight of the shortest path.

So, 0 in column A denotes we are at vertex A and ∞ in all other columns denote unexplored vertices.

Α	В	С	D
0	~		

Now that the 1st row is completely filled, our next job is to find the smallest unmarked value in the 1st row.

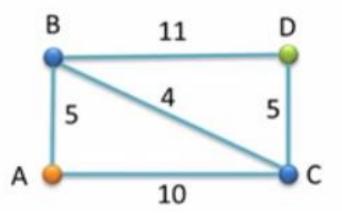
Looking at the table we can say that 0 is the smallest unmarked value in the 1st row. So we will mark it with a square box.



 Marked
 A
 B
 C
 D

 A
 0
 ∞
 ∞
 ∞

As column A was marked in the previous step, so we will now look for edges that are directly connected with vertex A.



Now draw another row and copy all the marked values in the new row.
In this case 0 is copied.

Marked	Α	В	С	D
A	0	000	∞	∞
	0			

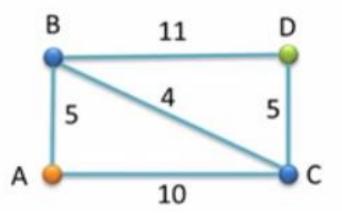
In this case we have an edge of weight 5 that directly connects A and B

Find the edge that **directly** connects vertex A and vertex B

 Marked
 A
 B
 C
 D

 A
 0
 ∞
 ∞
 ∞

As column A was marked in the previous step, so we will now look for edges that are directly connected with vertex A.



Now draw another row and copy all the marked values in the new row.
In this case 0 is copied.

Now before we proceed further I want to tell you something about the minimum value formula that we are going to using in our calculation.

Minimum Value Formula

If we consider two vertices X (Source vertex) and Y (Destination vertex) and an edge that directly connects them.

Then we will have the following formula:

Min(DestValue, MarkedValue + EdgeWeight)

DestValue = The value in the destination vertex (i.e., Y) column.

MarkedValue = The value in the source vertex (i.e., X) column.

EdgeWeight = The weight of the edge that connects the source (i.e., X) and the destination (i.e., Y) vertex.

Minimum Value Formula

Solving:

Min(DestValue, MarkedValue + EdgeWeight)

We will get the minimum value that we will put in the destination vertex (i.e., Y) column.

For example:

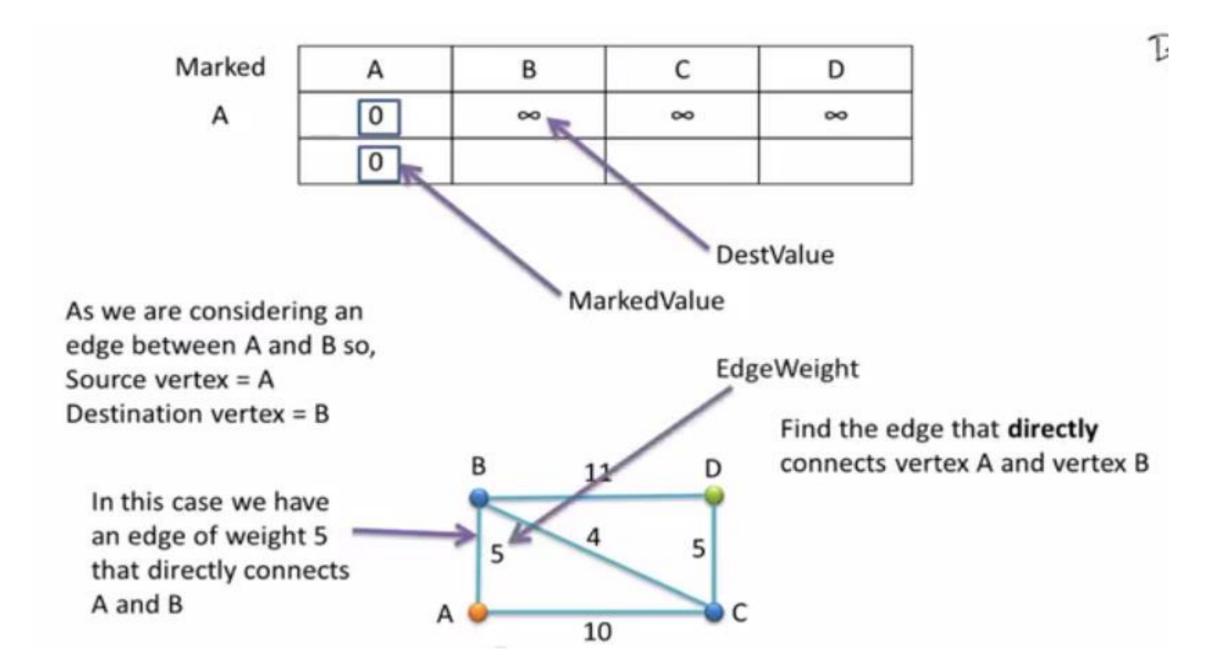
If DestValue = 10, MarkedValue = 5 and EdgeWeight = 4

Putting the value we get

Min(10, 5+4)

= Min(10, 9)

= 9 As 9 is smaller than 10.



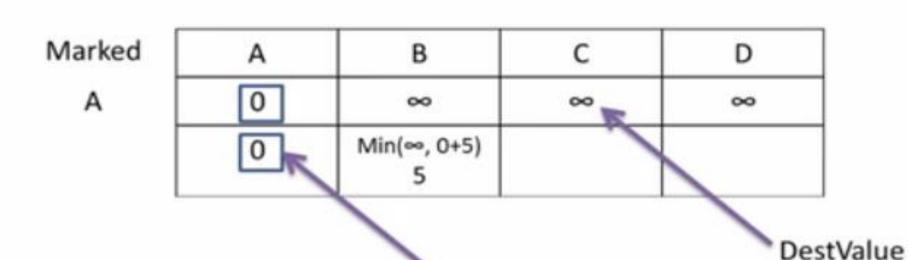
Marked	Α	В	С	D
A	0		∞	∞
	0	Min(∞, 0+5)		

So, we will write Min(∞, 0+5) in column B

Solving Min(∞, 0+5) we get 5. So, we will put the value 5 in column B.

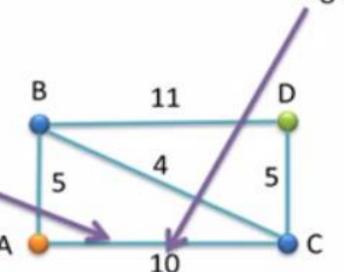
In this case we have an edge of weight 5 that directly connects A and B

Find the edge that directly connects vertex A and vertex B



As we are considering an edge between A and C so, Source vertex = A Destination vertex = C

In this case we have an edge of weight 10 that directly connects A and C



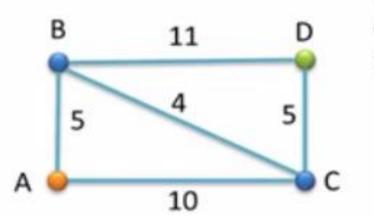
MarkedValue

EdgeWeight

Now find the edge that directly connects vertex A and vertex C Marked A

Α	В	С	D
0		∞	∞
0	Min(∞, 0+5) 5	Min(∞, 0+10) 10	∞

Looking at our graph we find no such edge that directly connects vertex A and D so we will simply copy the previous value in column D i.e., ∞

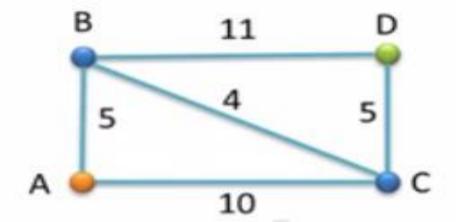


Now find the edge that directly connects vertex A and vertex D

Marked	Α	В	С	D
Α	0	~		∞
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	∞

Now that the 2nd row is completely filled, our next job is to find the smallest unmarked value in the 2nd row.

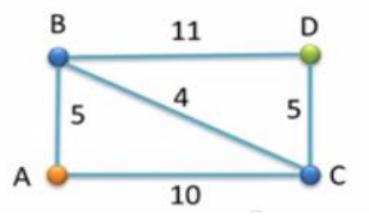
Looking at the table we can say that 5 is the smallest unmarked value in the 2nd row. So we will mark it with a square box.



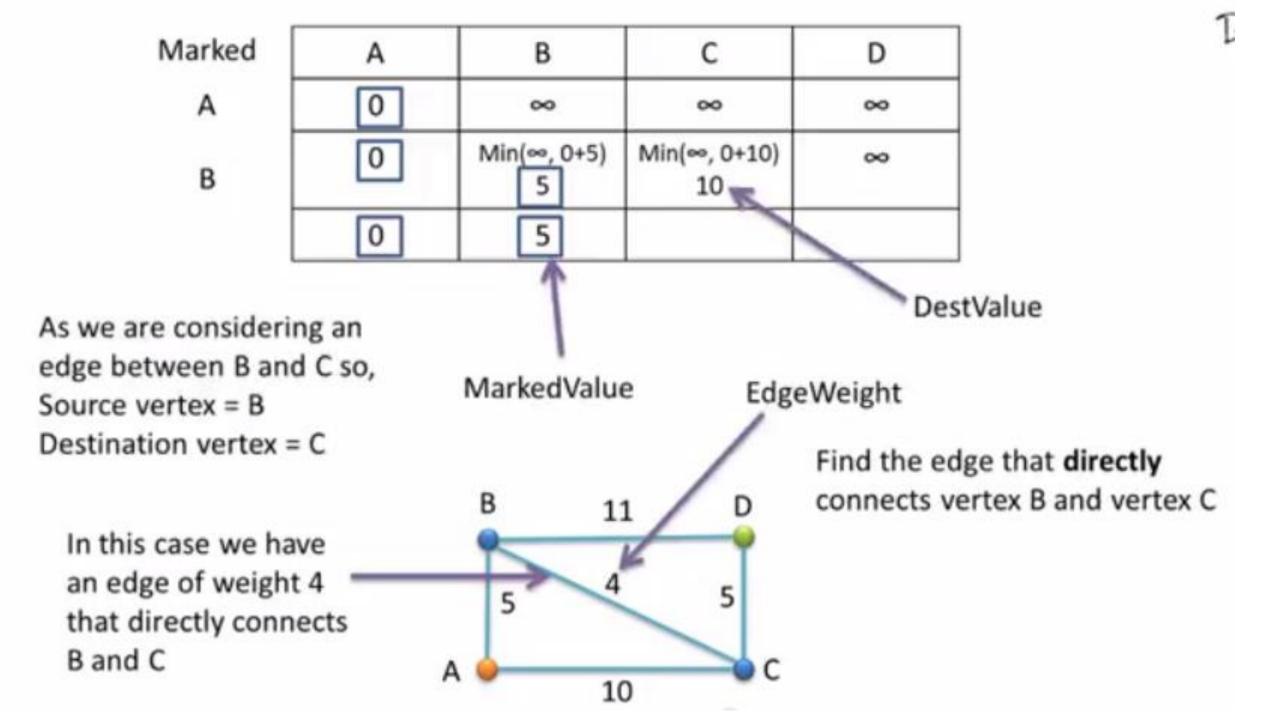
Marked C В Α D Α 0 ∞ 00 ∞ Min(∞, 0+10) Min(∞, 0+5) 0 ∞ В 5 10 5

As column B was marked in the previous step, so we will now look for edges that are directly connected with vertex B.

Note! We don't have to consider vertex A as it is already marked.

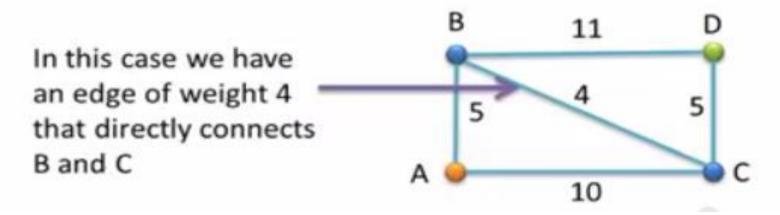


Now draw another row and copy all the marked values in the new row.
In this case 0 and 5 are copied.

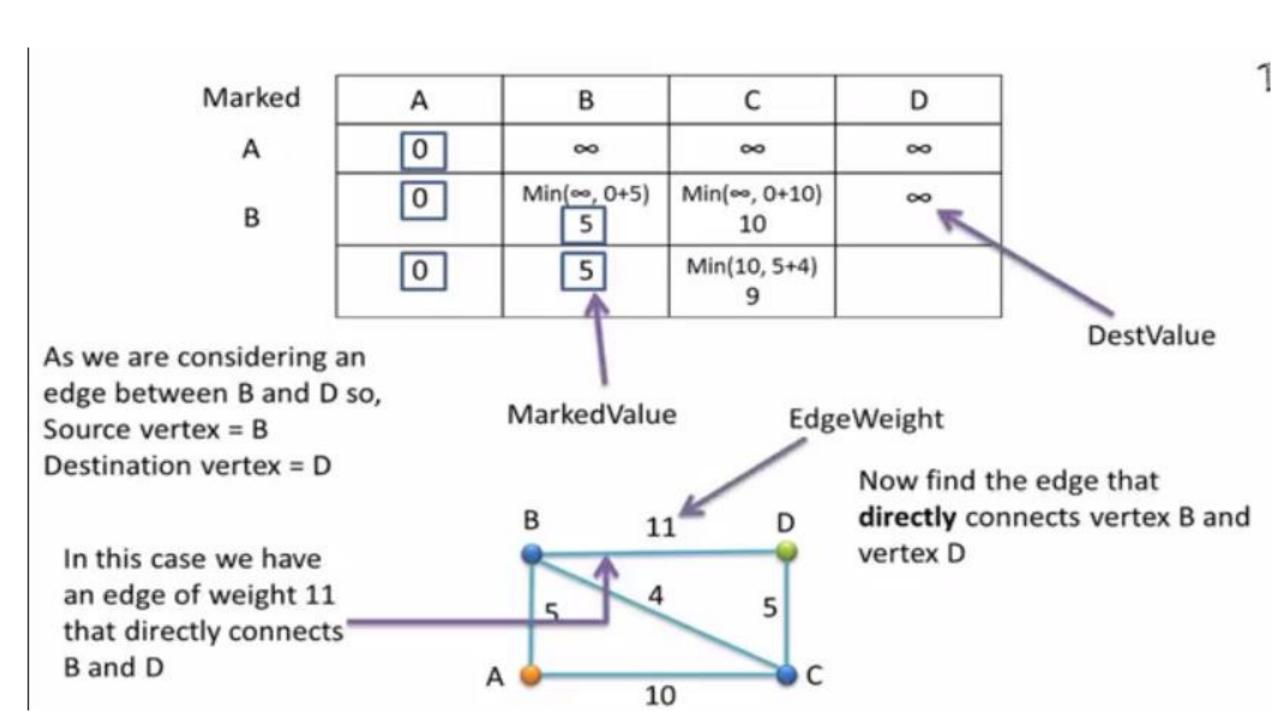


Marked	Α	В	С	D
Α	0		∞	∞
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	∞
	0	5		

So, we will write Min(10, 5+4) in column C. Solving it we get 9.

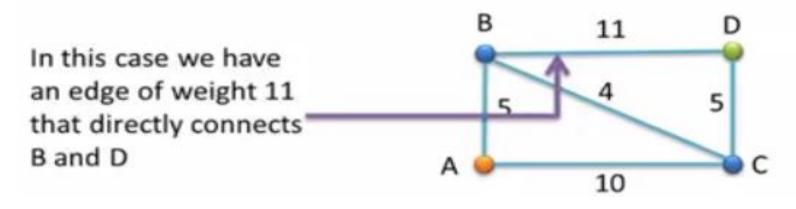


Find the edge that **directly** connects vertex B and vertex C



Marked C Α В D 0 Α ∞ ∞ ∞ Min(∞, 0+5) Min(∞, 0+10) 0 ∞ В 5 10 Min(10, 5+4) 0 5 Min(∞, 5+11) 9 16

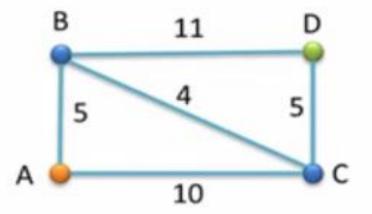
So, we will write $Min(\infty, 5+11)$ in column D. Solving it we get 16.



Now find the edge that directly connects vertex B and vertex D

Marked	Α	В	С	D
Α	0	∞	-	∞
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	000
С	0	5	Min(10, 5+4)	Min(∞, 5+11) 16

Now that the 3rd row is completely filled, our next job is to find the smallest unmarked value in the 3rd row.



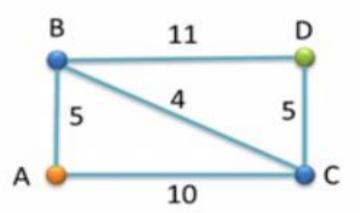
Looking at the table we can say that 9 is the smallest unmarked value in the 3rd row.

So we will mark it with a square box.

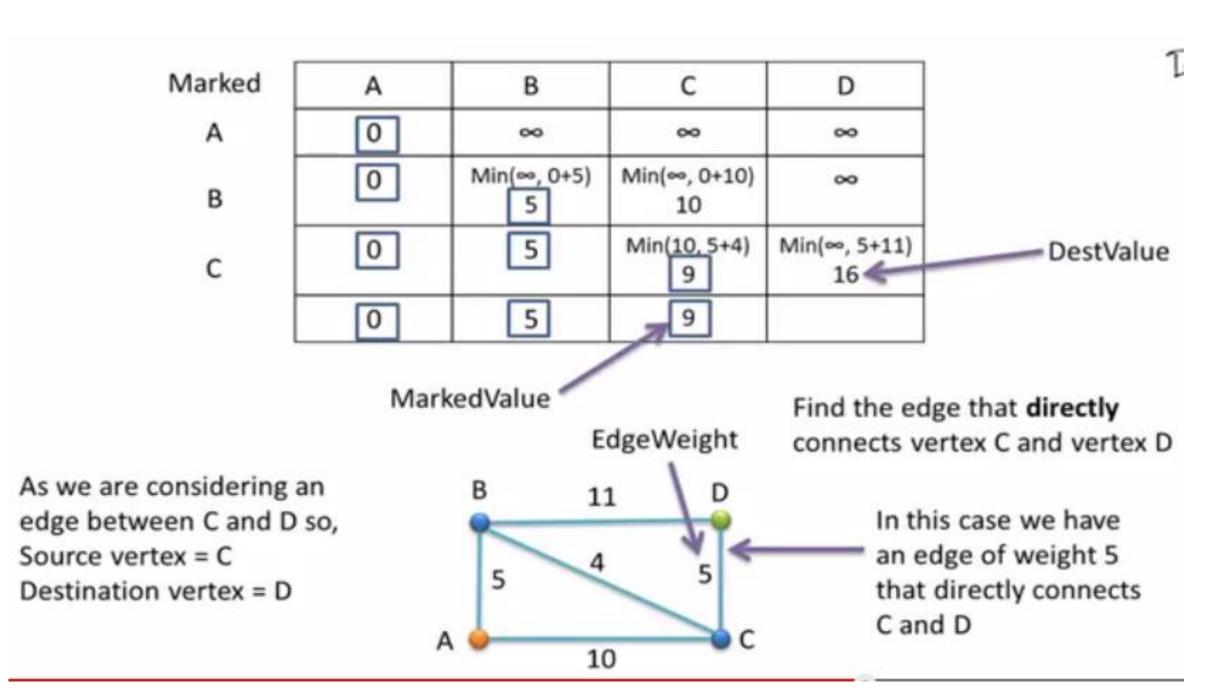
Marked	А	В	С	D
Α	0	∞	∞	∞
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	~
С	0	5	Min(10, 5+4)	Min(∞, 5+11) 16
	0	5	9	

As column C was marked in the previous step, so we will now look for edges that are directly connected with vertex C.

Note! We don't have to consider vertex A and B as they are already marked.



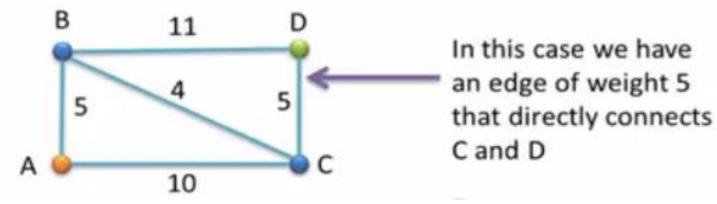
Now draw another row and copy all the marked values in the new row.
In this case 0, 5 and 9 are copied.



Marked	Α	В	С	D
Α	0	000	∞	∞
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	∞
С	0	5	Min(10, 5+4)	Min(∞, 5+11) 16
	0	5	9	Min(16, 9+5) 14

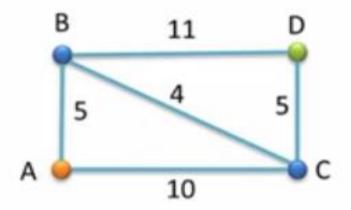
So, we will write Min(16, 9+5) in column D. Solving it we get 14.

Find the edge that **directly** connects vertex C and vertex D



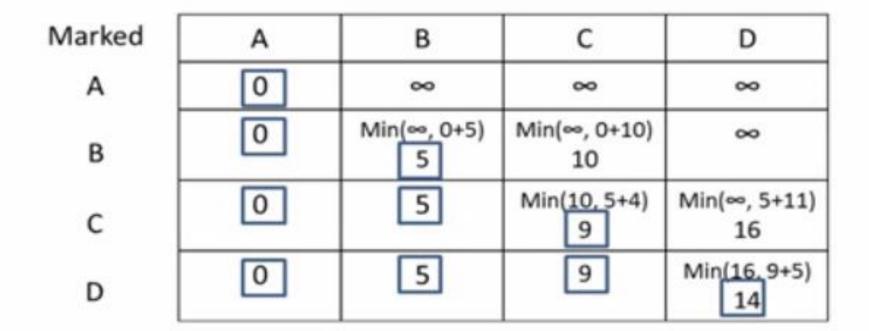
Marked	Α	В	С	D
Α	0	∞	∞	00
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	∞
С	0	5	Min(10, 5+4)	Min(∞, 5+11) 16
	0	5	9	Min(16, 9+5) 14

Now that the 4th row is completely filled, our next job is to find the smallest unmarked value in the 4th row.

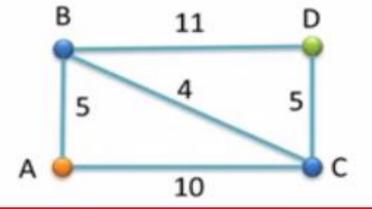


Looking at the table we can say that 14 is the smallest unmarked value in the 4th row.

So we will mark it with a square box.



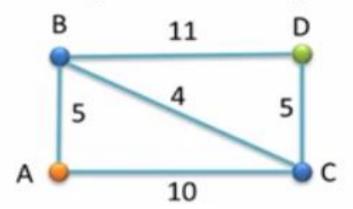
As final vertex **D** is marked so we will stop here.



Marked	Α	В	С	D
Α	0	∞	∞	∞
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	∞
С	0	5	Min(10, 5+4)	Min(∞, 5+11) 16
D	0	5	9	Min(16, 9+5)

Note! Column D has the marked value 14.

This means our shortest path has the weight 14.



ALGORITHM

//Algorithm:Dijkstra's Algorithm

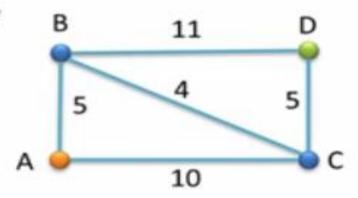
```
Let S be the set of explored nodes For each u \in S, we store a distance d(u) 1 Initially S = \{s\} and d(s) = 0 While S \neq V Select a node v \not\in S with at least one edge from S for which d'(v) = \min_{e=(u, v)} u \in S d(u) + \ell_e \text{ is as small as possible} Add v to S and define d(v) = d'(v) EndWhile
```

Time to find the shortest path using backtracking

Marked	Α	В	С	D
Α	0	∞		∞
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	∞
С	0	5	Min(10, 5+4)	Min(∞, 5+11) 16
D∜	0	5	9	Min(16, 9+5)

Backtracking is very simple.

We will move upwards row by row and will stop only when we find a change in value.



Start from the final marked value 14.

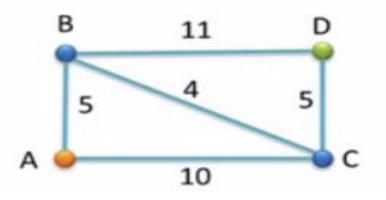
Follow the steps carefully.

Marked	Α	ВС		D
Α	0	∞ ∞		∞
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	~
C⋞	0	5 Min(10, 5+4)		Min(∞, 5+11) 16 (■
D∜	0	5	9	Min(16, 9+5) 14

Move one row upwards.

Has the value changed?

YES It is 16.

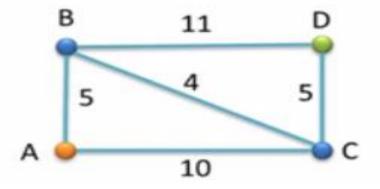


So, tick the vertex that was marked in that row.

i.e., vertex C

Marked	Α	В	С	D
Α	0	∞ ∞		∞
В	0	Min(∞, 0+5)	Min(∞, 0+10) 10	
C 🗸	0	5	Min(10, 5+4)	Min(∞, 5+11) 16
D⋞	0	5	9	Min(16, 9+5)

Move one row upwards.

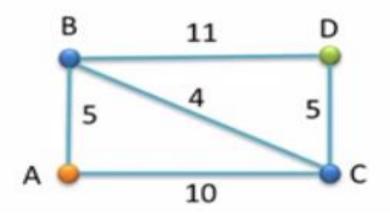


Marked	Α	В	С	D
Α	0	∞	∞	∞
B∢	0	Min(∞, 0+5)	Min(∞, 0+10) 10	∞
C∜	0	5	Min(10, 5+4)	Min(∞, 5+11) 16
D∜	0	5	9	Min(16, 9+5) 14

Move one row upwards.

Has the value changed?

YES It is 10.

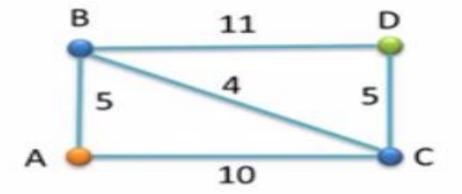


So, tick the vertex that was marked in that row.

i.e., vertex B

Marked	Α	В	С	D
Α	0	~	~	∞
B⋞	0	Min(∞, 0+5)	Min(∞, 0+10) 10	~
C 🗸	0	5	Min(10, 5+4)	Min(∞, 5+11) 16
D⊀	0	5	9	Min(16, 9+5) 14

Move the pointer to point at value 5 in column B



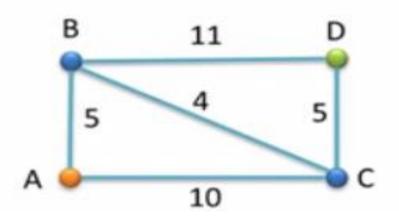
Marked	Α	В	С	D	
A-	0	∞ 🦛	∞		
B∢	0	Min(∞, 0+5)	Min(∞, 0+10) 10		
C∜	0	5	Min(10, 5+4)	Min(∞, 5+11) 16	
D∢	0	5	9	Min(16, 9+5)	

Move one row upwards.

Has the value changed?

YES

It is ∞ (Infinity).



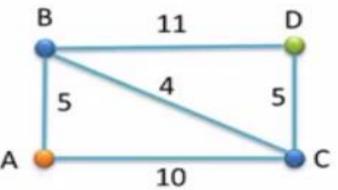
So, tick the vertex that was marked in that row.

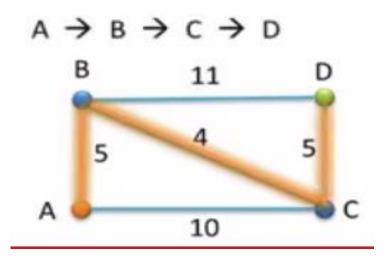
i.e., vertex A

Marked	Α	В	С	D
A-	0	∞ 🦛	∞	000
B√	0	Min(∞, 0+5)	Min(∞, 0+10) 10	
C~	0	5	Min(10, 5+4)	Min(∞, 5+11) 16
S D∢	0	5	9	Min(16, 9+5) 14

Therefore, the required shortest path is

Since the initial vertex A is ticked. So we will stop here.



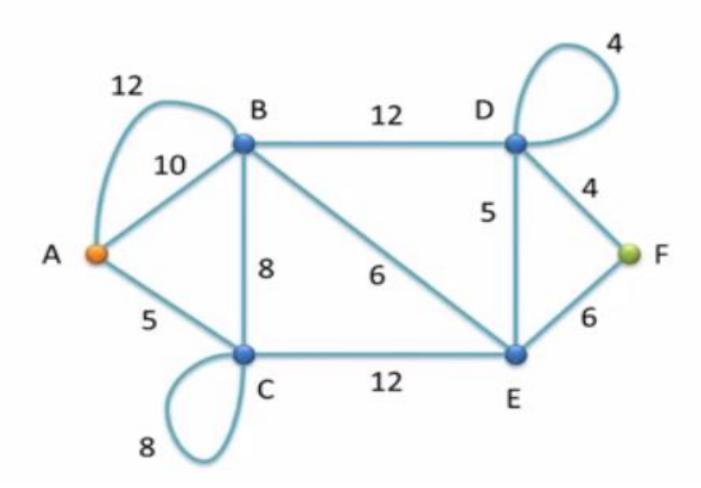


Point to Remember

In case there are two or more columns with the same smallest unmarked value, then you can choose anyone of them.

This only denotes that there will be more than one shortest path in the graph.

Here is our graph

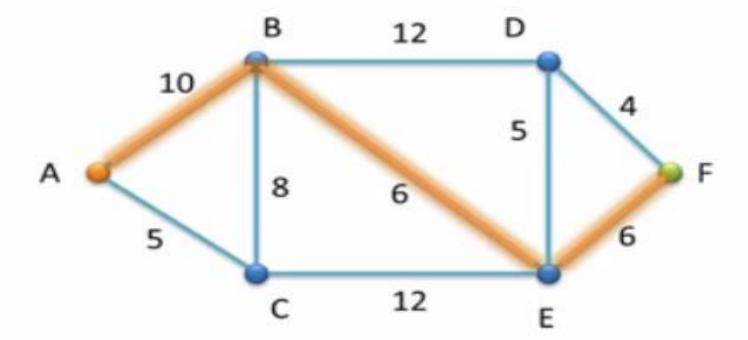


Marked	Α	В	С	D	E	F
/ A /	0	∞ 🦛	∞	∞	∞	∞
c	0	Min(∞, 0+10) 10	Min(∞, 0+5) 5	∞		∞
B✓	0	Min(10, 5+8)	5	∞	Min(∞, 5+12) 17	∞
E✓	0	10	5	Min(⊶, 10+12) 22	Min(17, 10+6)	000
D	0	10	5	Min(22, 16+5)	16	Min(∞, 16+6) 22
_ F-/	0	10	5	21	16	Min(22, 21+4) 22

Since the source vertex is ticked. So we will stop here.

Therefore, the required shortest path is

Lets mark the shortest path $A \rightarrow B \rightarrow E \rightarrow F$



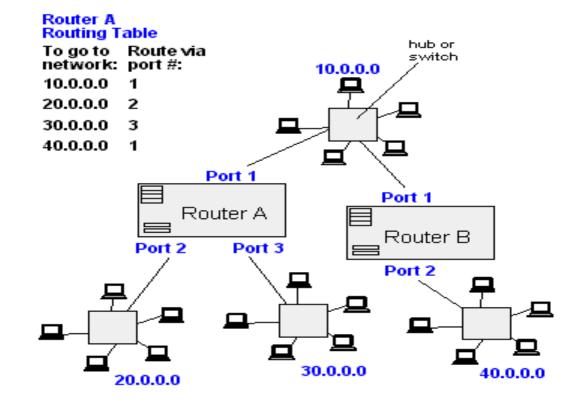
Applications of Dijkstra's Algorithm

- Traffic Information Systems are most prominent use
- Mapping (Map Quest, Google Maps)
- Routing Systems



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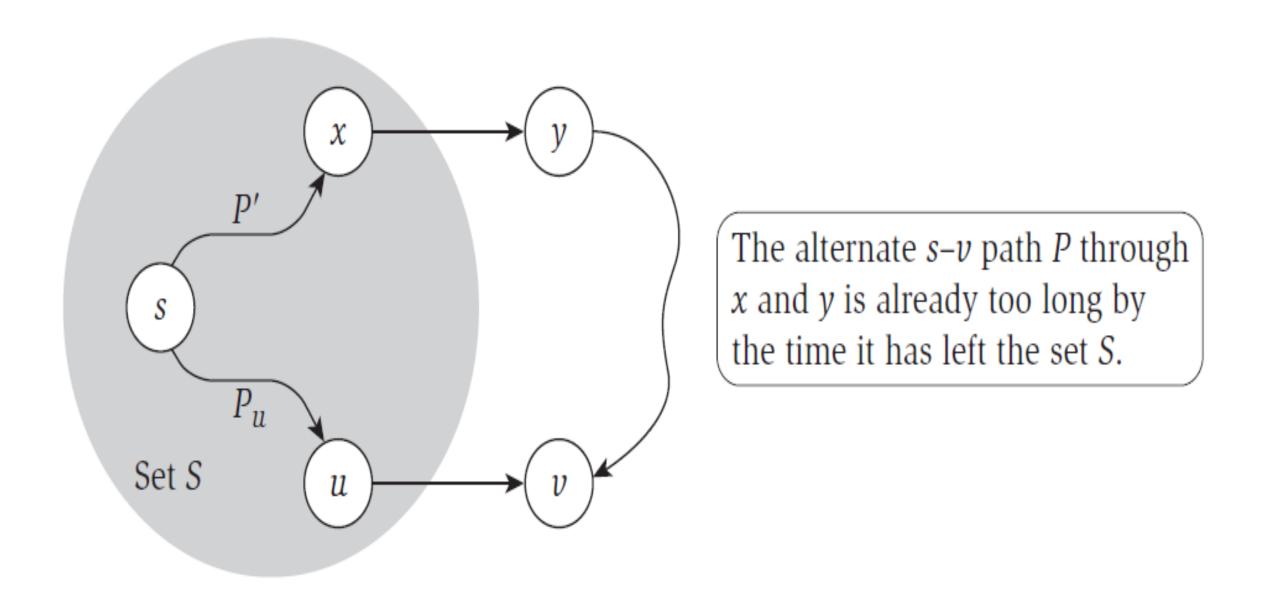
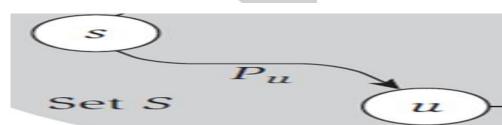


Figure 4.8 The shortest path P_v and an alternate s-v path P through the node y.

• Consider the set S at any point in the algorithm's execution. For each $u \in S$, the path Pu is a shortest s-u path.

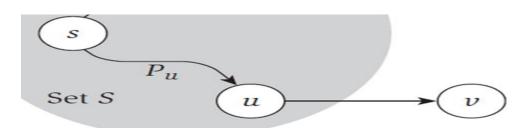
- **Proof.** We prove this by induction on the size of *S*.
- Case |S| = 1, we have set $S = \{s\}$ and d(s) = 0.
- when |S| = k for some value of $k \ge 1$



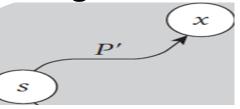
Set S

• By induction hypothesis, Pu is the shortest s-u path for each $u \in S$.

- Now grow S to size k + 1 by adding the node v.
- Let (u, v) be the final edge on our s-v path Pv.



- Consider any other s-v path P; we wish to show that it is at least as long as Pv.
- In order to reach v, this path P must leave the set S somewhere.



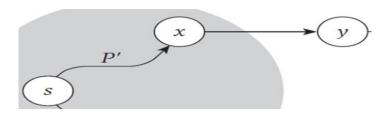
• Let y be the first node on P that is not in S, and let $x \in S$ be the node just before y.

• P cannot be shorter than Pv because it is already at least as long as Pv by the time it has left the set S.

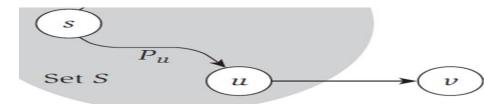
• In iteration k + 1, Dijkstra's Algorithm must have considered adding node y to the set S via the edge (x, y) and rejected this option in favor of adding v.



• Since edge lengths are nonnegative, the full path P is at least as long as Pv



P is at least as long as Pv



• Let P' be the subpath of P from s to x.

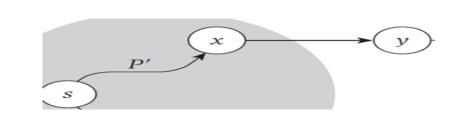


• Since $x \in S$, we know by the induction hypothesis that Px is a shortest s-x path and so

$$L(P') \ge L(Px) = d(x)$$
.

• The subpath of P out to node y has length

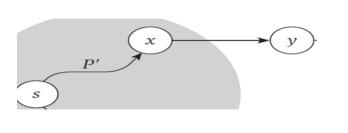
$$L(P') + L(x, y) \ge d(x) + L(x, y) \ge d'(y)$$



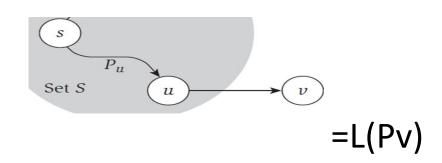
•

• Since Dijkstra's Algorithm selected v in this iteration. We know that

$$d'(y) \ge d'(v) = L(Pv).$$

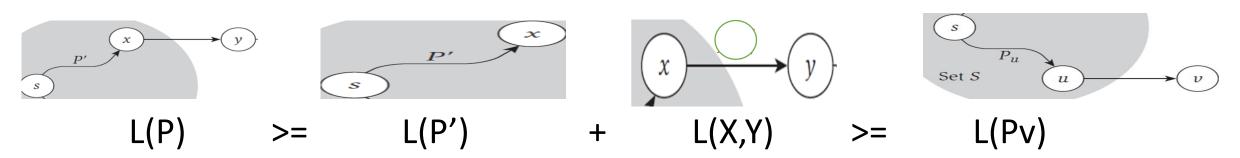


$$d'(Y) >= d'(v)$$

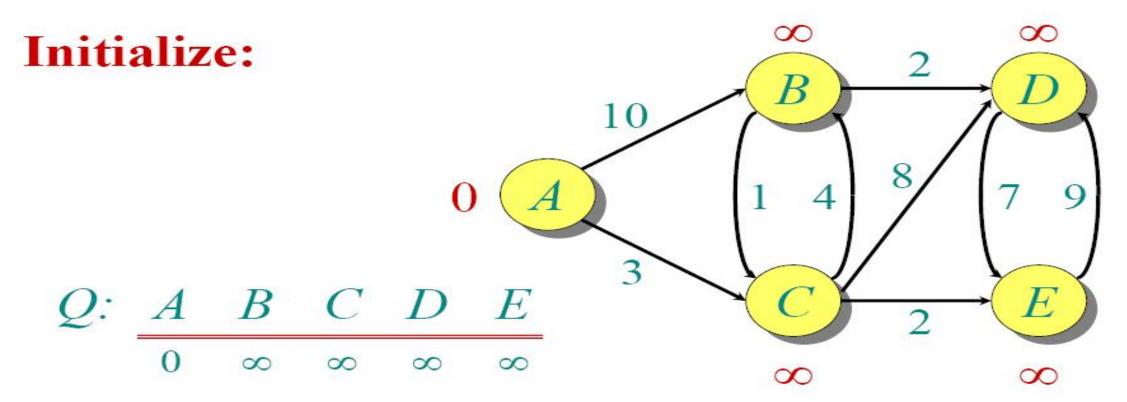


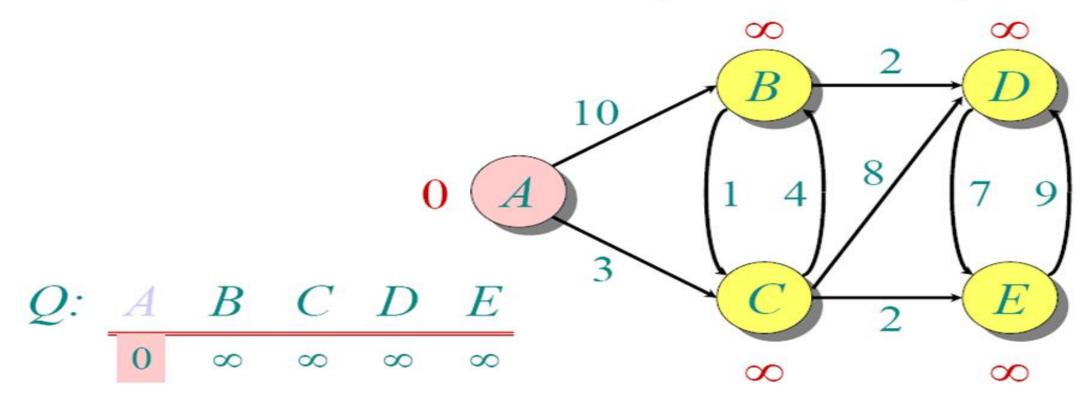
Combining these inequalities shows that

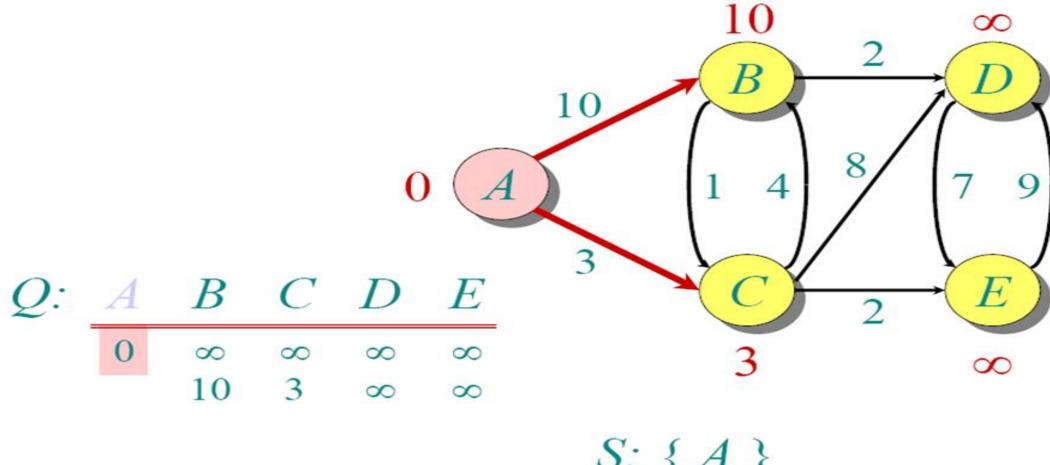
$$L(P) \ge L(P') + L(x, y) \ge L(Pv)$$
.



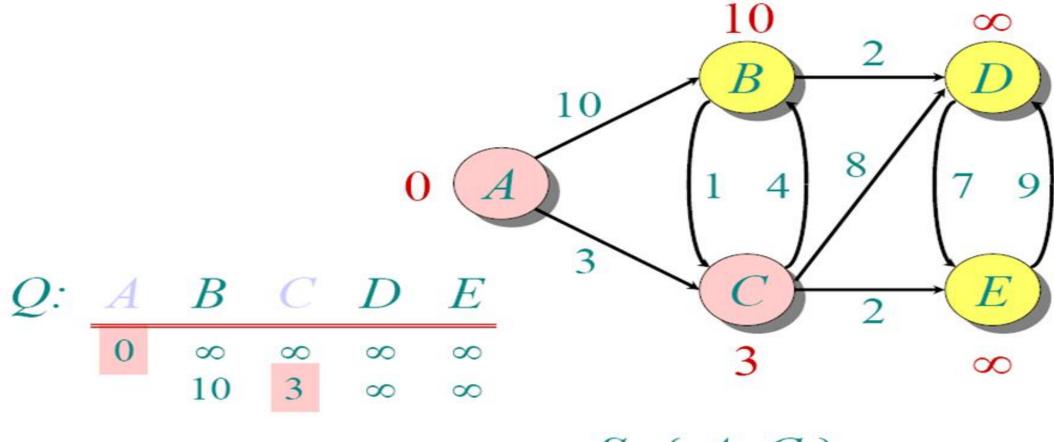
Dijkstra Example for Directed Graph







S: { A }



S: { A, C }

