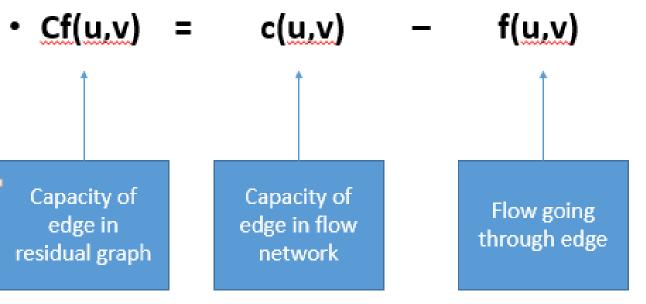
Max flow and flow network

FORD FULKERSON

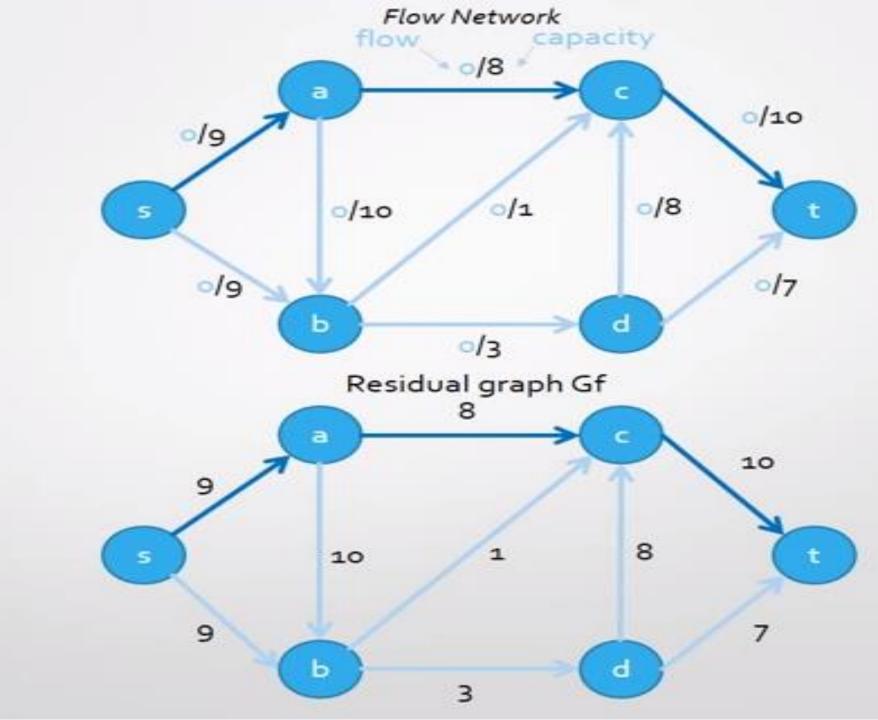
- Once the path is chosen, what ever will be left over we call it as "Residual Graph".
- Augmenting path is the path we are selecting
- Capacity minimum is the

 Augmenting Flow.



- REVERSE EDGE
- Cf(v,u) = c(v,u) + f(u,v)
- Capacity of reverse edge is increased every time when a new flow is flowing through it.

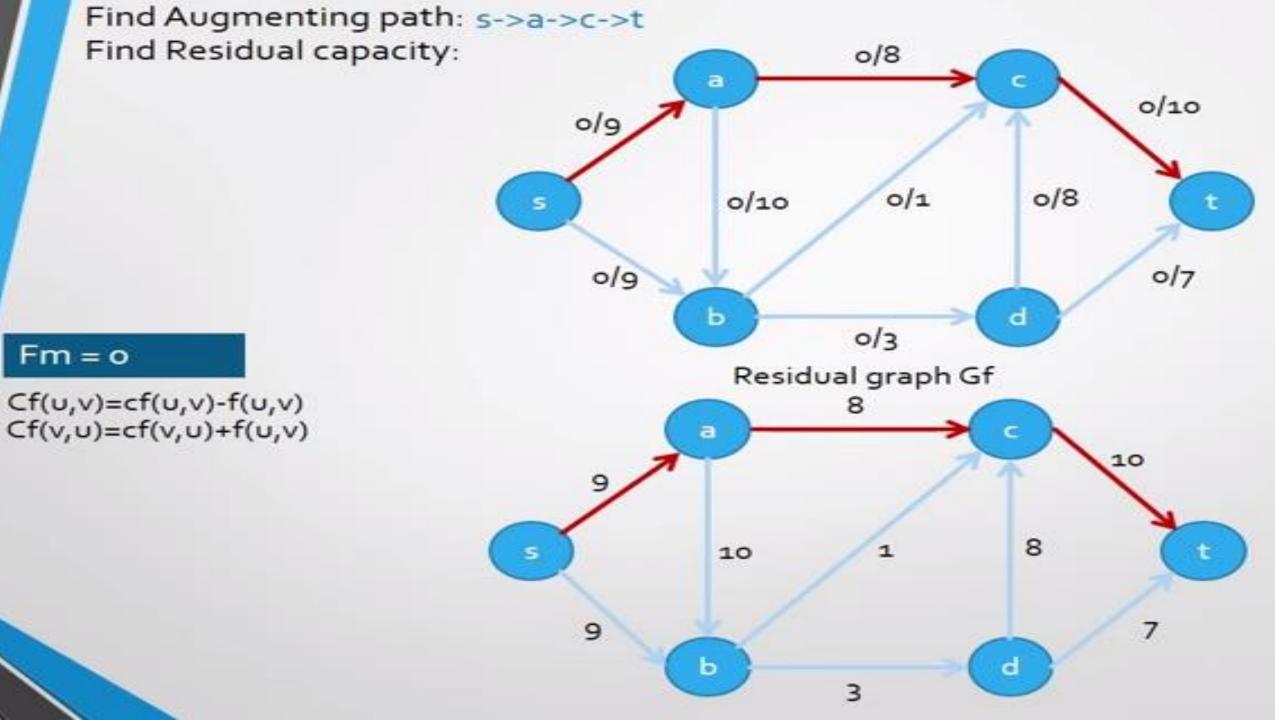
- Flow network (G)
 - Simple Directed graph
 - 1 source s, 1 sink t
 - Non-negative capacity for each edge
- Residual Graph (Gf)
 - Only edges from G that can still have more flow
 - Cf(u,v) = c(u,v) f(u,v)
 - Added edges: reverse edges to decrease flow 'cancellation'
 cf(v,u)=cf(v,u)+f(u,v)
- Augmenting Paths (p)
 - Path from s to t in Gf
 - Residual capacity = smallest capacity of edges of p

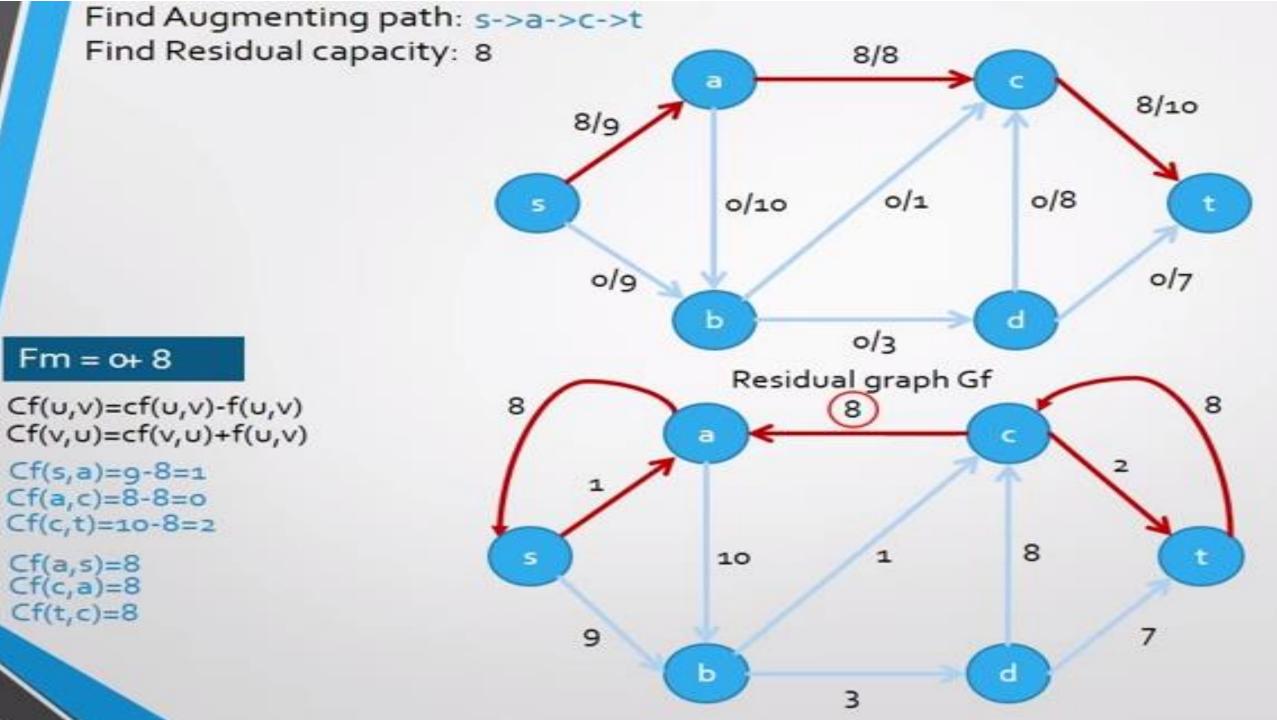


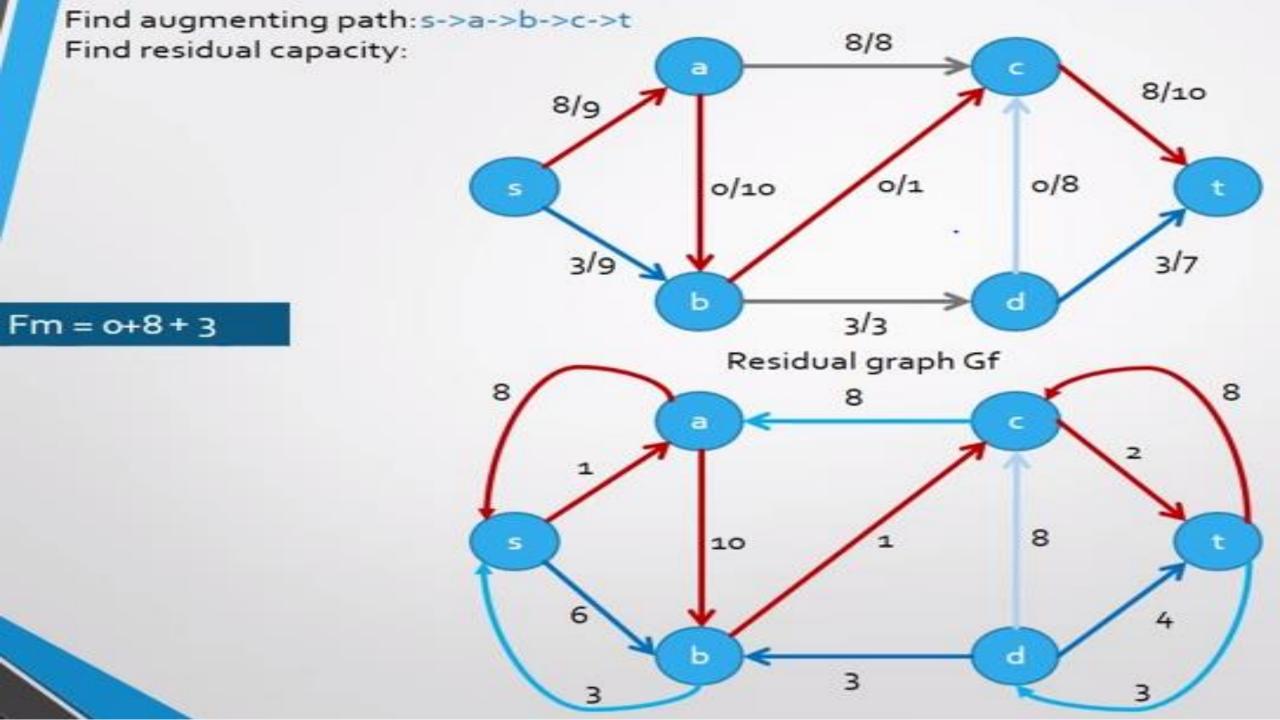
Start:

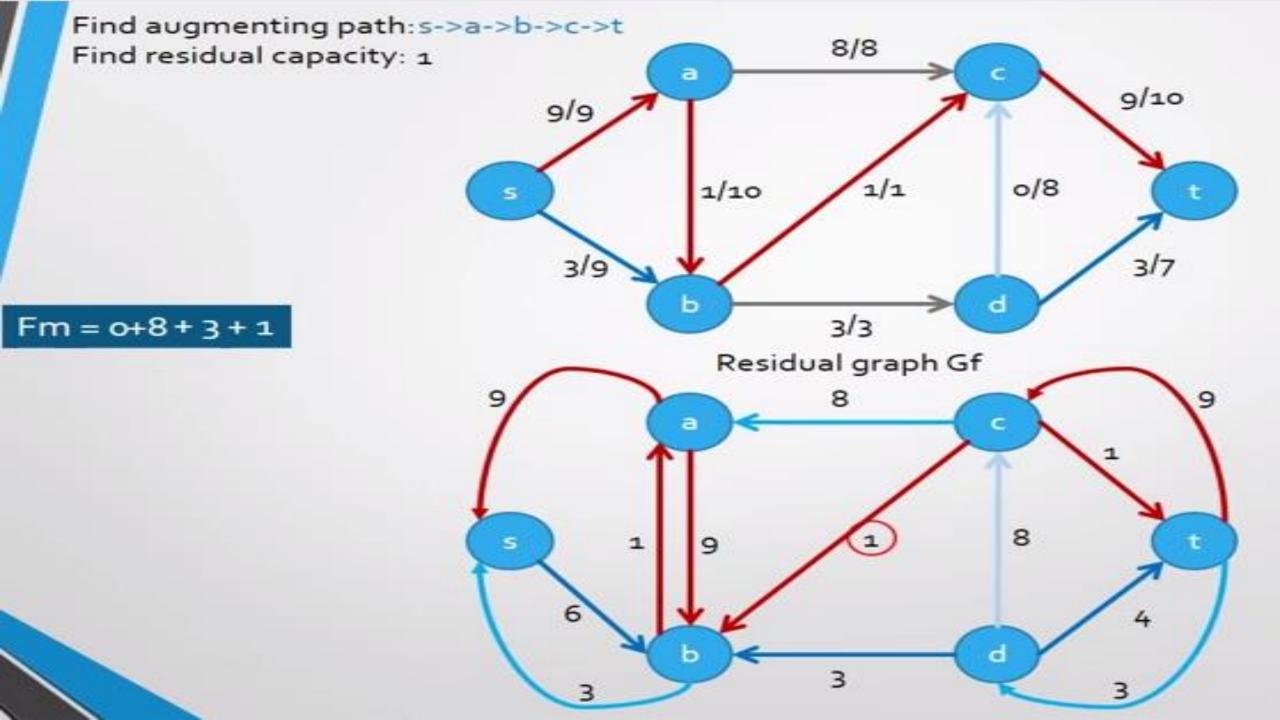
F(u,v) = 0 for all edges

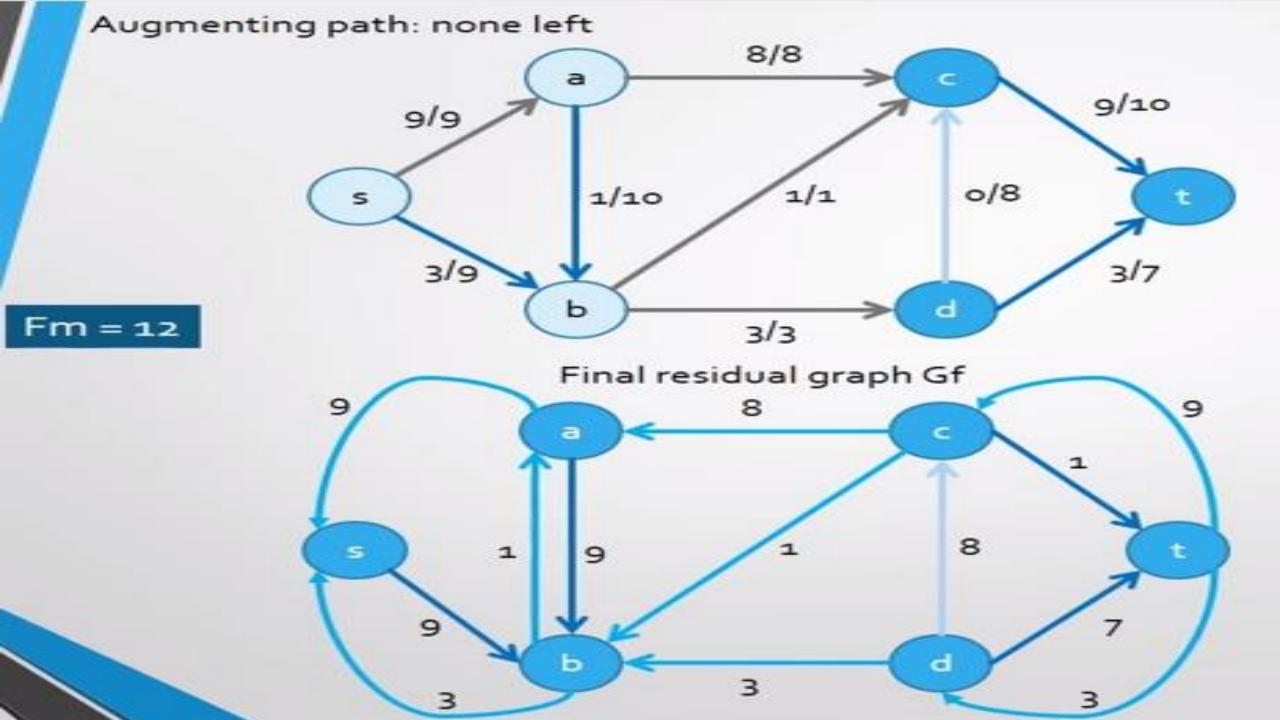
Fm = 0











The algorithm

```
Fm = 0
```

While there exist an augmenting path p in Gf

Find augmenting path p

Cf (p)= smallest capacity on p

Fm = Fm + Cf(p)

For each edge in p

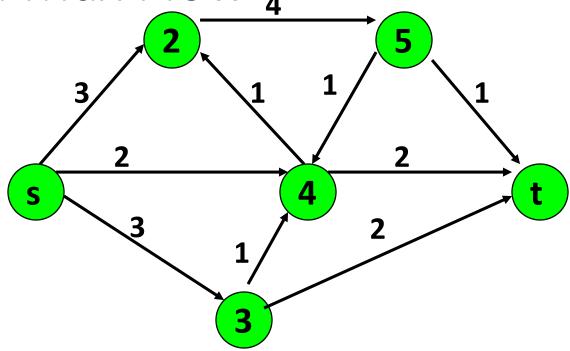
$$cf(u,v) = cf(u,v)-Cf(p)$$

$$cf(v,u) = cf(v,u) + cf(p)$$

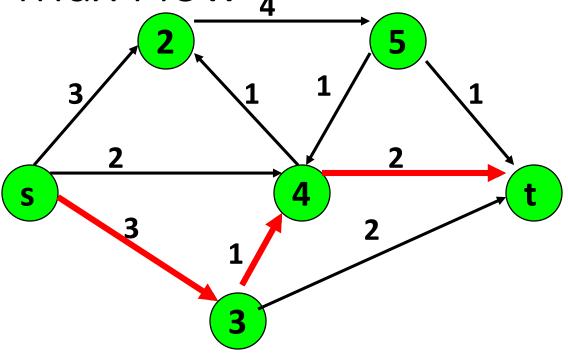
Analysis Complexity of the Algorithm

- Flow increased by at least 1 at every iteration, so the while loop is repeated Fm times at most, where Fm is the maximum flow
 - Finding an augmenting path : O(E) where E is the number of edges
 - Operations on value: O(1) Update the maximum flow, and capacities on the edges
 - Each iteration: O(E)

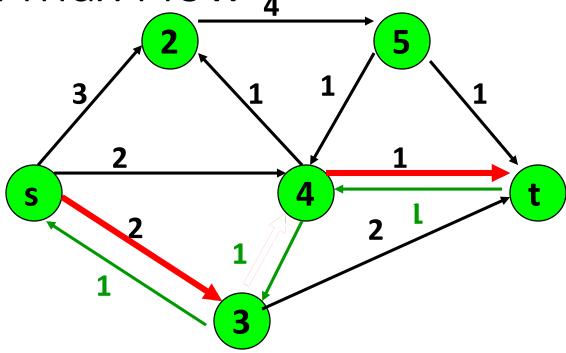
This algorithm runs in time O(E*Fm)



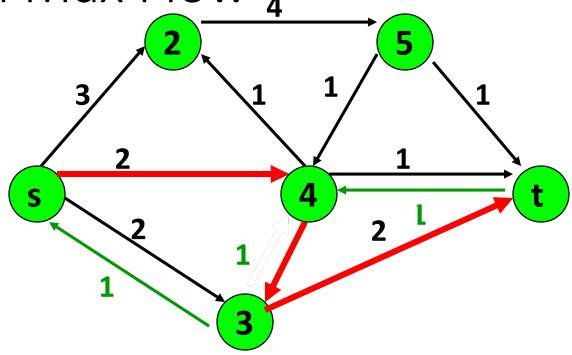
This is the original network, and the original residual network.

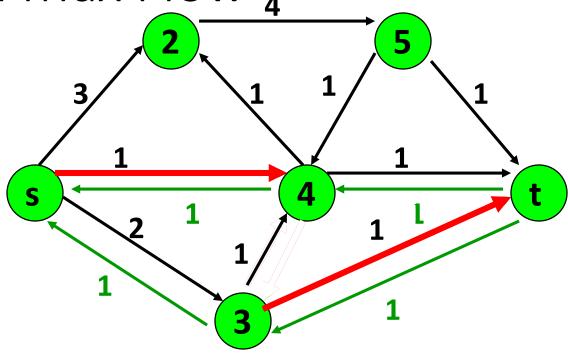


Find any s-t path in G(x)

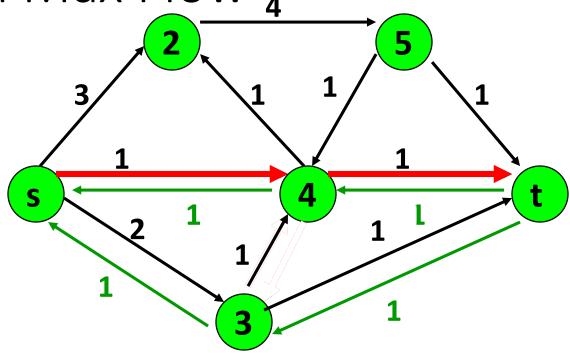


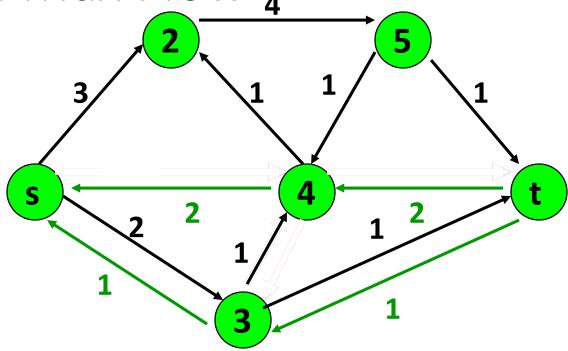
Determine the capacity Δ of the path.



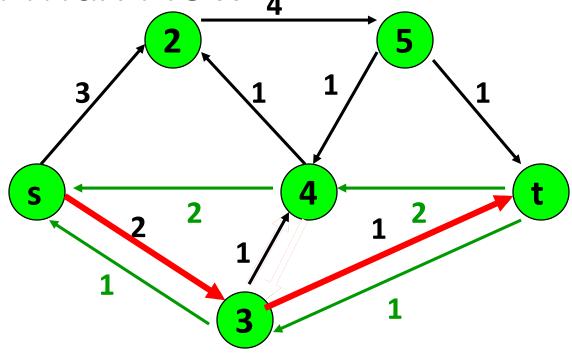


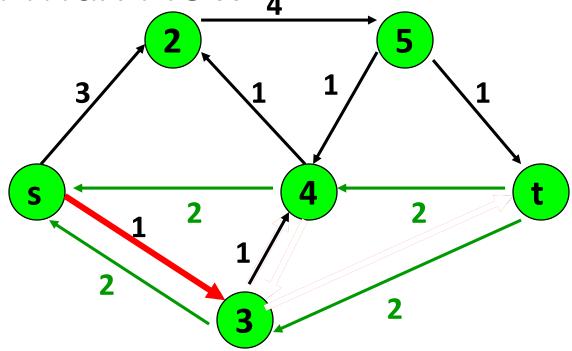
Determine the capacity Δ of the path.



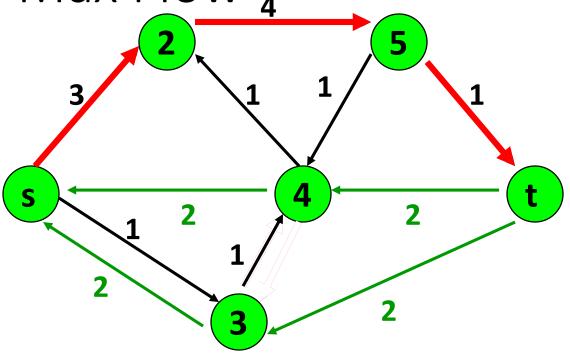


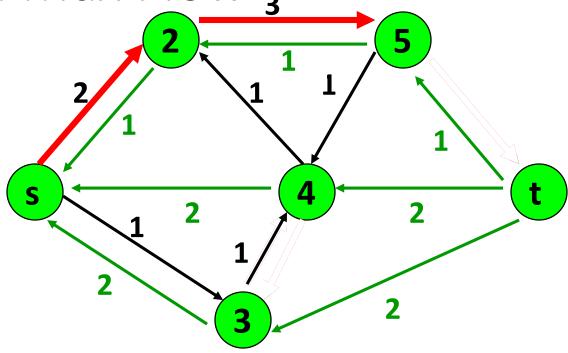
Determine the capacity Δ of the path.



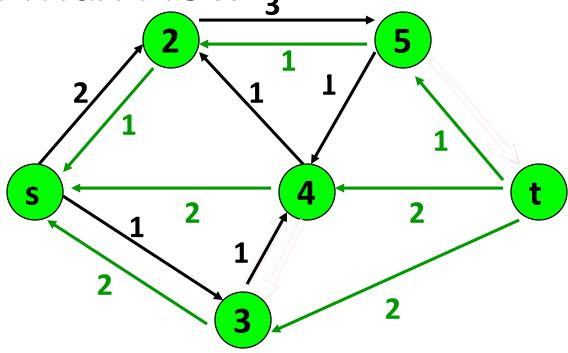


Determine the capacity Δ of the path.

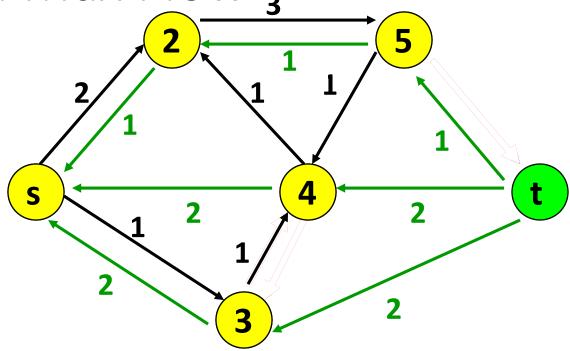




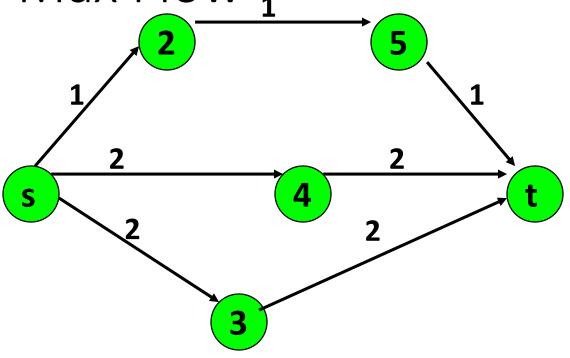
Determine the capacity Δ of the path.



There is no s-t path in the residual network. This flow is optimal



These are the nodes that are reachable from node s.



Here is the optimal flow