

**Artificial Intelligence and Machine Learning (CS52)****Term: October 2024 – Jan 2025****Unit 1 - Problems****Faculty Coordinator : Jamuna S Murthy**

1. Write the PEAS description and task environment characteristics for:
  - Robot vacuum cleaner operating in a household setting.
  - Automated medical diagnostic system for identifying skin cancer.
  - Voice-activated personal assistant (like Siri or Alexa) in a smart home.
  - Stock trading bot designed to maximize returns on stock investments.
  - Agricultural robot responsible for monitoring and optimizing crop growth in a farm field.
  - Speech-based language translation app for real-time conversation translation.
  - Search and rescue drone designed for locating people in a disaster-stricken area.
  - Recommendation system that suggests movies or TV shows to users based on their preferences.
  - AI-driven chatbot for customer service that assists users with common questions and issues.
  - Intelligent traffic management system that controls traffic lights to reduce congestion in a city.
  - Facial recognition system used for security purposes in airports.
  - AI-powered news aggregator that curates personalized news feeds for users.
  - Automated plant-watering system for indoor plants in a greenhouse.
  - Real-time game-playing AI agent designed to play chess against human players.
  - self-driving car navigating urban traffic.
2. Given an initial state of a 8-puzzle problem and final state to be reached-

2	8	3
1	6	4
7		5

**Initial State**

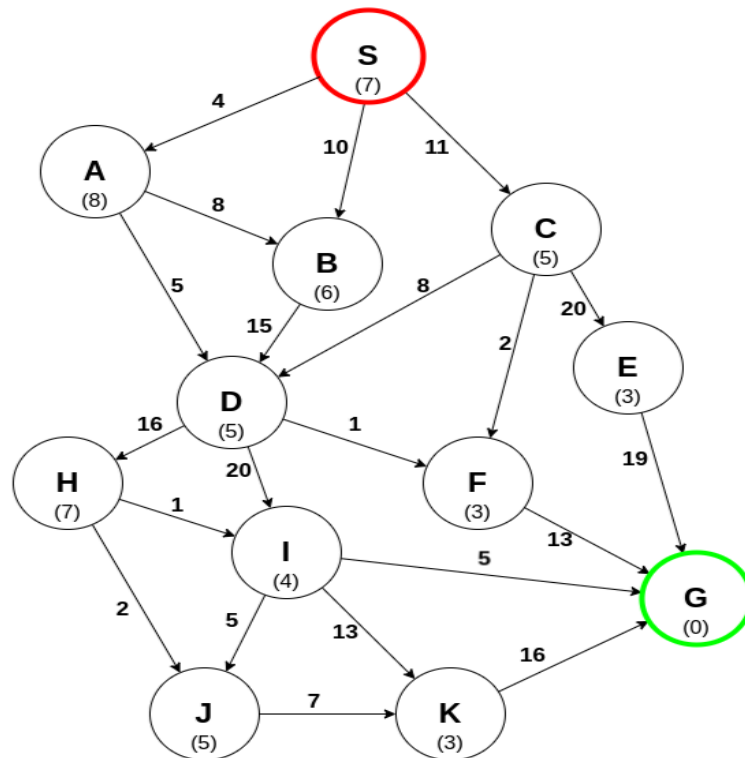
1	2	3
8		4
7	6	5

**Final State**

Find the most cost-effective path to reach the final state from initial state using A\* Algorithm. Consider  $g(n)$  = Depth of node and  $h(n)$  = Number of misplaced tiles.



3. Consider the following graph to find the shortest path from **S** to **G** using A\* Algorithm:



4. Consider the following graph. The numbers written on edges represent the distance between the nodes. The numbers written on nodes represent the heuristic value. Find the most cost-effective path to reach from start state A to final state J using A\* Algorithm.

