

# Applied Economic Forecasting

## 6. Moving Averages & Exponential Smoothing

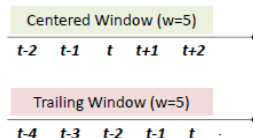
- 1 Moving Average Method
- 2 Simple exponential smoothing

## Section 1

### Moving Average Method

# 1. Centered Moving Averages

- These are powerful for visualizing the trends because they suppress seasonality and noise (the random component).
- These are not as useful for forecasting.



# 1. Centered Moving Averages

- In a centered moving average, the value of the moving average at time  $t$  ( $MA_t$ ) is computed by centering the window around time  $t$  and averaging across the  $k$  values within the window:

$$MA_t = \frac{1}{2k + 1} \sum_{j=-k}^k x_{t+j},$$

where  $t$  changes from  $k + 1$  to  $n - k$ .

For example, with a window of width  $w = 3$ ,

- the moving average at time point  $t = 2$  means averaging the values of the series at time points 1, 2, 3 ;
- at time point  $t = 3$  the moving average is the average of the values at time points 2, 3, 4 and so on.

# 1. Centered Moving Averages

In short, the moving average is centered at the middle of the values being averaged.

Time	Values	Centered MA(3)
1	4	N/A
2	5	4
3	3	4
4	4	4
5	5	N/A

## 2. Simple Moving Averages (Trailing Windows)

- A constant number of data points (fixed window length) are used for forecasting.
- The mean is computed by adding the newest value and dropping the oldest.
- A moving average of order  $k$  (the window length),  $MA(k)$ , is

$$\hat{y}_{t+1} = \frac{y_t + y_{t-1} + \cdots + y_{t-k+1}}{k} = \frac{\sum_{i=1}^k y_{t-i+1}}{k}$$

where  $\hat{y}_{t+1}$  is the forecast value for the next period.  $y_t$  is the actual value at period  $t$ ,  $k$  is the number of terms in the moving average

## 2. Simple Moving Averages (Trailing Windows)

- Calculates the simple arithmetic mean of the data of the  $k$  most recent data.
  - $k$  is determined by the researcher.
- Equal weights are assigned to each observation.
- Each new data point is included in the average as it becomes available, and the earliest data point is discarded.
- The rate of response to changes in the underlying data pattern depends on the number of periods,  $k$ , included in the moving average.



# Choosing the Forecast Window (k)

The choice of the smoothing parameter is a balance between under-smoothing and oversmoothing.

**Narrower windows** the smaller k is better for forecasting in unstable economic environments.

- can more quickly capture the most recent changes in economic conditions.
- reveal local trend.

**Wider windows** the larger k is better for forecasting in stable economic environments. - will expose more global trends

When  $k=1$ , MA becomes the naive forecasting, as  $\hat{y}_{t+1} = y_t$ .

# Examining the Amtrak Ridership Data

Let us apply the knowledge above the some real world data.

```
# Import the Amtrak ridership data from github
fileurl <- "https://raw.githubusercontent.com/Shamar-Stewart/ForecastingS21/master/Lectures/Lecture6/Amtrak_data.csv"
amtrak <- ts(read.csv(fileurl)[,2],
             frequency = 12, start = c(1991,1))

##### Centered MA(12)
order <- 12; ld <- length(amtrak)
ca.ma12 <- ma(amtrak,order = order, centre = TRUE)

##### Creating Rolling MA(12)

order <- 12
ld <- length(amtrak)
sma12 <- matrix(NA,ld)

for (j in 1:(ld - 11)){
  sma12[order+(j-1)] <- mean(amtrak[j: (11 +j)])
}

sma12 <- ts(sma12, frequency = 12, start = c(1991,1))

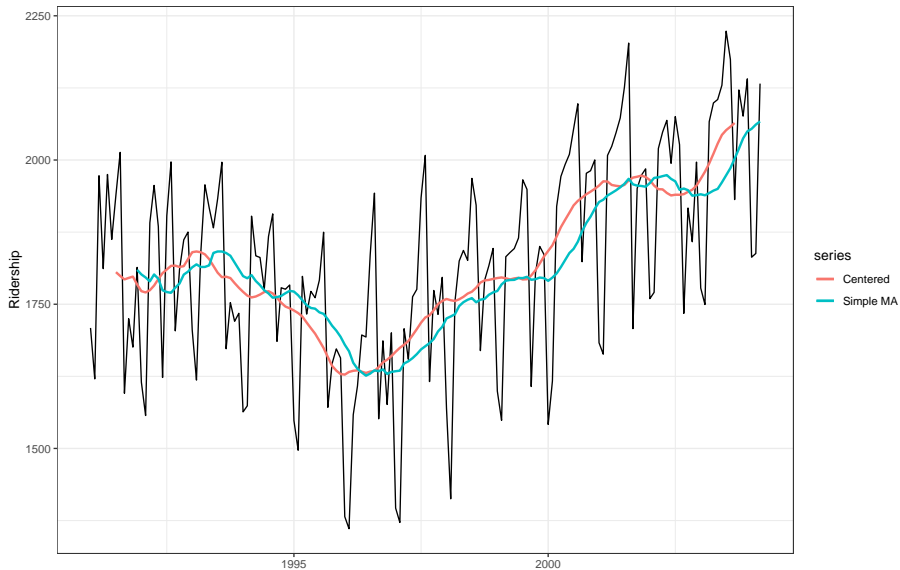
# Using the zoo library
zoo.sma12 <- zoo::rollmean(amtrak,k = 12, fill = NA,
                          align = "right")

# Plot the Amtrak data & MA(12) methods

autoplot(amtrak) + autolayer(ca.ma12 , series = "Centered", lwd = 0.9) +
  autolayer(sma12, series = "Simple MA", lwd = 0.9) +
  labs(title = "Plot of Amtrak Ridership with Trend",
       subtitle = "Trend calculated using a Simple and Centered MA(12)", x = "", y = "Ridership")
```

## Plot of Amtrak Ridership with Trend

Trend calculated using a Simple and Centered MA(12)



# Examining the Amtrak Ridership Data

## Discussion:

- The moving average method is inadequate for generating monthly forecasts because it does not capture the seasonality in the data.
  - Seasons with high ridership are under-forecasted, and seasons with low ridership are over-forecasted as the moving average “lags behind” the actual data.
- A similar issue arises when forecasting a series with a trend:
  - the moving average “lags behind”, thereby under-forecasting in the presence of an increasing trend and
  - over-forecasting in the presence of a decreasing trend.

# Final Words: Moving Averages

- In general, MAs can be used for forecasting only in series that lack seasonality and trend. There are a few popular methods for removing trends (de-trending) and removing seasonality (deseasonalizing) from a series:
  - Regression models,
  - Advanced exponential smoothing methods, and
  - Differencing.
- The MA method can then be used to forecast such de-trended and deseasonalized series, and then the trend and seasonality can be added back to the forecast (think of the series decomposition from Lecture 5).
- Moving Averages is, in general, better than the simple average method of forecasting.

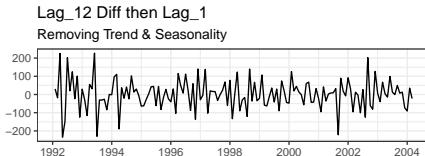
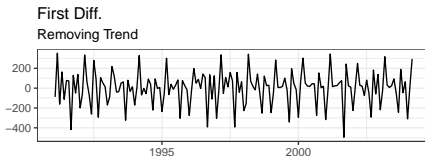
A simple and popular method for removing a trend and/or a seasonal pattern from a series is by the operation of differencing. **Differencing**, as the name suggest, is taking the difference between two values.

- A lag-1 difference (also called first difference) means taking the difference between every two consecutive values in the series  
( $\Delta y_t = y_t - y_{t-1}$ )
  - Lag-1 differencing measures the changes from one period to the next.
- Differencing at lag- $k$  means subtracting the value from  $k$  periods back ( $y_t - y_{t-k}$ ).
  - E.g., for a daily series, lag-7 differencing means subtracting from each value ( $y_t$ ) the value on the same day in the previous week ( $y_{t-7}$ ).
- We can difference the original series and obtain a differenced series that lacks trend and seasonality.

```

g1 <- autoplot(amtrak) + labs(title = "Amtrak Ridership", x = "", y = "Ridership")
g2 <- autoplot(diff(amtrak, 1)) + labs(title = "First Diff.", subtitle = "Removing Trend",
  x = "", y = "")
g3 <- autoplot(diff(amtrak, 12)) + labs(title = "Lag_12 Diff.", subtitle = "Removing Seasonality",
  x = "", y = "")
g4 <- autoplot(diff(diff(amtrak, 12), 1)) + labs(title = "Lag_12 Diff then Lag_1",
  subtitle = "Removing Trend & Seasonality", x = "", y = "")
gridExtra::grid.arrange(g1, g2, g3, g4, ncol = 2)

```



## Section 2

### Simple exponential smoothing



# Simple exponential smoothing

## Problem

In the case of both the simple and moving averages, we assigned equal weights to the most recent observations as well as those far into the past.

$$\hat{y}_{t+1} = \frac{y_t + y_{t-1} + \cdots + y_{t-k+1}}{k}$$

The issue is clear but how do we address this?

## Solution: Exponential Smoothing Methods

- Assign less weights to past observations
- Assign higher weights to more recent data

# Exponential Smoothing Methods

**This method is suitable for forecasting data with no clear trend or seasonal pattern.**

- The exponential smoothing equation can take the form

$$\hat{y}_{t+1} = \alpha y_t + (1 - \alpha) \hat{y}_t \quad (1)$$

where  $0 \leq \alpha \leq 1$  is the smoothing constant or weighting factor.

- Eqn. 1 can be rewritten as

$$\begin{aligned} \hat{y}_{t+1} &= \alpha y_t + \hat{y}_t - \alpha \hat{y}_t \\ &= \hat{y}_t + \alpha (y_t - \hat{y}_t) \end{aligned}$$

- The new forecast is the old forecast adjusted by  $\alpha$  times the forecast error in the old forecast

# Exponential Smoothing Methods

## Question:

In this equation,

$$\hat{y}_{t+1} = \alpha y_t + (1 - \alpha) \hat{y}_t$$

- ① What happens if  $\alpha \rightarrow 1$ ?

**Answer:** As  $\alpha$  is getting bigger, more weight is given to the most recent observation, but less weight to old information.

- ② What happens if  $\alpha \rightarrow 0$ ?

**Answer:** In this case, as  $\alpha$  is getting smaller, less weight is given to the most recent observation, but more weight to old information.

# Exponential Smoothing Methods

- Substitute  $\hat{y}_t = \alpha y_{t-1} + (1 - \alpha) \hat{y}_{t-1}$  into Eqn 1 to yield

$$\begin{aligned}\hat{y}_{t+1} &= \alpha y_t + (1 - \alpha) [\alpha y_{t-1} + (1 - \alpha) \hat{y}_{t-1}] \\ &= \alpha y_t + \alpha (1 - \alpha) y_{t-1} + (1 - \alpha)^2 \hat{y}_{t-1}\end{aligned}$$

# Exponential Smoothing Methods

- Substitute  $\hat{y}_t = \alpha y_{t-1} + (1 - \alpha) \hat{y}_{t-1}$  into Eqn 1 to yield

$$\begin{aligned}\hat{y}_{t+1} &= \alpha y_t + (1 - \alpha) [\alpha y_{t-1} + (1 - \alpha) \hat{y}_{t-1}] \\ &= \alpha y_t + \alpha (1 - \alpha) y_{t-1} + (1 - \alpha)^2 \hat{y}_{t-1}\end{aligned}$$

- Continue this substitution to obtain:

$$\begin{aligned}\hat{y}_{t+1} &= \alpha y_t + \alpha (1 - \alpha) y_{t-1} + \alpha (1 - \alpha)^2 y_{t-2} + \\ &\quad \alpha (1 - \alpha)^3 y_{t-3} + \alpha (1 - \alpha)^4 y_{t-4} + \cdots\end{aligned}\tag{2}$$

**Note**  $\alpha$  determines the speed of decaying impacts of past observations on the forecast value

# Exponential Smoothing Methods

To use exponential smoothing methods, we need to determine:

- ① the value of  $\alpha$  (can be determined by minimizing MSE)
- ② the initial value for the smoothing
  - a) the first observation
  - b) the average of the first five or six observations

# Exponential Smoothing Methods

**Example:** Use the sales data from Acme Tool Company.

- ① Consider  $\alpha = 0.1, 0.6$
- ② Consider the initial period forecast:  $\hat{y}_1 = 500$

Time		Actual Value	Smoothed Value	Forecast	Smoothed Value	Forecast
Year	Quarters	$Y_t$	$\hat{Y}_t(\alpha = .1)$	$e_t$	$\hat{Y}_t(\alpha = .6)$	$e_t$
2000	1	500	500.0	0.0	500.0	0.0
	2	350	500.0	-150.0	500.0	-150.0
	3	250	485.0 (1)	-235.0 (2)	410.0	-160.0
	4	400	461.5 (3)	-61.5	314.0	86.0
2001	5	450	455.4	-5.4	365.6	84.4
	6	350	454.8	-104.8	416.2	-66.2
	7	200	444.3	-244.3	376.5	-176.5
	8	300	419.9	-119.9	270.6	29.4
2002	9	350	407.9	-57.9	288.2	61.8
	10	200	402.1	-202.1	325.3	-125.3
	11	150	381.9	-231.9	250.1	-100.1
	12	400	358.7	41.3	190.0	210.0
2003	13	550	362.8	187.2	316.0	234.0
	14	350	381.6	-31.5	456.4	-106.4
	15	250	378.4	-128.4	392.6	-142.6
	16	550	365.6	184.4	307.0	243.0
2004	17	550	384.0	166.0	452.8	97.2
	18	400	400.6	-0.6	511.1	-111.1
	19	350	400.5	-50.5	444.5	-94.5
	20	600	395.5	204.5	387.8	212.2
2005	21	750	415.9	334.1	515.1	234.9
	22	500	449.3	-50.7	656.0	-156.0
	23	400	454.4	-54.4	562.4	-162.4
	24	650	449.0	201.0	465.0	185.0
2006	25	850	469.0	381.0	576.0	274.0

Figure 1: Exponentially Smoothed Values for Acme Tools Company

# Exponential Smoothing Methods

- ③ Use 1 at 2000Q2 to forecast for 2000Q3 with  $\alpha = 0.1$

$$\hat{y}_{2000Q3} = \alpha y_{2000Q2} + (1 - \alpha) \hat{y}_{2000Q2} = 0.1 * 350 + 0.9 * 500 = 485$$

- ④ The forecast error is

$$e_{2000Q3} = y_{2000Q3} - \hat{y}_{2000Q3} = 250 - 485 = -235$$

- ⑤ Use 1 at 2000Q3 to forecast for 2000Q4 with  $\alpha = 0.1$

$$\hat{y}_{2000Q4} = \alpha y_{2000Q3} + (1 - \alpha) \hat{y}_{2000Q3} = 0.1 * 250 + 0.9 * 485 = 461.5$$

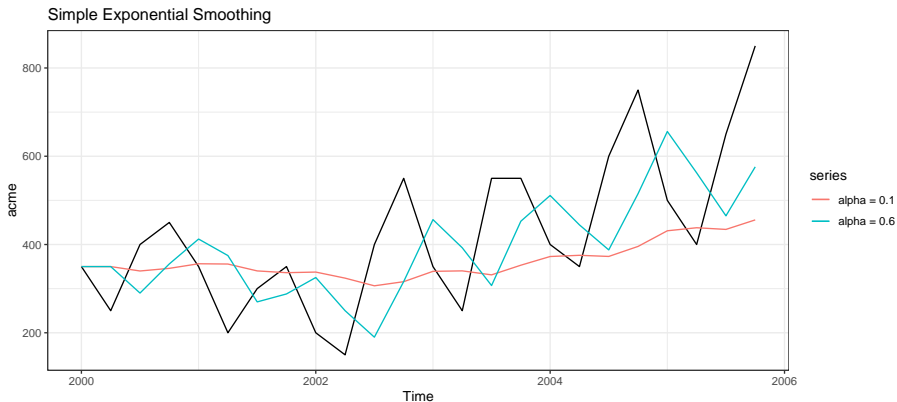
- ⑥ The forecast error is

$$e_{2000Q4} = y_{2000Q4} - \hat{y}_{2000Q4} = 400 - 461.5 = -61.5$$



```
acme <- ts(read.csv("Acme.csv"),frequency = 4,start=c(2000,1))
ses.acme1 <- ses(acme,initial = "simple", alpha = 0.1)
ses.acme2 <- ses(acme,initial = "simple", alpha = 0.6)

autoplot(acme) + autolayer(ses.acme1$fitted, series = "alpha = 0.1") +
  autolayer(ses.acme2$fitted, series = "alpha = 0.6") +
  labs(title = "Simple Exponential Smoothing")
```



```

acme1_MSE <- mean(ses.acme1$residuals^2)
acme2_MSE <- mean(ses.acme2$residuals^2)
acme1_MAPE <- mean(abs(ses.acme1$residuals/acme)*100)
acme2_MAPE <- mean(abs(ses.acme2$residuals/acme)*100)
c1 <- c("MSE" = acme1_MSE, "MAPE" = acme1_MAPE)
c2 <- c("MSE" = acme2_MSE, "MAPE" = acme2_MAPE)
knitr::kable(cbind('$\\alpha = 0.1$' = c1, '$\\alpha = 0.6$' = c2),
  format.args = list(big.mark = ","),
  caption = "Comparison of forecasting Performance")

```

Table 2: Comparison of forecasting Performance

	$\alpha = 0.1$	$\alpha = 0.6$
MSE	26,866.22	24,015.47
MAPE	30.94	35.38

$$MSE = \frac{1}{T} \sum_{t=1}^T e_t^2; \quad MAPE = \frac{1}{T} \sum_{t=1}^T \frac{|e_t|}{|y_t|} \times 100$$

**Notice:** Both MSE and MAPE are large. This means that the methods are not doing a great job of capturing the dynamics of the data.

**Solution:** In addition to  $\alpha$ , we try different initial values.

# Simple Exponential Smoothing

Alternatively, we can allow R to do the optimization and provide us with the optimal values of  $\alpha$ , and the initial forecast value:

```
ses(acme, initial = "optimal", alpha = NULL)
```

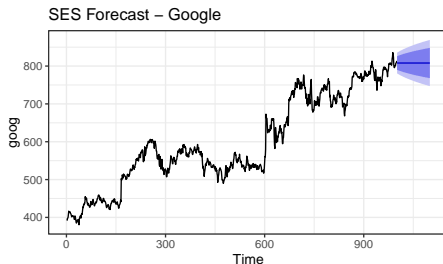
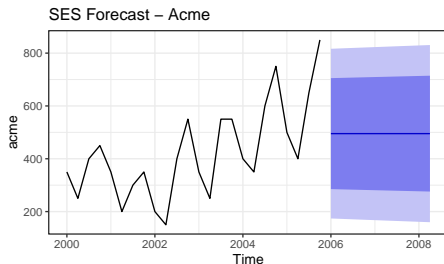
We can then view the optimal model using

```
ses(acme, initial = "optimal", alpha = NULL)$model
```

```
## Simple exponential smoothing
##
## Call:
## ses(y = acme, initial = "optimal", alpha = NULL)
##
## Smoothing parameters:
##   alpha = 0.3225
##
## Initial states:
##   l = 334.754
##
## sigma: 156
##
```

# Forecast from Simple Exponential Smoothing

```
g1 <- autoplot(ses.acme1) + labs(title = "SES Forecast - Acme")
ses.goog <- ses(goog, alpha = .2, h = 100)
g2 <- autoplot(ses.goog) + labs(title = "SES Forecast - Google")
gridExtra::grid.arrange(g1,g2,ncol = 2)
```



## CAUTION!!!

We see that our forecast projects a flatlined estimate into the future. This does not capture the possible positive trend in the data.

This is why a simple exponential smoothing should not be used on data with a trend or seasonal component.

# Exponential Smoothing Adjusted for Trend

## Holt's Method

### Holt's Method

- allows for evolving local linear trends in a time series
- can be used to generate forecasts
- Advantage: flexible to track changing in level and trend

## Equations for Holt's smoothing

- 1 The exponentially smoothed series, or current level estimate

$$L_t = \alpha y_t + (1 - \alpha) (L_{t-1} + T_{t-1}) \quad (3)$$

where  $L_t$  is the new smoothed value (estimate of current level).

Eq. 3 is very similar to the equation for simple exponential smoothing, except that a term ( $T_{t-1}$ ) has been incorporated to properly update the level when a trend exists.

- $\alpha \in (0, 1)$  is the smoothing constant for the level
- $y_t$  is the actual value at time  $t$
- $T_{t-1}$  is the trend estimate at time  $t - 1$

# Holt's Linear Trend Method

## 2 Trend Estimate

$$T_t = \beta (L_t - L_{t-1}) + (1 - \beta) T_{t-1} \quad (4)$$

where  $\beta \in (0, 1)$  is the smoothing constant for the trend estimate.

## 3 The forecast for $p$ periods into the future

$$\hat{y}_{t+p} = L_t + pT_t \quad (5)$$

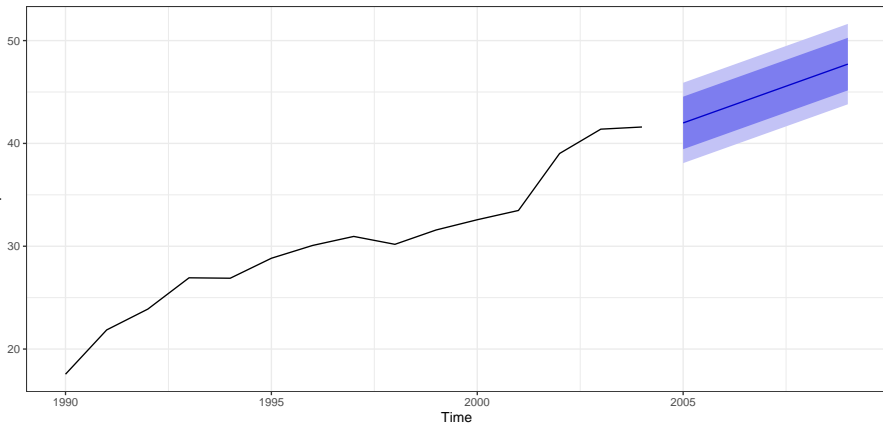
where  $p$  is the periods to be forecast into the future. Note that the forecasts for future periods lie along a straight line with the slope  $T_t$  and intercept  $L_t$ .

Two smoothing parameters  $\alpha$  and  $\beta$  ( $0 \leq \alpha, \beta \leq 1$ ).

# Holt's method in R

```
air <- window(ausair, start=1990, end=2004)
air %>% holt(h=5) %>% autoplot()
```

Forecasts from Holt's method





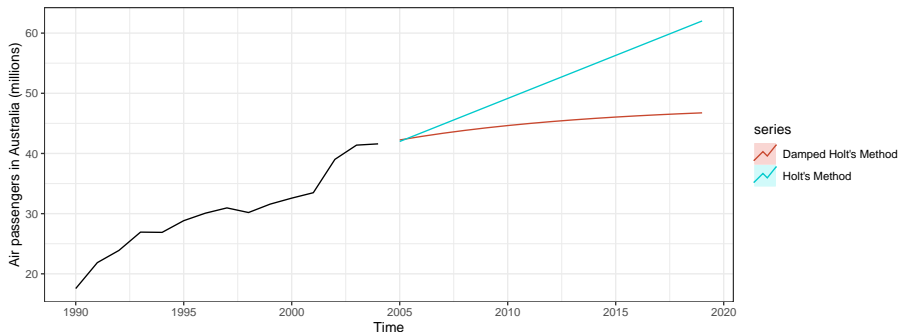
# Holt's Linear Trend Method with a Damped Trend

- The forecasts generated by Holt's linear method display a constant trend (increasing or decreasing) indefinitely into the future.
- Empirical evidence indicates that these methods tend to over-forecast, especially for longer forecast horizons.
- Gardner & McKenzie (1985) introduced a parameter that “dampens” the trend to a flat line some time in the future.
- Damping parameter  $0 < \phi < 1$ .
- If  $\phi = 1$ , identical to Holt's linear trend.

# Example: Air passengers

```
air %>% holt(damped=TRUE, h=15, phi = 0.9) -> w.damped
air %>% holt(damped=FALSE, h=15) -> n.damped
autoplot(air) +
  autolayer(w.damped, series = "Damped Holt's Method", PI = FALSE) +
  autolayer(n.damped, series = "Holt's Method", PI = FALSE) +
  labs(title = "Forecasts from Holt's method",
       y = "Air passengers in Australia (millions)")
```

Forecasts from Holt's method



## **Exponential Smoothing Adjusted for Trend and Seasonal Variation: Winters' Method**

- Three parameter linear and seasonal exponential smoothing method
- an extension of Holt's method
- one additional equation for seasonality
- Has both an additive and multiplicative method.

# Holt-Winter's Exponential Smoothing Methods

## Multiplicative Method

The four equations used in **Holt-Winter's** (multiplicative) smoothing are:

- 1 The exponentially smoothed series, or level estimate.

$$L_t = \alpha \frac{y_t}{S_{t-s}} + (1 - \alpha) (L_{t-1} + T_{t-1}) \quad (6)$$

### Notice:

In Eq. 6,  $y_t$  is divided by  $S_{t-s}$  which adjusts  $y_t$  for seasonality. Think back to when you did the classical decomposition in Lecture 5.

- 2 The trend estimate:

$$T_t = \beta (L_t - L_{t-1}) + (1 - \beta) T_{t-1} \quad (7)$$

# Holt-Winter's Exponential Smoothing Methods

- ③ The seasonality estimate:

$$S_t = \gamma \frac{y_t}{L_t} + (1 - \gamma) S_{t-s} \quad (8)$$

We can consider  $y_t/L_t$  as a seasonal index ratio that can be used in a multiplicative fashion to adjust a forecast to account for seasonal peaks and valleys as in Eq. 9.

- ④ The forecast for  $p$  periods into the future:

$$\hat{y}_{t+p} = (L_t + pT_t) S_{t-s+p} \quad (9)$$

where  $S_t$  is the seasonal estimate,  $\gamma$  is the smoothing constant for the seasonality estimate,  $s$  is the length of seasonality.

The difference compared to (5) is it is multiplied by  $S_{t-s+p}$  to adjust the forecast for seasonality.

# Holt-Winter's Exponential Smoothing Methods

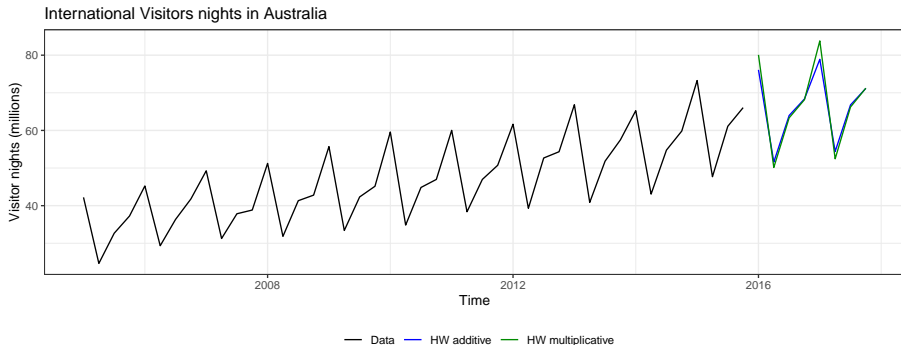
- Winter's method provides an easy way to account for seasonality when data have a seasonal pattern.
- In general, exponential smoothing methods have the major advantages of low cost and simplicity.
- The methods assign weights that decline exponentially as the observations get older.

```

aust <- window(austourists, start=2005)
fit1 <- hw(aust,seasonal="additive")
fit2 <- hw(aust,seasonal="multiplicative")
tmp <- cbind("Data"=aust, "HW additive" = fit1[["mean"]],
            "HW multiplicative" = fit2[["mean"]])

autoplot(tmp) +
  scale_color_manual(name="", values=c('black','blue','green4')) +
  labs(title = "International Visitors nights in Australia",
       y = "Visitor nights (millions)") + theme(legend.position = "bottom")

```



# Your turn

- ① Return to the Acme Dataset and see if you can improve the fit by using the Holt and Holt Winter models.
- ② Apply Holt-Winters' multiplicative method to the **gas** data.
- a. Why is multiplicative seasonality necessary here?
- b. Experiment with a dampened trend.
- c. Check that the residuals from the best method look like white noise.



# R functions

- Simple exponential smoothing: no trend: `ses(y)`
- Holt's method: linear trend: `holt(y)`
- Damped trend method: `holt(y, damped=TRUE)`
- Holt-Winters methods: `hw(y, damped=TRUE, seasonal = "additive")`  
`hw(y, damped=FALSE, seasonal = "additive")`  
`hw(y, damped=TRUE, seasonal = "multiplicative")`  
`hw(y, damped=FALSE, seasonal = "multiplicative")`
- Combination of no trend with seasonality not possible using these functions.