

## ① Programming AVR microcontrollers

example → microchip pic, Atmel AVR

Freescale semiconductors,

## ② Introduction to AVR microcontroller intel 8051



Microcontroller → Can perform some specific tasks

CPU	RAM	ROM
I/O ADC	Timer	serial com port

All these units are connected peripherally

Atmel

product  
family

amount of  
flash memory in kB  
(power of 2)

Atmega328P → include in arduino uno



8 bit processor

131 instructions

32 general purpose registers

### ③ Status register (SReg)

flag register

8 bit register

corresponding flags are set by the execution of arithmetic or logical instructions

Bit D<sub>7</sub> D<sub>6</sub> D<sub>5</sub> — — — D<sub>1</sub> D<sub>0</sub>

SReg I T H S V N Z C

C → Carry

Z → zero

N → Negative

V → overflow

S → sign

H → Half

T → Bit copy storage

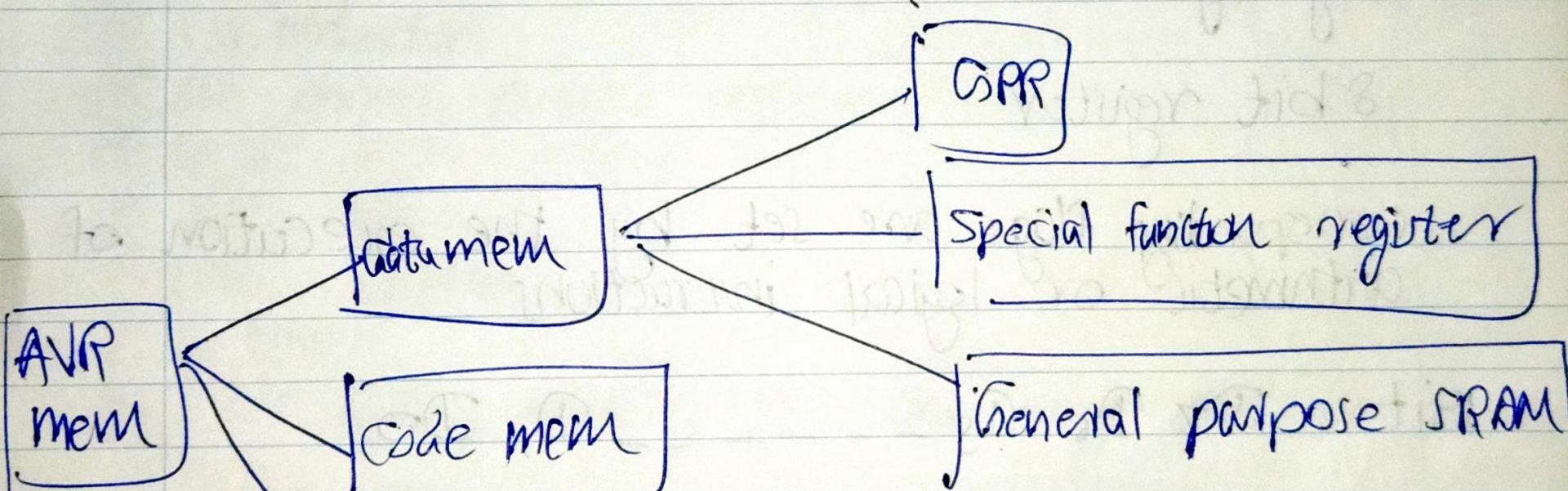
I → Global interrupt enable

reduced instruction set computer

most of instructions take single clock cycle

2 stage pipeline → fetch  
→ execute

## ⑤ AVR memory architecture



## ④ SRAM

use for storing data and parameters  
called the scratch pad  
each location 8 bit

## ④ EEPROM

storing data which are changed rarely or  
should not lost when power is off

## ④ Program memory

\* stores the program code

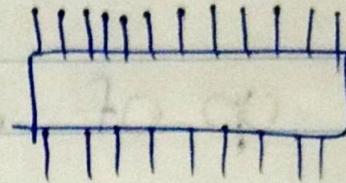
\* made up of flash memory

\* mem location  $\rightarrow$  2 bytes

1 byte  $\rightarrow$  8 bits

\* different package types

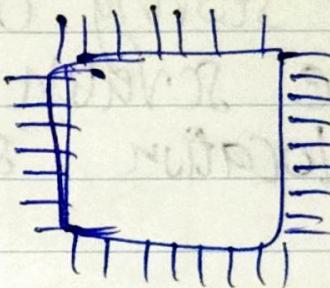
DIP (dual in line) →



MLF (micro lead frame) →



QFP (quad flat) →



\* pin description

VCC → power supply pin., SV

port B → 8 bit bidirectional I/O

→ P<sub>O</sub>6:0

port C → 7 bit bidirectional I/O

port D → 8 bit bidirectional I/O

→ P<sub>O</sub>7:0

Hex files for AVR

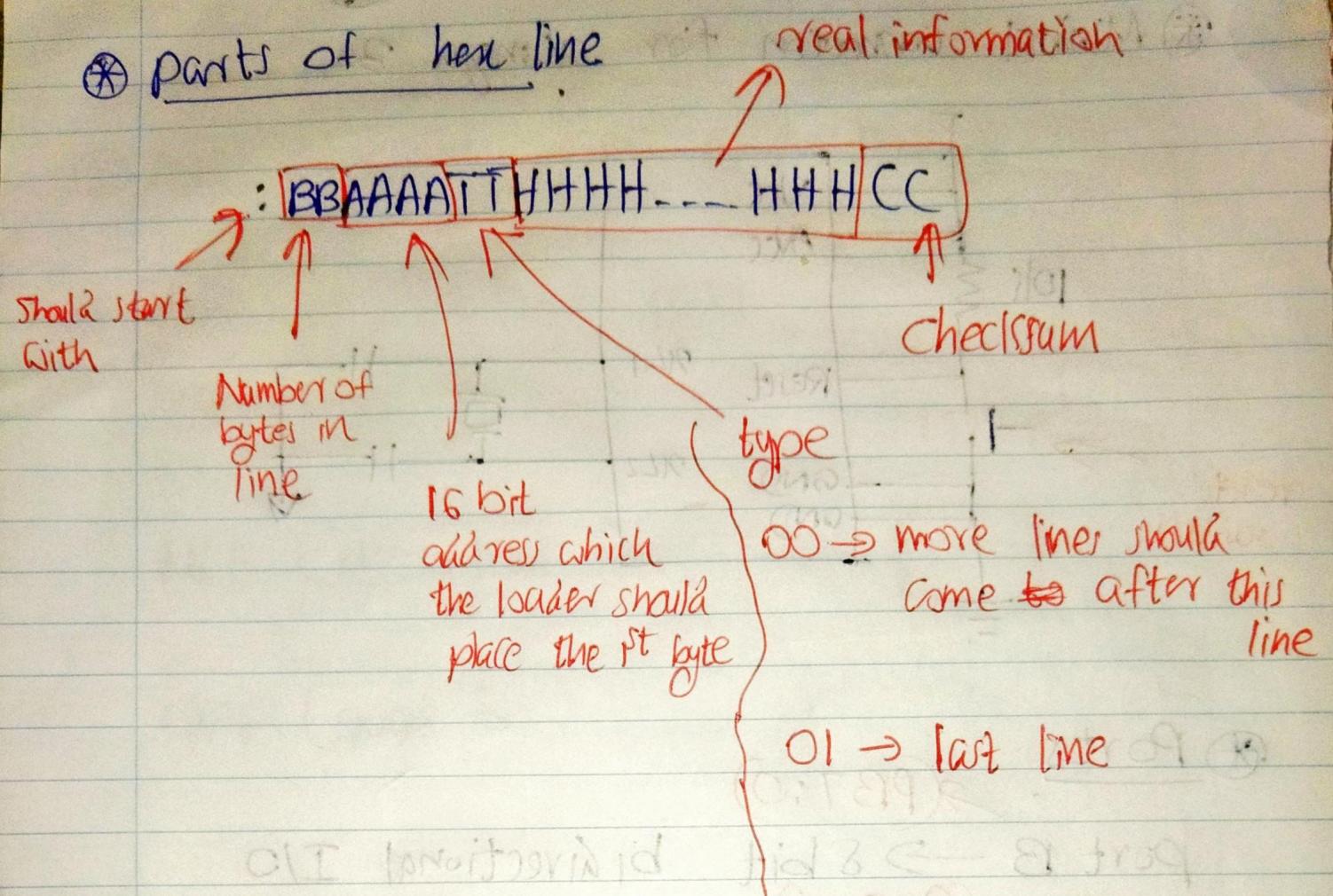
intell hex is a widely used file format for loading of executable machine code into a chip

instructions which are included in hex file

Number of bytes of informations to be loaded  
Information to be loaded

Starting Address where information must be placed.

## ⑤ Parts of hex line



## ⑥ AVR programming

3 ways to load a program to the flash memory

## ⑦ Parallel programming

- ① chip is programmed before inserted
- ② or the chip is removed and reprogrammed
- ③ ZIF sockets are used

requires communication port and program space on the microcontroller

#### ④ Advantage → Convenience

A

#### Data types in AVR/C

Type	Size in bits	Data range
unsigned char	8	0 - 255
char	8	-128 - +127
unsigned int	16	0 - 65535
int	32	16

# AVRGC install

## ④ Examples

- ① Code for send values 00-FF to port B

```
#include <avr/io.h>
```

```
int main(void){
```

```
    unsigned char z;
```

```
    DDRB = 0xFF;
```

```
    for(z=0; z<=255; z++){
```

```
        PORTB = z;
```

```
}
```

```
    return 0;
```

## ④ Example 02

Blinking led with binary values options

```
0000
```

```
1011
```

```
0001
```

```
1100
```

```
0010
```

```
1101
```

```
0011
```

```
1110
```

```
0100
```

```
1111
```

```
0101
```

```
000F
```

```
0110
```

```
0000
```

```
0111
```

```
0000
```

```
1000
```

```
0000
```

```
1001
```

```
0000
```

```
1010
```

```
0000
```

at 1 → bulb on  
0 → bulb off

```
#include <avr/io.h>
# include <util/delay.h>
```

```
DDRB = 0x0F; }
```

```
for(z=0; z<15; z++){}
```

```
PORTB = z; }
```

```
_delay_ms(BLINK_
```

```
_DELAY_MS); }
```

```
return 0; }
```

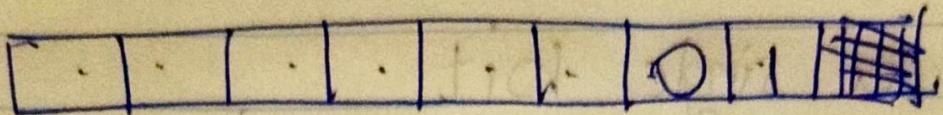
```
#define BLINK_DELAY_
```

```
MS 2000
```

```
int main(void){
```

```
unsigned char z;
```

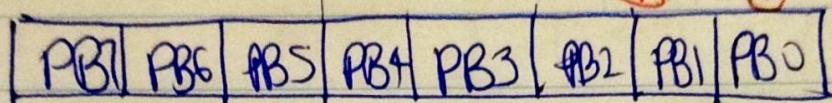
DDR B



input

output

PORT B



to make PB0 as output  $\text{DDRBO} = 1$   
PB0 as input  $\text{DDRBO} = 0$

④ PINB

use when the port should be input

④ Setting a single bit

way to accessing only one bit

④ set only bit 4

④ clearing a single bit

clearing bit 4

$$\text{PORTB} = \text{PORTB} \& \sim (1 \ll 4)$$

④ Toggling a single bit

Toggle only bit 4

$$\text{PORTB} = \text{PORTB} \wedge (1 \ll 4)$$

④ Checking a single bit

Checking if bit 4 set to 1

- ① if ((PORTB >> 4) & 1) { }
- ② if (PORTB & (1 << 4)) { }

④ changing multiple bits

$$\text{PORTB} = \text{PORTB} | ((1 \ll 1) | (1 \ll 4))$$