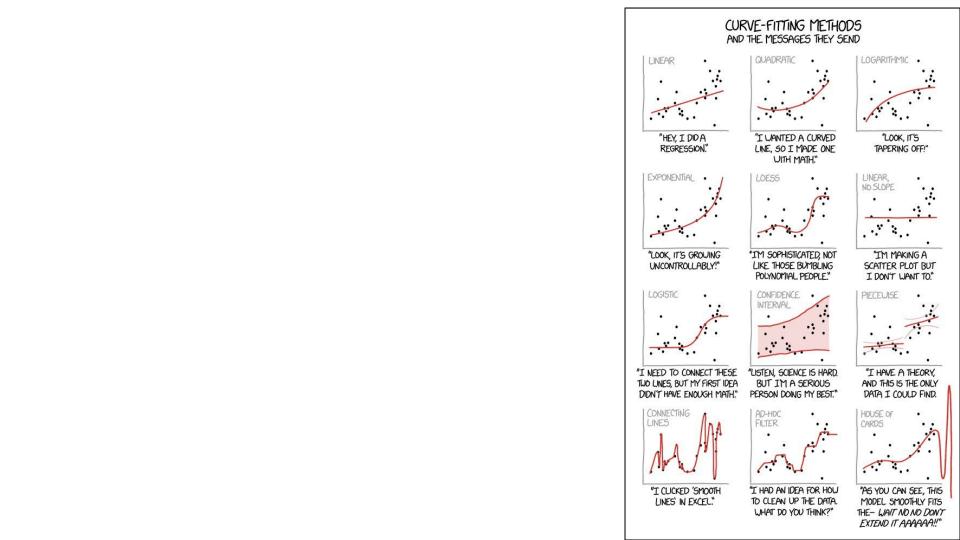
Machine Learning Course

# Lecture 2: Linear regression

MIPT, 2019

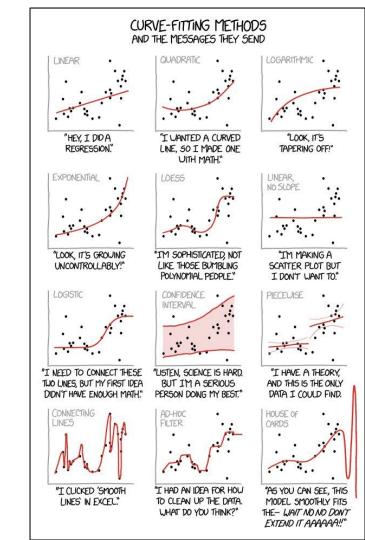
### Outline

- Overview of linear models.
- 2. Linear regression.
- 3. Analytical solution.
- 4. Regularization.
- 5. Gauss-Markov theorem.
- 6. Probabilistic interpretation and intuition.



Example questions linear regression can solve (up right picture):

- What will be my monthly spending for the next year?
- Which factor is more important in deciding my monthly spending?
- How monthly income and trips per month are correlated with monthly spending?



$$Y = X_1 + X_2 + X_3$$

Dependent Variable

Independent Variable

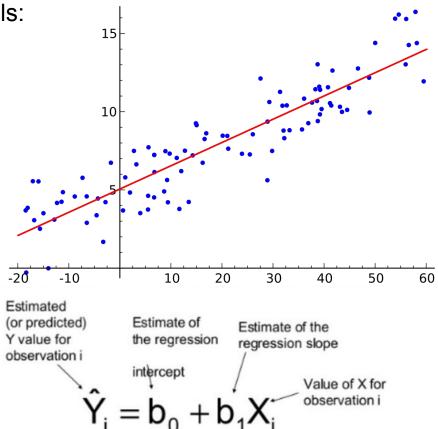
Outcome Variable

Predictor Variable

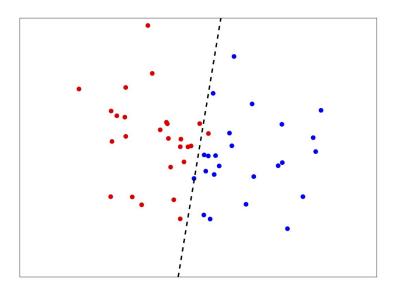
Response Variable

Explanatory Variable

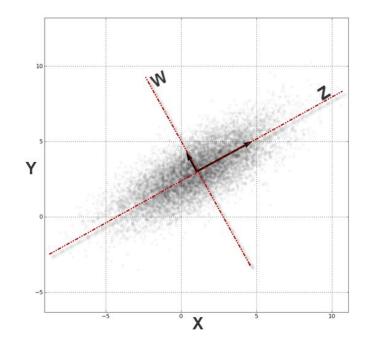
Predictive models:



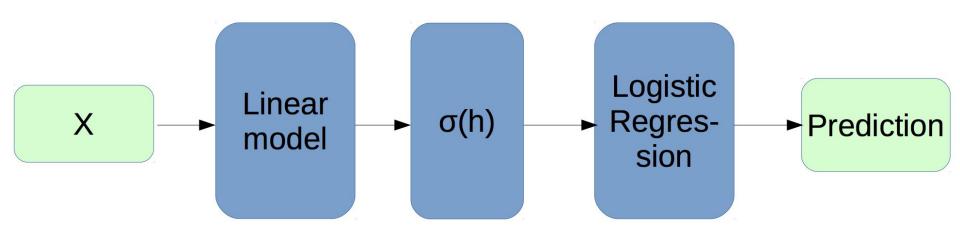
- Predictive models:
- Classification models:



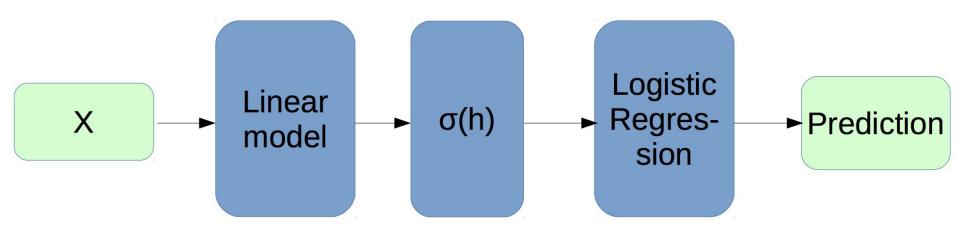
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- Unsupervised models (e.g. PCA analysis)



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- Building block of other models (ensembles, NNs, etc.)



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## Linear regression

#### Linear regression problem statement:

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• Prediction model is linear:  $\hat{y_i} = a(w_0, \mathbf{w}, \mathbf{x}_i) = w_0 + w_1 x_{i1} + \dots w_p x_{ip}$ , Where  $\mathbf{w} = (w_1, \dots w_p)$  is weights vector,  $w_0$  is bias term.

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- Least squares method provides a solution:

$$\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \|\mathbf{w}_0 + (\mathbf{x}_1 \dots \mathbf{x}_n)^T \mathbf{w} - (y_1, \dots, y_n)\|_2^2$$

Denote quadratic loss function:  $Q(\mathbf{w}) = (Y - X\mathbf{w})^T (Y - X\mathbf{w}) = \|Y - X\mathbf{w}\|_2^2$ , where  $X = [\mathbf{x}_1, \dots, \mathbf{x}_n], \quad \mathbf{x}_i \in \mathbb{R}^p, \ Y = [y_1, \dots, y_n], \quad y_i \in \mathbb{R}$ .

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what if this matrix is *singular?* 

#### Unstable solution

In case of multicollinear features the matrix  $X^TX$  is almost singular .

It leads to unstable solution:

```
w_true
array([ 2.68647887, -0.52184084, -1.12776533])

w_star = np.linalg.inv(X.T.dot(X)).dot(X.T).dot(Y)
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the coefficients are huge and sum up to almost 0

## Regularization

To make the matrix nonsingular, we can add a diagonal matrix:

$$\hat{\mathbf{w}} = (X^T X + \lambda I)^{-1} X^T Y,$$

where  $I = \operatorname{diag}[1_1, \dots, 1_p]$ .

Actually, it's a solution for the case  $Q(\mathbf{w}) = ||Y - X\mathbf{w}||_2^2 + \lambda^2 ||\mathbf{w}||_2^2$ .

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exercise: check it by yourself

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Then the solution  $\hat{\mathbf{w}} = (X^T X)^{-1} X^T Y$  delivers BLEU: **B**est **L**inear **U**nbiased **E**stimator.

### Different norms

Once more: loss functions:

• 
$$MSE = \frac{1}{n} \|\mathbf{x}^T \mathbf{w} - \mathbf{y}\|_2^2$$

Regularization terms:

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$$L_2$$
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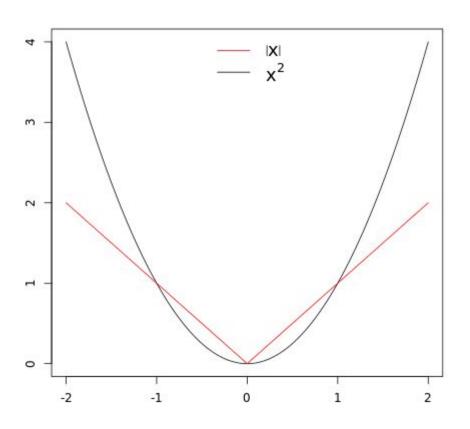
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only works for Gauss-Markov theorem

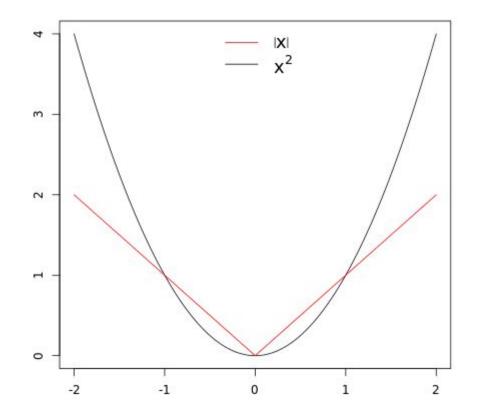
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- differentiable
- sensitive to noise

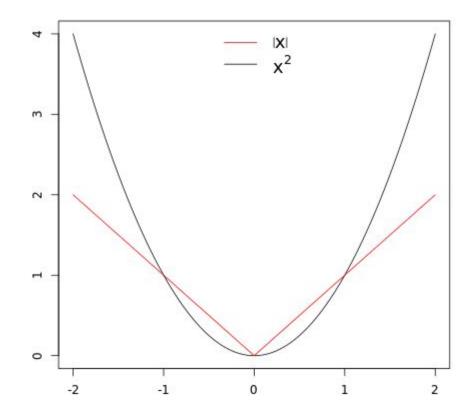


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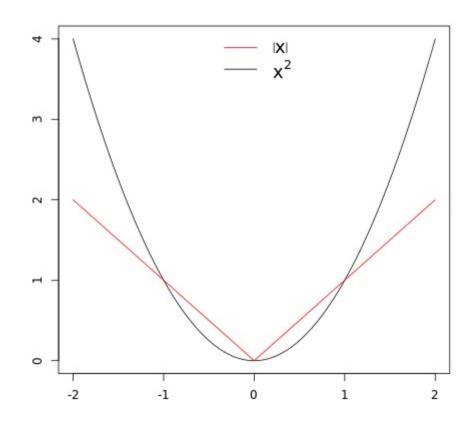


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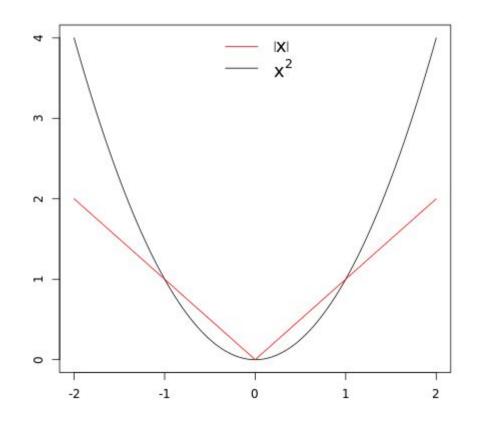
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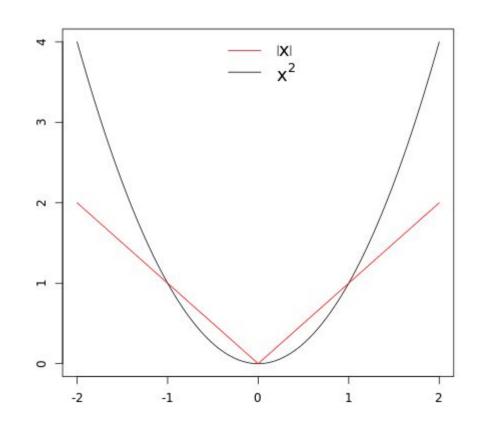


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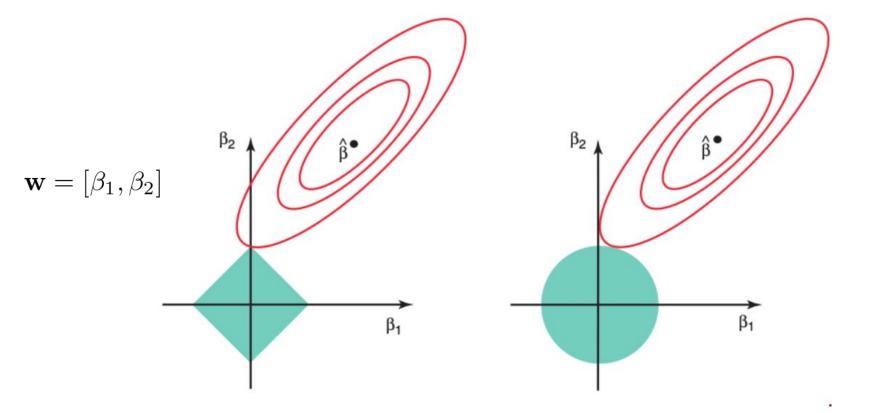
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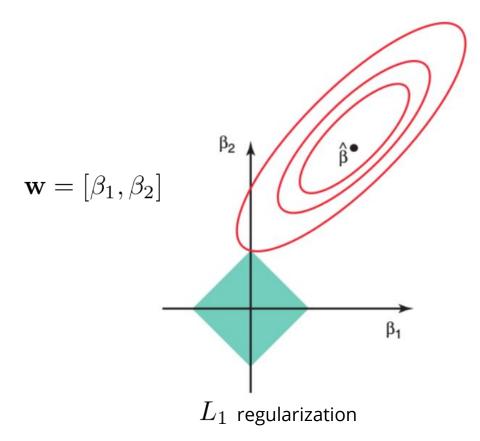
Does what?

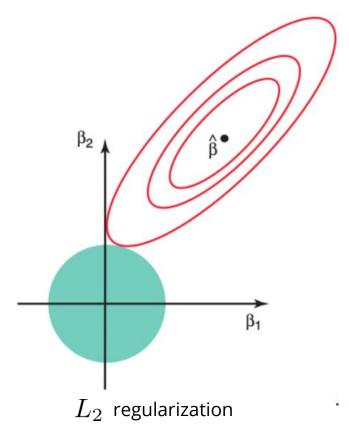


## Regularization: illustration



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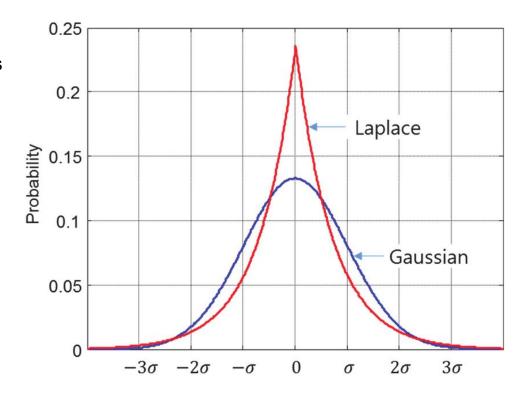




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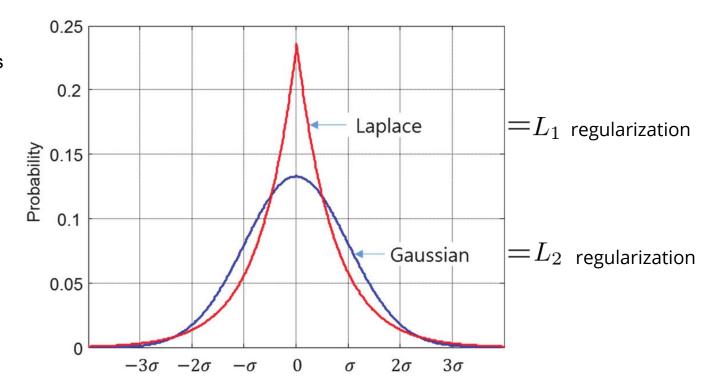
## Regularization: probability interpretation

assume **w** elements are sampled from some *specific* distribution (prior distribution for the weights vector)



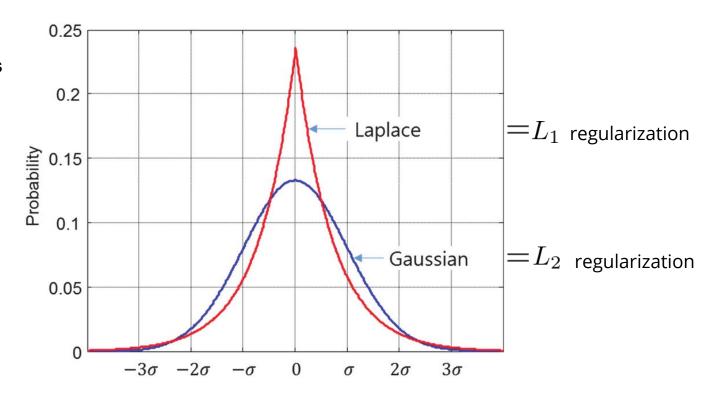
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see seminar extra materials for more

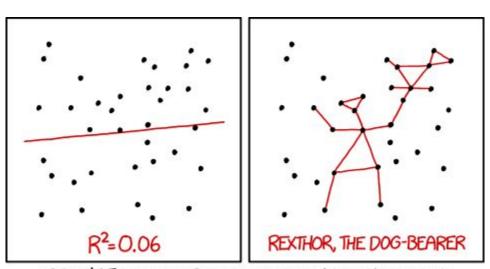
## Welcome to the church of Bayes





Дмитрий Ветров - заведующий Международной лабораторией глубинного обучения и байесовских метод∕ов

## That's all. Practice coming next.



I DON'T TRUST LINEAR REGRESSIONS WHEN IT'S HARDER TO GUESS THE DIRECTION OF THE CORRELATION FROM THE SCATTER PLOT THAN TO FIND NEW CONSTELLATIONS ON IT.