```
root@ubuntu: ~/gazebo plugin tutorial
                                                                            root@ubuntu: ~/gazebo plugin tutorial 80x24
root@ubuntu:~/gazebo_plugin_tutorial# gedit hello.world
** (qedit:11634): WARNING **: 00:32:14.248: Set document metadata failed: Settin
q attribute metadata::gedit-spell-language not supported
** (qedit:11634): WARNING **: 00:32:14.259: Set document metadata failed: Settin
q attribute metadata::gedit-encoding not supported
** (gedit:11634): WARNING **: 00:32:15.591: Set document metadata failed: Settin
q attribute metadata::gedit-position not supported
root@ubuntu:~/gazebo plugin tutorial# gzserver ~/gazebo plugin tutorial/hello.wo
rld --verbose
Gazebo multi-robot simulator, version 9.0.0
Copyright (C) 2012 Open Source Robotics Foundation.
Released under the Apache 2 License.
http://gazebosim.org
[Msg] Waiting for master.
[Msg] Connected to gazebo master @ http://127.0.0.1:11345
[Msg] Publicized address: 192.168.40.154
Hello Shanawar , Vikash, Abudrahman munir ,World!
[Wrn] [Publisher.cc:141] Queue limit reached for topic /gazebo/default/physics/c
ontacts, deleting message. This warning is printed only once.
```



