```
class Solution {
private:
int partition(vector<int>& nums, int low, int high) {
 int I = low;
 int r = high + 1;
 while (I < r) {
   while (I < high && nums[low] > nums[++I]);
   while (r > low && nums[low] < nums[--r]);
   if (I >= r) {
     break;
   }
   swap(nums[I], nums[r]);
 swap(nums[r], nums[low]);
 return r;
}
void quickSort(vector<int>& nums, int I, int r) {
 if (l \ll r) {
   int p = partition(nums, l, r);
   quickSort(nums, I, p - 1);
   quickSort(nums, p + 1, r);
 } else {
   return;
 }
}
public:
 int kthLargestElement(int n, vector<int> &nums) {
   // write your code here
   quickSort(nums, 0, nums.size() - 1);
   return nums[nums.size() - n];
 }
};
class Solution {
private:
ListNode* partition(ListNode* low, ListNode* high) {
 ListNode* p = low;
 ListNode* q = low->next;
 int key = low->val;
 while (q != high) {
   if (q->val < key) {
     p = p->next;
     swap(p->val, q->val);
   }
   q = q->next;
 }
```

```
swap(low->val, p->val);
  return p;
}
void quickSortList(ListNode* low, ListNode* high) {
  if (low != high) {
    ListNode* p = partition(low, high);
    quickSortList(low, p);
    quickSortList(p->next, high);
  }
}
public:
  /**
   * @param head: The head of linked list.
  * @return: You should return the head of the sorted linked list, using constant space complexity.
  */
  ListNode * sortList(ListNode * head) {
    // write your code here
    ListNode* low = head;
    ListNode* high = nullptr; // one of the new features
    quickSortList(low, high);
    return head;
  }
};
///// priority_queue
int kthLargestElement(int n, vector<int> &nums) {
    // write your code here
    //int k = nums.size() - n;
    priority_queue<int, vector<int>> pq;
    for (auto num: nums) {
      pq.push(num);
    }
    int res;
    for (int i = 0; i < n; ++i) {
      res = pq.top();
      pq.pop();
    }
    return res;
  }
  //// half-quick-sort: O(n)
  int kthLargestElement(int n, vector<int> &nums) {
      // write your code here
      int k = nums.size() - n;
      int low = 0;
      int high = nums.size() - 1;
      while (low <= high) {
        int p = partition(nums, low, high);
```

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if (p > k) {
         high = p - 1;
       } else if (p < k) {
         low = p + 1;
       } else {
         break;
       }
     }
   return nums[k];
  }
int findPosition(vector<int> nums, int target) {
   if (!nums.size()) {
       return -1;
   }
   int I = 0, r = nums.size() - 1;
   while (l + 1 < r) {
       int m = I + (r - I) / 2;
       if (nums[m] == target) { return m; }
       else if (nums[m] < target) { I = m; }
       else \{ r = m; \}
   if (nums[l] == target) { return l; }
   if (nums[r] == target) { return r; }
   return -1;
}
int lastPosition(vector<int> &nums, int target) {
   // write your code here
   int size = nums.size();
   if (!size) return -1;
   int I = 0;
   int r = size - 1;
   while (l + 1 < r) {
     int m = I + (r - I) / 2;
     if (nums[m] > target) {
       r = m;
     else if (nums[m] <= target) {
       I = m;
     }
   }
   if (nums[r] == target) {
     return r;
   }
   if (nums[l] == target) {
     return I;
   }
```

```
return -1;
 }
int binarySearch(vector<int> &nums, int target) {
    // write your code here
    int size = nums.size();
    if(!size) return -1;
    int I = 0, r = size - 1;
    while(l + 1 < r) {
     int m = I + (r - I) / 2;
     if (nums[m] >= target) {
        r = m;
     }
     else {
       I = m;
    if (nums[l] == target) {
      return I;
    if (nums[r] == target) {
     return r;
    }
    return -1;
int getLeftCloest(vector<int> A, int target) {
    int I = 0;
    int r = A.size() - 1;
    while (l + 1 < r) {
     int m = I + (r - I) / 2;
     if (A[m] < target) {
       I = m;
     } else {
        r = m;
     }
    if (A[r] < target) {
      return r;
    if (A[I] < target) {
      return I;
    return -1;
 }
vector<int> kClosestNumbers(vector<int> &A, int target, int k) {
    // write your code here
    vector<int> res;
    int size = A.size();
    if (!size) return res;
    if (k > size) return res;
```

```
int leftCloest = getLeftCloest(A, target);
   int I = leftCloest;
   int r = l + 1;
   for (int i = 0; i < k; ++i) {
     if (1 \ge 0 \&\& r < size) {
       if (abs(A[I] - target) <= abs(A[r] - target)) {
         res.push_back(A[I]);
         --|:
       } else {
         res.push_back(A[r]);
         ++r;
       }
     }
     else {
       if (1 < 0) {
         res.push_back(A[r]);
         ++r;
       else if (r \ge size) {
         res.push_back(A[I]);
         --I;
       }
     }
   return res;
 }
vector<int> inorderTraversal(TreeNode * root) {
   // write your code here
   // if (root) {
   // inorderTraversal(root->left);
       res.push_back(root->val);
   // inorderTraversal(root->right);
   //}
   stack<TreeNode*> st;
   TreeNode* p = root;
   while (!st.empty() | | p) {
     if (p) {
       st.push(p);
       p = p - | eft;
     } else {
       TreeNode* c = st.top();
       st.pop();
       res.push_back(c->val);
       p = c->right;
     }
   }
   return res;
 }
```

```
vector<int> preorderTraversal(TreeNode * root) {
    // write your code here
    // if (root) {
    // res.push back(root->val);
    // preorderTraversal(root->left);
    // preorderTraversal(root->right);
    //}
    stack<TreeNode*> st;
    if (root) {
      st.push(root);
      while(!st.empty()) {
        TreeNode* p = st.top();
        st.pop();
        res.push_back(p->val);
        if (p->right) {
          st.push(p->right);
        }
        if (p->left) {
          st.push(p->left);
      }
    }
    return res;
  }
class Solution {
  vector<int> res;
public:
  /**
  * @param root: A Tree
  * @return: Postorder in ArrayList which contains node values.
  vector<int> postorderTraversal(TreeNode * root) {
    // write your code here
    // if (root) {
    // postorderTraversal(root->left);
    // postorderTraversal(root->right);
    // res.push_back(root->val);
    //}
    stack<TreeNode*> st;
    if (root) {
      st.push(root);
      while(!st.empty()) {
        TreeNode* p = st.top();
        st.pop();
        res.push_back(p->val);
        if (p->left) {
          st.push(p->left);
        }
```

```
if (p->right) {
         st.push(p->right);
       }
     }
   reverse(res.begin(), res.end());
   return res;
 }
};
vector<vector<int>> levelOrder(TreeNode * root) {
   // write your code here
   if (!root) return {};
   queue<TreeNode*> q;
   q.push(root);
   vector<vector<int>> res;
   while (!q.empty()) {
     int n = q.size();
     vector<int> cur;
     while(n--) {
       TreeNode* node = q.front();
       q.pop();
       cur.push back(node->val);
       if (node->left) {
         q.push(node->left);
       if (node->right) {
         q.push(node->right);
       }
     }
     res.push_back(cur);
   return res;
 }
vector<vector<int>> zigzagLevelOrder(TreeNode * root) {
   // write your code here
   if (!root) return {};
   deque<TreeNode*> dq;
   dq.push back(root);
   vector<vector<int>> res;
   bool isOdd = true;
   while(!dq.empty()) {
     int n = dq.size();
     vector<int> cur;
```

```
while (n--) {
       if(isOdd) {
         TreeNode* node = dq.front();
         dq.pop front();
         cur.push back(node->val);
         if(node->left)
           dq.push back(node->left);
         if(node->right)
           dq.push back(node->right);
       } else {
         TreeNode* node = dq.back();
         dq.pop_back();
         cur.push back(node->val);
         if (node->right)
           dq.push front(node->right);
         if (node->left)
           dq.push front(node->left);
       }
     res.push_back(cur);
     isOdd = !isOdd;
   }
   return res;
 }
class Solution {
private:
 int getDepth(TreeNode* node, int depth) {
   if (!node) return depth - 1;
   return max(getDepth(node->left, depth + 1),
         getDepth(node->right, depth + 1));
 }
public:
  * @param root: The root of binary tree.
  * @return: True if this Binary tree is Balanced, or false.
 bool isBalanced(TreeNode * root) {
   // write your code here
   if (!root) return true;
   int leftDepth = getDepth(root->left, 1);
   int rightDepth = getDepth(root->right, 1);
   return abs(leftDepth - rightDepth) <= 1 &&
       isBalanced(root->left) &&
       isBalanced(root->right);
};
```

```
class Solution {
private:
  bool validBST(TreeNode* node, long min, long max) {
   if (!node) return true;
   if (node->val <= min \mid \mid node->val >= max) {
      return false;
   }
   return validBST(node->left, min, node->val) &&
       validBST(node->right, node->val, max);
  }
public:
  /**
  * @param root: The root of binary tree.
  * @return: True if the binary tree is BST, or false
  bool isValidBST(TreeNode * root) {
   // write your code here
   if(!root) return true;
   return validBST(root, LONG_MIN, LONG_MAX);
 }
};
ListNode * reverse(ListNode * head) {
   // write your code here
   // if (!head | | !head->next) return head;
   // ListNode* p = nullptr;
   // while (head) {
   // ListNode* next = head->next;
      head->next = p;
   // p = head;
   // head = next;
   //}
   // return p;
   if (!head | | !head->next) return head;
   ListNode* newhead = reverse(head->next);
   head->next->next = head;
   head->next = nullptr;
   return newhead;
  }
ListNode * mergeTwoLists(ListNode * I1, ListNode * I2) {
   // write your code here
   if (!l1) return l2;
   if (!12) return 11;
   ListNode* p;
   ListNode* head;
   if (I1->val > I2->val) {
     head = 12;
     p = 12;
```

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12 = 12 - \text{next};
    }
    else {
      head = 11;
      p = 11;
      l1 = l1->next;
    while(I1 && I2) {
      if (l1->val > l2->val) {
        p->next = I2;
        12 = I2->next;
      } else {
        p->next = l1;
        I1 = I1->next;
      }
      p = p->next;
    }
    if (I1) {
      p->next = l1;
    if (I2) {
      p->next = l2;
    }
    return head;
  }
int mySqrt(long x) {
    // binary search
//
      if (x \le 1) return x;
//
      long eps = 0.000001;
//
      int low = 1;
//
      int high = x / 2;
      while (low <= high) {
//
//
        long mid = low + (high - low) / 2;
        if (mid * mid == x) {
//
//
           return mid;
        } else if (mid * mid < x) {
//
          if ((mid + 1) * (mid + 1) > x) {
//
             return mid;
//
//
//
          low = mid + 1;
//
        } else {
           high = mid - 1;
//
//
        }
//
      }
//
      return 1;
    // newton:
    long a = x;
    long eps = 0.00001;
```

```
while (a * a - x > eps) {
     a = 0.5 * (a + x / a);
   }
   return a;
 }
 double myPow(double x, long long n) {
     if(n == 0)
       return 1;
     if(n < 0){
       n = -n;
       x = 1 / x;
     return !(n \& 1)? myPow(x * x, n / 2) : x * myPow(x * x, n / 2);
   }
 // this is for integer & matrix!
 long myPow(int x, int x) {
     int res = 1;
     int tmp = x;
     while (n) {
       if (n & 1) {
         res *= tmp;
       tmp *= tmp;
       n >>= 1;
     }
     return res;
 }
 int getShortestPath(vector<vector<int>>& maze, pair<int, int> start, pair<int, int> end){
      // never forget to check corner cases [or ask your interviewer to make sure your inputs are
valid]
      int rows = maze.size();
      if (!rows) return -1;
      int cols = maze[0].size();
      if (!cols) return -1;
      if (start.first < 0 || start.second < 0 || start.first >= rows || start.second >= cols ||
             end.first < 0 || end.second < 0 || end.first >= rows || end.second >= cols) {
             return -1;
      // do real things now.
      // initialization
      queue<pair<int, int>> q;
      q.push(start);
      vector<vector<int>> visited(rows, vector<int>(cols, -1));
      visited[start.first][start.second] = 1;
      vector<pair<int, int>> dir = { {1, 0}, {-1, 0}, {0, 1}, {0, -1} };
      while (!q.empty()) {
             pair<int, int> cur = q.front();
             q.pop();
             if (cur.first == end.first && cur.second == end.second) {
                   return visited[cur.first][cur.second];
             }
```

```
for (auto d : dir) {
                   int new_r = cur.first + d.first;
                   int new_c = cur.second + d.second;
                   if (new_r < 0 || new_r >= rows || new_c < 0 || new_c >= cols ||
                          visited[new_r][new_c] != -1 ||
                          !maze[new_r][new_c]) {
                          continue;
                   else {
                          pair<int, int> new_node = { new_r, new_c };
                          visited[new_r][new_c] = visited[cur.first][cur.second] + 1;
                          q.push(new_node);
                   }
             }
      }
      return -1;
int main() {
      vector<vector<int>> maze1 =
      {
             { 1, 0, 1, 1, 1, 0, 1, 1, 1 },
             { 1, 0, 1, 0, 1, 1, 1, 0, 1, 1 },
             { 1, 1, 1, 0, 1, 1, 0, 1, 0, 1 },
             { 0, 0, 0, 0, 1, 0, 0, 0, 0, 1 },
             { 1, 1, 1, 0, 1, 1, 1, 0, 1, 0 },
              1, 0, 1, 1, 1, 0, 1, 0, 0 },
             { 1, 0, 0, 0, 0, 0, 0, 0, 0, 1 },
             { 1, 0, 1, 1, 1, 0, 1, 1, 1 },
             { 1, 1, 0, 0, 0, 0, 1, 0, 0, 1 }
      };
      //vector<int> start = { 1, 0 };
      //vector<int> end = { 1, 3 };
      pair<int, int> start = { 0, 0 };
      pair<int, int> end = {8, 1};
      int shortestPath = 0;
      shortestPath = getShortestPath(maze1, start, end);
      std::cout << "shortest path length: " << shortestPath << endl;</pre>
      char e;
      std::cin >> e;
      return 0;
// Your task!
class Solution {
private:
 void dfs(vector<vector<bool>>& grid, int r, int c) {
   if (r < 0 | | r >= grid.size() | | c < 0 | | c >= grid[0].size() | |
     grid[r][c] == false) {
       return;
   }
   grid[r][c] = false;
   dfs(grid, r + 1, c);
   dfs(grid, r - 1, c);
```

```
dfs(grid, r, c + 1);
    dfs(grid, r, c - 1);
    return;
  }
public:
  * @param grid: a boolean 2D matrix
  * @return: an integer
  int numIslands(vector<vector<bool>> &grid) {
    // write your code here
    int rows = grid.size();
    if (!rows) return 0;
    int cols = grid[0].size();
    if (!cols) return 0;
    int num = 0;
    for (int r = 0; r < rows; ++r) {
      for (int c = 0; c < cols; ++c) {
        if (grid[r][c]) {
          dfs(grid, r, c);
          ++num;
        }
      }
    }
    return num;
  }
};
vector<int> numIslands2(int n, int m, vector<Point> &operators) {
    // write your code here
    vector<int> res;
    if (!(n * m)) return res;
    if (!operators.size()) return res;
    vector<int> roots(n * m, -1);
    vector<pair<int, int>> dir = {{1, 0}, {-1, 0}, {0, 1}, {0, -1}};
    unordered set<int> us;
    int num = 0;
    for (auto p : operators) {
      int r = p.x;
      int c = p.y;
      int id = r * m + c;
      roots[id] = id;
      if (us.find(id) != us.end()) {
        res.push back(num);
        continue;
      }
      us.insert(id);
      ++num;
```

```
for (auto d: dir) {
        int nr = r + d.first;
        int nc = c + d.second;
        int nid = nr * m + nc;
        if (nr \ge 0 \&\& nr < n \&\& nc \ge 0 \&\& nc < m \&\& roots[nid] != -1) {
          while (id != roots[id]) {
            roots[id] = roots[roots[id]];
            id = roots[id];
          }
          while(nid != roots[nid]) {
            roots[nid] = roots[roots[nid]];
            nid = roots[nid];
          if (roots[nid] != roots[id]) {
            roots[nid] = roots[id];
            --num;
          }
        }
      }
      res.push back(num);
    return res;
  }
// convolution-series
// 2d median filter - no stride & zero padding
vector<vector<int>> medianFilter(vector<vector<int>>& img, int kw, int kh) {
       int rows = img.size();
       int cols = img[0].size();
       vector<vector<int>> res(rows, vector<int>(cols));
       for (int r = 0; r < rows; ++r) {
               for (int c = 0; c < cols; ++c) {
                      int left = max(0, int(c - kw / 2.0 + 1));
                      int right = min(cols - 1, c + kw / 2);
                      int upper = max(0, int(r - kh / 2.0 + 1));
                      int lower = min(rows - 1, r + kh / 2);
                      int n = (right - left + 1) * (lower - upper + 1);
                      /// task 1: this is for kth-largest element
                      priority_queue<int> pq;
                      for (int h = upper; h <= lower; ++h) {</pre>
                              for (int w = left; w <= right; ++w) {</pre>
                                     // now we are duling with how to find out the median value
                                     // if odd: [n / 2]
                                     // if even: ([n / 2] + [(n - 1) / 2]) / 2
                                     pq.push(img[h][w]);
                              }
                      if !((n & 1)) {
                                             // if it's even
                              int val1;
                              for (int i = 0; i <= (n - 1) / 2; ++i) {
                                     val1 = pq.top();
                                     pq.pop();
                              int val2 = pq.top();
```

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res[r][c] = (val1 + val2) / 2;
                     }
                     else { // if it's odd
                           int val;
                            for (int i = 0; i <= n / 2; ++i) {
                                   val = pq.top();
                                   pq.pop();
                            res[r][c] = val;
                     // time complexity of this is O(nlogk) , k is kth
                     /// end for kth-largest element
/// task 2: if it's for the maximum within a window
// the best normal way is to traverse the window directly and the time complexity in total would be
// O(rows * cols * kw * kh)
//
// the better way to find out the maximum is try to use deque in 2d (seperately in c-direction and r-
direction)
// time complexity would be O(rows * cols * kw) + O(rows * cols * kh) = O(rows * cols * (kw + kh))
/// end for fidning maximum with in a window
       }
       return res;
}
// 3d average pooling - with zero padding & stride
vector<vector<int>>> pooling3D(vector<vector<int>>>& img, int kw, int kh, int stride) {
       int rows = img.size();
       int cols = img[0].size();
       int channels = img[0][0].size();
       int res_rows = rows / stride;
       int res cols = cols / stride;
       int res channels = channels;
       vector<vector<int>>>
              res(res rows, vector<vector<int>>(res cols, vector<int>(res channels)));
       for (int cl = 0; cl < channels; ++cl) {</pre>
              int r num = 0;
              for (int r = 0; r < rows; r += stride) {
                     int c num = 0;
                     for (int c = 0; c < cols; c += stride) {</pre>
                            int left = max(0, int(c - kw / 2.0 + 1));
                            int right = min(cols - 1, c + kw / 2);
                            int upper = max(0, int(r - kh / 2.0 + 1));
                            int lower = min(rows - 1, r + kh / 2);
                            int area = (right - left + 1) * (lower - upper + 1);
                            int sum = 0;
                            /// this is for average pooling in 3d
                            for (int h = upper; h <= lower; ++h) {</pre>
                                   for (int w = left; w <= right; ++w) {</pre>
                                          sum += img[h][w][c1];
                                   }
                            }
                            res[r_num][c_num][cl] = sum / area;
                            /// end for average pooling
// time complexity of this method is O(W * H * C * kw * kh)
// better result for this:
// best time complmexity: O(W * H * C);
// Because we are using sum with an area. this is actually leetcode/lintcode problem: "Range Sum in 2D
- Immutable"
```

```
// by using techniques provided in that problem, which is called Integeral Image, we can compress time
complexity apperently.
                          ++c_num;
                    ++r_num;
             }
      }
      return res;
}
vector<int> maxSlidingWindow(vector<int>& nums, int k) {
   vector<int> res;
   deque<int> index;
   int size = nums.size();
   if (k > size) return res;
   for (int i = 0; i < k; ++i) {
     while (!index.empty() && nums[i] >= nums[index.back()]) {
       index.pop_back();
     index.push_back(i);
   }
   for (int i = k; i < size; ++i) {
     res.push back(nums[index.front()]);
     while (!index.empty() && nums[i] >= nums[index.back()]) {
       index.pop back();
     }
     while (!index.empty() && index.front() <= i - k) {
       index.pop_front();
     }
     index.push_back(i);
   res.push_back(nums[index.front()]);
   return res;
class NumArray {
private:
 int len;
 vector<int> cumSum;
public:
 int len;
 vector<int> cumSum;
 NumArray(vector<int> nums) {
   len = nums.size();
   cumSum = vector<int>(len + 1, 0);
   if (len) {
     for (int i = 1; i <= len; ++i) {
       cumSum[i] = cumSum[i - 1] + nums[i - 1];
     }
   }
 }
```

```
int sumRange(int i, int j) {
    return (cumSum[j + 1] - cumSum[i]);
 }
};
class NumMatrix {
private:
  vector<vector<int>> integralMatrix;
public:
  NumMatrix(vector<vector<int>> matrix) {
    if (!matrix.size() | | !matrix[0].size()) return;
    int rows = matrix.size();
    int cols = matrix[0].size();
    integralMatrix.resize(rows + 1, vector<int>(cols + 1, 0));
    for (int r = 1; r < rows + 1; ++r) {
      for (int c = 1; c < cols + 1; ++c) {
        integralMatrix[r][c] =
              -integralMatrix[r-1][c-1] + integralMatrix[r-1][c] + integralMatrix[r][c-1] + matrix[r-1][c-1];
     }
    }
    return;
  }
  int sumRegion(int row1, int col1, int row2, int col2) {
    return integralMatrix[row2 + 1][col2 + 1] + integralMatrix[row1][col1] -
       integralMatrix[row2 + 1][col1] - integralMatrix[row1][col2 + 1];
  }
};
int longestCommonSubsequence(string &A, string &B) {
    // write your code here
    if (!(A.size() * B.size())) return 0;
    int rows = A.size();
    int cols = B.size();
    vector<vector<int>> dp(rows + 1, vector<int>(cols + 1, 0));
    for (int r = 1; r <= rows; ++r) {
      for (int c = 1; c <= cols; ++c) {
        if (A[r-1] == B[c-1]) {
         dp[r][c] = dp[r - 1][c - 1] + 1;
       } else {
         dp[r][c] = max(dp[r - 1][c], dp[r][c - 1]);
       }
     }
    return dp[rows][cols];
```

```
////////////////////////////////// 硬币翻转/红绿灯问题 ///////////////////////////////////
float getProb(vector<float> p, int k) {
      int n = p.size();
      vector<vector<float>> dp(n + 1, vector<float>(k + 1, 0.0));
      dp[0][0] = 1.0;
      for (int i = 1; i <= n; ++i) {
             dp[i][0] = (1.0 - p[i - 1]) * dp[i - 1][0]; // 反面朝上概率
      for (int i = 1; i <= n + 1; ++i) {
             for (int j = 1; j \le i \&\& j \le k; ++j) {
                   dp[i][j] = dp[i - 1][j - 1] * p[i - 1] + // 本次是正面
                          dp[i - 1][j] * (1.0 - p[i - 1]);
                                                                 // 本次是反面的概率
             }
      return dp[n][k];
}
class Solution {
private:
    struct TrieNode {
        vector<TrieNode*> child;
        string word;
        TrieNode() : word(""), child(vector<TrieNode*>(26, nullptr)) {}
    };
TrieNode* buildTrie(vector<string>& words) {
    TrieNode* root = new TrieNode();
    for (string w : words) {
        TrieNode* curr = root;
        for (char c : w) {
            int i = c - 'a';
            if (curr->child[i] == NULL) curr->child[i] = new TrieNode();
            curr = curr->child[i];
        curr->word = w;
    return root;
}
    void dfs(vector<vector<char>>& board, int i, int j, TrieNode* curr, vector<string>& out) {
        if (i < 0 || j < 0 || i >= board.size() || j >= board[0].size()) return;
        char c = board[i][j];
        if(c == '#' || curr->child[c - 'a'] == NULL) return;
        curr = curr->child[c - 'a'];
        if (curr->word != "") {
            out.push_back(curr->word);
            curr->word = "";
        }
        board[i][j] = '#';
        dfs(board, i - 1, j, curr, out);
        dfs(board, i, j - 1, curr, out);
        dfs(board, i + 1, j, curr, out);
        dfs(board, i, j + 1, curr, out);
        board[i][j] = c;
    }
public:
    vector<string> findWords(vector<vector<char>>& board, vector<string>& words) {
        vector<string> out;
        TrieNode* root = buildTrie(words);
        for(int i = 0; i < board.size(); ++i)</pre>
```