```
a = complex(input("Enter 1st complex no.: "))
b = complex(input("Enter 2nd complex no.: "))
print("Given complex numbers are: 1.", a, " 2.", b)
print("Addition of two complex numbers: ", a, "+", b, "=", a+b)
print("Subtraction of two complex numbers: ", a, "-", b, "=", a-b)
print("Multiplication of two complex numbers:", a, "*", b, "=", a*b)
print("Division of two complex numbers:", a, "/", b, "=", a/b)
1.2
a = complex(input("Enter 1st complex no.: "))
b = complex(input("Enter 2nd complex no.: "))
print("The conjugate of the given complex numbers are: \nln 1: ", a.conjugate(), "\nln 2: ", b.conjugate())
1.3
import matplotlib.pyplot as plt
S = \{3+3j, 2+1j\}
x = [z.real for z in S]
y = [z.imag for z in S]
plt.plot(x, y, 'o') # 'o' for points
plt.axis([-6, 6, -6, 6])
plt.show()
1.4
import matplotlib.pyplot as plt
angle = int(input("Enter angle: "))
if angle == 90:
 S1 = \{2*x \text{ for } x \text{ in } \{3+2j\}\} \# Adjusting the set to create a simple complex number
  print(S1)
 x = [z.real for z in S1]
 y = [z.imag for z in S1]
  plt.plot(x, y, 'o')
  plt.axis([-6, 6, -6, 6])
  plt.show()
elif angle == 180:
 S1 = \{x-1 \text{ for } x \text{ in } \{3+2j\}\} # Adjusting the set for a different transformation
  print(S1)
 x = [z.real for z in S1]
 y = [z.imag for z in S1]
  plt.plot(x, y, 'o')
  plt.axis([-6, 6, -6, 6])
  plt.show()
```

```
elif angle == 270:
  S1 = \{x-1j \text{ for } x \text{ in } \{3+2j\}\} \# Another transformation
  print(S1)
  x = [z.real for z in S1]
  y = [z.imag for z in S1]
  plt.plot(x, y, 'o')
  plt.axis([-6, 6, -6, 6])
  plt.show()
else:
  print("Invalid angle.")
2
import numpy as np
# Part A: Displaying 2 matrices
a = np.array([[1, 2], [3, 4]])
print("First matrix is: \n", a)
b = np.array([[1, 2, 3], [-4, -5, 0], [7, 8, 9]])
print("Second matrix is: \n", b)
# Part B: Retrieving rows and specific elements
a = np.array([[1, 2, 3], [11, 12, 13], [12, 23, 34]])
print("\nMatrix: \n", a)
print("1st row of matrix: ", a[0, :])
print("2nd row of matrix: ", a[1, :])
print("3rd row of matrix: ", a[2, :])
print("2nd element of 3rd row of matrix: ", a[2, 1])
print("3rd element of 2nd row of matrix: ", a[1, 2])
# Part C: Retrieving columns of a matrix
a = np.array([[1, 2, 3], [11, 12, 13], [12, 23, 34]])
print("\nMatrix: \n", a)
print("1st column of matrix: ", a[:, 0])
print("2nd column of matrix: ", a[:, 1])
print("3rd column of matrix: ", a[:, 2])
3
3.1
# Part A: Input matrix dimensions and elements from the user
rows = int(input("Enter the number of rows: "))
columns = int(input("Enter the number of columns: "))
matrix = []
print("Enter the matrix elements row-wise:")
for i in range(rows):
  row = [int(x) for x in input().split()] # Splitting and converting input to integers
  matrix.append(row)
```

```
print("Matrix:")
for row in matrix:
  print(row)
3.2
# Part B: Matrix operations using NumPy
import numpy as np
a = np.array([[1, 2, 3], [11, 12, 13], [12, 23, 34]])
print("Matrix:\n", a, "\n")
# Retrieving rows
print("1st row of matrix: ", a[0, :])
print("2nd row of matrix: ", a[1, :])
print("3rd row of matrix: ", a[2, :])
# Retrieving columns
print("1st column of matrix: ", a[:, 0])
print("2nd column of matrix: ", a[:, 1])
print("3rd column of matrix: ", a[:, 2])
3.3
import numpy as np
a = 5 # Scalar value
M = np.array([[1, 2], [3, 4]]) # Matrix
print("Matrix:\n", M)
# Scalar multiplication
b = a * M
print("\nScalar multiplication of the matrix is:\n", b)
import numpy as np
a = np.array([[12, 7], [4, 5], [3, 8]]) # Matrix
print("Matrix is:\n", a)
# Transpose of the matrix
print("\nTransposed matrix is:\n", a.transpose())
4
import numpy as np
# Input number of rows and columns
r = int(input("Enter the number of rows: "))
c = int(input("Enter the number of columns: "))
# Check if the matrix is square
```

```
if r != c:
  print("Matrix must be square to be invertible")
else:
  print("Enter the matrix elements row-wise:")
  # Inputting the matrix
  matrix = np.array([list(map(float, input().split())) for _ in range(r)])
  # Calculate the determinant
  det = np.linalg.det(matrix)
  # Check if the determinant is zero
  if det == 0:
    print("The matrix is not invertible (determinant is zero)")
  else:
    # Calculate the inverse of the matrix
    inverse_matrix = np.linalg.inv(matrix)
    print("The matrix is invertible.")
    print("Inverse of the matrix:")
    print(inverse_matrix)
5.A
   import numpy as np
   # Vector and matrix definitions
   x = np.array([2, 1, 3]) # Corrected the vector definition
   y = np.array([[4, 5], [6, 7], [8, 9]]) # Corrected the matrix definition
   print("Vector:", x)
   print("Matrix:\n", y)
   # Vector-matrix multiplication
   result = np.dot(x, y)
   print("The vector-matrix multiplication is:\n", result)
   5.B
   import numpy as np
   # Matrix definitions
   x = np.array([[1, 2], [3, 4]]) # Corrected the matrix definition
   y = np.array([[1, 2], [3, 4]]) # Corrected the matrix definition
```

```
print("1st matrix:\n", x)
print("2nd matrix:\n", y)
# Matrix-matrix multiplication
result = np.dot(x, y)
print("The matrix-matrix multiplication is:\n", result)
6.A GCD
import math
# Input two numbers
a = int(input("Enter a number: "))
b = int(input("Enter another number: "))
# Calculate GCD
gcd_value = math.gcd(a, b)
# Print the result
print("GCD of", a, "and", b, "is", gcd_value)
6.B
import math
def find_factors(N):
 factors = []
 for i in range(1, int(math.sqrt(N)) + 1):
   if N % i == 0:
     factors.append(i)
     if i!= N // i: # Avoid adding the square root twice
       factors.append(N // i)
  return sorted(factors)
def verify_m_and_n(N):
```

```
factors = find_factors(N)
  print(f"Factors of {N}: {factors}")
  for a in factors:
    for b in factors:
      if (a + b) \% 2 == 0 and (b - a) \% 2 == 0:
        m = (a + b) // 2
        n = (b - a) // 2
        if m^*2 - n^*2 == N:
          print(f"Verification: \{m\}^2 - \{n\}^2 = \{N\}^n)
          return
  print(f"No valid (m, n) pair found for N = {N}")
# Main function to input a number and verify m and n
N = int(input("Enter a Number: "))
verify_m_and_n(N)
7
import numpy as np
def oprojection(of_vec, on_vec):
  x1 = np.array(of_vec)
  x2 = np.array(on_vec)
  print(f"1st vector a = {x1}")
  print(f"2nd vector b = {x2}")
  scalar = np.dot(x1, x2) / np.dot(x2, x2)
  vec = scalar * x2
  print("Projection of a on b = ", vec)
  print("Om Singh 46")
```

```
# Example usage
oprojection([2, 4], [8, 6])
import numpy as np
# Define the matrix A
A = np.array([[-2, 1], [12, -30]])
print("Matrix A:\n", A)
# Compute eigenvalues and eigenvectors
eigen_values, eigen_vectors = np.linalg.eig(A)
print("Eigenvalues of A are:", eigen_values)
print("Eigenvectors of A are:\n", eigen_vectors)
def How_echelon(matrix):
  Rows = len(matrix)
  Cols = len(matrix[0])
  for i in range(Rows):
    if matrix[i][i] != 0:
      divisor = matrix[i][i]
      for j in range(i, Cols):
        matrix[i][j] = matrix[i][j] / divisor
    for k in range(i + 1, Rows):
      factor = matrix[k][i]
      for j in range(i, Cols):
        matrix[k][j] = matrix[k][j] - factor * matrix[i][j]
```

return matrix

```
A = \hbox{\tt [[2,1,-1,-3],[4,5,-3,-7],[2,6,-1,6]]}
```

```
# Calling the function

ref_matrix = How_echelon(A)

print("Om Singh 46")

for row in ref_matrix:

print(row)
```