

Eigenpairs

DSTA

Eigenpairs

Study materials

I. Goodfellow, Y. Bengio and A. Courville:

[Deep Learning](#), MIT Press, 2016.

J. Lescovec, A. Rajaraman, J. Ullmann:

[Mining of Massive datasets](#), MIT Press, 2016.

The material covered here is presented in the excerpts available for download.

Spectral Analysis

Eigenpairs

If, given a matrix A we find a real λ and a vector \mathbf{e} s.t.

$$A\mathbf{e} = \lambda\mathbf{e}$$

then λ and \mathbf{e} will be an eigenpair of A .

...

In principle, if A has rank n there should be n such pairs.

...

In practice, eigenpairs

- are always *costly* to find.

- they might have $\lambda = 0$: no information, or
- λ might not be a real number: no interpretation.

Conditions for *good* eigen-

A square matrix A is called *positive semidefinite* when for any \mathbf{x} we have

$$\mathbf{x}^T A \mathbf{x} \geq 0$$

In such case its eigenvalues are non-negative: $\lambda_i \geq 0$.

Underlying idea, I

In Geometry, applying a matrix to a vector, $A\mathbf{x}$, creates all sorts of alteration to the space, e.g.,

- rotation
- deformation

Eigenvectors, i.e., solutions to $A\mathbf{e} = \lambda\mathbf{e}$

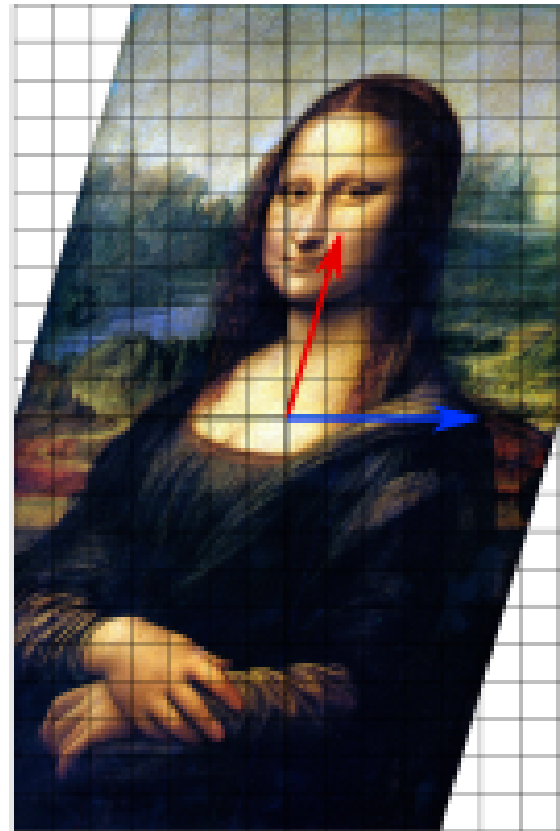
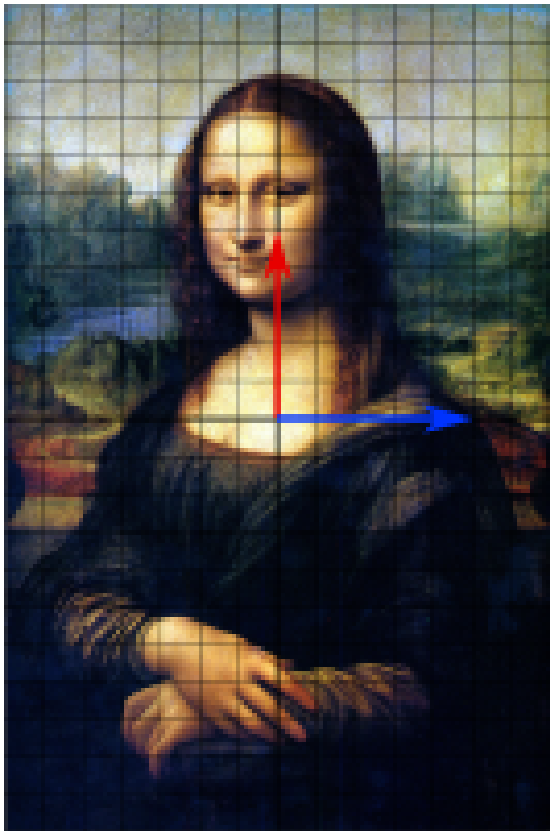
describe the direction along which matrix A operates an **expansion**

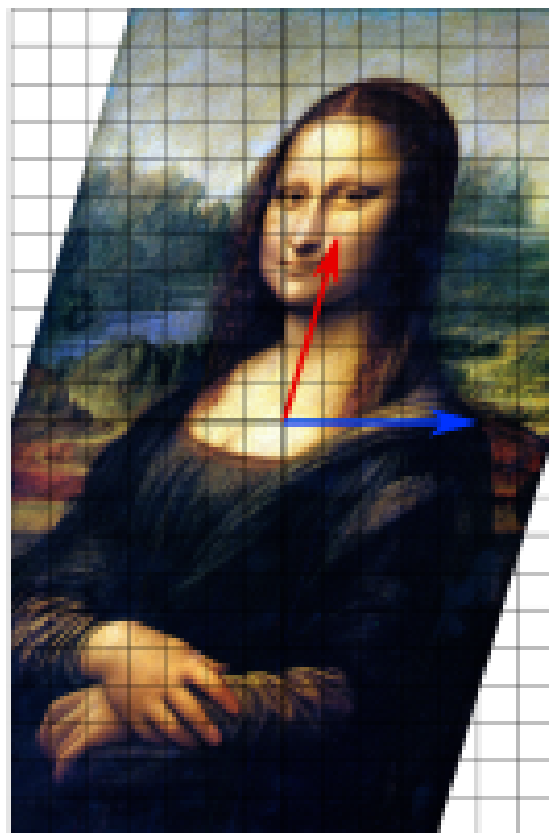
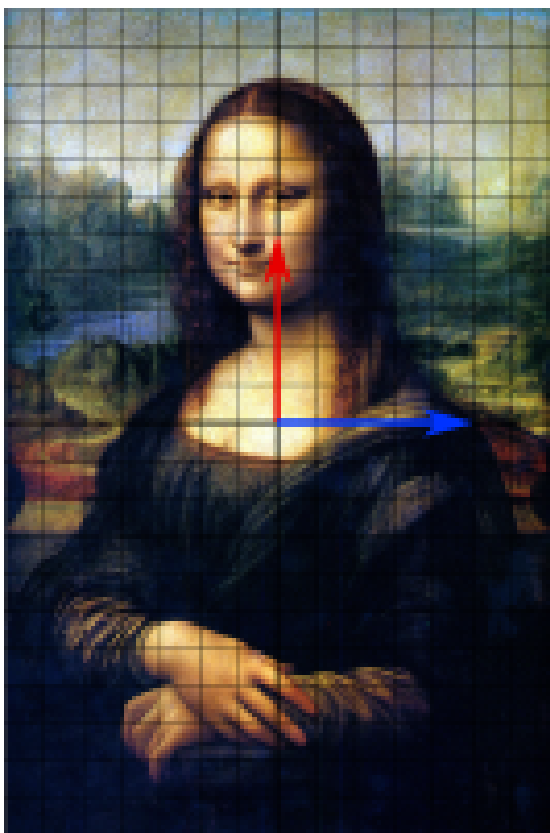
Example: shear mapping

```
A = [[1, .27],
      [0,  1]]
```

deforms a vector by increasing the first dimension by a quantity proportional to the value of the second dimension:

$$\begin{bmatrix} x \\ y \end{bmatrix} \rightarrow \begin{bmatrix} x + \frac{3}{11}y \\ y \end{bmatrix}$$





The blue line is unchanged:

- an $[x, 0]^T$ eigenvector
- corresponding to $\lambda = 1$

Activity matrices, I

Under certain conditions:

- the eigenpairs exist,
- e-values are real, non-negative numbers (0 is ok), and
- e-vectors are orthogonal with each other:

...

User-activity matrices normally meet those conditions!

Activity matrices, II

If an activity matrix has *good* eigenpairs,

...

each e-vector represents a *direction*

we interpret those directions as *topics* that hidden (latent) within the data.

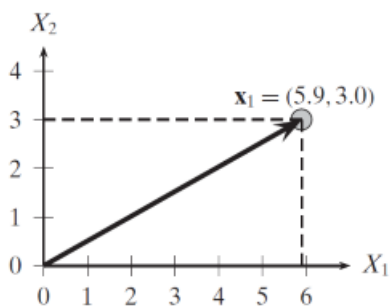
e-values *expand* one's affiliation to a specific *topic*.

Norms and distances

Euclidean norm

Pythagora's theorem, essentially.

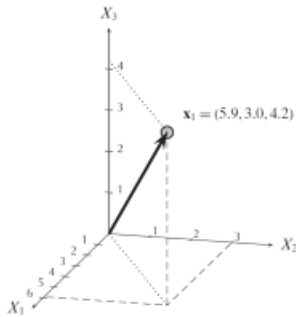
$$||\mathbf{x}|| = \sqrt{\mathbf{x}^T \mathbf{x}} = \sqrt{\sum_{i=1}^m x_i^2}$$



...

Generalisation:

$$||\mathbf{x}||_p = (|x_1|^p + |x_2|^p + \dots + |x_m|^p)^{\frac{1}{p}} = (\sum_{i=1}^m |x_i|^p)^{\frac{1}{p}}$$



...

The Frobenius norm $\|\cdot\|_F$ extends $\|\cdot\|_2$ to matrices:

$$\|\mathbf{A}\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2}$$

Normalization

The *unit* or *normalized* vector of \mathbf{x}

$$\mathbf{u} = \frac{\mathbf{x}}{\|\mathbf{x}\|} = \left(\frac{1}{\|\mathbf{x}\|}\right)\mathbf{x}$$

- has the same direction of the original
- its norm is constructed to be 1.

Computing Eigenpairs

With Maths

$$M\mathbf{e} = \lambda\mathbf{e}$$

...

Handbook solution: solve the equivalent system

$$(M - \lambda\mathbf{I})\mathbf{e} = \mathbf{0}$$

...

Either of the two factors should be 0. Hence, a non-zero vector \mathbf{e} is associated to a solution of

$$|M - \lambda \mathbf{I}| = 0$$

$$|M - \lambda \mathbf{I}| = 0$$

In Numerical Analysis many methods are available.

Their general algorithmic structure:

-find the λ s that make $|\dots| = 0$, then

-for each λ find its associated vector \mathbf{e} .

With Computer Science

At the scale of the Web, few methods will still work!

Ideas:

1. find the e-vectors first, with an iterated method.
2. interleave iteration with control on the *expansion in value*

...

$$\mathbf{x}_0 = [1, 1, \dots, 1]^T$$

...

$$\mathbf{x}_{k+1} = \frac{M\mathbf{x}_k}{\|M\mathbf{x}_k\|}$$

...

until an approximate fix point: $x_{l+1} \approx x_l$.

Now, eliminate the contribution of the first eigenpair:

$$M^* = M - \lambda'_1 \mathbf{x}_1 \mathbf{x}_1^T$$

(since \mathbf{x}_1 is a column vector, $\mathbf{x}_1^T \mathbf{x}_1$ will be a scalar: its norm. Vice versa, $\mathbf{x}_1 \mathbf{x}_1^T$ will be a matrix)

...

Now, we repeat the iteration on M^* to find the second eigenpair.

Times are in $\Theta(dn^2)$.

For better scalability, we will cover [Pagerank](#) later.

Eigenpairs in Python

E-pairs with Numpy

```
import numpy as np

# this is the specific submodule
from numpy import linalg as la
```

```
m = np.array((7, 5))

m = [[1, 1, 1, 0, 0],
      [3, 3, 3, 0, 0],
      [4, 4, 4, 0, 0],
      [5, 5, 5, 0, 0],
      [0, 0, 0, 4, 4],
      [0, 0, 0, 5, 5],
      [0, 0, 0, 2, 2]]
```



```
def find_eigenpairs(mat):
    """Test the quality of Numpy eigenpairs"""
    n = len(mat)

    # is it squared?
    m = len(mat[0])

    eig_vals, eig_vects = la.eig(mat)

    # they come in ascending order, take the last one on the right
    dominant_eig = abs(eig_vals[-1])
    return dominant_eig
```

E-values come normalized: $\sqrt{\lambda_1^2 + \dots + \lambda_n^2} = 1$; hence we later multiply them by $\frac{1}{\sqrt{n}}$

```
# lambda_1 = find_eigenpairs(m)

# lambda_1
```

Coda: non-norms

$\|\mathbf{x}\|_0 = \#$ of non-zero scalar values in \mathbf{x}

$\|\mathbf{x}\|_\infty = \max\{|x_i|\}$