F. completed panels for assemblages
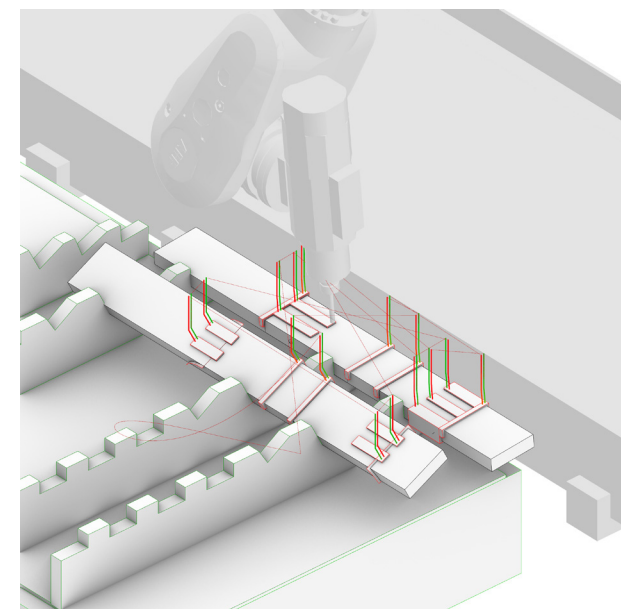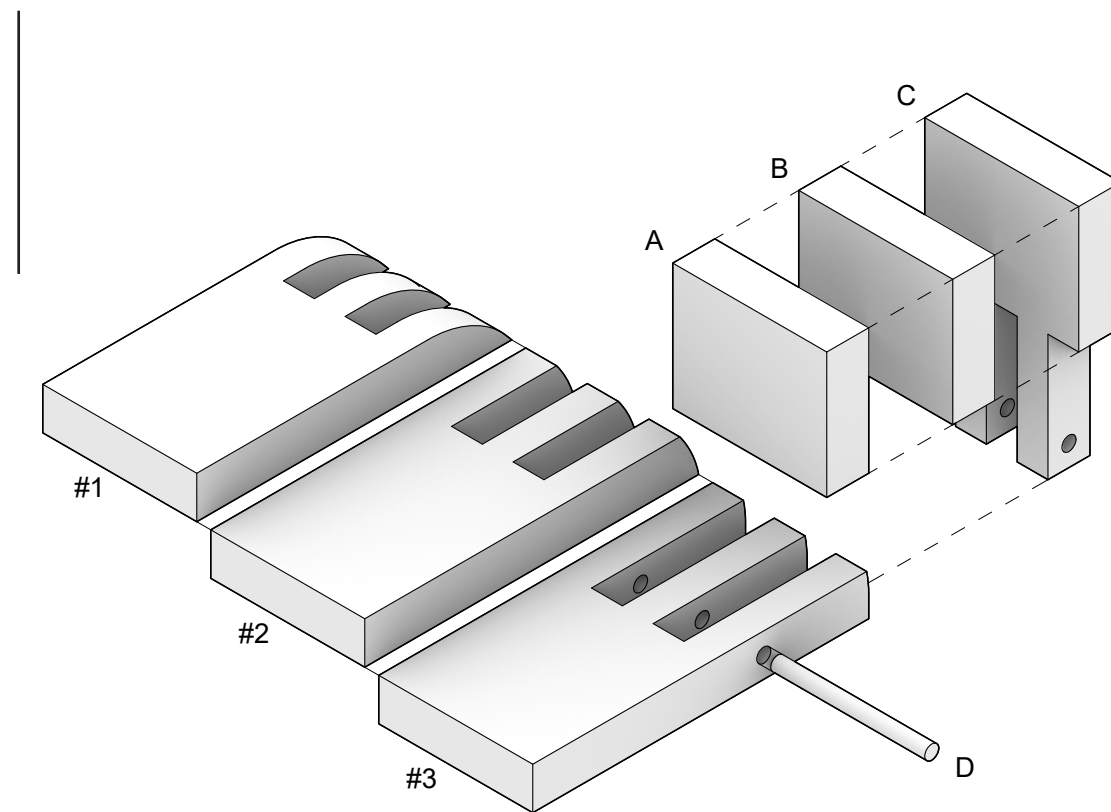

A. set up robot
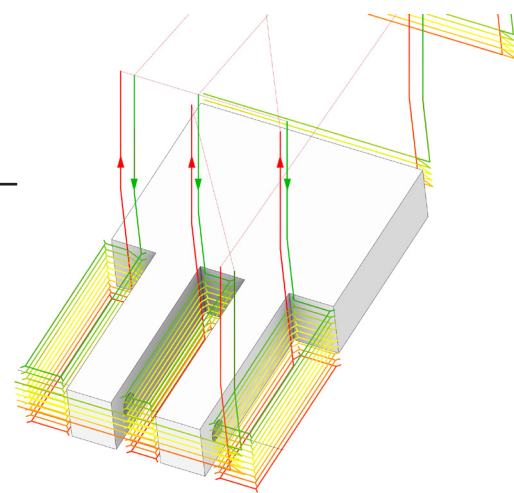

B. drill in stock material for milling
*areas shown in color are scripted cuts with
a 1/2" endmill

C. detail of finger mill pathway
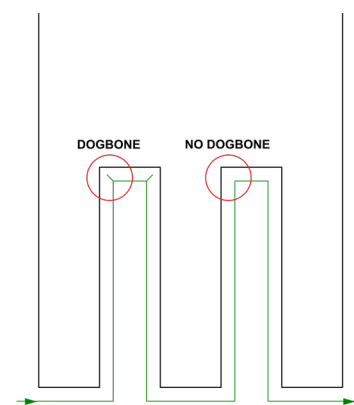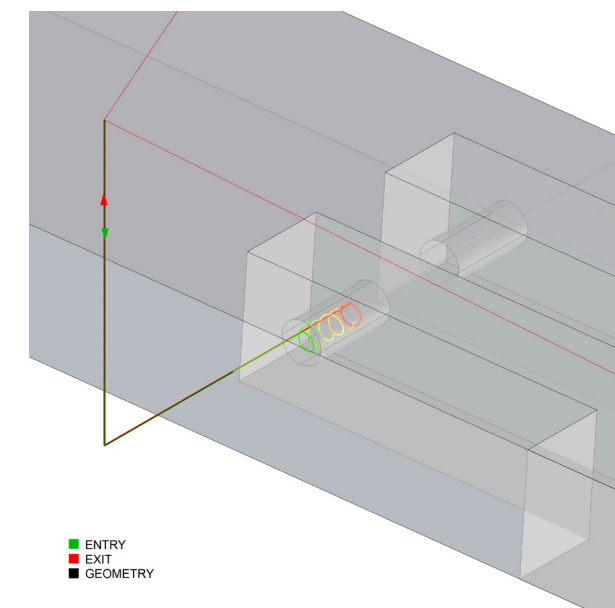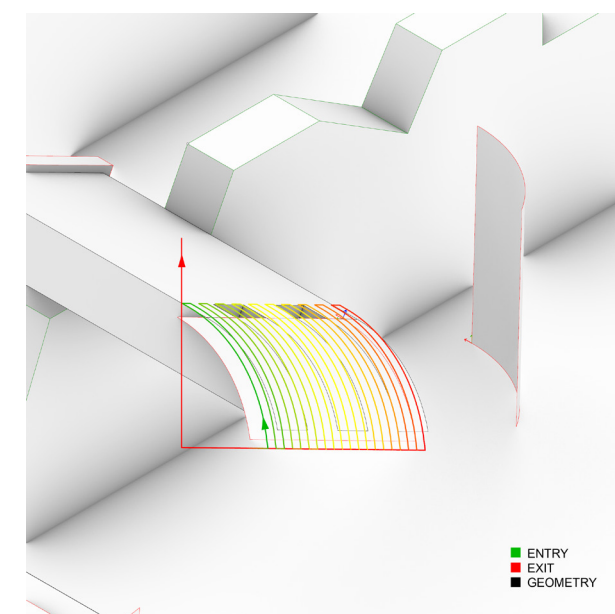*dogbone feature is implemented to ensure interior corners of all fingers align

DOGBONE   NO DOGBONE

ENTRY
EXIT
GEOMETRY

#1
#2
#3

A
B
C
D

E. finish with hole profiling（1/4"
endmill）to locate hole positions

ENTRY
EXIT
GEOMETRY

D. swarfing component implemented
to allow rotation and curvature

ENTRY
EXIT
GEOMETRY