Machine Learning PyTorch Tutorial

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Outline

- Prerequisites
- What is PyTorch?
- PyTorch v.s. TensorFlow
- Overview of the DNN Training Procedure
- Tensor
- How to Calculate Gradient?
- Dataset & Dataloader
- torch.nn
- torch.optim
- Neural Network Training/Evaluation
- Saving/Loading a Neural Network
- More About PyTorch

Prerequisites

- We assume you are already familiar with...
 - Python3
 - if-else, loop, function, file IO, class, ...
 - refs: <u>link1</u>, <u>link2</u>, <u>link3</u>



- array & array operations
- ref: <u>link</u>





What is PyTorch?

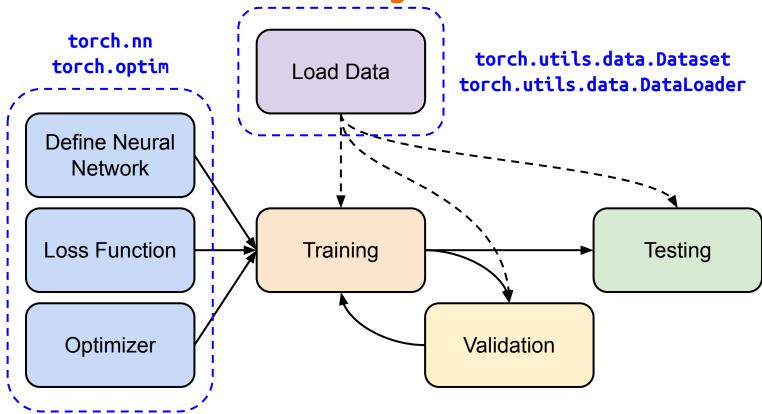
- An open source **machine learning framework**.
- A Python package that provides two high-level features:
 - Tensor computation (like NumPy) with strong GPU acceleration
 - Deep neural networks built on a tape-based autograd system



PyTorch v.s. TensorFlow

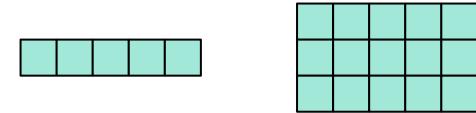
	PyTorch 💍	TensorFlow †
Developer	Facebook Al	Google Brain
Interface	Python & C++	Python, C++, JavaScript, Swift
Debug	Easier	Difficult (easier in 2.0)
Application	Research	Production

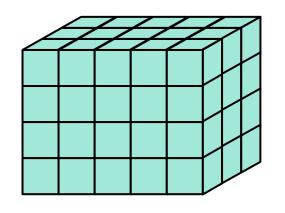
Overview of the DNN Training Procedure



Tensor

High-dimensional matrix (array)





1-D tensor

2-D tensor

3-D tensor

Tensor -- Data Type

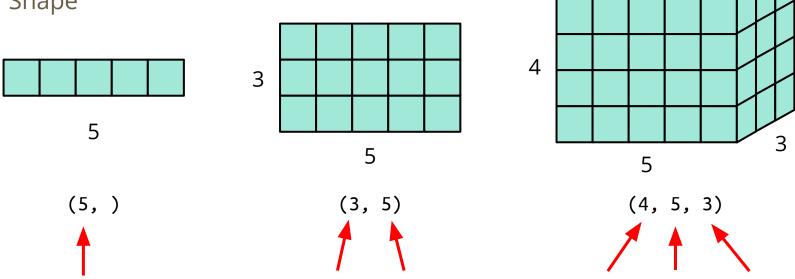
Data type	dtype	tensor
32-bit floating point	torch.float	torch.FloatTensor
64-bit integer (signed)	torch.long	torch.LongTensor

ref: https://pytorch.org/docs/stable/tensors.html

Tensor -- Shape of Tensors

Shape

dim 0



Note: dim in PyTorch == axis in NumPy

dim 0 dim 1

dim 0 dim 1

dim 2

Tensor -- Constructor

From list / NumPy array

```
x = torch.tensor([[1, -1], [-1, 1]])
```

```
tensor([[1., -1.], [-1., 1.]])
```

x = torch.from_numpy(np.array([[1, -1], [-1, 1]]))

Zero tensor

```
x = torch.zeros([2, 2])
```

Unit tensor

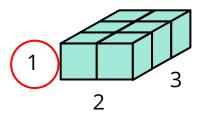
```
x = torch.ones([1, 2, 5])
```

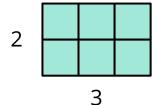
```
tensor([[0., 0.], [0., 0.]])
```

```
tensor([[[1., 1., 1., 1., 1.],
[1., 1., 1., 1., 1.]])
```

Squeeze: remove the specified dimension with length = 1

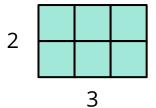
```
\Rightarrow x = \text{torch.zeros}([1, 2, 3])
>>> x.shape
torch.Size(([1,)2, 3])
>>> x = x.squeeze(0)
                  (dim = 0)
>>> x.shape
torch.Size([2, 3])
```

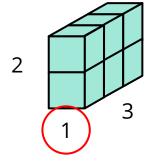




• **Unsqueeze**: expand a new dimension

```
>>> x = torch.zeros([2, 3])
>>> x.shape
torch.Size([2, 3])
                          (dim = 1)
>>> x = x.unsqueeze(1)
>>> x.shape
torch.Size([2,
```



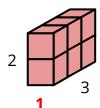


• **Transpose**: transpose two specified dimensions

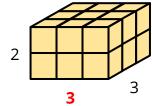
```
>>> x = torch.zeros([2, 3])
>>> x.shape
torch.Size([2, 3])
>>> x = x.transpose(0, 1)
>>> x.shape
                                                 3
torch.Size([3, 2])
```

• **Cat**: concatenate multiple tensors

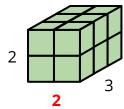




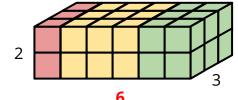
v



7



W



Addition

$$z = x + y$$

Subtraction

$$z = x - y$$

Power

$$y = x.pow(2)$$

Summation

$$y = x.sum()$$

Mean

$$y = x.mean()$$

Tensor -- PyTorch v.s. NumPy

Attributes

PyTorch	NumPy
x.shape	x.shape
x.dtype	x.dtype

ref: https://github.com/wkentaro/pytorch-for-numpy-users

Tensor -- PyTorch v.s. NumPy

Shape manipulation

PyTorch	NumPy
x.reshape / x.view	x.reshape
x.squeeze()	x.squeeze()
x.unsqueeze(1)	np.expand_dims(x, 1)

ref: https://github.com/wkentaro/pytorch-for-numpy-users

Tensor -- Device

Default: tensors & modules will be computed with CPU

CPU

GPU

```
x = x.to('cuda')
```

Tensor -- Device (GPU)



Check if your computer has NVIDIA GPU

```
torch.cuda.is_available()
```

Multiple GPUs: specify 'cuda:0', 'cuda:1', 'cuda:2', ...

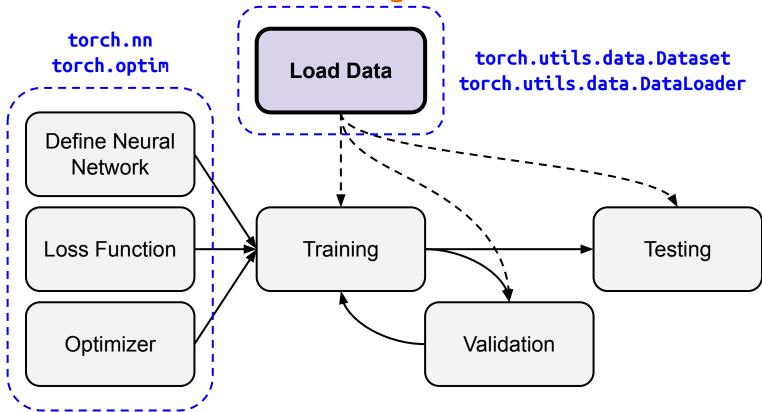
- Why GPU?
 - Parallel computing
 - https://towardsdatascience.com/what-is-a-gpu-and-do-you-need-one-in-deep-learning-718b9597aa0d

How to Calculate Gradient?

[-2., 2.]

```
1 >>> x = torch.tensor([[1., 0.], [-1., 1.]], requires_grad=True)
2 >>> z = x.pow(2).sum()
3 >>> z.backward()
4 >>> x.grad
tensor([[ 2., 0.], x = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} z = \sum_{i} \sum_{j} x_{i}
```

Overview of the DNN Training Procedure



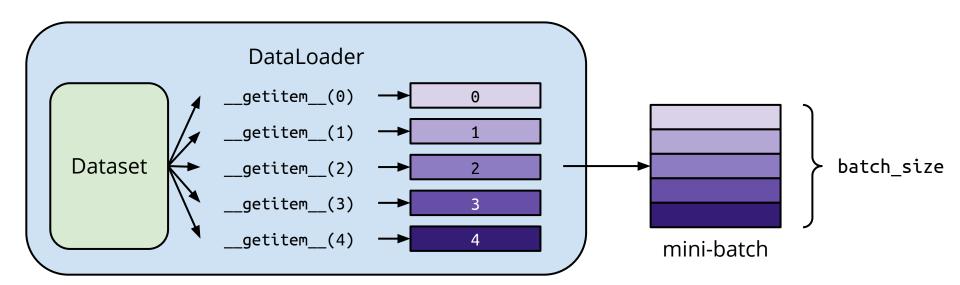
Dataset & Dataloader

```
from torch.utils.data import Dataset, DataLoader
class MyDataset(Dataset):
  def __init__(self, file):
    self.data = ...
                                      Read data & preprocess
  def __getitem__(self, index):
                                        Returns one sample at a time
       return self.data[index]
  def __len__(self):
                                    Returns the size of the dataset
       return len(self.data)
```

Dataset & Dataloader

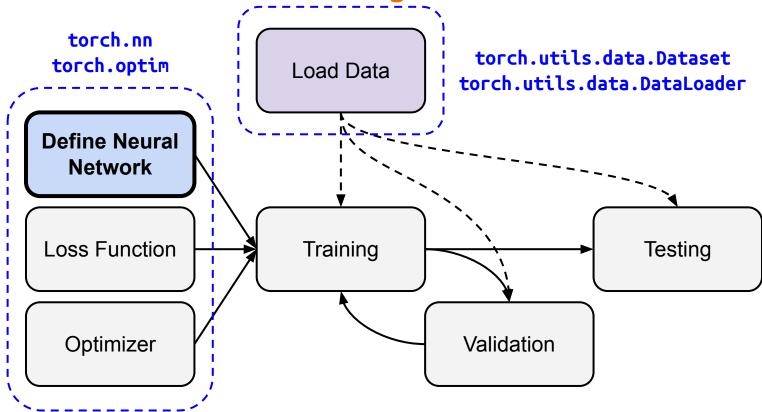
```
dataset = MyDataset(file)

dataloader = DataLoader(dataset, batch_size, shuffle=True)
```



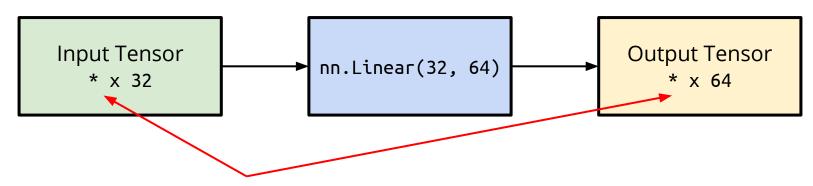
Training: True

Overview of the DNN Training Procedure



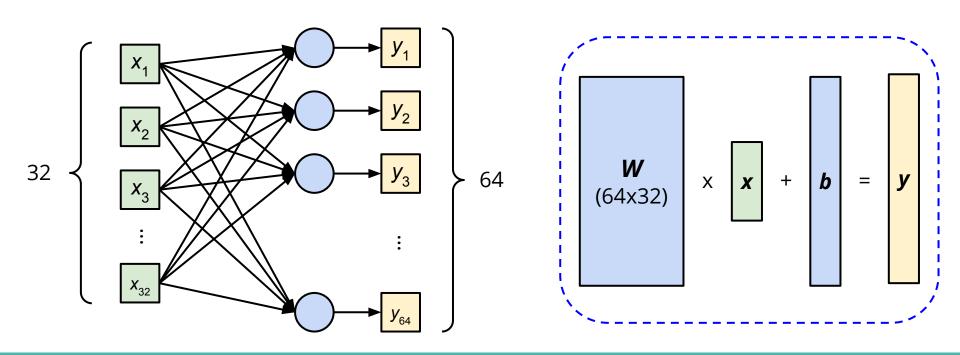
Linear Layer (Fully-connected Layer)

```
nn.Linear(in_features, out_features)
```

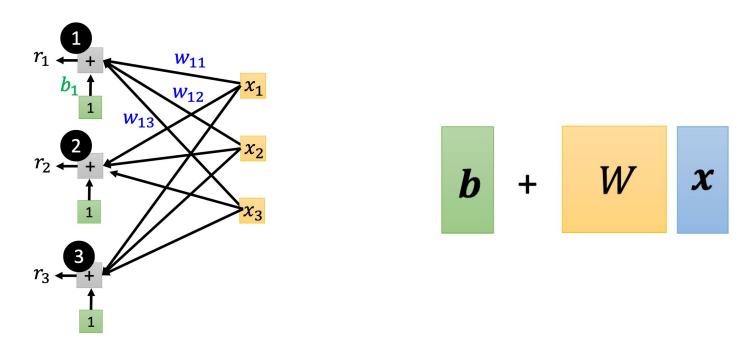


can be any shape but the last dimension must be 32 e.g. (10, 32), (10, 5, 32), (1, 1, 3, 32), ...

Linear Layer (Fully-connected Layer)

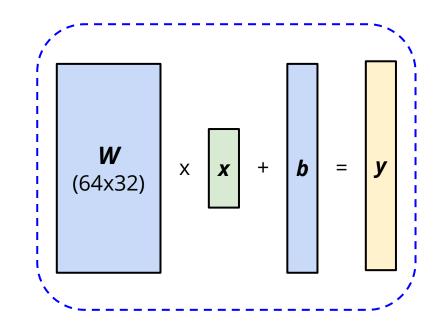


Linear Layer (Fully-connected Layer)



Linear Layer (Fully-connected Layer)

```
>>> layer = torch.nn.Linear(32, 64)
>>> layer.weight.shape
torch.Size([64, 32])
>>> layer.bias.shape
torch.Size([64])
```



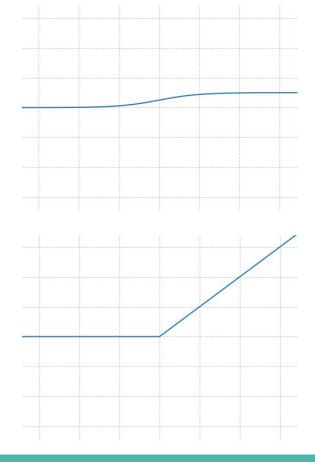
torch.nn -- Activation Functions

Sigmoid Activation

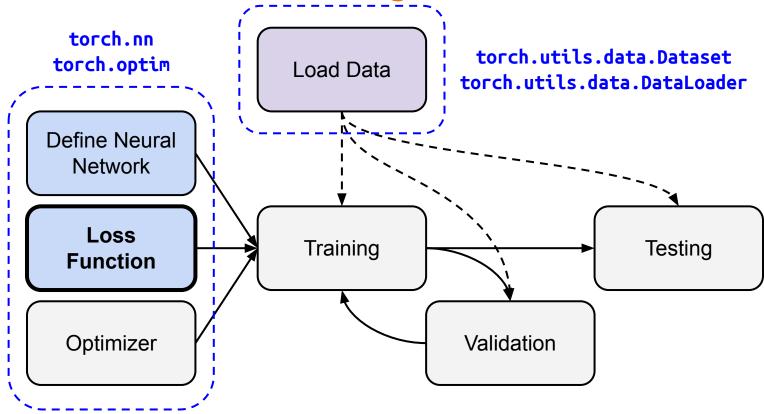
nn.Sigmoid()

ReLU Activation

nn.ReLU()



Overview of the DNN Training Procedure



torch.nn -- Loss Functions

Mean Squared Error (for linear regression)

nn.MSELoss()

Cross Entropy (for classification)

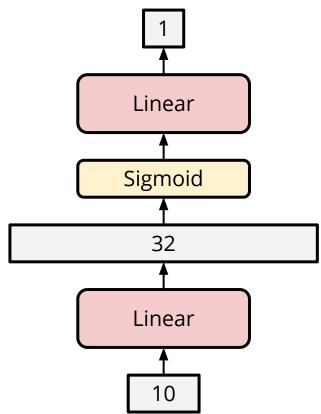
nn.CrossEntropyLoss()

torch.nn -- Build your own neural network

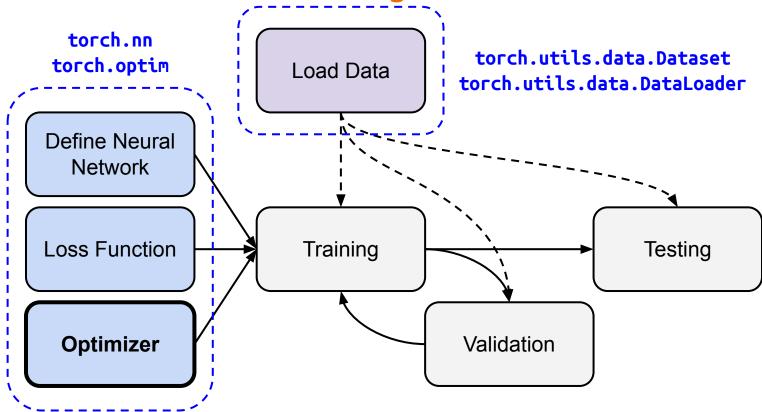
```
import torch.nn as nn
class MyModel(nn.Module):
   def init (self):
       super(MyModel, self).__init__()
       self.net = nn.Sequential(
                                           Initialize your model & define layers
           nn.Linear(10, 32),
           nn.Sigmoid(),
           nn.Linear(32, 1)
                                           Compute output of your NN
   def forward(self, x):
       return self.net(x)
```

torch.nn -- Build your own neural network

```
import torch.nn as nn
class MyModel(nn.Module):
   def init (self):
        super(MyModel, self).__init__()
        self.net = nn.Sequential(
            nn.Linear(10, 32),
            nn.Sigmoid(),
            nn.Linear(32, 1)
   def forward(self, x):
        return self.net(x)
```



Overview of the DNN Training Procedure

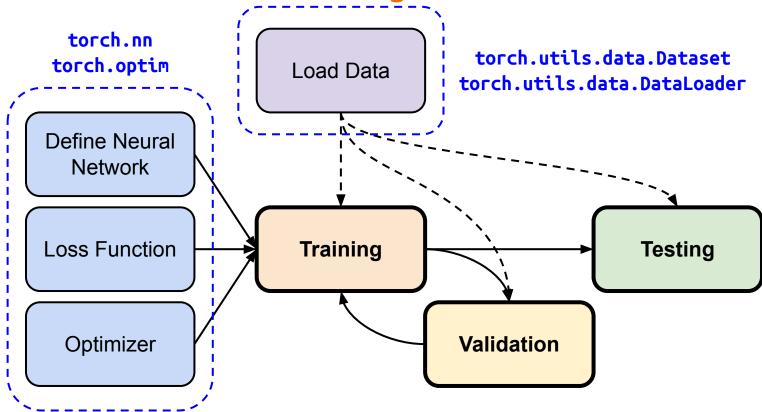


torch.optim

Optimization algorithms for neural networks (gradient descent)

Stochastic Gradient Descent (SGD)

Overview of the DNN Training Procedure



Neural Network Training

Neural Network Training

```
for epoch in range(n_epochs):
                                                iterate n epochs
                                                set model to train mode
     model.train()
     for x, y in tr set:
                                                iterate through the dataloader
          optimizer.zero_grad()
                                                set gradient to zero
          x, y = x.to(device), y.to(device)
                                                move data to device (cpu/cuda)
          pred = model(x)
                                                forward pass (compute output)
          loss = criterion(pred, y)
                                                compute loss
          loss.backward()
                                                compute gradient (backpropagation)
          optimizer.step()
                                                update model with optimizer
```

Neural Network Evaluation (Validation Set)

```
model.eval()
                                                          set model to evaluation mode
total loss = 0
for x, y in dv set:
                                                          iterate through the dataloader
     x, y = x.to(device), y.to(device)
                                                          move data to device (cpu/cuda)
     with torch.no grad():
                                                          disable gradient calculation
          pred = model(x)
                                                          forward pass (compute output)
          loss = criterion(pred, y)
                                                          compute loss
     total loss += loss.cpu().item() * len(x)
                                                          accumulate loss
     avg loss = total loss / len(dv set.dataset)
                                                          compute averaged loss
```

Neural Network Evaluation (Testing Set)

```
model.eval()
                                                set model to evaluation mode
preds = []
for x in tt set:
                                                iterate through the dataloader
    x = x.to(device)
                                                move data to device (cpu/cuda)
    with torch.no_grad():
                                                disable gradient calculation
        pred = model(x)
                                                forward pass (compute output)
        preds.append(pred.cpu())
                                                collect prediction
```

Save/Load a Neural Network

Save

```
torch.save(model.state_dict(), path)
```

Load

```
ckpt = torch.load(path)
model.load_state_dict(ckpt)
```

More About PyTorch

- torchaudio
 - speech/audio processing
- torchtext
 - natural language processing
- torchvision
 - computer vision
- skorch
 - scikit-learn + pyTorch

More About PyTorch

- Useful github repositories using PyTorch
 - Huggingface Transformers (transformer models: BERT, GPT, ...)
 - <u>Fairseq</u> (sequence modeling for NLP & speech)
 - <u>ESPnet</u> (speech recognition, translation, synthesis, ...)
 - Many implementation of papers
 - 0 ...

Reference

- https://pytorch.org/
- https://github.com/pytorch/pytorch
- https://github.com/wkentaro/pytorch-for-numpy-users
- https://blog.udacity.com/2020/05/pytorch-vs-tensorflow-what-you-need-to-know.html
- https://www.tensorflow.org/
- https://numpy.org/

Any questions?