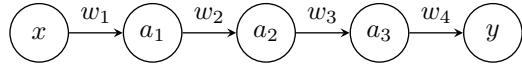


Deep Learning and Artificial Intelligence
 WS 2025/26

Exercise 3: Computational Graphs and Vanishing Gradients

Exercise 3-1 Vanishing Gradients Problem

Consider a network with input $x \in \mathbb{R}$, 3 hidden layers each having only one node, and one output $y \in \mathbb{R}$:



In the network each node corresponds to a nonlinear function of the preceding node multiplied with some weight: $a_i = \sigma(w_i \cdot a_{i-1})$, $i = 1, \dots, 4$, with $\sigma(x) = \frac{1}{1+e^{-x}}$ where a_0 corresponds to the input x and a_4 corresponds to the output y .

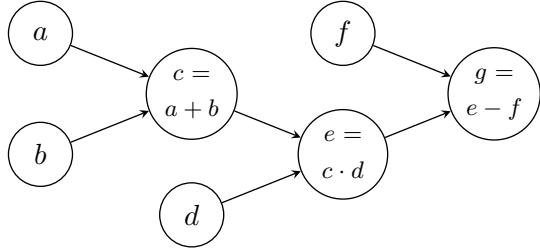
Task:

- (a) By using the chain rule, calculate the derivative $\frac{\partial y}{\partial x}$!

$$\left[\text{Solution: } \frac{\partial y}{\partial x} = \sigma'(z_4) w_4 \cdot \sigma'(z_3) w_3 \cdot \sigma'(z_2) w_2 \cdot \sigma'(z_1) w_1 \right]$$
- (b) Calculate the maximum of the derivative $\sigma' = \frac{\partial}{\partial z} \frac{1}{1+e^{-z}}$!
Hint: The derivative can be written as $\sigma' = \sigma(1 - \sigma)$. [Solution: $\frac{1}{4}$]
- (c) How does this result relate to the vanishing gradients problem?
- (d) How can we avoid the vanishing gradients problem during weight initialization?
- (e) What are advantages of using the ReLU activation function instead of s-shaped ones? What could be disadvantages?

Exercise 3-2 Computational Graphs

Computational graphs are directed graphs that represent the dependencies between the variables and operations within a model or, more generally, a mathematical expression. As an example, consider the expression: $g = (a + b) \cdot d - f$. To build the computational graph for this example we represent each of the operations as well as all of the input variables as nodes and draw an arrow from one node to another if the first is the input to the latter (see figure below). Such a node is called *gate* or *layer* in common. Note that we introduced 2 intermediate variables c and e so that every node has a name.

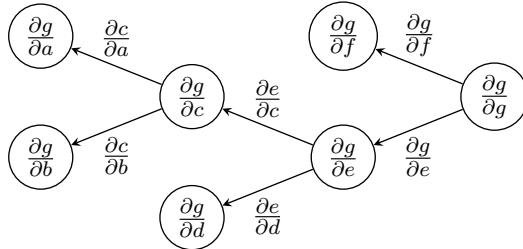


Computational graphs are used by popular deep learning frameworks like Theano and Tensorflow in order to optimize execution, for example, through parallelizing or fusing calculations.

Task: Given an input $\mathbf{x} \in \mathbb{R}^2$, a weight vector $\mathbf{w} \in \mathbb{R}^2$ and a bias $p_0 \in \mathbb{R}$. Draw the computation graph for the mean squared error $L = MSE(\hat{y}, y)$ of a prediction $\hat{y} = \sigma(\mathbf{w}^T \mathbf{x} + p_0)$ ¹ with respect to the true value y .

Exercise 3-3 Derivatives on Computational Graphs

Most deep learning frameworks provide an automatic differentiation procedure to compute the gradients based on the backpropagation algorithm introduced in the lecture. Those gradients can be written as a computational graph as well. Consider the example from exercise 2 again. The computational graph for the gradients (with respect to g) would look as follows:



Task:

- (a) Given $\mathbf{x} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, $\mathbf{w} = \begin{pmatrix} \frac{4}{5} \\ -\frac{7}{5} \end{pmatrix}$, $p_0 = \frac{3}{5}$, $y = 1$ and the loss function $L = (\hat{y} - y)^2$. Calculate the missing values in the computation graph of exercise 2.

$$\left[\text{Solution: } p_1 = \frac{4}{5}, p_2 = -\frac{7}{5}, z = 0, \hat{y} = \frac{1}{1+e^{-0}} = \frac{1}{2}, L = (\frac{1}{2} - 1)^2 = \frac{1}{4} \right]$$

- (b) Draw the corresponding computational gradient graph for the computational graph from exercise 2.
(c) Calculate the gradient values for each edge and node in the computational gradient graph.

Exercise 3-4 Computational Graphs in Python

In this exercise you will implement a computational graph in python. For this purpose please use the corresponding jupyter notebook for this exercise. There you will find a template for the implementation of an abstract gate. Every gate has a set of inputs (input_nodes) and consumers. Additionally a gate has to implement the methods **forward** and **backward**. The **forward** method computes the result with respect to the given input nodes (use the *out* field) of the input gates and stores the value in the field *out*. The **backward** function computes and propagates the gradient for the given gate. On call of the **backward** function, the gate uses the incoming gradient *dz* and adds to all input nodes the corresponding gradient. In the template you will find two input gates (*InputGate* and *AddGate*) as simple example.

¹The sigmoid function $\sigma(z) = \frac{1}{1+e^{-z}}$ is often used in logistic regression and binary classification tasks.

In addition, the template provides a *ComputationalGraph* class. This class implements the **backward** and **forward** function as well, but for the whole graph. Both methods return a graphviz object visualizing the respective steps. To draw the computational graphs in jupyter notebook you can for instance use the imported *display* function.

- (a) Implement a gate that represents a weight (*WeightGate*). The constructor shall take the parameter α that represents the learning rate of this weight.
- (b) Implement a gate that multiplies the outputs of a set of input gates (*MultiplyGate*).
- (c) Implement a sigmoid gate that computes the sigmoid σ of one input (*SigmoidGate*). *Hint:* The derivative can be written as $\sigma' = \sigma(1 - \sigma)$.
- (d) Implement a gate (*SquaredLossGate*) with the following loss function $L(y, \hat{y}) = (\hat{y} - y)^2$.
- (e) Build the computational graph from exercise 3-1 in python and compute display the computational graph after forward and backward. *Hint:* You can validate your calculation with this implementation.
- (f) Construct and train a computational graph / network that can classify the XOR dataset with stochastic gradient descent and the already implemented squared loss function.

Gradient Descent (GD)

$$w = w - \alpha \nabla \sum_{i=1}^N L(\hat{y}_i, y_i)$$

Conversion to local minima

Expensive for large dataset

(needs to calculate sum of loss everytime)

Stochastic Gradient Descent (SGD)

$$w = w - \alpha \nabla L(\hat{y}_i, y_i)$$

More noisy

More robust against convergence to local minima

Slower to converge

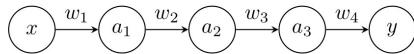
Minibatch GD

$$w = w - \alpha \sum_{i \in B} L(\hat{y}_i, y_i)$$

Balance between GD and SGD

Exercise 3-1 Vanishing Gradients Problem

Consider a network with input $x \in \mathbb{R}$, 3 hidden layers each having only one node, and one output $y \in \mathbb{R}$:



In the network each node corresponds to a nonlinear function of the preceding node multiplied with some weight: $a_i = \sigma(w_i \cdot a_{i-1})$, $i = 1, \dots, 4$, with $\sigma(x) = \frac{1}{1+e^{-x}}$ where a_0 corresponds to the input x and a_4 corresponds to the output y .

Task:

- (a) By using the chain rule, calculate the derivative $\frac{\partial y}{\partial x}$!

$$[\text{Solution: } \frac{\partial y}{\partial x} = \sigma'(z_4) w_4 \cdot \sigma'(z_3) w_3 \cdot \sigma'(z_2) w_2 \cdot \sigma'(z_1) w_1]$$

$$y = \delta(w_4 \cdot a_3)$$

$$\frac{\partial y}{\partial x} = \frac{\partial a_4}{\partial a_3} \cdot \frac{\partial a_3}{\partial a_2} \cdot \frac{\partial a_2}{\partial a_1} \cdot \frac{\partial a_1}{\partial a_0}$$

$$\text{let } z_i = w_i \cdot a_{i-1}$$

$$\begin{aligned} \frac{\partial a_i}{\partial a_{i-1}} &= \frac{\partial \delta(w_i \cdot a_{i-1})}{\partial a_{i-1}} = \frac{\partial \delta(w_i \cdot a_{i-1})}{\partial (w_i \cdot a_{i-1})} \cdot \frac{\partial (w_i \cdot a_{i-1})}{\partial a_{i-1}} \\ &= \frac{\partial \delta(z_i)}{\partial z_i} \cdot w_i = \delta'(z_i) \cdot w_i \end{aligned}$$

$$\Rightarrow \frac{\partial y}{\partial x} = \delta'(z_4) \cdot w_4 \cdot \delta'(z_3) \cdot w_3 \cdot \delta'(z_2) \cdot w_2 \cdot \delta'(z_1) \cdot w_1$$

*

- (b) Calculate the maximum of the derivative $\sigma' = \frac{\partial}{\partial z} \frac{1}{1+e^{-z}}$!

Hint: The derivative can be written as $\sigma' = \sigma(1-\sigma)$. [Solution: $\frac{1}{4}$]

$$\begin{aligned} \text{let } \delta &= \delta(1-\delta) + \delta(1-\delta)' \quad \text{sum rule} \\ &= \delta'(1-\delta) + \delta(-\delta') \\ &= \delta'(1-2\delta) = 0 \end{aligned}$$

since $\delta' = \delta(1-\delta)$ always > 0 , $1-2\delta$ is 0

$$\Rightarrow 1-2\delta = 0 \Rightarrow \delta = \frac{1}{2}$$

$$\Rightarrow \frac{1}{1+e^{-z}} = \frac{1}{2} \Rightarrow z = 0$$

$$\delta' = \frac{1}{1+e^{-z}} \left(1 - \frac{1}{1+e^{-z}} \right) = \frac{1}{2} - \frac{1}{4} = \frac{1}{4}$$

*

(c) How does this result relate to the vanishing gradients problem?

$$\frac{\partial y}{\partial x} = \delta'(z_4) \cdot w_4 \cdot \delta'(z_3) \cdot w_3 \cdot \delta'(z_2) \cdot w_2 \cdot \delta'(z_1) \cdot w_1$$

If weights initialized as $w \sim N(0, 1)$

95% are within $(-2, 2)$ \Rightarrow most of the factors will satisfy $|\delta'(z_j) w_j| \leq \frac{1}{4}$

\Rightarrow the gradient becomes very small when multiplying many such terms (ie. learning becomes very slow)

(d) How can we avoid the vanishing gradients problem during weight initialization?

Use Glorot initialization of weights

Idea: Keep variance of activation and gradients similar across all layers

(e) What are advantages of using the ReLU activation function instead of s-shaped ones? What could be disadvantages?

Advantage

Possible issues

Avoid the vanishing gradient problem

Unbounded

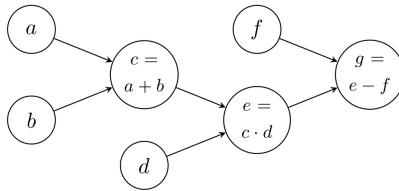
More efficient to calculate than sigmoid and tanh

Dying ReLU

(ReLU's derivative is either 0 or 1, while sigmoid and tanh needs to calculate e^x derivative)

Exercise 3-2 Computational Graphs

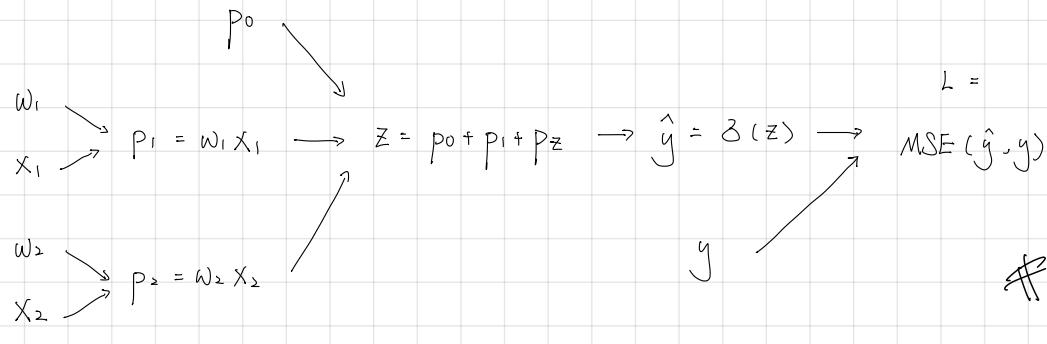
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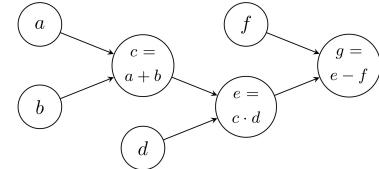
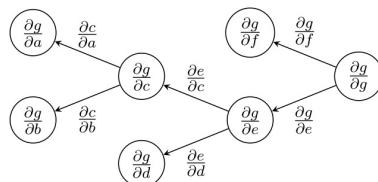
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$$L = MSE(\hat{y}, y) = (y - \delta(w^T x + p_0))^2$$



Exercise 3-3 Derivatives on Computational Graphs

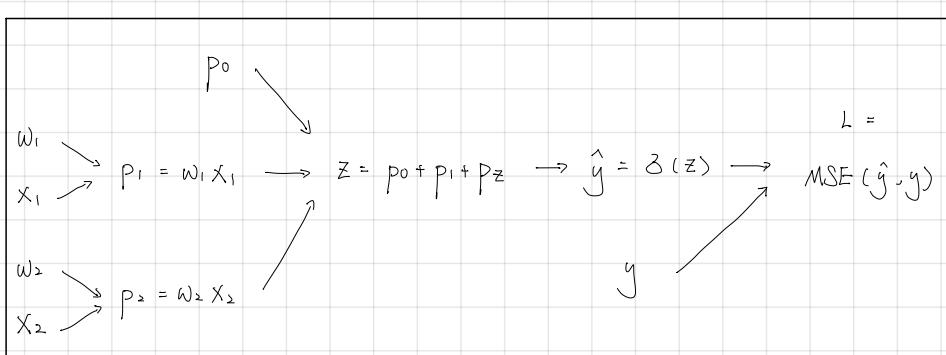
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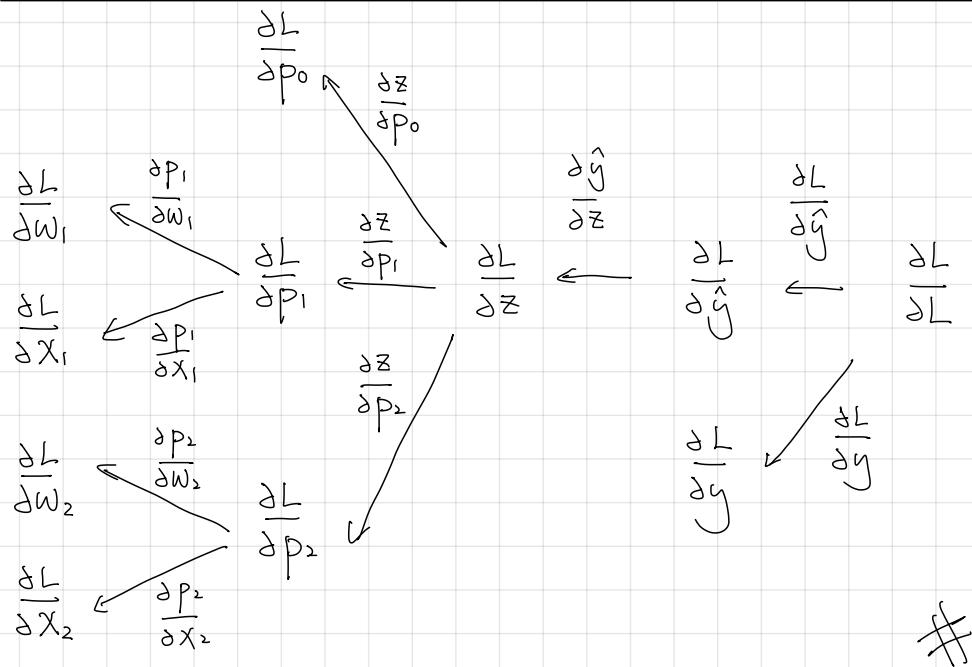
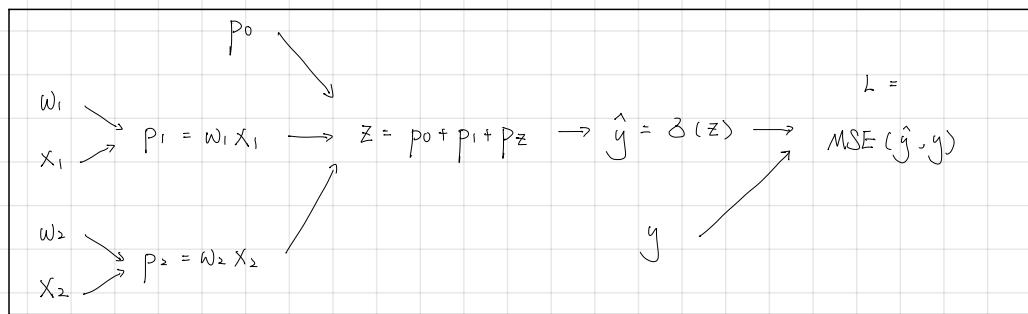
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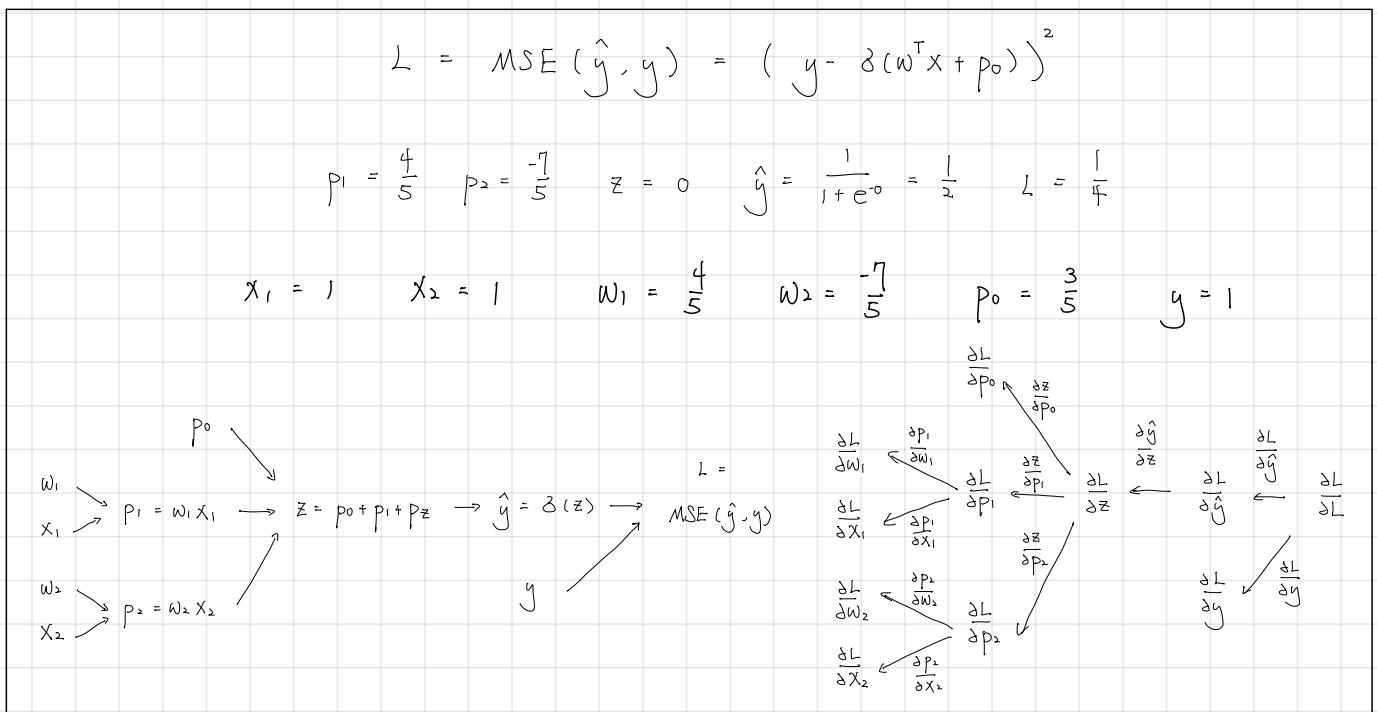
[Solution: $p_1 = \frac{4}{5}$, $p_2 = -\frac{7}{5}$, $z = 0$, $\hat{y} = \frac{1}{1+e^{-0}} = \frac{1}{2}$, $L = (\frac{1}{2} - 1)^2 = \frac{1}{4}$]



(b) Draw the corresponding computational gradient graph for the computational graph from exercise 2.



(c) Calculate the gradient values for each edge and node in the computational gradient graph.



$$\frac{\partial L}{\partial L} = 1 \quad \frac{\partial L}{\partial \hat{y}} = \frac{\partial (\hat{y} - y)^2}{\partial \hat{y}} = 2(\hat{y} - y) \cdot 1 = -1$$

$$\frac{\partial L}{\partial y} = \frac{\partial (\hat{y} - y)^2}{\partial y} = 2(\hat{y} - y) \cdot (-1) = 1$$

$$\frac{\partial \hat{y}}{\partial z} = \frac{\partial}{\partial z} \frac{1}{(1+e^{-z})} = \frac{0 - 1 \cdot (1+e^{-z})'}{(1+e^{-z})^2} = \frac{e^{-z}}{(1+e^{-z})^2} = \frac{1}{4}$$

$$\frac{\partial L}{\partial z} = \frac{\partial L}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial z} = \frac{-1}{4}$$