

Mathematical Definition of Discrete Random Variables

Probability and Statistics for Data Science

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These slides are based on the book [Probability and Statistics for Data Science](#) by Carlos Fernandez-Granda, available for purchase [here](#). A free preprint, videos, code, slides and solutions to exercises are available at <https://www.ps4ds.net>

Goal

Model uncertain quantities that can take discrete values

- ▶ Number of students attending a class
- ▶ Number of goals scored in a soccer game
- ▶ Number of earthquakes in San Francisco over a year

We represent them using **random variables**

Notation

Deterministic variables: a , b , x , y

Random variables: \tilde{a} , \tilde{b} , \tilde{x} , \tilde{y}

Deterministic variables represent fixed values

Random variables represent **uncertain** values

They are described **probabilistically**, we don't say

the random variable \tilde{a} equals 3

but rather

*the **probability** that \tilde{a} equals 3 is 0.5*

What is a random variable?

Data scientist:

An uncertain variable described by probabilities estimated from data

Mathematician:

A function mapping outcomes in a probability space to real numbers

Rolling a die twice

Probability space representing two rolls of a six-sided die

Outcomes?

$$\omega := \begin{bmatrix} \omega_1 \\ \omega_2 \end{bmatrix} \quad \omega_1, \omega_2 \in \{1, 2, 3, 4, 5, 6\}$$

Quantity of interest: Result of first roll

Key insight: It can be represented as a **function of the outcome**

Functions of Outcomes

A random variable is a function that maps outcomes to real numbers

$$\tilde{a}(\omega) := \omega_1$$

The **range** of a random variable is the set of values that it can take

Range of \tilde{a} ? $\{1, 2, 3, 4, 5, 6\}$

Functions of Outcomes

We can define many random variables in the same probability space

Value of second roll $\tilde{b}(\omega) := \omega_2$

Sum of rolls $\tilde{c}(\omega) := \omega_1 + \omega_2$

The outcome **fixes** the values of all random variables **simultaneously**

Very useful to represent dependencies between uncertain quantities

Probability mass function

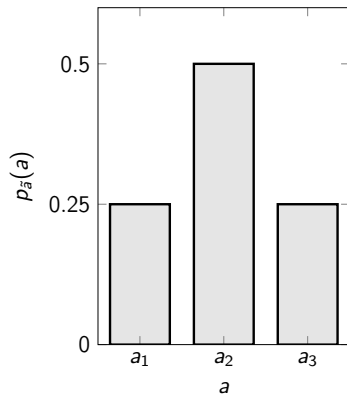
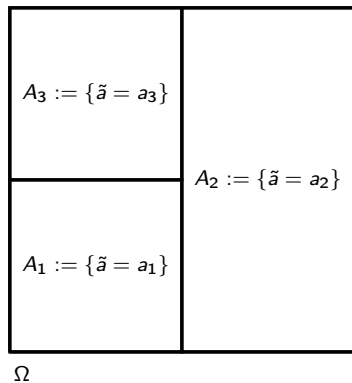
The probability mass function (pmf) $p_{\tilde{a}} : \mathbb{R} \rightarrow [0, 1]$ of \tilde{a} is the probability that \tilde{a} equals each of its possible values a_1, a_2, \dots :

$$p_{\tilde{a}}(a_i) := \mathbb{P}(\{\omega \mid \tilde{a}(\omega) = a_i\})$$

We say that \tilde{a} is **distributed** according to $p_{\tilde{a}}$

Wait, are we sure we can assign probabilities to these events?

Probability mass function



Formal definition

Probability space (Ω, \mathcal{C}, P)

Function $\tilde{a} : \Omega \rightarrow \mathbb{R}$ maps Ω to discrete set $\{a_1, a_2, \dots\}$

The function \tilde{a} is a discrete random variable if the sets

$$A_i := \{\omega \mid \tilde{a}(\omega) = a_i\} \quad i = 1, 2, \dots$$

are in the collection \mathcal{C} so that the probability

$$P(\tilde{a} = a_i) := P(A_i) \quad i = 1, 2, \dots$$

is well defined

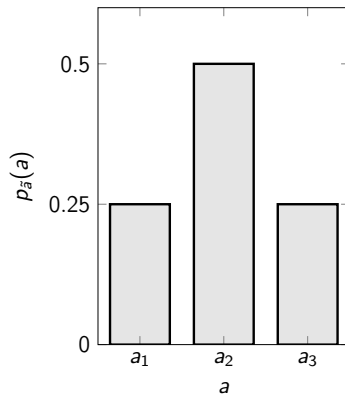
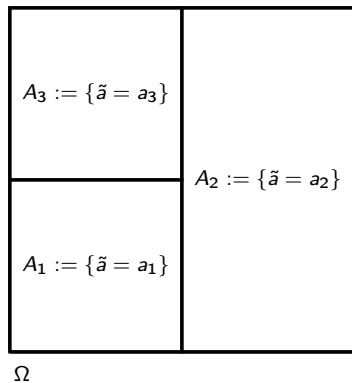
Such functions are called **measurable**

In practice

We never define random variables as functions of outcomes

Instead, we define them through their pmf

Important: Preimages form a partition of Ω



Preimages form a partition

Probability space (Ω, \mathcal{C}, P)

Function $\tilde{a} : \Omega \rightarrow \mathbb{R}$ maps Ω to discrete set $\{a_1, a_2, \dots\}$

The events

$$A_i := \{\omega \mid \tilde{a}(\omega) = a_i\}, \quad i = 1, 2, \dots$$

form a partition of Ω

Computing probabilities

Probability that \tilde{a} is in any set $S \subseteq \{a_1, a_2, \dots\}$

$$\begin{aligned} P(\tilde{a} \in S) &= P(\{\omega \mid \tilde{a}(\omega) \in S\}) \\ &= P(\cup_{a_i \in S} A_i) \\ &= \sum_{a_i \in S} P(A_i) \\ &= \sum_{a_i \in S} p_{\tilde{a}}(a) \end{aligned}$$

The pmf is all we need, we can forget about the probability space!

Any pmf must sum to one

$$\begin{aligned}\sum_{i=1,2,\dots} p_{\tilde{a}}(a_i) &= P(\cup_i A_i) \\ &= P(\Omega) = 1\end{aligned}$$

In practice

To model an uncertain quantity with values in a discrete set A using a discrete random variable \tilde{a} we just **estimate the pmf** $p_{\tilde{a}}$

Mathematician: *How do we know there's an underlying probability space?*

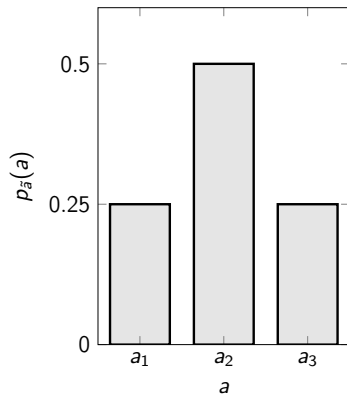
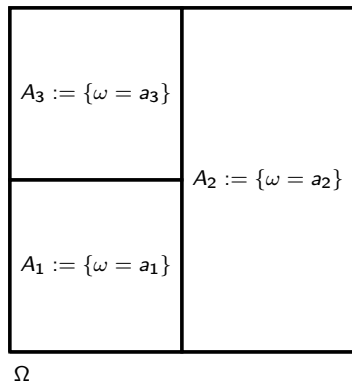
If $p_{\tilde{a}}$ is nonnegative and sums to one, we can build it:

Sample space: A

Collection of events: **Power set** of A

Probability measure: $p_{\tilde{a}}$

Reverse-engineering the probability space



What have we learned?

Data scientist:

An uncertain variable described by probabilities estimated from data

Mathematician:

A function mapping outcomes in a probability space to real numbers

That they are both right!