

# Workshop (Part1) on Deep Learning

*facilitator*

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University of Windsor

# Key Topics

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Why Deep Learning?

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What is Deep Learning?

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Machine Learning vs Deep Learning.

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Why is Deep Learning getting popular now?

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Concept Neuron, Artificial Neuron and Neural Networks.

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Why do we call it Deep Learning?

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How Neural Networks work?

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Ingredients to train a Deep Neural Network.

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Overview: How do Neural Networks Learn?

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Parameters vs. Hyperparameters.

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Deep Learning hands-on.

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# Why Deep Learning? (Applications)

**Deep Learning** shines when it comes to complex problems such as pattern recognition, image (/video) classification, natural language processing, and speech recognition.

Some major fields of Deep Learning applications include:

- Computer Vision and Pattern recognition
- Autonomous vehicle
- Speech Recognition
- Information Retrieval
- Aerospace and Defense
- Marketing
- Medical Diagnosis and Drug Discovery
- Agriculture and Other Industries
- Natural Language Processing
- Social Network Analysis

# Why Deep Learning? (Employment Opportunities)

- 40 percent say they're adding jobs due to AI
  - 133 million new jobs created by AI by 2022
  - #2 in-demand AI job: Deep learning engineer
- 

## Top 10 jobs involving AI skills

Top jobs seeking machine learning or artificial intelligence skills

Rank	Job title	% of postings containing AI or machine learning	Rank	Job title	% of postings containing AI or machine learning
1.	Machine learning engineer	75.0%	6.	Algorithm developer	46.9%
2.	Deep learning engineer	60.9%	7.	Junior data scientist	45.7%
3.	Senior data scientist	58.1%	8.	Developer consultant	44.5%
4.	Computer vision engineer	55.2%	9.	Director of data science	41.5%
5.	Data scientist	52.1%	10.	Lead data scientist	32.7%

Source: Indeed

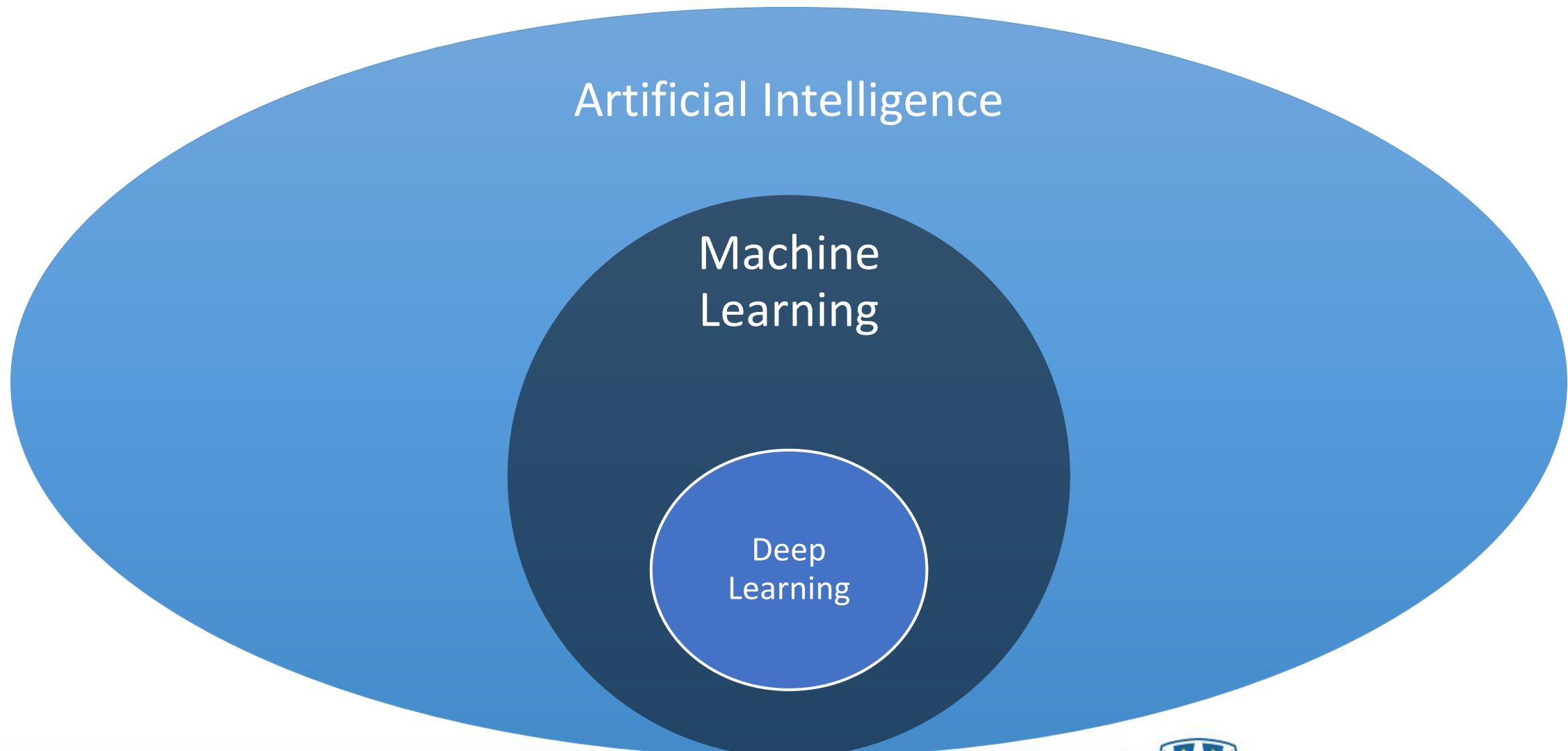


# Why Deep Learning? (Employment Opportunities)

Job Title	Annual Salary	Monthly Pay	Weekly Pay	Hourly Wage
Applied Machine Learning	\$182,341	\$15,195	\$3,507	\$87.66
Deep Learning Engineer	\$175,774	\$14,648	\$3,380	\$84.51
Senior Machine Learning Scientist	\$174,375	\$14,531	\$3,353	\$83.83
Director Machine Learning	\$163,686	\$13,640	\$3,148	\$78.70
Computer Vision Deep Learning Engineer	\$160,553	\$13,379	\$3,088	\$77.19

Source: Forbes.com  
ziprecruiter.com

# What is Deep Learning?



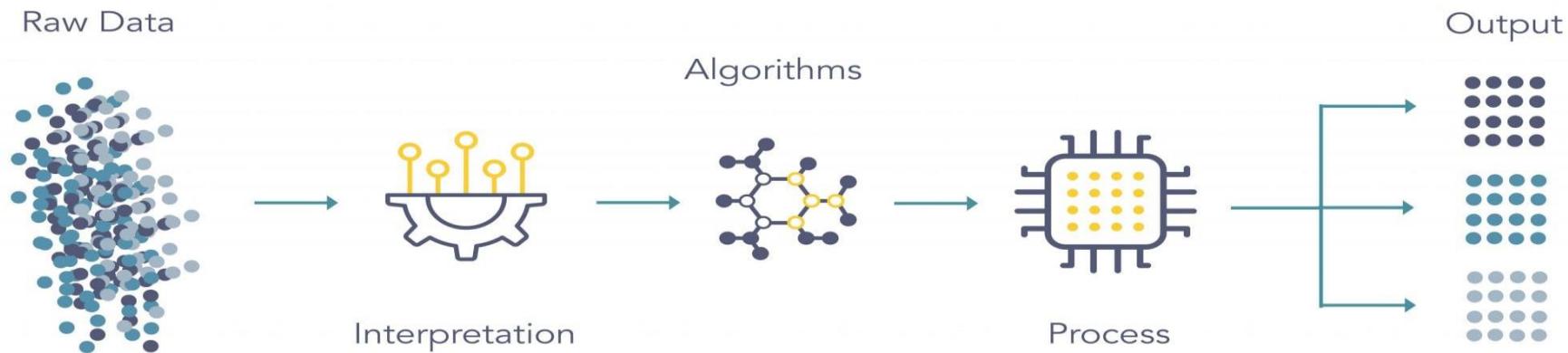
# What is Deep Learning?

- ❖ Deep Learning is a subfield of Machine Learning(ML)\*\* concerned with algorithms inspired by the structure and function of the brain called artificial neural networks. [source: machinelearningmastery.com]
- ❖ Deep Learning (DL) is a machine learning technique that teaches computers to do what comes naturally to humans: learn by example. [source: mathworks.com]

\*\*Machine learning is an application of artificial intelligence (AI) that provides systems the ability to automatically learn and improve from experience without being explicitly programmed. **Machine learning focuses on the development of computer programs** that can access data and use it learn for themselves.

# What is Machine Learning?

- Machine learning is an application of artificial intelligence (AI) that provides systems the ability to automatically learn and improve from experience without being explicitly programmed.
- **Machine learning focuses on the development of computer programs** that can access data and use it learn for themselves.



# Major Categories of Machine Learning?

- **Supervised Learning:** To learn a mapping between input examples and target variables. Ex: Support vector machine, logistic regression, decision trees, linear regression etc.
  - **Classification Problem:** involves predicting a class level or categorial value.
  - **Regression Problem:** involves predicting a numerical value.  
[both cases may have one input variables, which could be numerical or categorical]
- **Unsupervised Learning:** Operates on input data without output or target variables to describe or extract relationship in data. Ex: K-means Clustering, Affinity Propagation etc.
  - **Clustering:** involves finding groups in data.
  - **Density Estimation:** summarizing the distribution of data.
  - **Projection:** involves creating lower dimensional representation of data.
  - **Visualization:** involves creating plots of data.
- **Reinforcement Learning:** Agents operates on an environment must learn to operate using feedback. Ex. Q-Learning, Temporal-difference Learning, Deep reinforcement Learning etc.
  - The use of an environment means that there is no fixed training dataset, rather a goal or set of goals that an agent is required to achieve, actions they may perform, and feedback about performance toward the goal.

# Other Categories of Machine Learning?

- Hybrid Learning Problems:

- **Semi-Supervised Learning:** a supervised learning problem where training data contains very few labeled examples and a large number of unlabeled examples.
- **Self-Supervised Learning:** an unsupervised learning problem that is framed as a supervised learning problem in order to apply supervised learning algorithms to solve it. Such as, Autoencoders, Generative-Adversarial Networks(GAN) etc.
- **Multi-Instance Learning:** a supervised learning problem where individual examples are unlabeled; instead, bags or groups of samples are labeled.

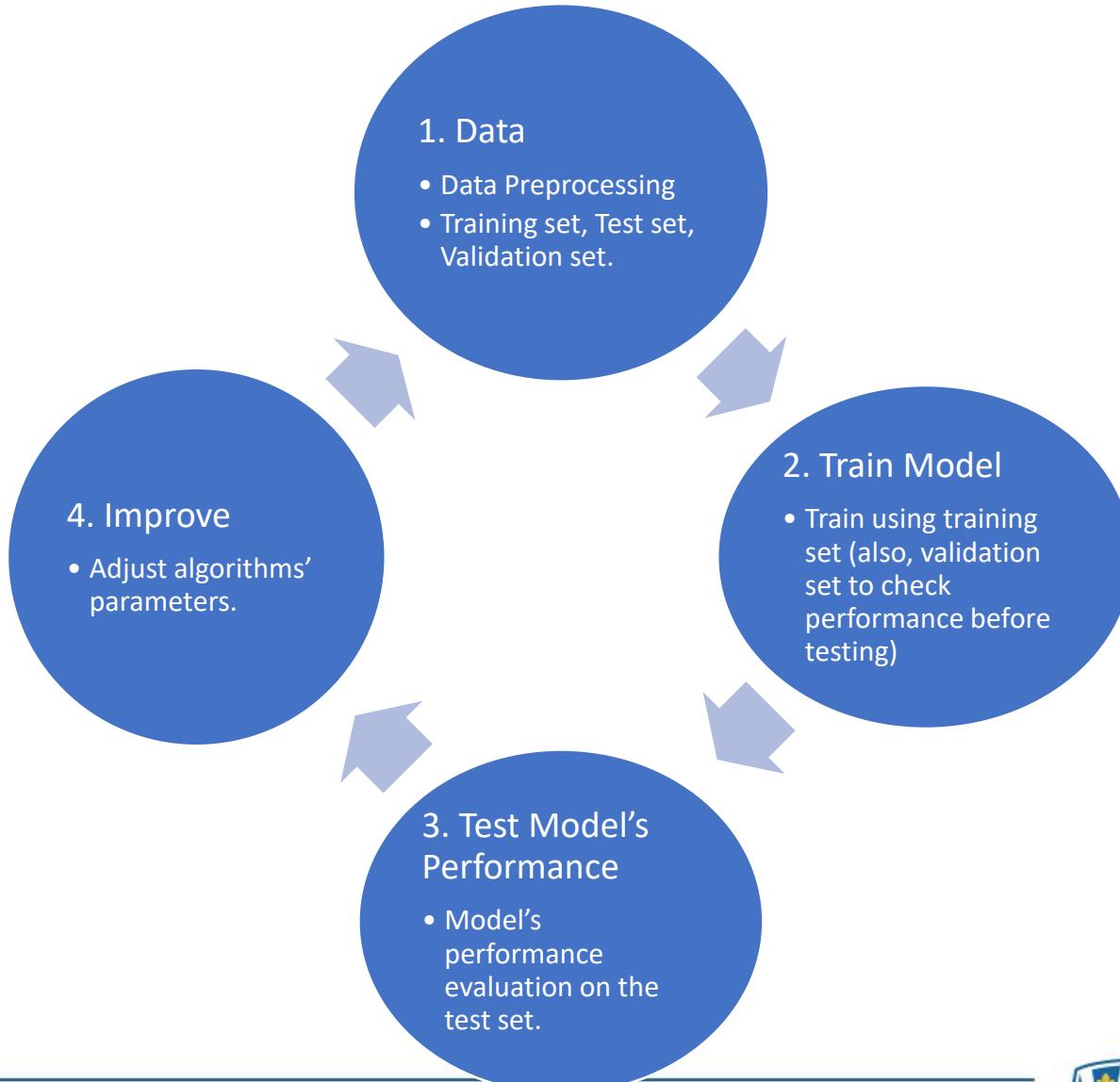
- Statistical Inference:

- **Inductive Learning:** involves using evidence(specific) to determine the outcome(general). Fitting a machine learning model is a process of induction. The model is a generalization of the specific examples in the training dataset.
- **Deductive Learning:** refers to using general rules to determine specific outcomes. Top-down approach. Using trained model to predict specific outcome.
- **Transduction/Transductive Learning:** refer to predicting specific examples given specific examples from a domain. No generalization is required, instead specific examples are used directly each time a prediction is required. Ex. K-Nearest Neighbors.

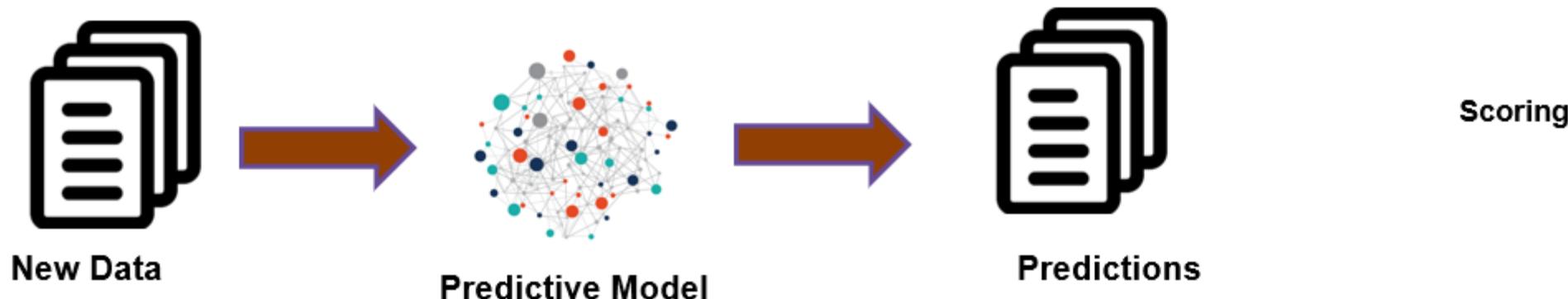
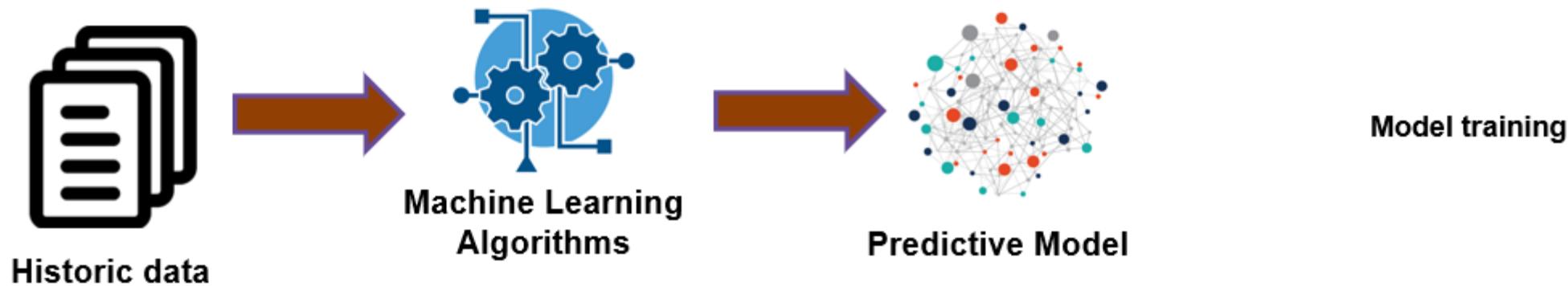
- Learning Techniques:

- **Transfer Learning:** a model is first trained on one task, then some or all of the model is used as the starting point for a related task.
- **Ensemble Learning:** an approach where two or more models are fit on the same data and the predictions from each model are combined.
- **Multi-Task Learning:** supervised learning that involves fitting a model on one dataset that addresses multiple related problems.
- **Online Learning:** involves using the data available and updating the model directly before a prediction is required or after the last observation was made. Where examples or minibatches are drawn from a stream of data.
- **Active Learning:** A supervised or semi-supervised learning, where model is able to query a human user operator during the learning process in order to resolve ambiguity during the learning process. Useful when there is not much data available and new data is expensive to collect or label.

# Common Steps in Machine Learning?



# Common Steps in Machine Learning?



# Machine Learning vs. Deep Learning

- After reaching a threshold of training data, older ML algorithms often plateau in performance.
- DL: More data, Better performance.

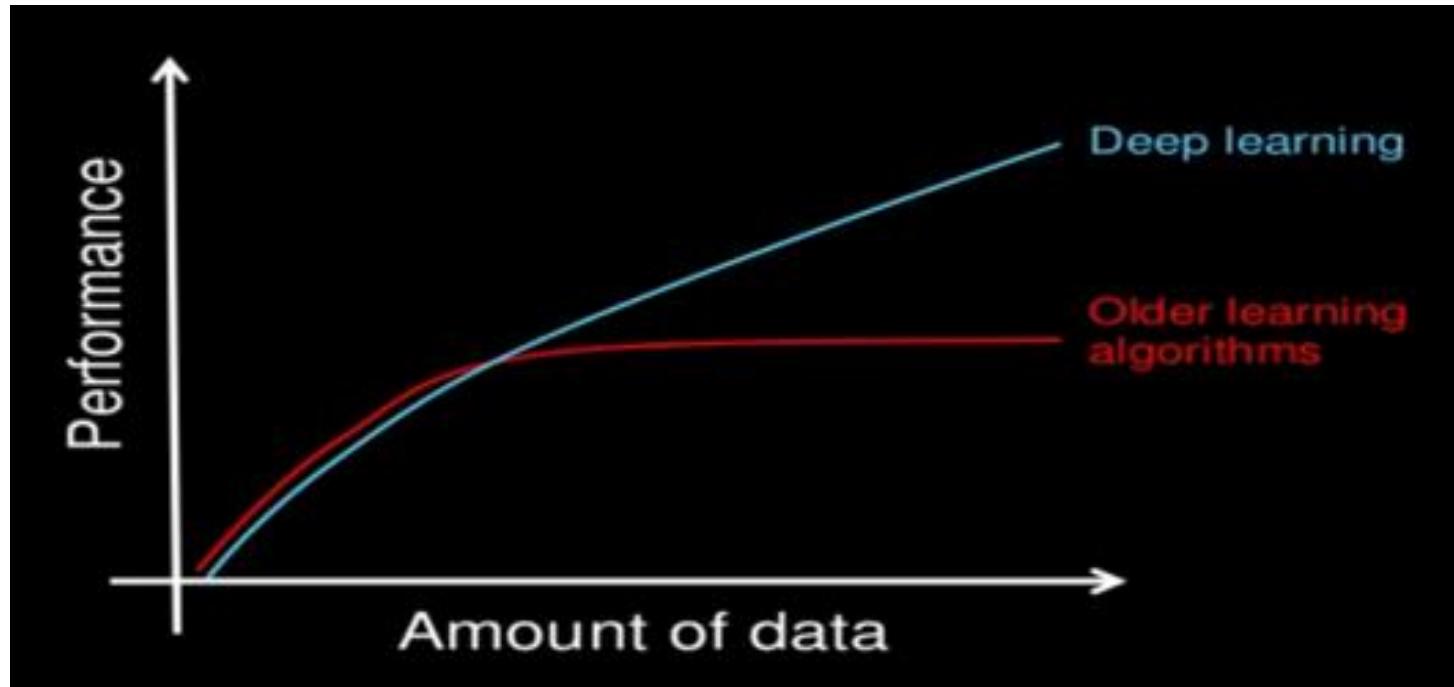
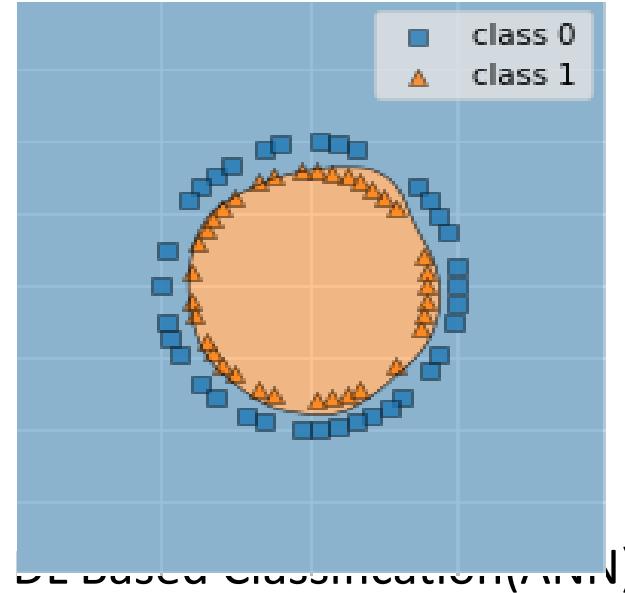
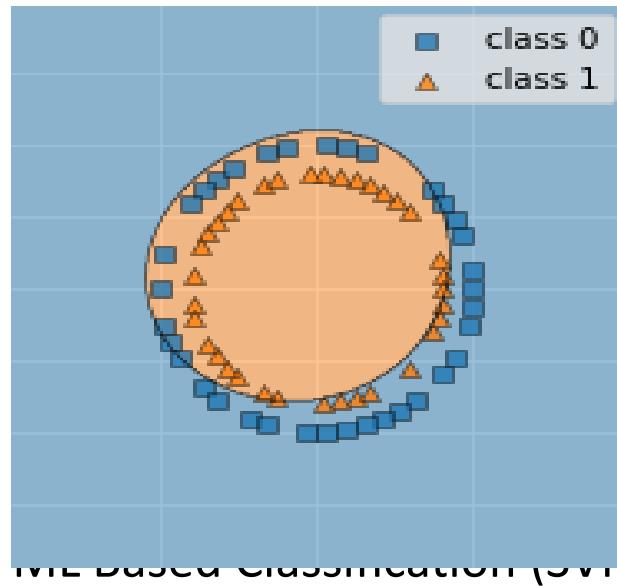


Image © Andrew Ng,

# Machine Learning vs. Deep Learning

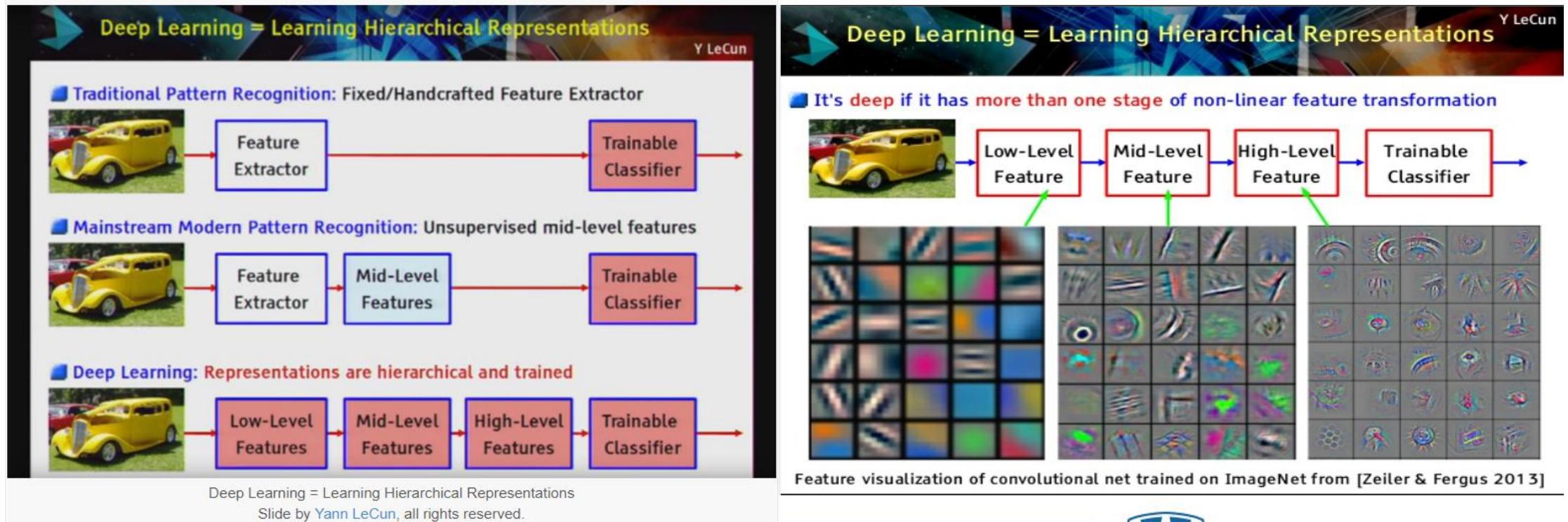
- **Complex Problem:**

- ML: May struggle to find out decision boundary for complex problem.
- DL: Often performs better when the problem (data) is complex.

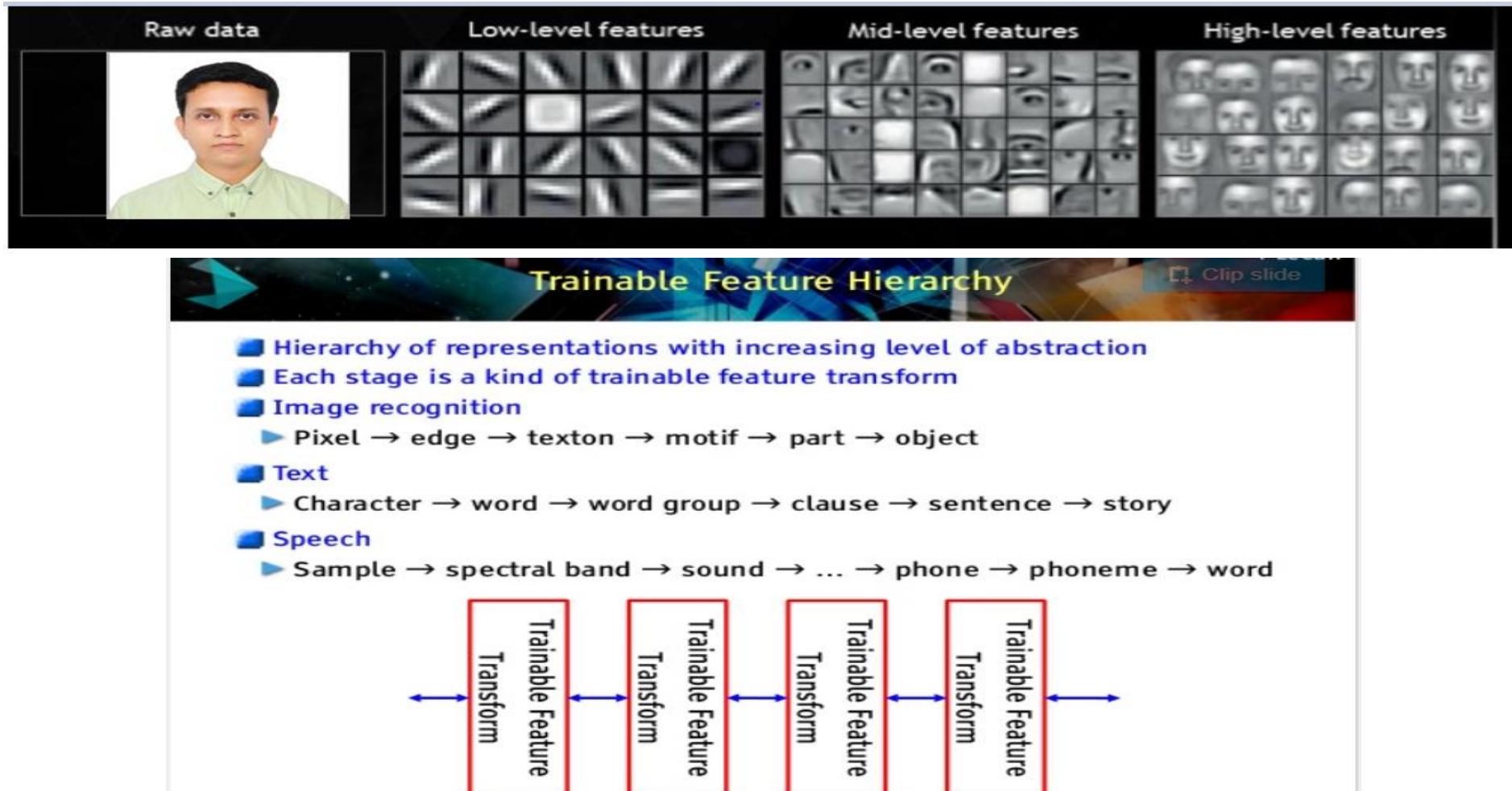


# Machine Learning vs. Deep Learning

- Feature Engineering:
  - In Machine learning, most of the applied features need to be identified by an expert.
  - However, Deep learning algorithms try to learn different-level of features from data.  
(For example, in case of image classification features can be pixel values, shape, textures, position and orientation.)



# Feature Engineering



# Machine Learning vs. Deep Learning

## ❑ Execution Time:

DL: Requires long time to train.

ML: Requires comparatively much less time to train.

## ❑ Hardware Dependencies:

DL: Requires high-end machines.

ML: Algorithms can work on low-end machines.

## ❑ Interpretability:

DL: It is often difficult to interpret the reason behind the outcome.

(Attention Mechanism may help in that case)

ML: Comparatively easy to interpret the reasoning behind the result.

# Machine Learning vs. Deep Learning

## □ Problem Solving Approach:

- ML: It is generally recommended to divide the problem into smaller parts, then solve them individually and finally combine them to get the result.
- DL: Advocates to solve the problem end-to-end.

For example:

Problem: Multiple object detection in an image.

ML Approach: Typical ML approach would divide the problem into two steps, object detection and object recognition. In that case, we may need to combine two different algorithms for two different tasks.

Deep Learning: Would process end-to-end. We just pass an image; it would give us the outcome without the help of different algorithm.

# Brief History of Deep Learning

- **McCulloch and Pitts(1943):**
  - Shows the mathematical model of biological neuron with very limited capability and has no learning mechanism. Considered as the foundation for ANN.
- **Rosenblatt (1957):**
  - Demonstrated ‘Perceptron’ that had true learning capabilities to do binary classification on its own.
- **Kelley (1960):**
  - Shows the first ever version of continuous backpropagation model in context to Control Theory. Later Dreyfus (1962) uses simple derivative chain rule, instead of dynamic programming.
- **Ivakhnenko and Lapa (1965):**
  - Creates first ever multi-layer perceptron, a hierarchical representation of Neural Networks(NN) with polynomial activation function. This model was trained using Group Method of Data Handling (GMDH). Later in 1971 he created 8-layer Deep NN. **Ivakhnenko is often considered as the father of Deep Learning.**
- **Rumelhart et al (1986):**
  - Rumelhart, Geoffrey Hinton, and Williams solved one of the main obstructions of earlier DNN with the successful implementation of backpropagation in the neural network. **Hinton is often called as God Father of Deep Learning in the DL- based research community.**

# Brief History of Deep Learning

- **LeCun et al. (1989):**

- Yann LeCun and his colleagues uses backpropagation to train Convolutional Neural Network(CNN) to recognize handwritten digits. This was a breakthrough moment and considered as the foundation of modern computer vision using deep learning.

- **Sepp Hochreiter (1991):**

- Identifies Vanishing Gradient Problem, because of that the learning of Deep NN extremely slow and almost impractical to use. Later his work on Long Short-Term Memory (LSTM) (Hochreiter and Schmidhuber,1997) is consider as a revolutionary approach and one of the most used algorithms for RNN.

- **Hinton et al. (2006):**

- Introduced a fast-learning algorithm for Deep Belief Nets which was is much more efficient for large amount of data. This helps to rejuvenate the interest on DL-based research world-wide.

- **Glarot et al. (2011):**

- Xavier Glorot, Antoine Bordes and Yoshua Bengio shows that ReLU activation function can avoid vanishing gradient problem to avoid issues of longer and impractical training times of Deep NN.

- **Goodfellow et al. (2014):**

- Proposed Generative Adversarial Neural Network also known as GAN, which open a whole new dimension of application of deep learning.

- **Silver et al. (2016):**

- Deepmind (google) introduced deep reinforcement learning model (AlphaGo) which beats human champion in the complex game of Go.

# God Fathers of Deep Learning

**Geoffrey Hinton:** Geoffrey Everest Hinton is an English Canadian cognitive psychologist, professor of computer science at the University of Toronto and a part of the Google Brain project. Hinton is considered by many to be the 'godfather of deep learning.'

Some people also add two other scientists in the list:

**Yoshua Bengio:** A Canadian computer scientist, professor at the University of Montreal, Canada and started an AI company called Element AI.

**Yann LeCun:** A French-American computer scientist, Facebook's chief AI scientist and a professor at New York University, USA. He is a student of Geoffrey Hinton.



From left to right: Yann LeCun | Photo: Facebook; Geoffrey Hinton | Photo: Google; Yoshua Bengio | Photo: Botler AI

The 2018 **Turing Award**, known as the “Nobel Prize of computing,” has been given to the trio of researchers who laid the foundations for the current boom in artificial intelligence.

# Why is Deep Learning getting popularity now?

## Building Traditional Model is Expensive:

- - Designing feature extractor is long, painful and expensive.
- - Industry need more and more models.
- - The process must be automated.

## Computational Power is Increasing:

- -**Moore's Law(1975)** states the number of transistors in an integrated circuit would double every two years. In layman's terms, this effectively means that the **processing power** of computers **will double every two years**. (Moore, G.E.(1998))

## Data Size and Storage Capacity are Increasing:

- -There are **2.5 quintillion bytes** of **data created** each day at our current pace, but that pace is only accelerating with the growth of the Internet of Things (IoT). Over the last two years alone 90 percent of the **data** in the world was generated. (Forbes.com, May21, 2018)
- -The storage cost is also reducing exponentially.

# Growth of Computational Power

The accelerating pace of change and exponential growth in computing power will lead to the Singularity.

- 2045: The Year Man Becomes Immortal  
Image Source: Time Magazine

## 1 The accelerating pace of change ...



## 2 ... and exponential growth in computing power ...

Computer technology, shown here climbing dramatically by powers of 10, is now progressing more each hour than it did in its entire first 90 years

### COMPUTER RANKINGS

By calculations per second per \$1,000



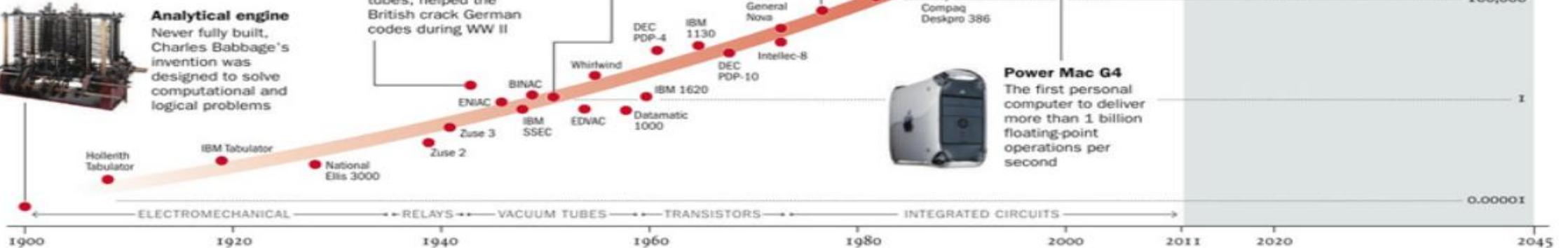
**Analytical engine**  
Never fully built, Charles Babbage's invention was designed to solve computational and logical problems



**Colossus**  
The electronic computer, with 1,500 vacuum tubes, helped the British crack German codes during WW II



**UNIVAC I**  
The first commercially marketed computer, used to tabulate the U.S. Census, occupied 943 cu. ft.



## 3 ... will lead to the Singularity

Surpasses brainpower equivalent to that of all human brains combined

$10^{26}$

Surpasses brainpower of human in 2023

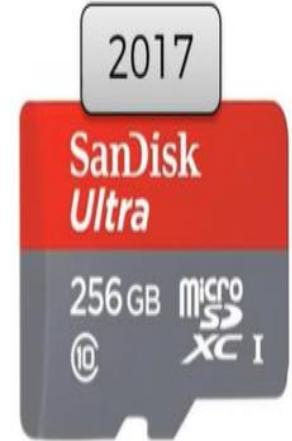
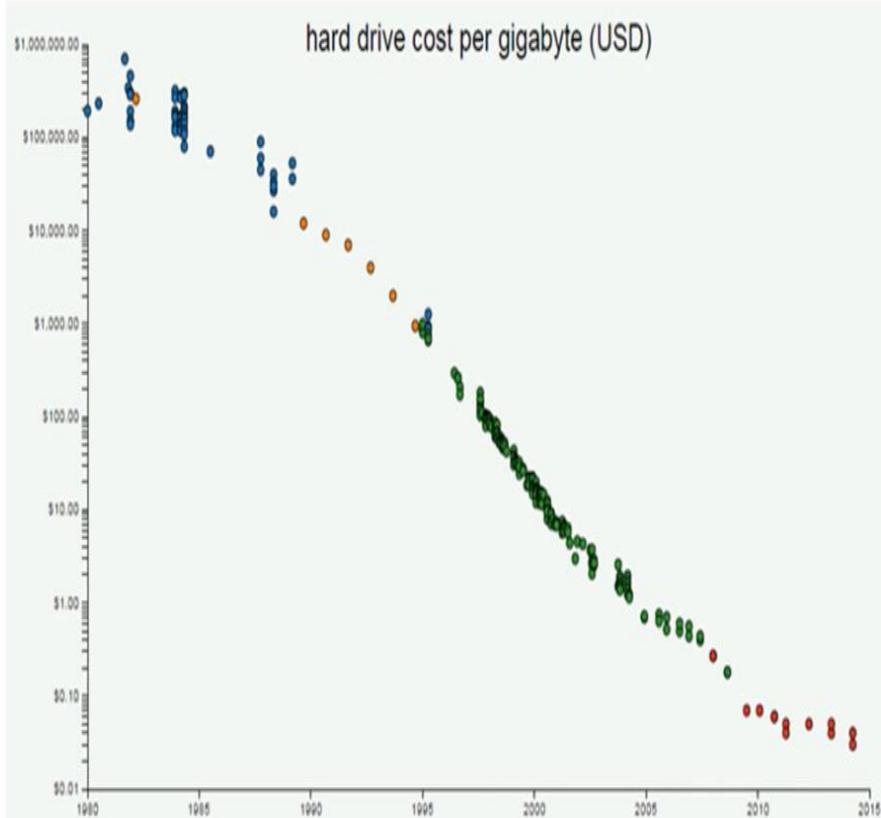
$10^{20}$

Surpasses brainpower of mouse in 2015



# Storage Capacity and Price

Log-scale



SanDisk Ultra 256GB MicroSDXC UHS-I Card with Adapter (SDSQUNI-256G-GN6MA).

by SanDisk

\$149.99 \$199.99 Prime  
Wednesday, Mar 22  
21,224 shipping on eligible  
Product Features  
256GB capacity breakthrough  
25,600X choices  
\$147.99 (10 new offers)

Image source: SuperDataScience

# Neuron (Nervous System)

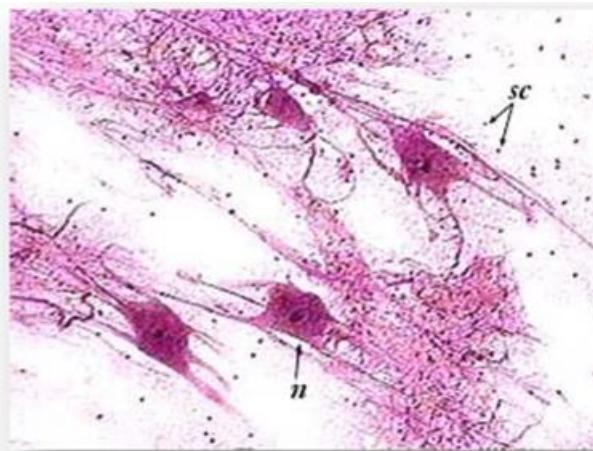
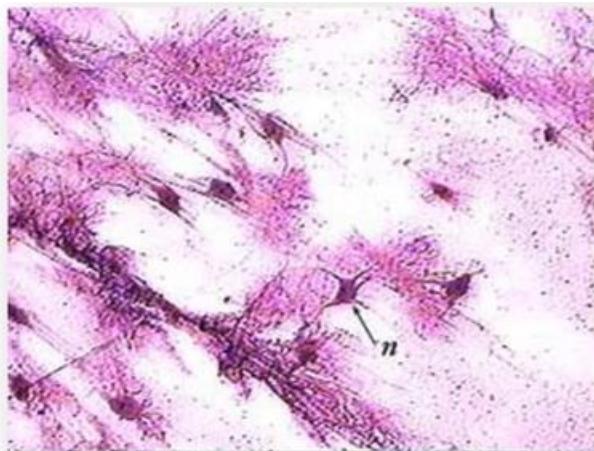


Image source: [www.austicc.edu](http://www.austicc.edu).

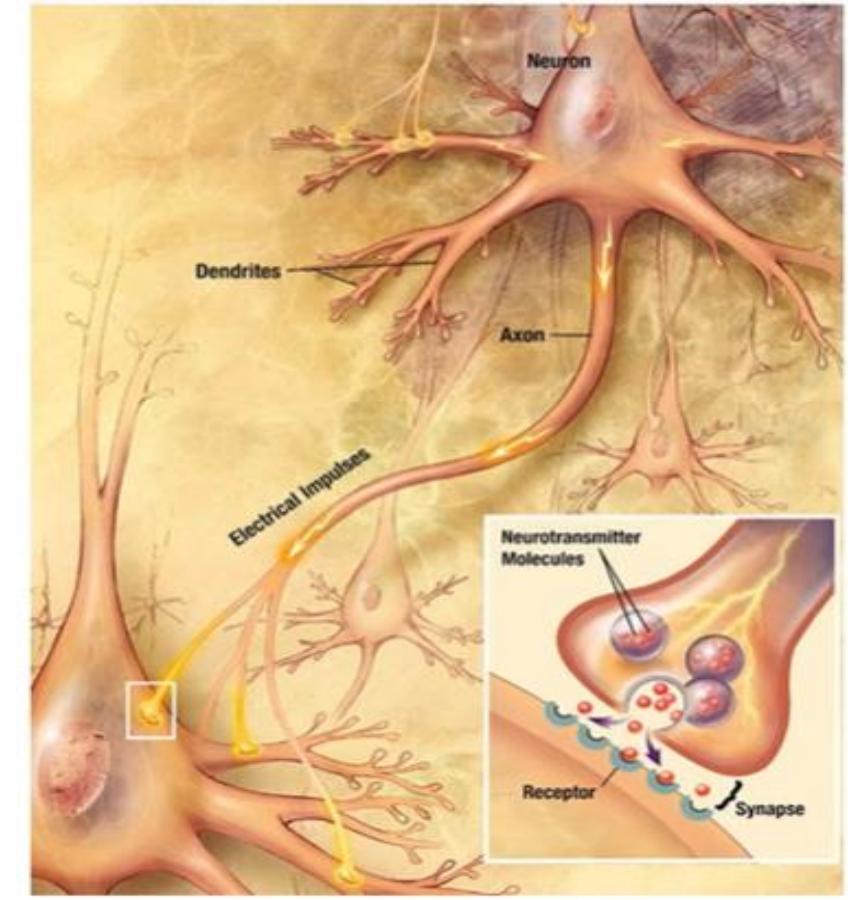
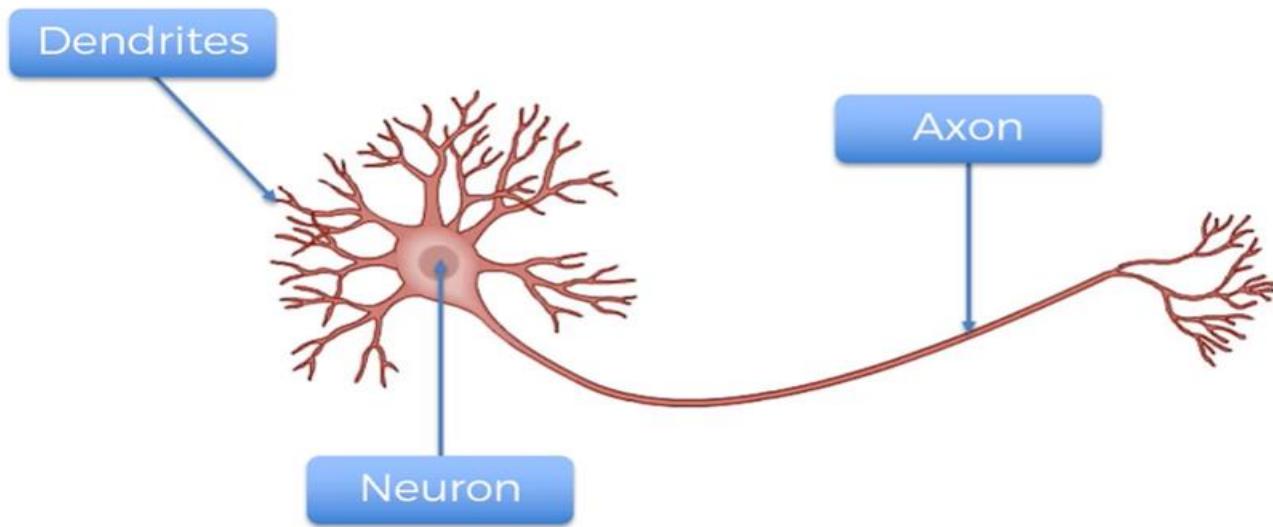
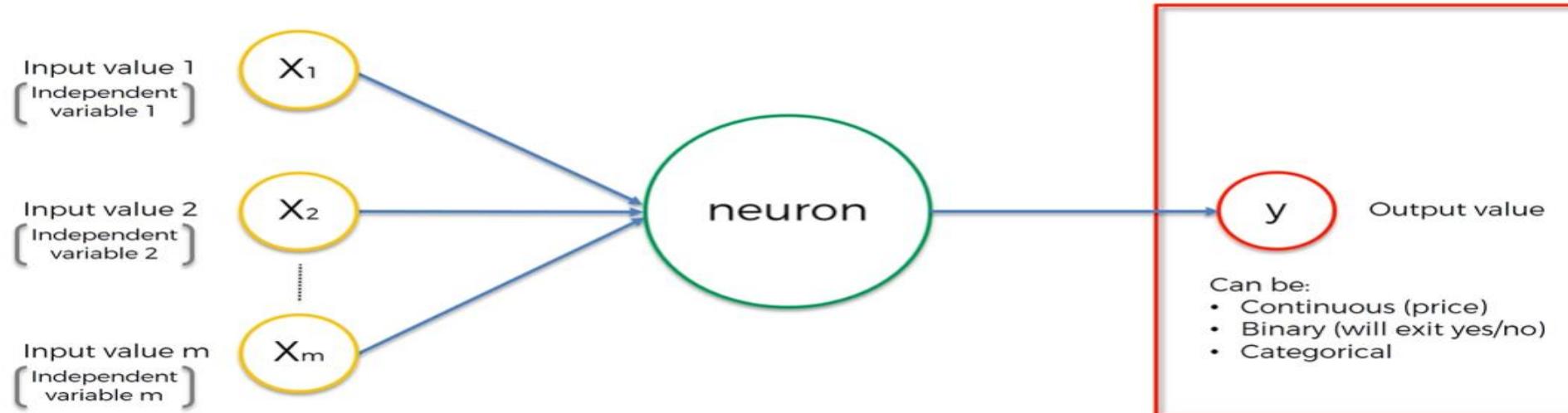


Image source: wikipedia

# Neuron (Artificial): also known as Node/Unit in DL

The earliest form of neuron was called perceptron. Professor Frank Rosenblatt introduced the term in 1957. However, earlier perceptron can only handle binary outputs.



Output can have multiple values in case of categorial output (dummy variables) :

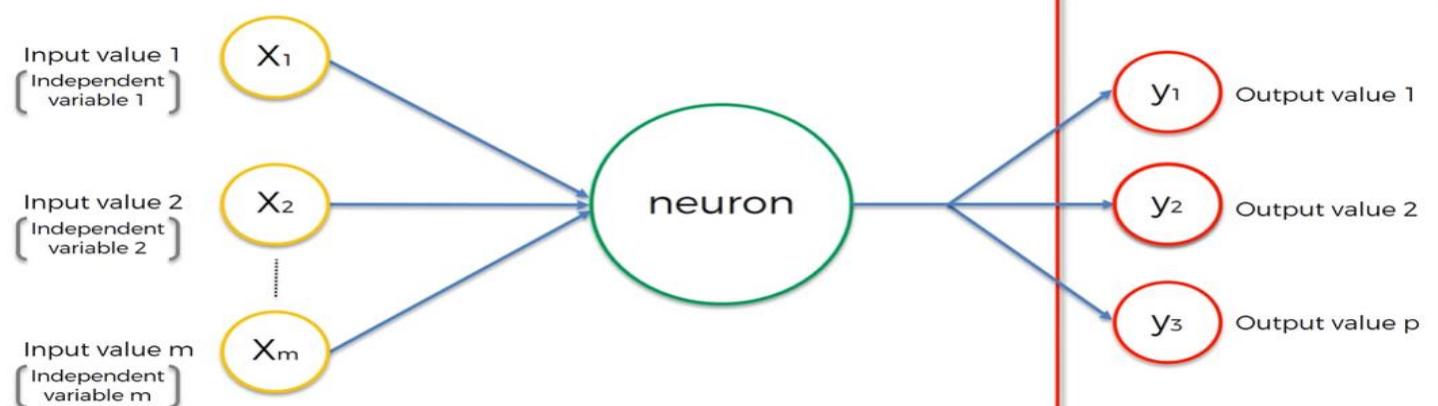
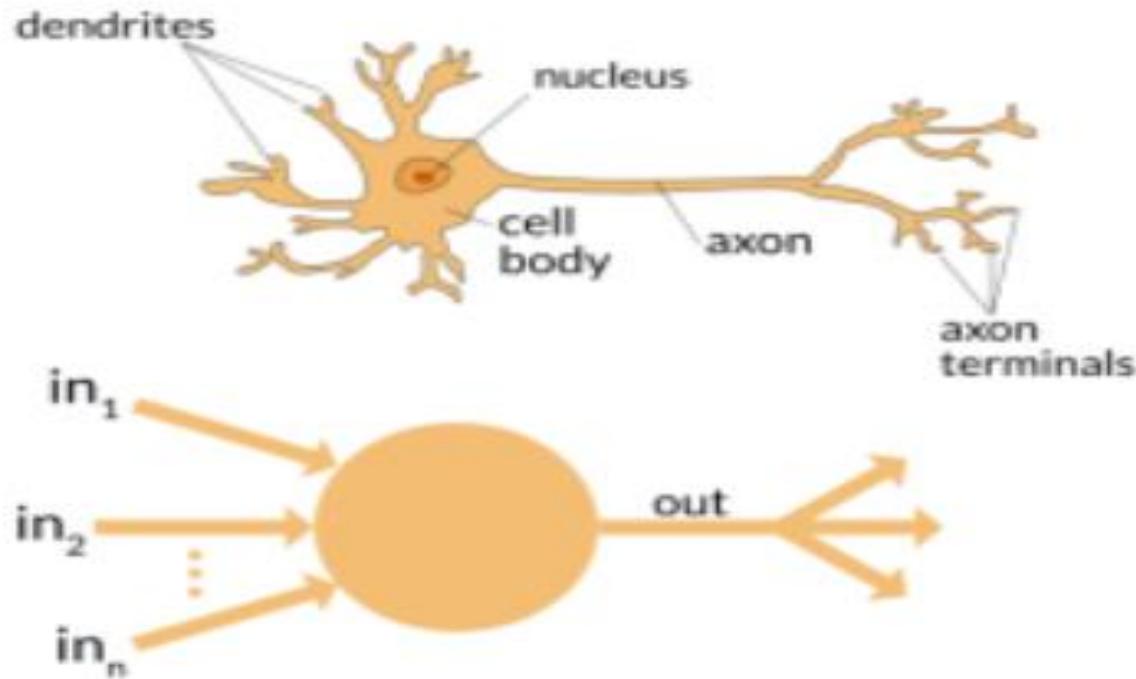


Image source: SuperDataScience

# Similarities (Biological Neuron & Artificial Neuron)?



## How Biological Neuron produces output?

-It's completely unclear today whether the human brain uses an algorithm.

## How an Artificial Neuron produces output?

$$\text{Output} = \text{Activation} \left( \sum_1^n (\text{weight} * \text{input}) + \text{bias} \right)$$

Since we deal with matrix/vectors, therefore,  $\text{Output} = \text{activation}(\text{dot}(\text{kernel}, \text{input}) + \text{bias})$

# Weight and Bias?

(commonly referred to as w and b) are the learnable parameters of a machine learning model. (Bias is like the intercept in linear equation )

**Table:1**

Input(X)	Output(Y)
1	4
2	9
5	24
8	39
3	14

**Table:2**

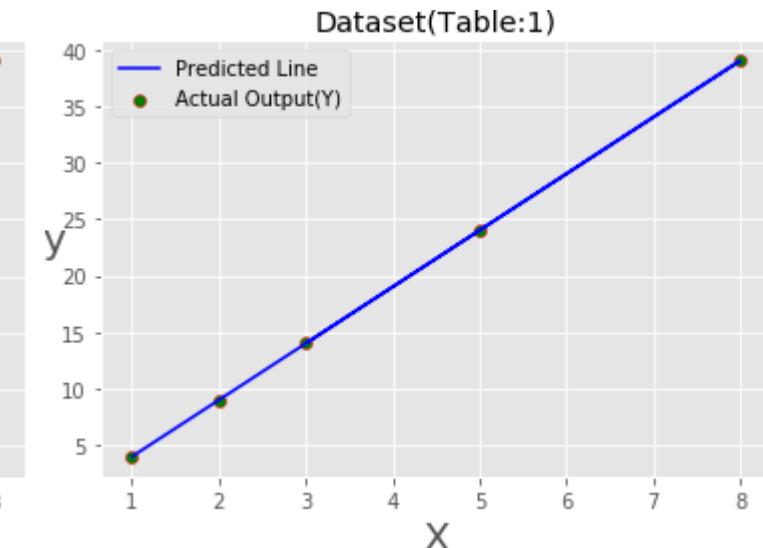
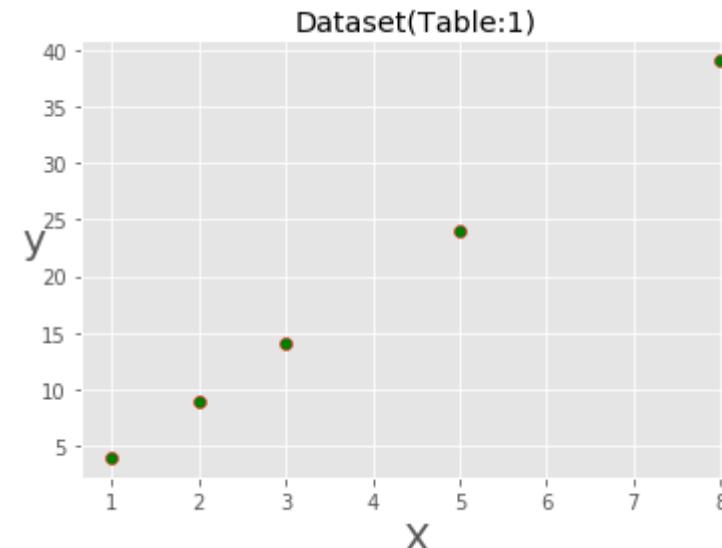
Input(X)		Output(Y)
x1	x2	Y
2	1	4
3	4	8
1	5	7
3	2	6

$$\text{Output} = \text{Activation} (\sum_1^n (\text{weight} * \text{input}) + \text{bias})$$

Let's Calculate Weight and Bias for given tables?

For Table 1: Output (prediction),  $y = w*x+b$

$$w = ?, b = ?$$



$$\text{For Table 2: } y = w_1*x_1 + w_2*x_2 + b$$

$$w_1 = ?, w_2 = ?, b = ?$$

# Let's look at another example:

X	Y
1	4
2	14
5	24
8	28
3	18

X	Y	$\hat{Y}$
1	4	10.7
2	14	13.5
5	24	21.7
8	28	29.9
3	18	16.2

**Output = Activation ( $\sum_1^n(\text{weight} * \text{input}) + \text{bias}$ )**

For given data :  $y_{\text{hat}} (\text{prediction}) = w*x+b$

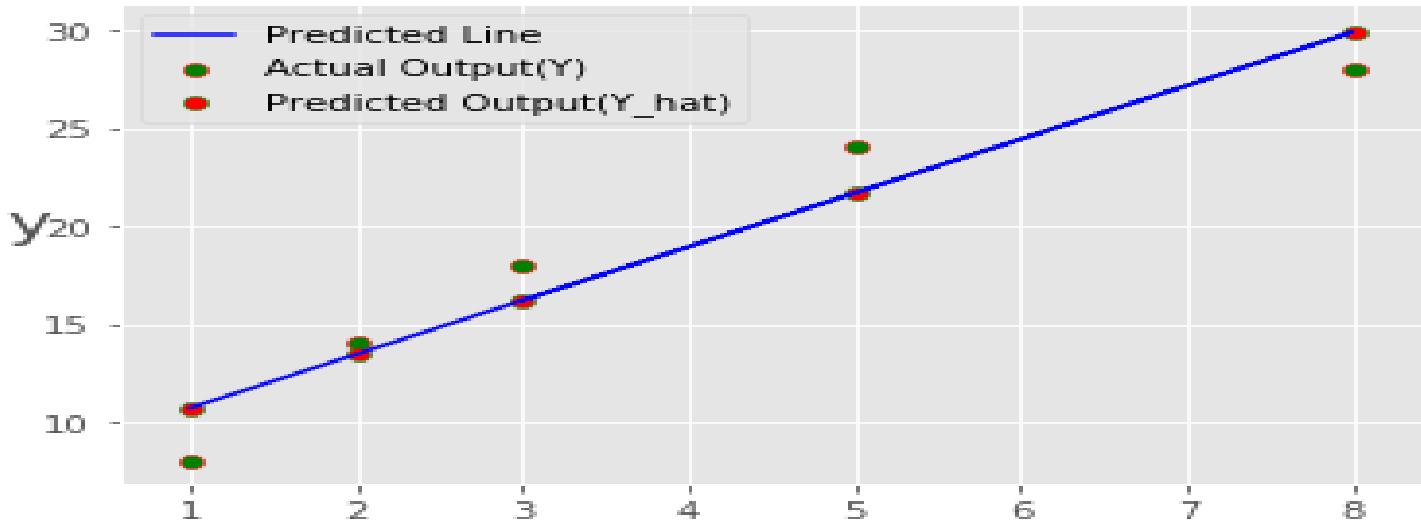
$w = ?, b = ?$

Not easy to predict the exact output?

Let's consider,  $w = 2.74$ ,  $b = 7.99$ . However, we can minimize the error and adjust the value of w and b to get best fitting line using loss functions, a simple loss function

$$\text{MSE} = \frac{1}{n} \sum_{i=1}^n (Y_i - \hat{Y}_i)^2$$

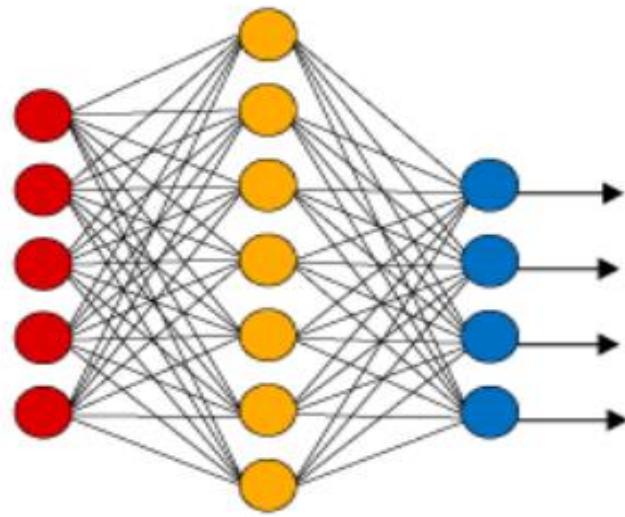
Dataset(Table:1)



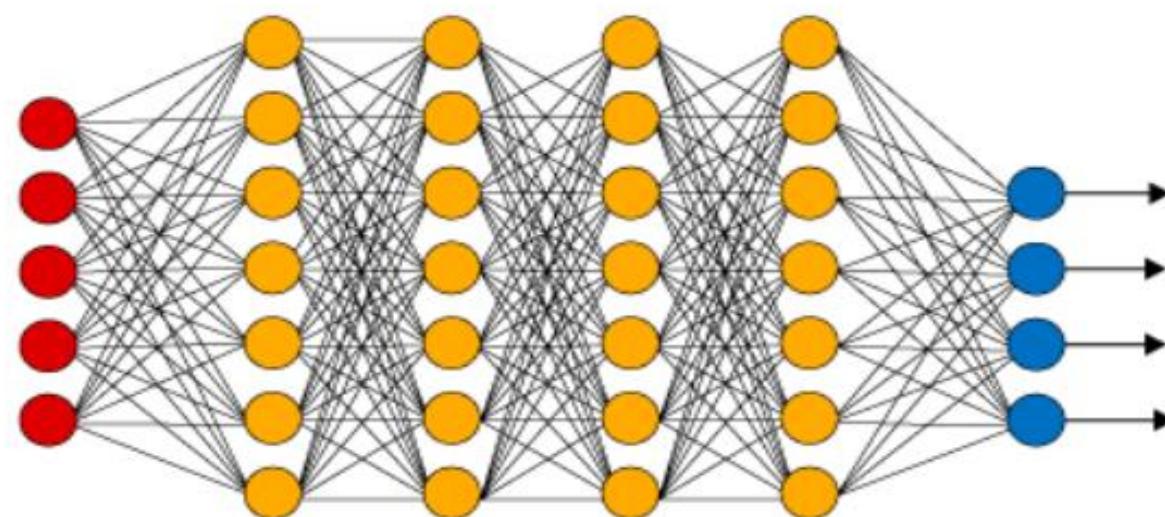
Here, the Value of **MSE = 11.5** [we can try for different w, b values to optimize]

# Why do we call it Deep Learning?

**Simple Neural Network**



**Deep Learning Neural Network**



● Input Layer

● Hidden Layer

● Output Layer

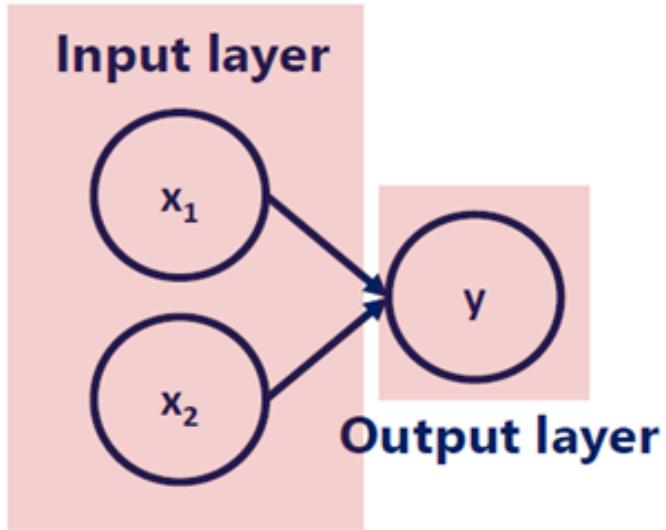
- Row = Depth of Network [The number of hidden layers in a network]
- Column = Width of the Layer. [The number of units(nodes) in a layer is the width of the layer]
- The **width** of the net is the number of units of the biggest layer.
- Neural Networks also known as multilayer perceptron.

Image source: [www.kdnuggets.com](http://www.kdnuggets.com).

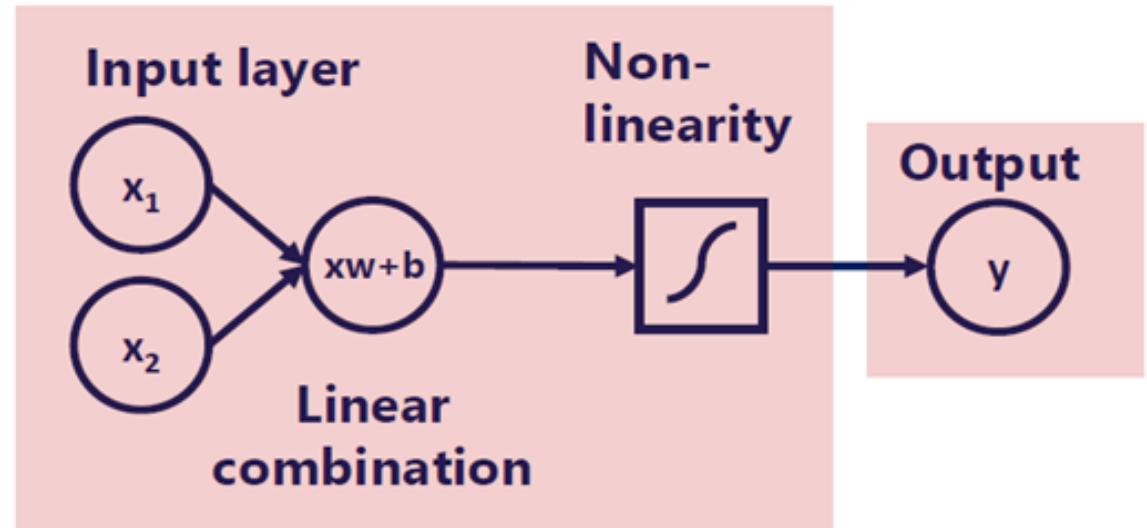
# Layers

An initial linear combination and the added non-linearity form a **layer**. The layer is the building block of neural networks.

## Minimal example (a simple neural network)



## Neural networks



In the minimal example we trained a *neural network* which had no depth. There were solely an input layer and an output layer. Moreover, the output was simply **a linear combination** of the input.

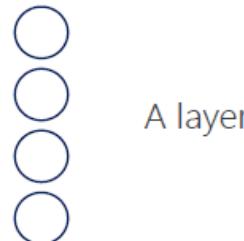
Image source: 365DataScience

Neural networks step on linear combinations, but add a non-linearity to each one of them. Mixing linear combinations and non-linearities allows us to model arbitrary functions.

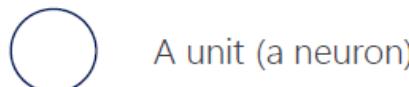
# A Deep Neural Network.

This is a deep neural network (deep net) with 5 layers.

## How to read this diagram:



A layer



A unit (a neuron)

→ Arrows represent mathematical transformations

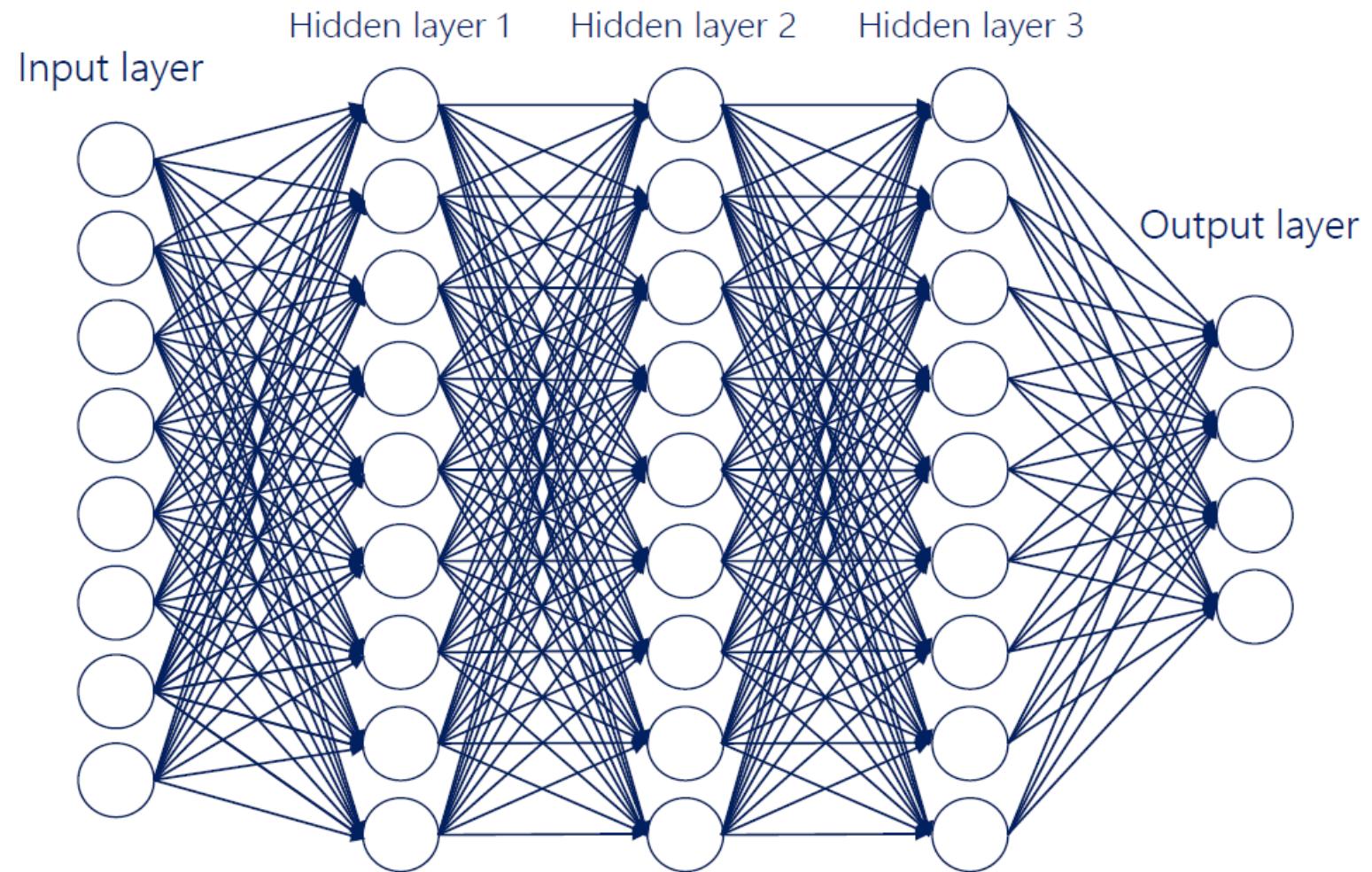
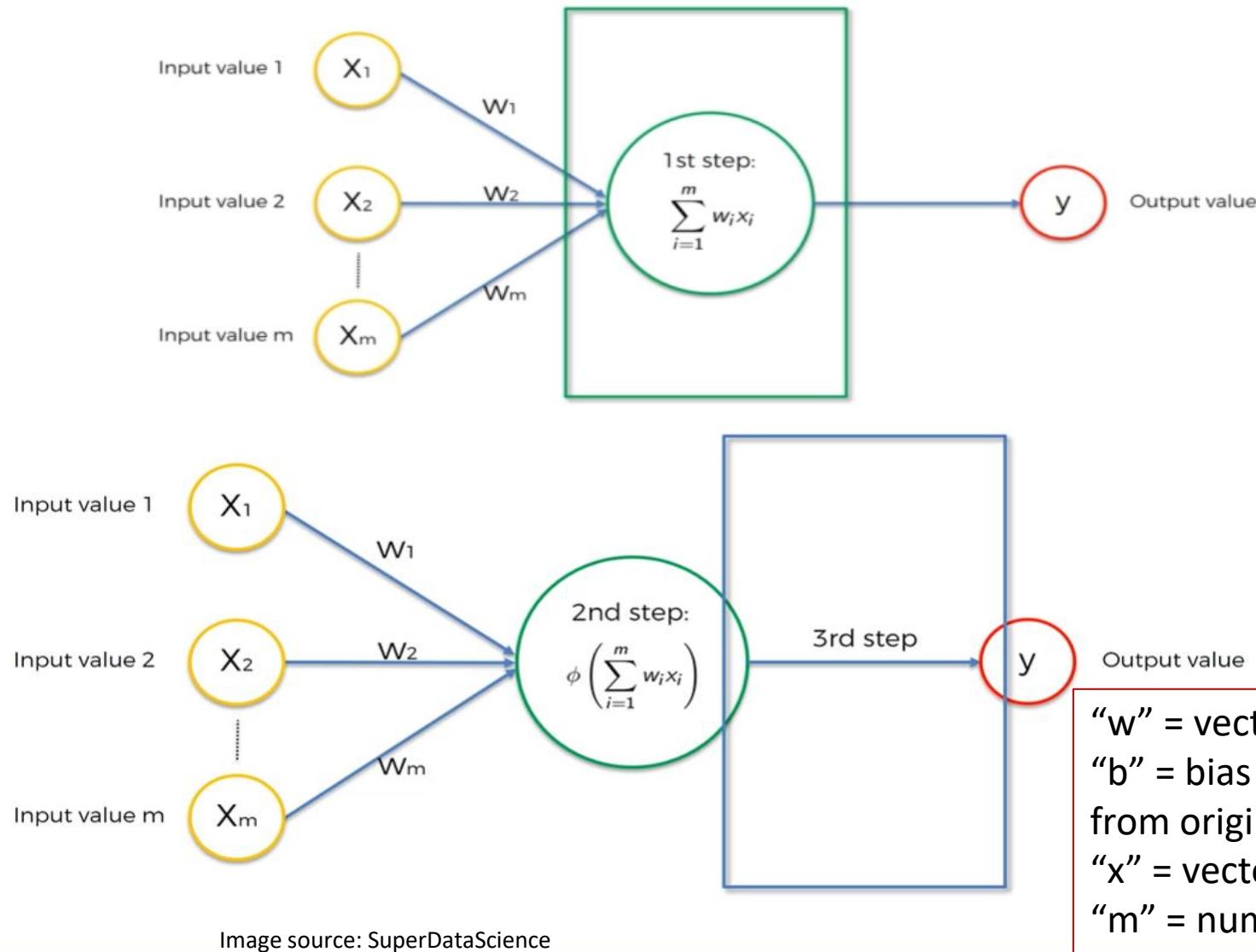


Image source: 365DataScience

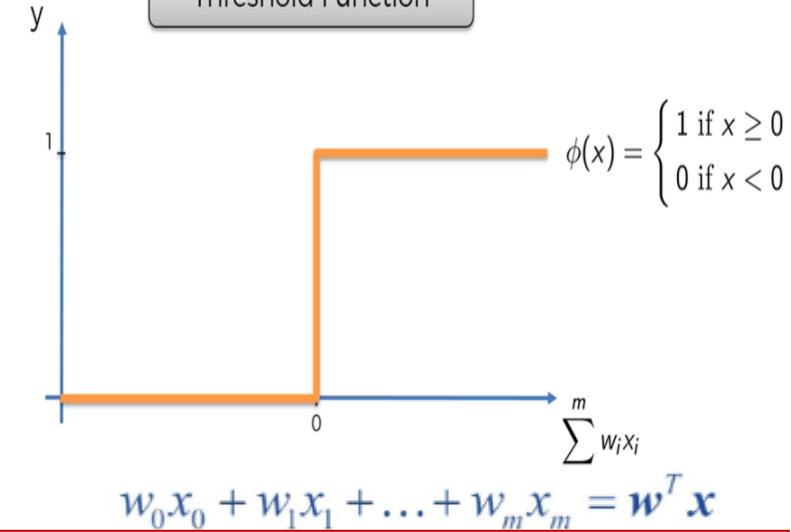
# How do Neural Networks work?



Example: Perceptron Learning  
(single input) uses threshold activation function.

$$f(x) = \begin{cases} 1 & \text{if } w \cdot x + b > 0 \\ 0 & \text{otherwise} \end{cases}$$

Threshold Function

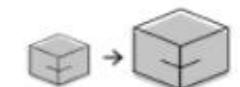


“w” = vector of real-valued weights  
“b” = bias (an element that adjusts the boundary away from origin without any dependence on the input value)  
“x” = vector of input x values  
“m” = number of inputs to the Perceptron

# How do Neural Networks work?

The basic process carried out by a neuron in a neural network is:

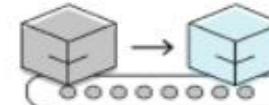
Initialization : Randomly initialized weights to small number close to 0 (but not 0). Then, Input first observation in your dataset in the input layer, each feature in one input node.



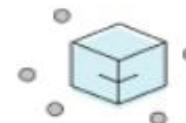
Take input and multiply by the neuron's weight.



Add bias\*



Feed the result,  $x$ , to the activation function:  $f(x)$



Take the output and transmit to the next layer of neurons.

\* This is just the number 1, making it possible to represent activation functions that do not cross the origin. Biases are also assigned a weight.

Image source: [www.missinglink.ai](http://www.missinglink.ai).

# Why Non-Linearity? To Stack Layers

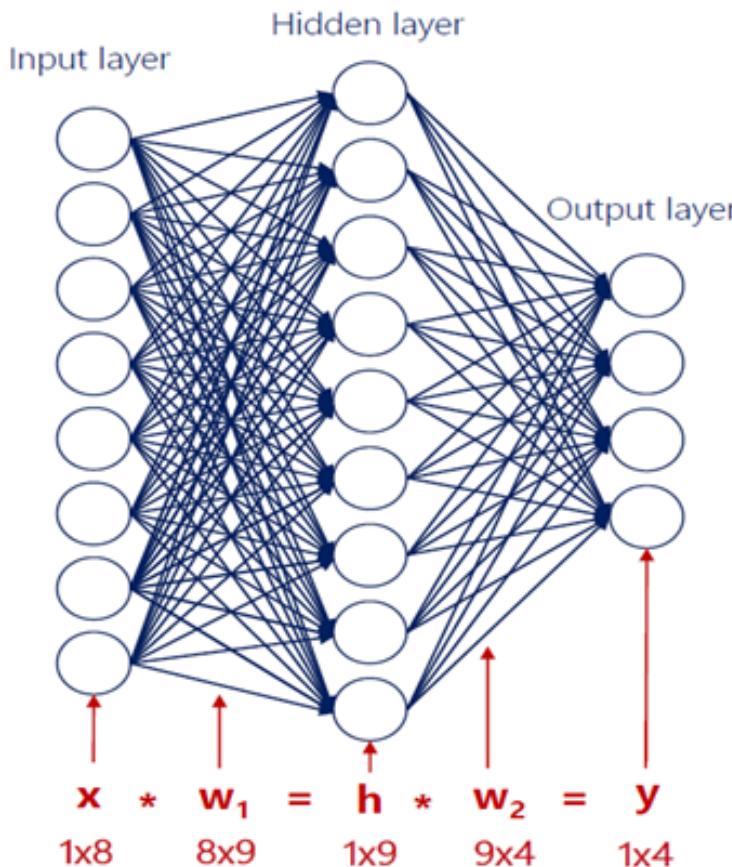
Non-linearities

Stacking Layers

Depth

Deep Learning

You can see a net with no non-linearities: just linear combinations.



$$\begin{aligned} h &= x * w_1 \\ y &= h * w_2 \\ y &= x * w_1 * w_2 \\ &\quad 8 \times 9 \quad 9 \times 4 \\ y &= x * w^* \\ &\quad 8 \times 4 \end{aligned}$$

Two consecutive linear transformations are equivalent to a single one.

Two consecutive linear transformations are equivalent to a single one.

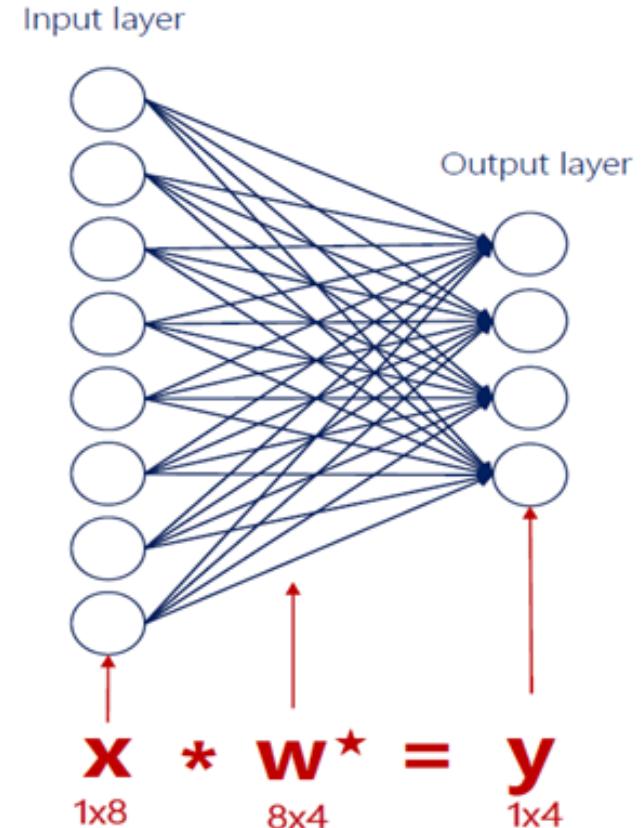
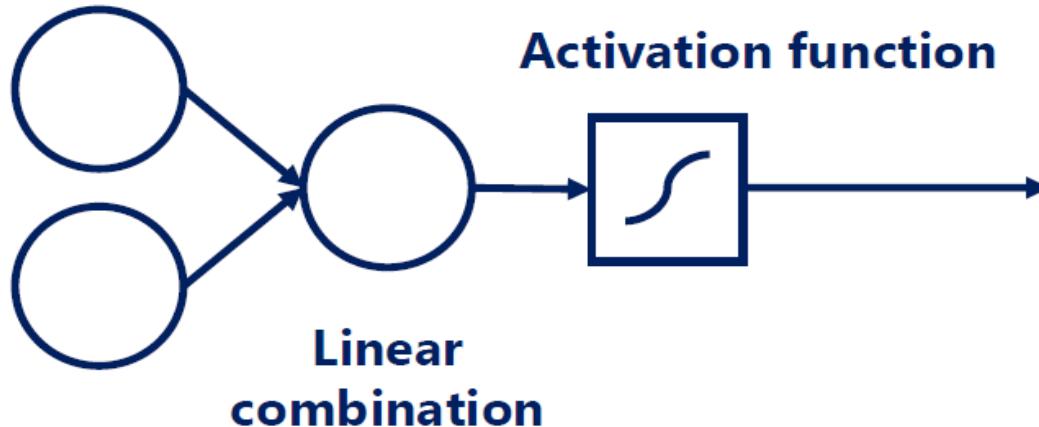


Image source: 365DataScience

# Activation Functions (Non-linearities): also called Transfer Function

## Input



Non-Linearity does not change the shape of the expression, it only changes its linearity.

The temperature starts decreasing (which is a numerical change). Our brain is a kind of an 'activation function'. It tells us whether it is **cold enough** for us to put on a jacket.

Putting on a jacket is a binary action: 0 (no jacket) or 1 (jacket).

This is a very intuitive and visual (yet not so practical) example of how activation functions work.

Activation functions (non-linearities) are needed so we can break the linearity and represent more complicated relationships.

Moreover, activation functions are required in order to **stack layers**.

Activation functions transform inputs into outputs of a different kind.

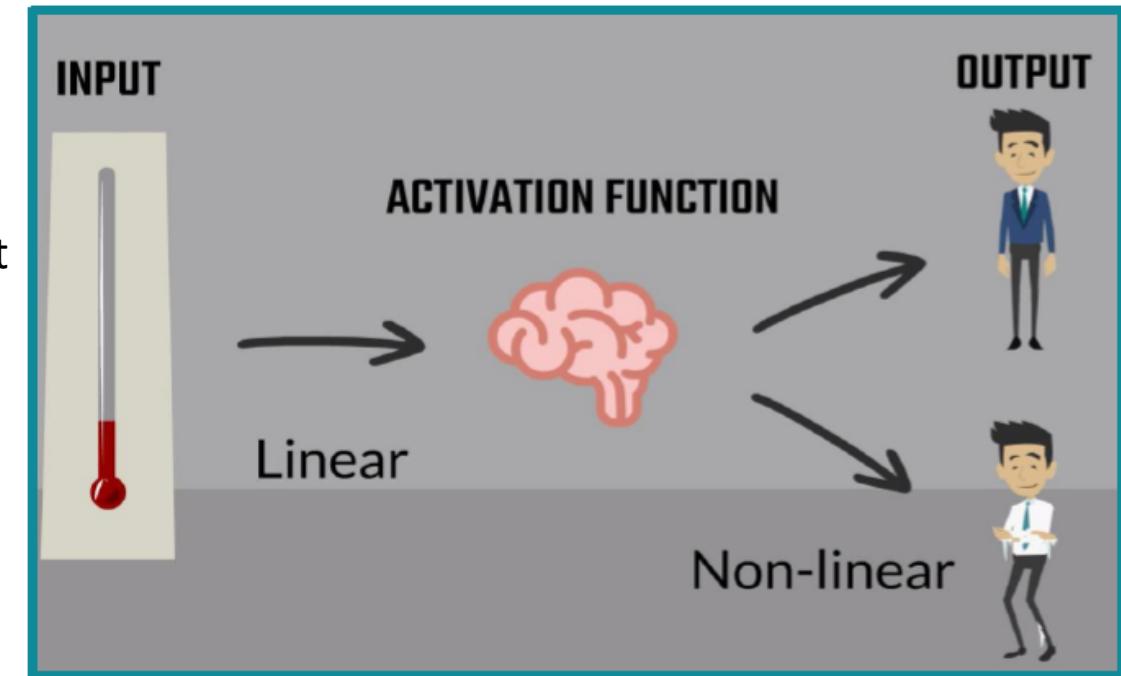
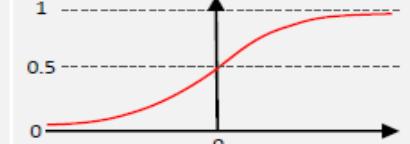
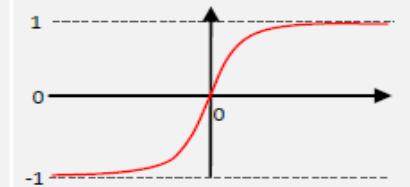
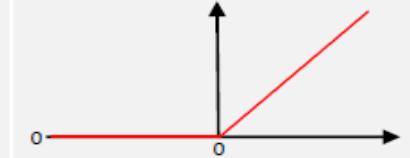


Image source: 365DataScience

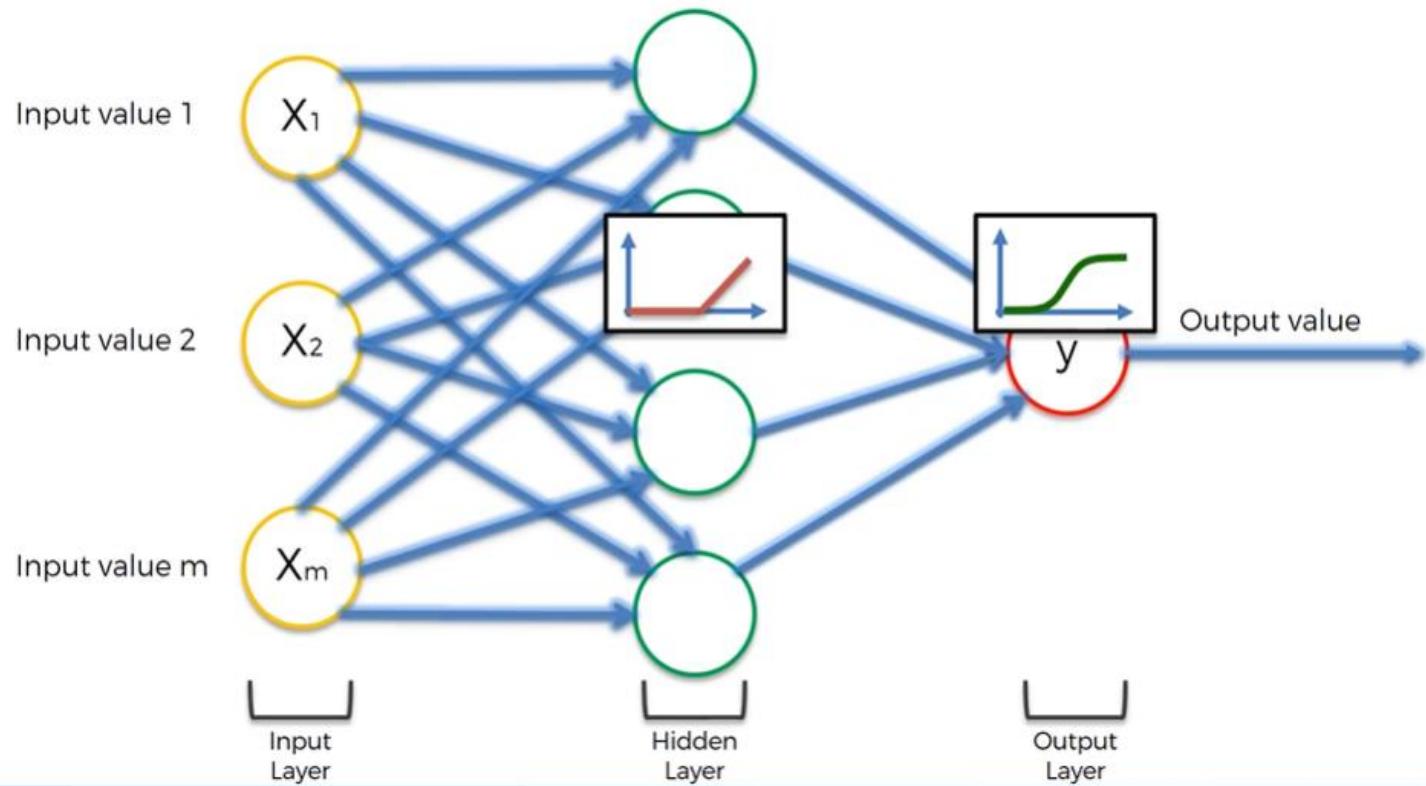
# Some commonly used activation functions:

Name	Formula	Derivative	Graph	Range
<b>sigmoid (logistic function)</b>	$\sigma(a) = \frac{1}{1+e^{-a}}$	$\frac{\partial \sigma(a)}{\partial a} = \sigma(a)(1 - \sigma(a))$		(0, 1)
<b>TanH (hyperbolic tangent)</b>	$\tanh(a) = \frac{e^a - e^{-a}}{e^a + e^{-a}}$	$\frac{\partial \tanh(a)}{\partial a} = \frac{4}{(e^a + e^{-a})^2}$		(-1, 1)
<b>ReLU (rectified linear unit)</b>	$\text{relu}(a) = \max(0, a)$	$\frac{\partial \text{relu}(a)}{\partial a} = \begin{cases} 0, & \text{if } a \leq 0 \\ 1, & \text{if } a > 0 \end{cases}$		(0, ∞)
<b>softmax</b>	$\sigma_i(a) = \frac{e^{a_i}}{\sum_j e^{a_j}}$	$\frac{\partial \sigma_i(a)}{\partial a_j} = \sigma_i(a) (\delta_{ij} - \sigma_j(a))$ Where $\delta_{ij}$ is 1 if $i=j$ , 0 otherwise	different every time	(0, 1)

All common activation functions are: **monotonic**, **continuous**, and **differentiable**. These are important properties needed for the optimization.

Image source: 365DataScience

# Common combination of activation functions:

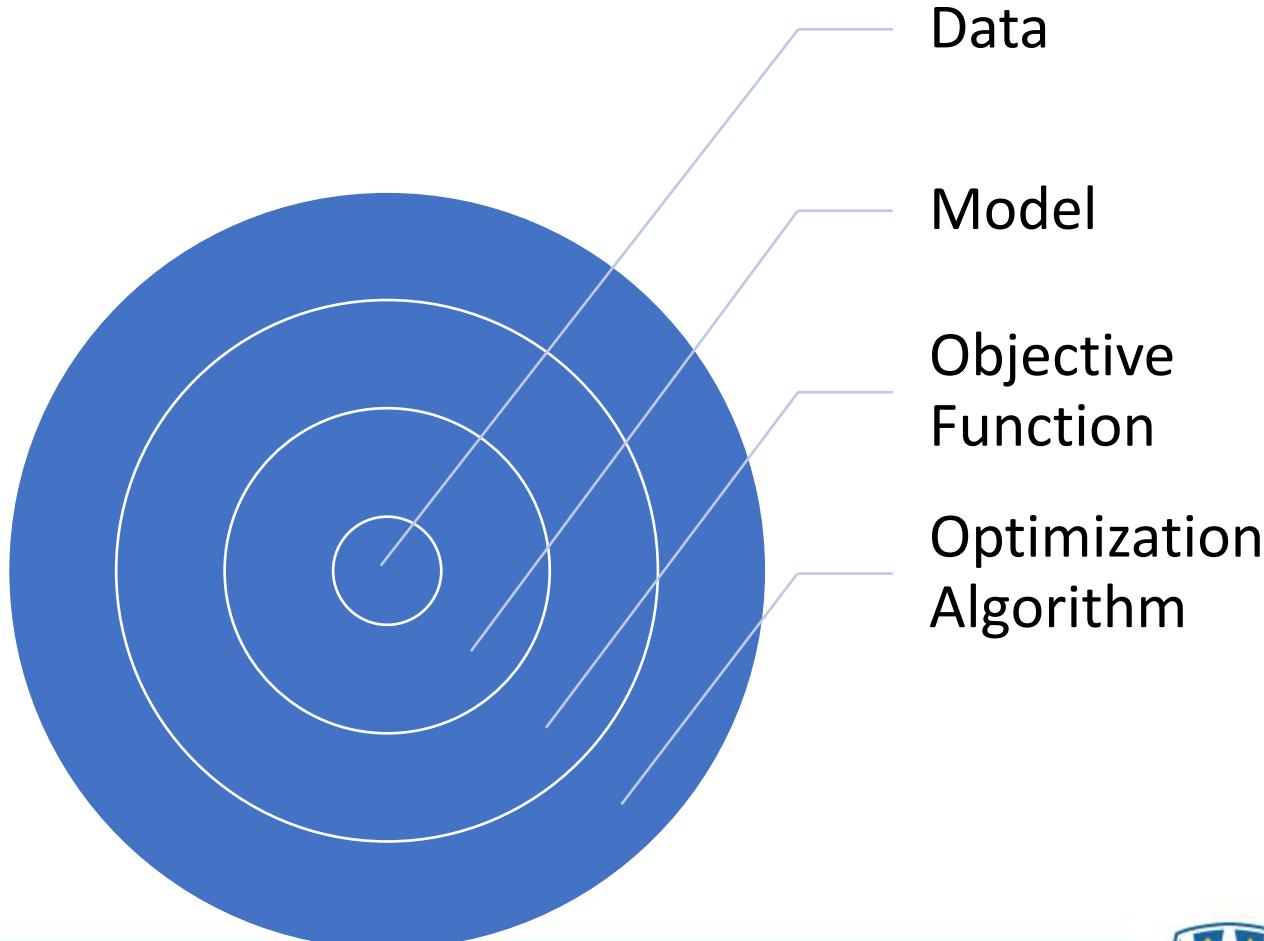


## Summary:

- Activation functions are **non-linear** and **differentiable**.
- Differentiable for back propagation (We will discuss later. )
- Non-linear to approximate complex function. (We've already discussed.)

Image source: SuperDataScience

# Deep Neural Network : Involves 4 Ingredients



Need to prepare a certain amount of data to train with.

## DATA MODEL OBJECTIVE FUNCTION OPTIMIZATION ALGORITHM

	A	B	C	D	E	F	G	H	I	J	K	L	M	N	O
1		Weather historical data													
2															
4	Location	Year	Month	Date	Temp	Dew point	Pressure	Visibility	Wind speed	Max wind speed	Max wind gust	Max temp	Min temp	Precipitation	
5	723150	###	'	1	44.7	40.3	1022.00	6	3.2	15	20	64	30.9	0.00D	
6	723150	###	1	2	55.5	50	1022.10	7.2	6.6	15.9	21	66.0*	48.2*	0.00D	
7	723150	###	1	3	58.1	53.6	1019.70	9.5	7.2	15	20	66.9	48	0.00D	
8	723150	###	1	4	57.7	50.8	1012.30	8.2	10.4	18.1	23.9	62.1*	46.4*	0.06G	
9	723150	###	1	5	34.9	23.8	1021.60	10	10.2	17.1	27	46.0*	28.0*	0.14G	
10	723150	###	1	6	31.6	22.1	1030.60	9.6	2.9	8.9	999.9	48	19	0.00G	
11	723150	###	1	7	36.6	24.7	1028.50	9.9	8.2	17.1	23.9	50.0*	27.0*	0.00D	
12	723150	###	1	8	35.7	23.5	1027.50	9.9	3.4	8.9	999.9	50	24.1	0.00C	
13	723150	###	1	9	42.5	30.9	1018.90	6.6	4.2	8.9	999.9	50	24.1	0.44D	
14	723150	###	1	10	52.8	34.1	1008.50	5.7	6.5	17.1	27	60.8*	46.4*	1.42G	
15	723150	###	1	11	46.5	24.1	1013.20	10	6.5	25.1	33	64.9	28.9	0.03G	
16	723150	###	1	12	44.7	24.9	1021.30	9.9	4.4	11.1	999.9	66	28	0.00G	
17	723150	###	1	13	53.7	35	1017.60	9.9	10.6	24.1	34	66	28	0.08D	
18	723150	###	1	14	31.5	12.7	1032.70	9.9	16.4	28.9	37.9	41.0*	24.1*	0.00H	
19	723150	###	1	15	29.4	13.3	1037.00	9.9	3.3	8	999.9	50	15.1	0.00I	
20	723150	###	1	16	38.6	23.9	1028.70	8.8	5.2	10.1	999.9	50	15.1	0.00H	
21	723150	###	1	17	44.3	24.9	1026.30	9.6	6.4	8.9	15	52	27	0.03A	
22	723150	###	1	18	35	25.8	1018.80	7.1	8.6	19	23.9	52	30	0.21G	
23	723150	###	1	19	36.1	25.9	1015.60	9.9	12.2	20	27	45	30	0.01G	
24	723150	###	1	20	35.4	27.7	1005.60	8	17.7	34	42.9	42.1*	26.6*	0.14G	
25	723150	###	1	21	21.8	6.8	1016.30	9.9	16.2	25.1	32.1	39.9	14	0.01G	
26	723150	###	1	22	21.6	11.5	1021.30	7.4	7.2	14	999.9	28.9	14	0.00G	
27	723150	###	1	23	29.6	27.3	1016.30	5.9	4.3	8.9	999.9	36	18	0.03B	

Image source: 365DataScience

Model will find some coefficients(weights) to determine the relationship between input data and output value.

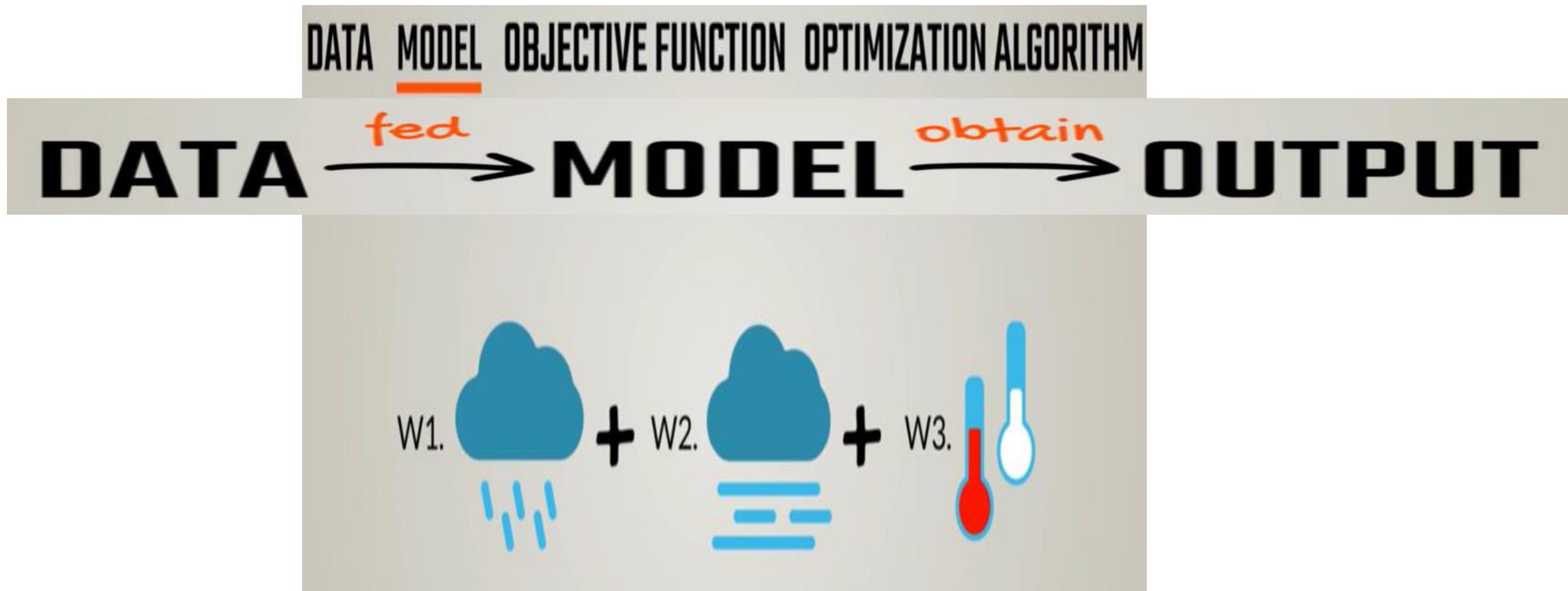


Image source: 365DataScience

Objective function estimates how correct the model's output are on average:(Predicted vs. Actual )

DATA	MODEL	<b>OBJECTIVE FUNCTION</b>	OPTIMIZATION ALGORITHM
OUTPUT	CORRECT VALUE	OBJECTIVE FUN.	VALUE
		far from reality	200
		Closer	100
		Very close	0

365 DataScience

Minimizing Error = Minimizing/Maximizing Objective Function.

Image source: 365DataScience

# Objective Function are mainly 2 types:

## Loss Function

## Reward Function

The lower the loss, the higher the accuracy.

Used mainly in Supervised Learning.

The higher the reward, the higher the accuracy.

Used mainly in Reinforcement Learning.

# Loss Function/Cost Function/Error Function calculates model's errors.

Measures the difference between our model's predictions and actual outcome that we want to predict.

Maximum Likelihood Estimation (MLE) is a framework for inference for finding the best statistical estimates of parameters from training data.

Two most commonly used loss functions when training Neural Network models used under MLE framework:

**Mean Squared Error (MSE)**  
[Suitable for Regression]

**Cross-Entropy**  
(Also known as Log loss/ Logistic Loss/Logarithmic Loss)  
[Suitable for Classification]

# Commonly used combination of Activation Function and Loss Function:

## Regression Problem:

- **Output Layer Configuration:** One node with a linear activation unit.
- **Loss Function:** Mean Squared Error (MSE), L-2 Norm(Euclidian Distance).

## Binary Classification Problem:

- **Output Layer Configuration:** One node with a sigmoid activation unit.
- **Loss Function:** Cross-Entropy, also referred to as Logarithmic loss.

## Multi-Class Classification Problem:

- **Output Layer Configuration:** One node for each class using the softmax activation function.
- **Loss Function:** Cross-Entropy, also referred to as Logarithmic loss.

Optimization Algorithm varies the model's parameters, i.e., weights and bias to optimize the objective function, i.e., loss function/reward function.

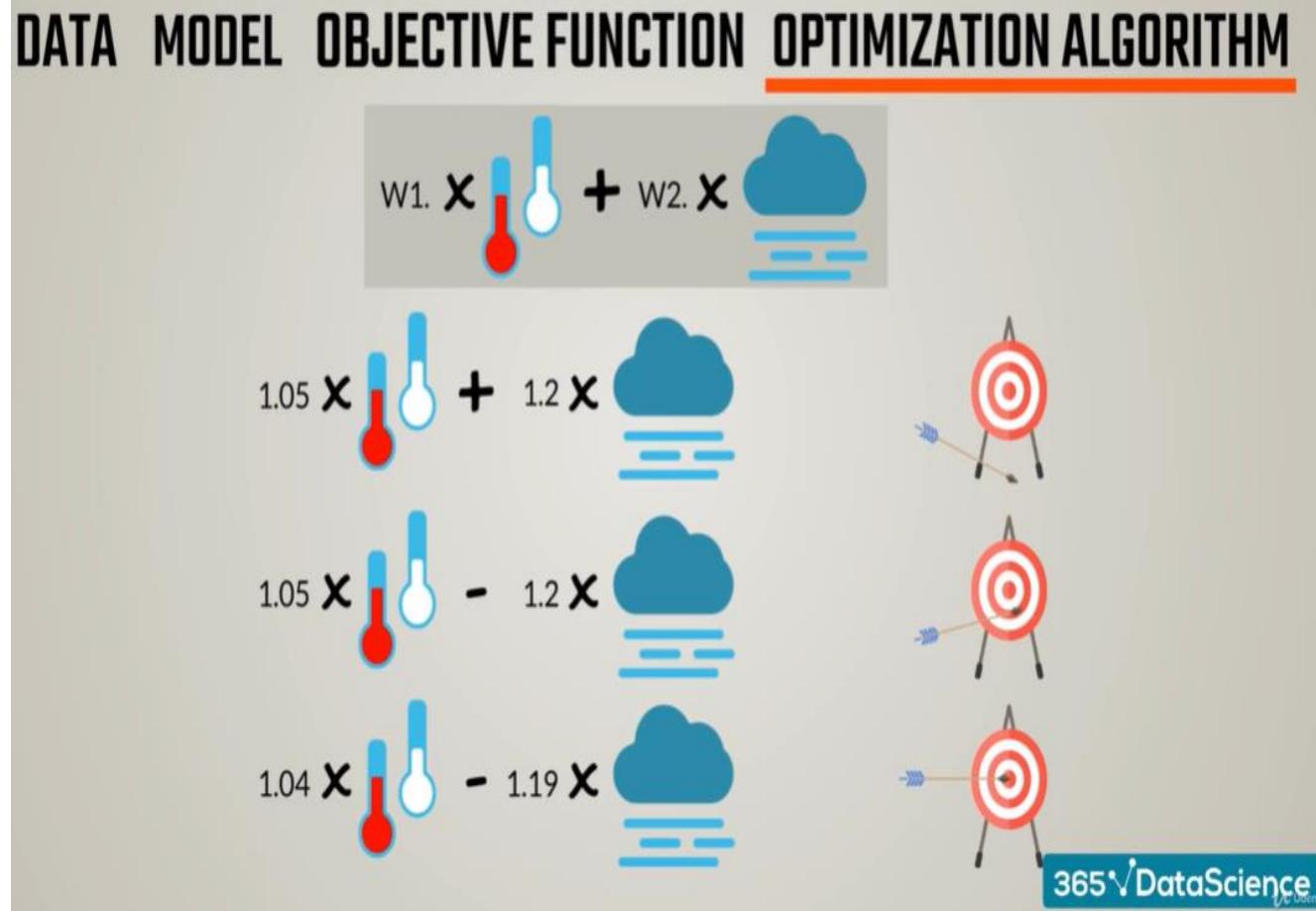
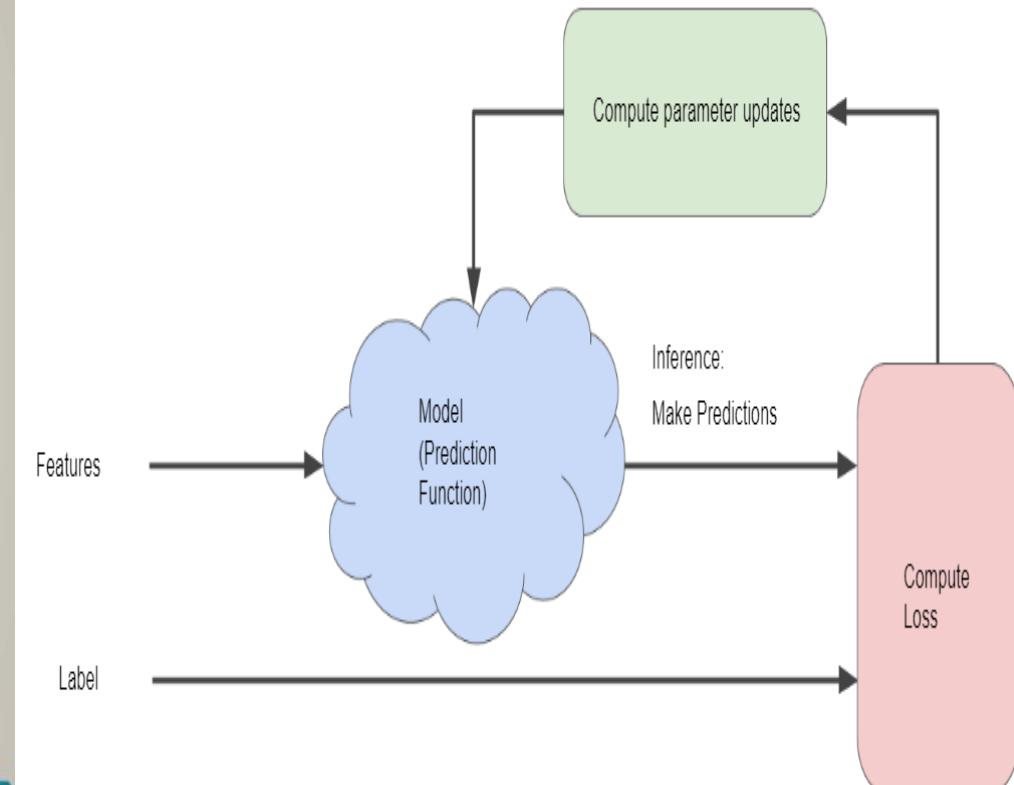


Image source: 365DataScience



# Some commonly used Optimization Algorithms:

Batch Gradient Descent

Stochastic Gradient Descent (SGD)

Mini-batch SGD / with  
Momentum

AdaGrad

RMSProp

Adam



# Optimization Algorithms help taking two crucial decisions:

1. Which way to go:

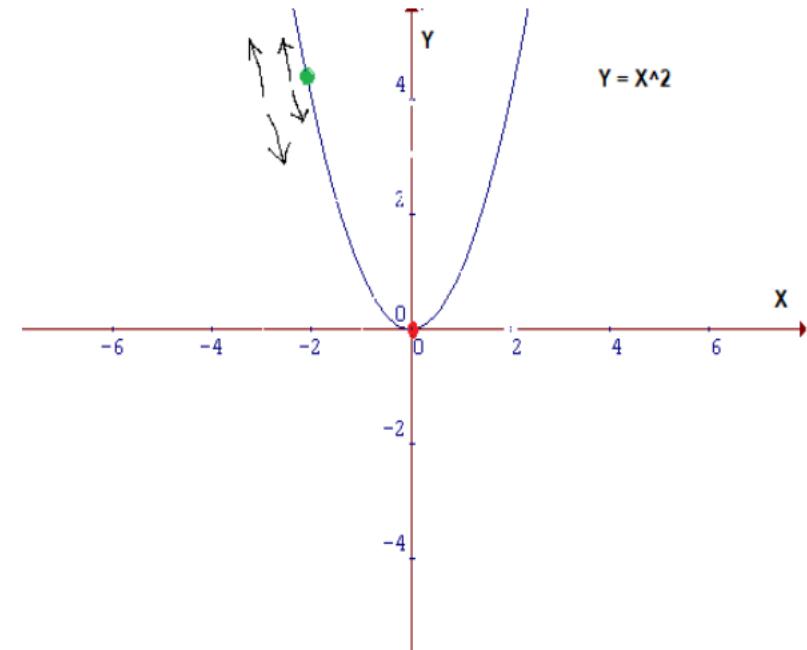
- Upward or Downward?

2. How you take the step to reach the destination:

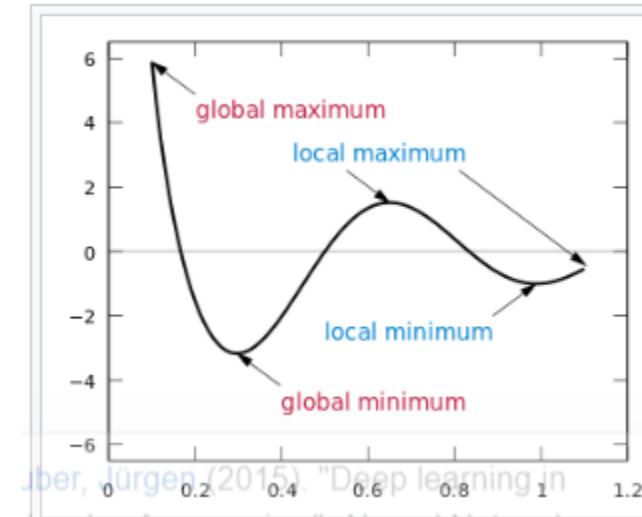
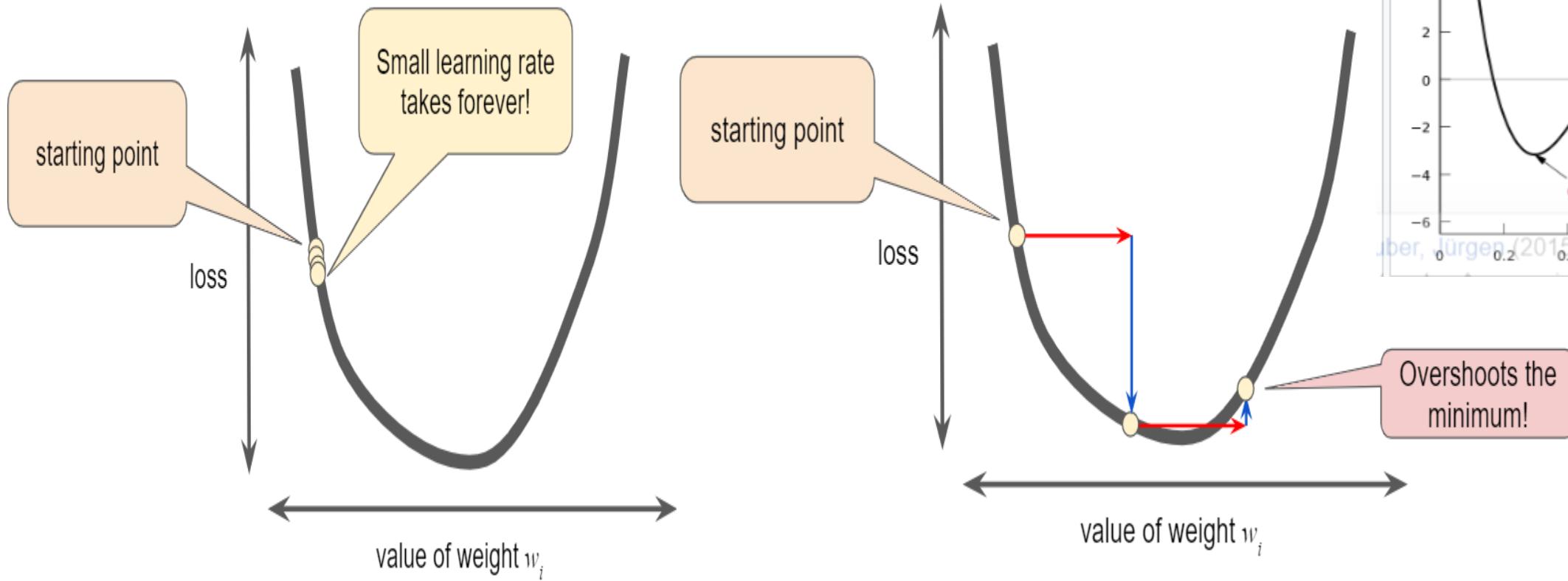
- Big or Small?

The idea is that by being able to compute the derivative/slope of the function, we can find the minimum of a function.

- If we are able to compute the derivative of a function, we know in which direction to proceed to minimize it.
- Learning Rate decides the steps size towards the direction. [learning rate \* derivatives]
- Here, Function indicates the objective function of our model.



# Learning Rate: size of steps taken to reach the minimum or bottom Too Small vs Too Large



Try and visualize at : <https://developers.google.com/machine-learning/crash-course/fitter/graph>

**Backpropagation:** Calculates gradient descent(partial derivatives) of cost function and repeat the steps by going back and updating the weights (and biases) to get the optimum values.

Backpropagation was invented in 1960. Later, the term in neural networks was announced by Rumelhart, Hinton & Williams (1986).

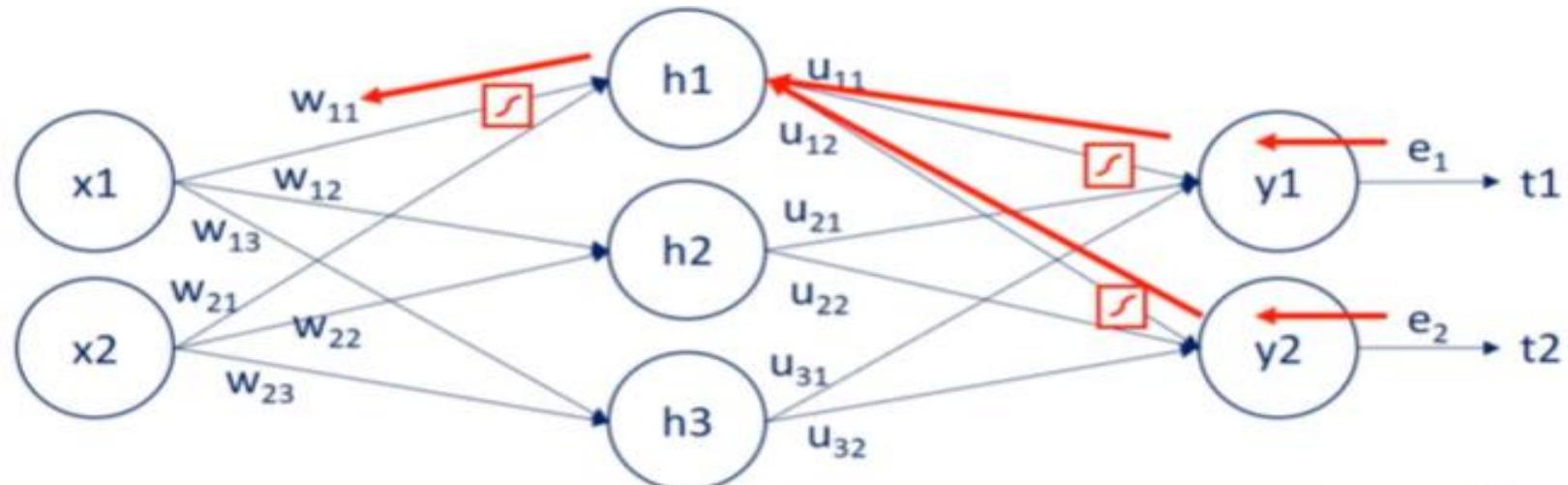
### What was actually wrong with backpropagation in 1986?

- We all drew the wrong conclusions about why it failed.  
The real reasons were:
  1. Our labeled datasets were thousands of times too small.
  2. Our computers were millions of times too slow.
  3. We initialized the weights in a stupid way.
  4. We used the wrong type of non-linearity.

What Was Actually Wrong With Backpropagation in 1986?  
Slide by Geoff Hinton, all rights reserved.

# Backpropagation: is one of the biggest challenges for the speed of an algorithm.

At the end of epoch the network back propagates and change the parameters accordingly



## The algorithm adjusts:

the weights that have a **bigger** contribution to the errors by **more**;  
the weights that have a **smaller** contribution to the errors by **less**

Image source: 365DataScience

# Backpropagation: Why Computing Gradients?

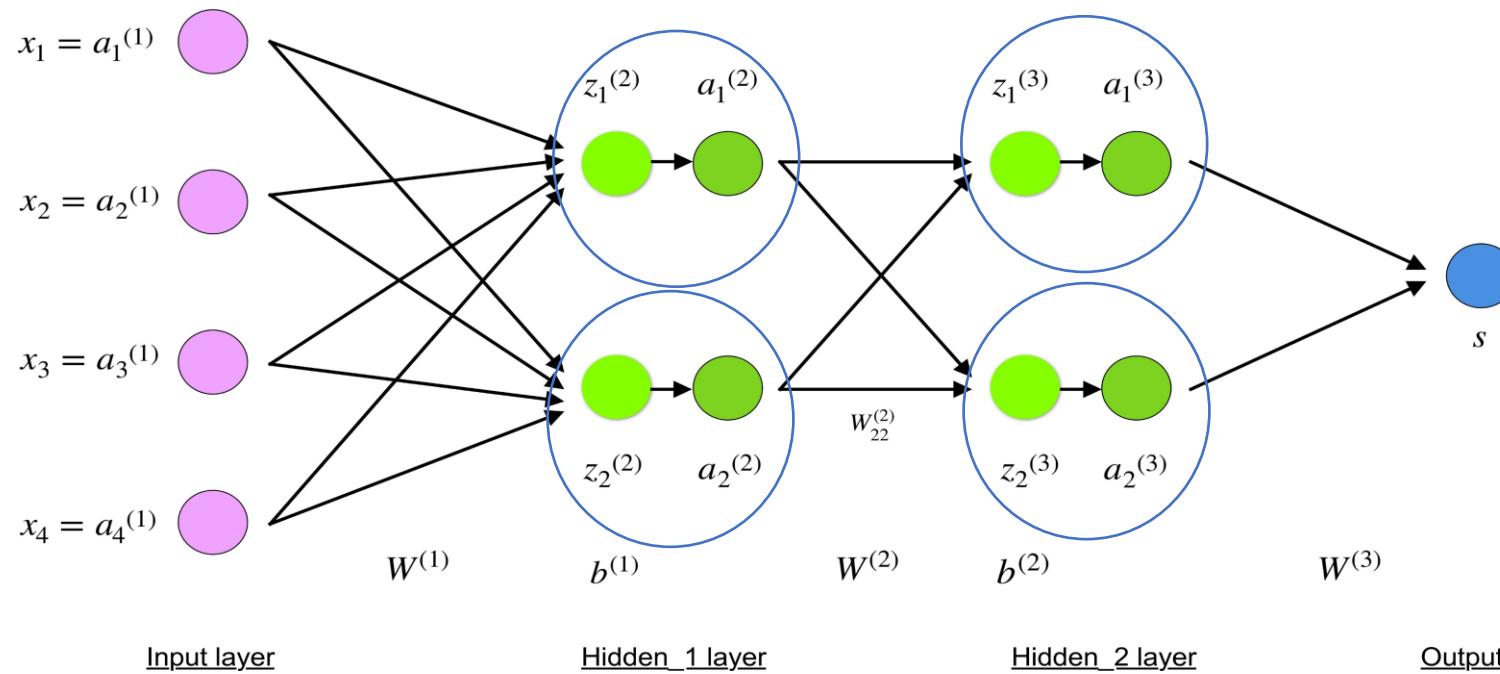
To answer this, we first need to revisit some calculus terminology:

- *Gradient of a function  $C(x_1, x_2, \dots, x_m)$  in point  $x$  is a vector of the partial derivatives of  $C$  in  $x$ .*

$$\frac{\partial C}{\partial x} = \left[ \frac{\partial C}{\partial x_1}, \frac{\partial C}{\partial x_2}, \dots, \frac{\partial C}{\partial x_m} \right]$$

- The derivative of a function  $C$  measures the sensitivity to change of the function value (output value) with respect to a change in its argument  $x$  (input value).  
In other words, the derivative tells us the direction  $C$  is going.
- The gradient shows how much the parameter  $x$  needs to change (in positive or negative direction) to minimize  $C$ .

# Backpropagation: How to Compute Gradients?



$x = a^{(1)}$  *Input layer*

$z^{(2)} = W^{(1)}x + b^{(1)}$  *neuron value at Hidden<sub>1</sub> layer*

$a^{(2)} = f(z^{(2)})$  *activation value at Hidden<sub>1</sub> layer*

$z^{(3)} = W^{(2)}a^{(2)} + b^{(2)}$  *neuron value at Hidden<sub>2</sub> layer*

$a^{(3)} = f(z^{(3)})$  *activation value at Hidden<sub>2</sub> layer*

$s = W^{(3)}a^{(3)}$  *Output layer*

$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \quad W^{(1)} = \begin{bmatrix} W_{11}^{(1)} & W_{12}^{(1)} & W_{13}^{(1)} & W_{14}^{(1)} \\ W_{21}^{(1)} & W_{22}^{(1)} & W_{23}^{(1)} & W_{24}^{(1)} \end{bmatrix} \quad b^{(1)} = \begin{bmatrix} b_1^{(1)} \\ b_2^{(1)} \end{bmatrix} \quad z^{(2)} = \begin{bmatrix} W_{11}^{(1)}x_1 + W_{12}^{(1)}x_2 + W_{13}^{(1)}x_3 + W_{14}^{(1)}x_4 \\ W_{21}^{(1)}x_1 + W_{22}^{(1)}x_2 + W_{23}^{(1)}x_3 + W_{24}^{(1)}x_4 \end{bmatrix} + \begin{bmatrix} b_1^{(1)} \\ b_2^{(1)} \end{bmatrix} = \begin{bmatrix} z_1^{(2)} \\ z_2^{(2)} \end{bmatrix}$$

Image source: towardsdatascience.com

# Backpropagation: How to Compute Gradients?

Computing those gradients happens using a technique called **chain rules**:

For a single weight  $W_{jk}^l$ , the gradient is:

$$\frac{\partial C}{\partial w_{jk}^l} = \frac{\partial C}{\partial z_j^l} \frac{\partial z_j^l}{\partial w_{jk}^l} \quad \text{chain rule}$$

$$z_j^l = \sum_{k=1}^m w_{jk}^l a_k^{l-1} + b_j^l \quad \text{by definition}$$

$m$  – number of neurons in  $l-1$  layer

$$\frac{\partial z_j^l}{\partial w_{jk}^l} = a_k^{l-1} \quad \text{by differentiation (calculating derivative)}$$

$$\frac{\partial C}{\partial w_{jk}^l} = \frac{\partial C}{\partial z_j^l} a_k^{l-1} \quad \text{final value}$$

Similar set of equations can be applied to  $b_j^l$  is:

$$\frac{\partial C}{\partial b_j^l} = \frac{\partial C}{\partial z_j^l} \frac{\partial z_j^l}{\partial b_j^l} \quad \text{chain rule}$$

$$\frac{\partial z_j^l}{\partial b_j^l} = 1 \quad \text{by differentiation (calculating derivative)}$$

$$\frac{\partial C}{\partial b_j^l} = \frac{\partial C}{\partial z_j^l} 1 \quad \text{final value}$$

# Backpropagation: How to Compute Gradients?

- The common part in both equations is often called “*local gradient*” and is expressed as follows:

$$\delta_j^l = \frac{\partial C}{\partial z_j^l} \quad \text{local gradient}$$

The “*local gradient*” can easily be determined using the chain rule.

- Algorithm for optimizing weights and biases (also called “Gradient descent”)

*while (termination condition not met)*

$$w := w - \epsilon \frac{\partial C}{\partial w}$$

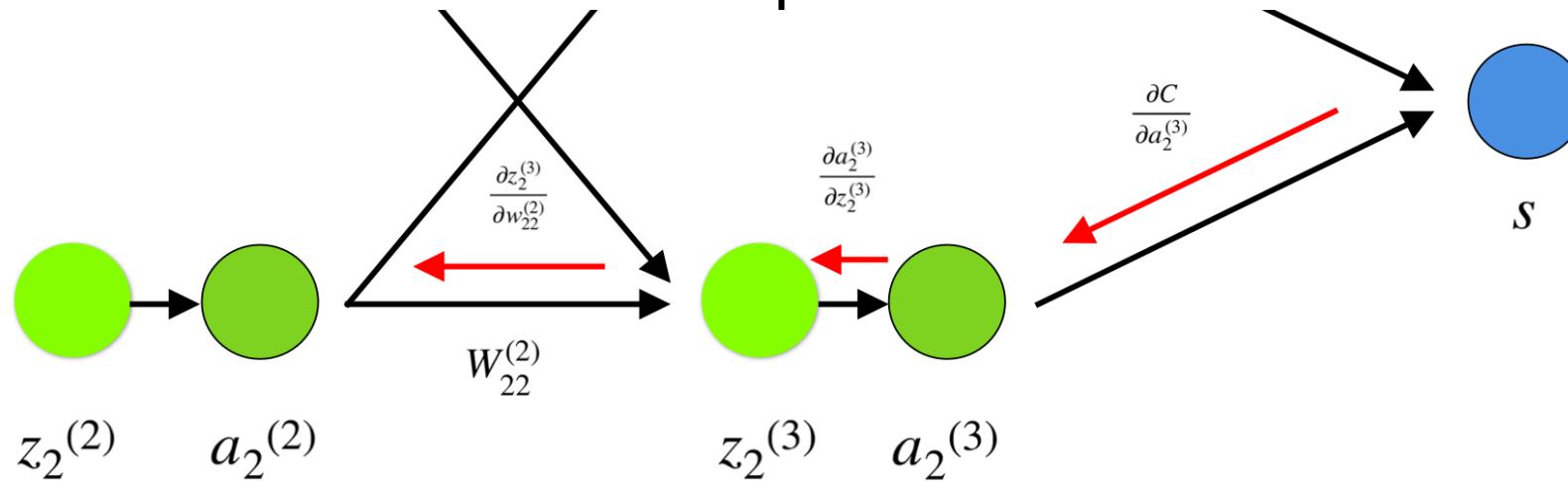
$$b := b - \epsilon \frac{\partial C}{\partial b}$$

*end*

- Initial values of  $w$  and  $b$  are randomly chosen.
- Epsilon ( $\epsilon$ ) is the learning rate. It determines the gradient’s influence (Also represented as Eta( $\eta$ )).
- $w$  and  $b$  are matrix representations of the weights and biases. Derivative of  $C$  in  $w$  or  $b$  can be calculated using partial derivatives of  $C$  in the individual weights or biases.
- Termination condition is met once the cost function is minimized (Can be terminated by setting number of epochs/early stopping)

# Back Propagation: How to Compute Gradients?

Let's look into the bottom part of the neural network:



Weight  $W_{22}^2$  connects  $a_2^2$  and  $z_2^2$ , so computing the gradient requires applying the chain rule through  $z_2^3$  and  $a_2^3$

$$\frac{\partial C}{\partial w_{22}^{(2)}} = \frac{\partial C}{\partial z_2^{(3)}} \cdot \frac{\partial z_2^{(3)}}{\partial w_{22}^{(2)}} = \frac{\partial C}{\partial a_2^{(3)}} \cdot \frac{\partial a_2^{(3)}}{\partial z_2^{(3)}} \cdot a_2^{(2)} = \frac{\partial C}{\partial a_2^{(3)}} \cdot f'(z_2^{(3)}) \cdot a_2^{(2)}$$

Calculating the final value of derivative of  $C$  in  $a_2^3$  requires knowledge of the function  $C$ . Since  $C$  is dependent on  $a_2^3$ , calculating the derivative should be fairly straightforward.

Image source: towardsdatascience.com

# Steps to train a Model:

1. • Randomly **initialized weights** to small number close to 0 (but not 0).
2. • Input first observation in your dataset in the input layer, **each feature in one input node.**
3. • **Forward-Propagation:** From left to right, the neuron are activated in such a way the impact of each neuron activation is limited by the weights associates with the neuron. Propagate the activation until getting the predicted result  $y$ .
4. • **Compare** the predicted result with the actual result and measure the error.
5. • **Back-Propagation:** From right to left, the error is back-propagated. Update the weights according to how much they are responsible for the error. The learning rate decides by how much the model updates the weights.
6. • **Repeat** the steps **1 to 5** and update the weights after each observation (Reinforcement Learning).  
Or,  
• Repeat the steps 1 to 5 but update the weights after a batch of observations (Batch Learning).
7. • When the whole training set passed throw the model (ANN), that makes an epoch. **Redo more epochs.**

# Training a model: Summary

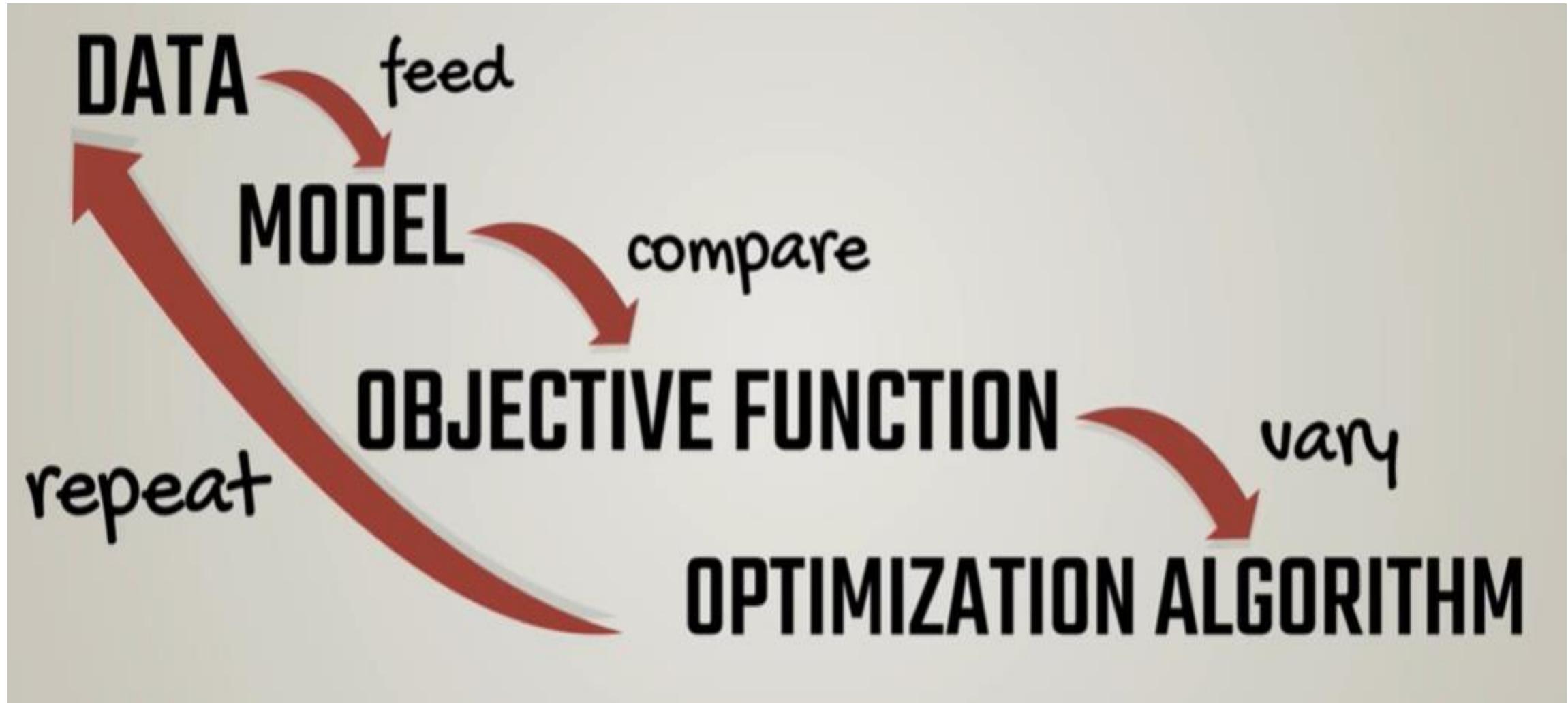


Image source: 365DataScience

# How do Neural Networks Learn ?

[Single Neuron(Node) with Single observation]

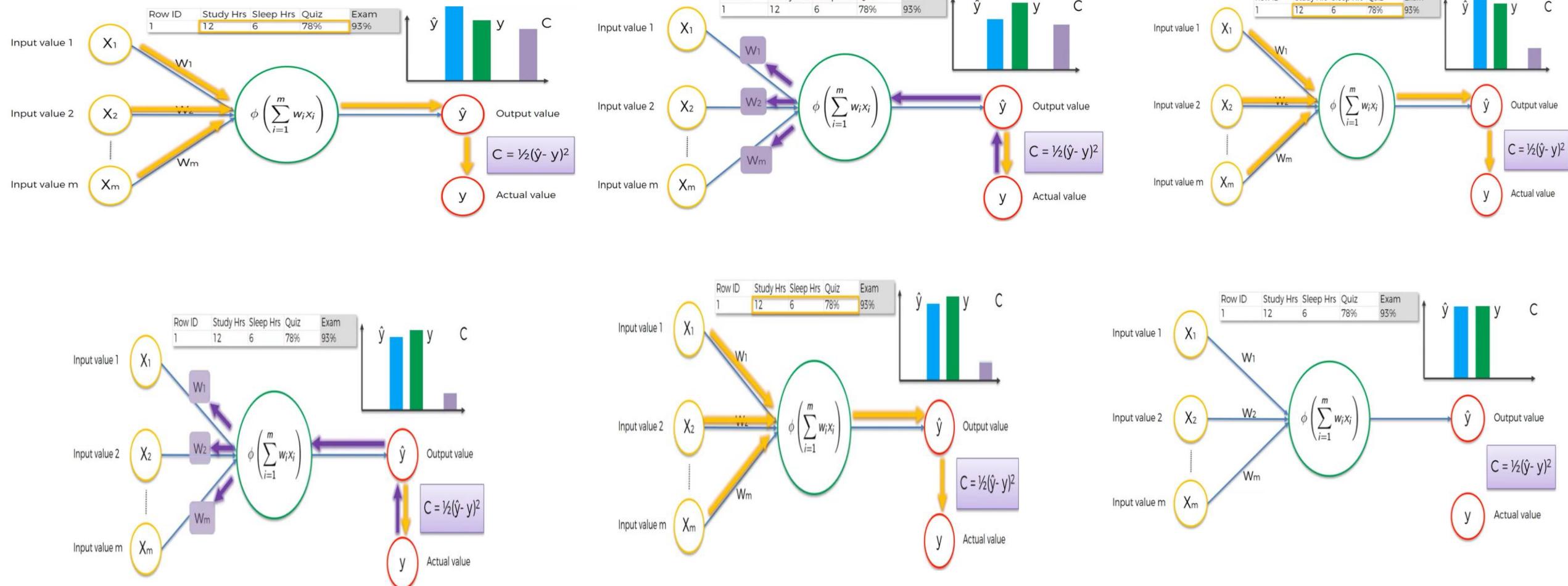
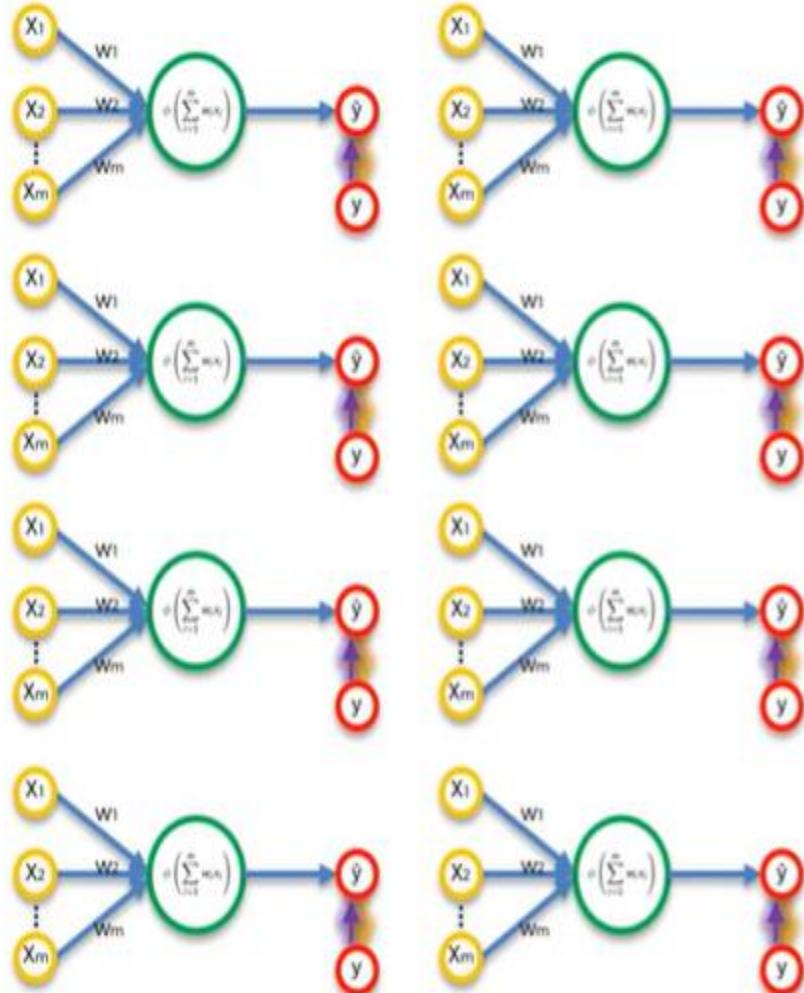


Image source: SuperDataScience

# How do Neural Networks Learn ?

(Single Neuron(Node) with multiple observations)



Row ID	Study Hrs	Sleep Hrs	Quiz	Exam
1	12	6	78%	93%
2	22	6.5	24%	68%
3	115	4	100%	95%
4	31	9	67%	75%
5	0	10	58%	51%
6	5	8	78%	60%
7	92	6	82%	89%
8	57	8	91%	97%

$$C = \sum \frac{1}{2}(\hat{y} - y)^2$$

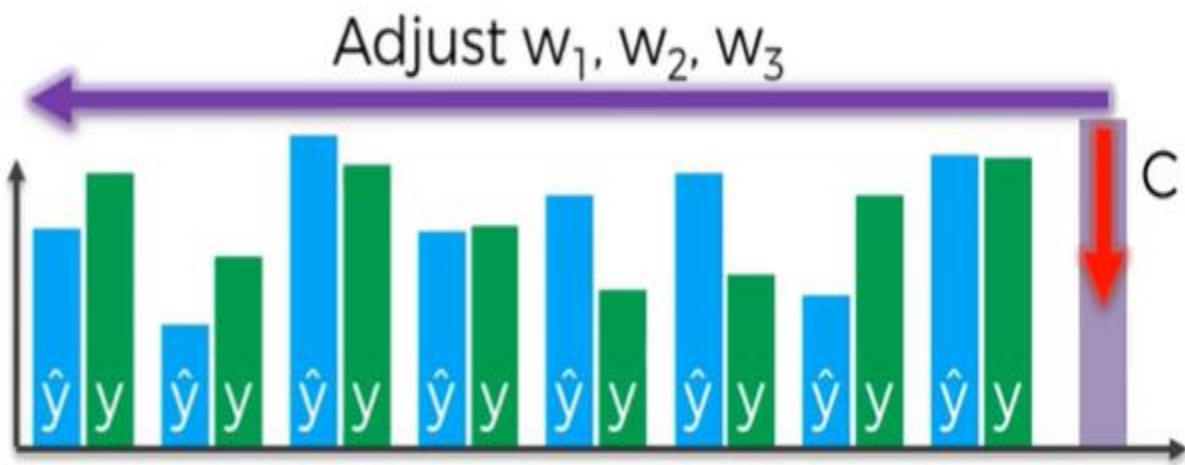


Image source: SuperDataScience

# How do Neural Networks Learn ?



## An illustration of deep nets

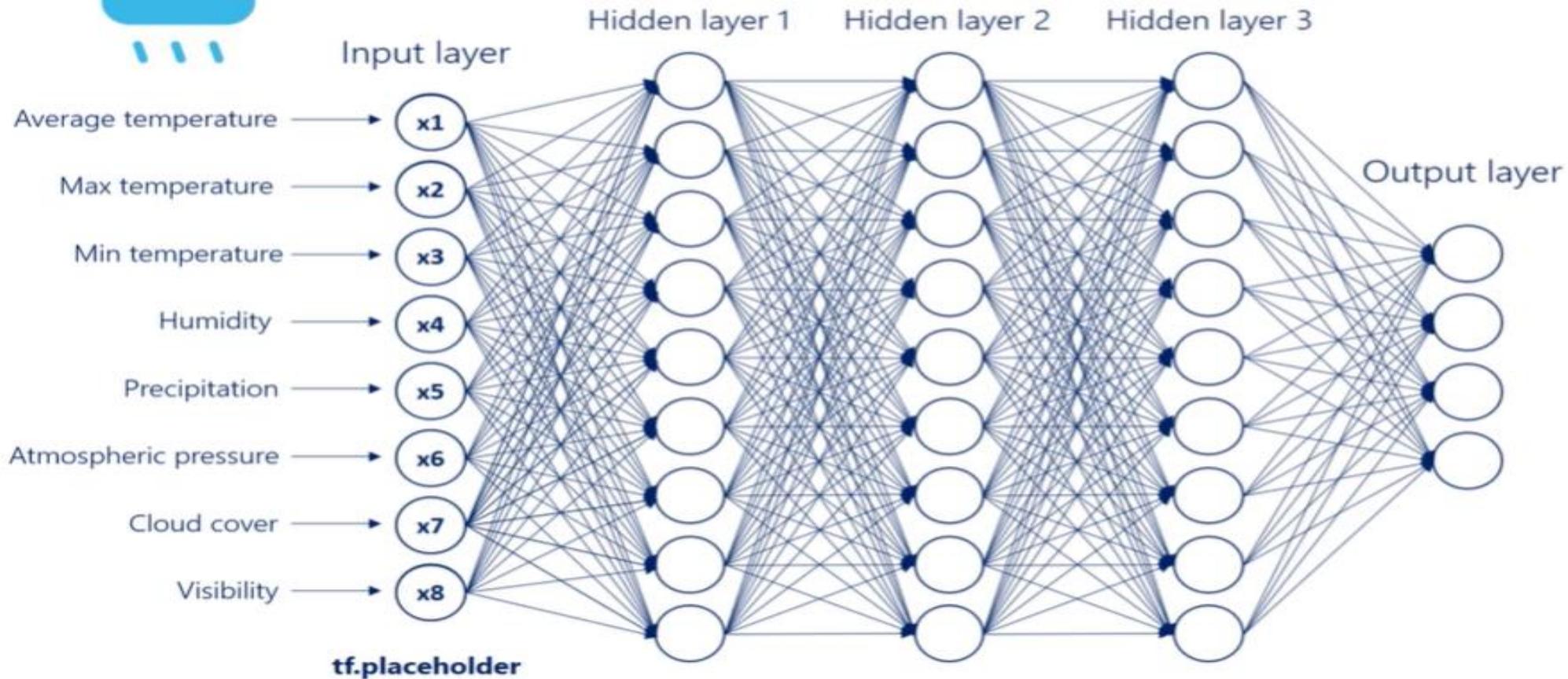
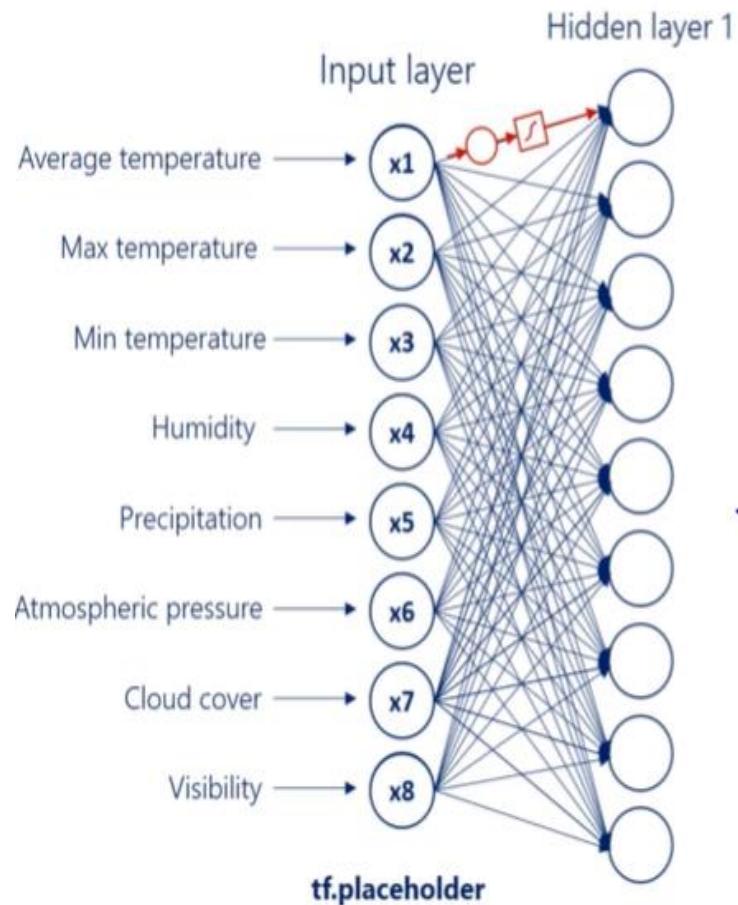


Image source: 365DataScience

# How do Neural Networks Learn ?

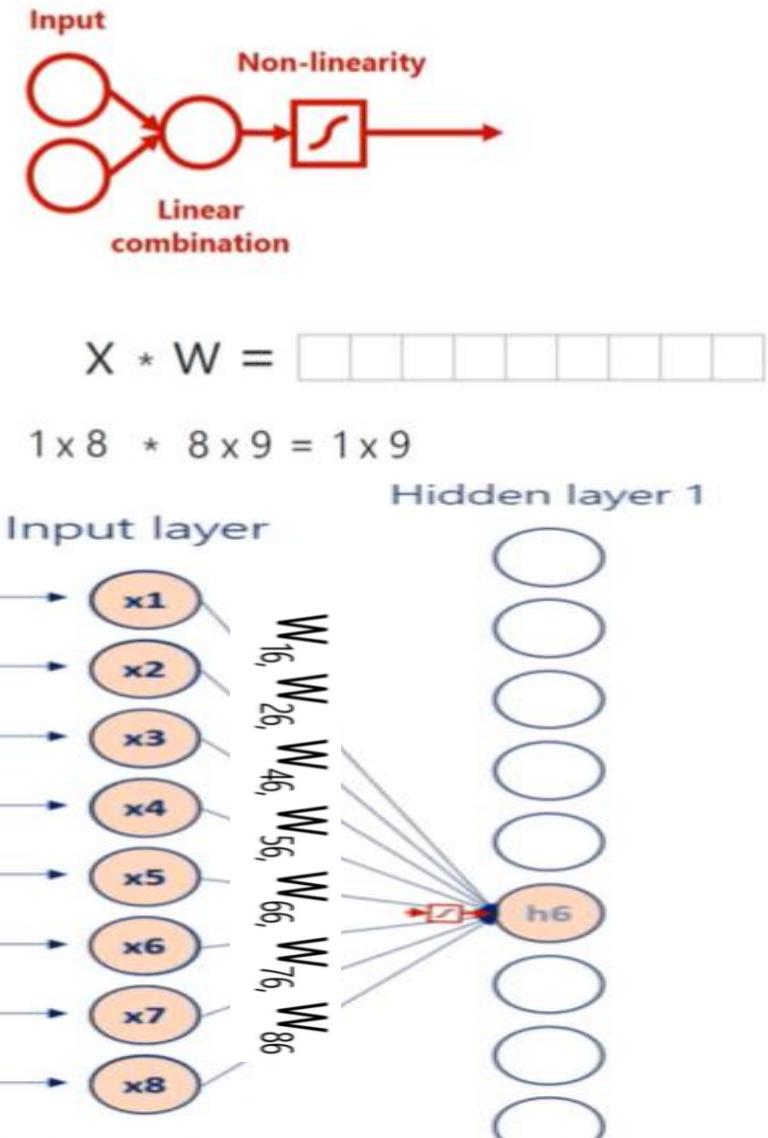


w11	w12	w13	w14	w15	w16	w17	w18	w19
w21	w22	w23	w24	w25	w26	w27	w28	w29
w31	w32	w33	w34	w35	w36	w37	w38	w39
w41	w42	w43	w44	w45	w46	w47	w48	w49
w51	w52	w53	w54	w55	w56	w57	w58	w59
w61	w62	w63	w64	w65	w66	w67	w68	w69
w71	w72	w73	w74	w75	w76	w77	w78	w79
w81	w82	w83	w84	w85	w86	w87	w88	w89

$$8 \times 9 = 72$$

$W_{36}$

Input unit      Hidden unit

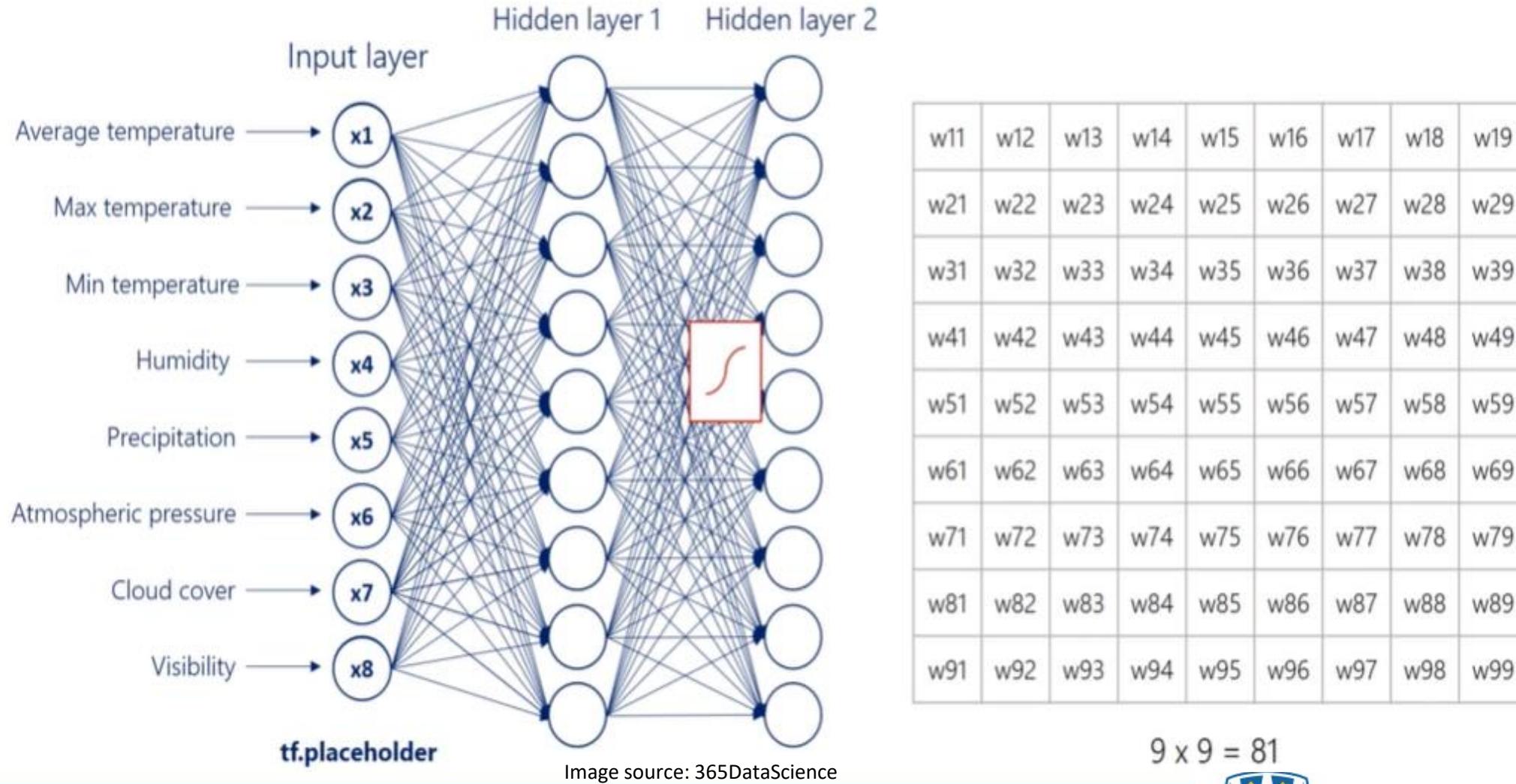


Each arrows multiplies weights (also added bias).

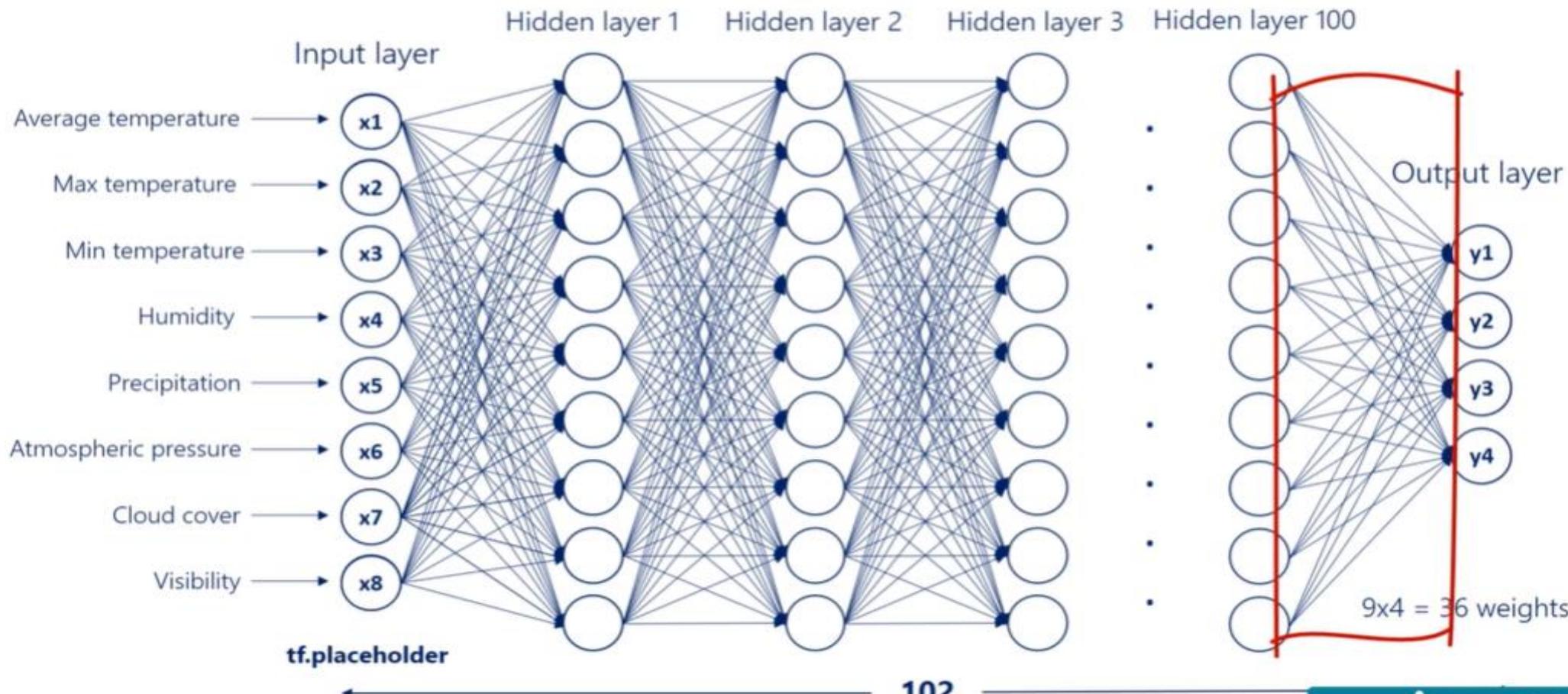
Then applies non-linearity.

Image source: 365DataScience

# How do Neural Networks Learn ?



# How do Neural Networks Learn ?



Try and visualize at: <http://playground.tensorflow.org/>

# Parameters vs. Hyperparameters

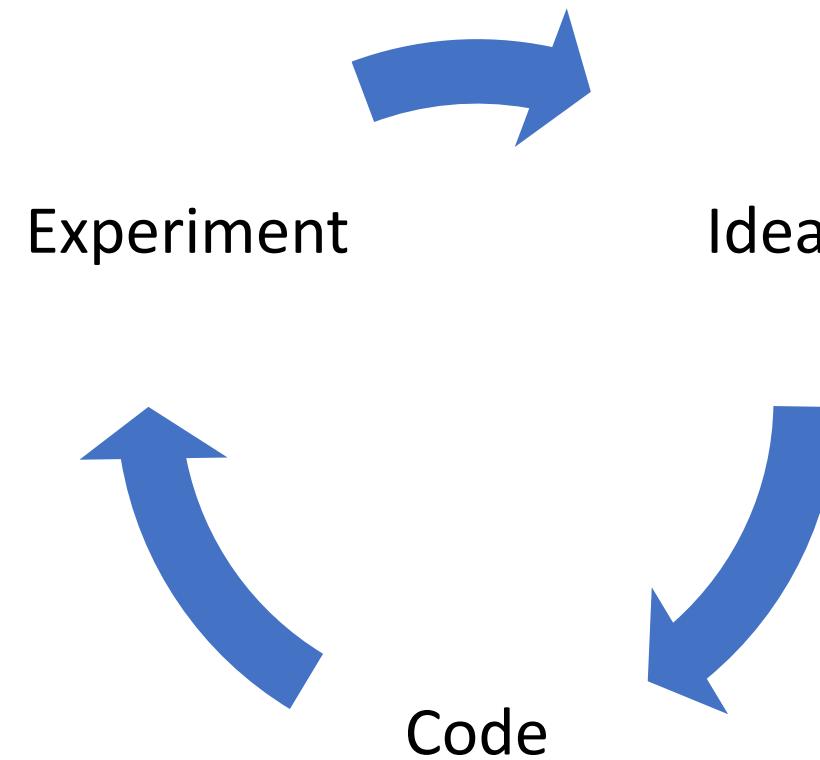
## Parameters

- Estimated or learned from Data (found by optimization).
- Are not often set manually.
- Examples: Weights( $w/\theta/j$ ), Biases( $b$ ) etc.

## Hyperparameters

- To help estimate model's parameter.
- Are often pre-set manually.
- Examples:  
Width, Depth, Epochs, Learning Rate( $\eta$ ), Batch Size, Momentum Coefficient( $\alpha$ ), Decay Coefficient( $c$ ) etc.

Experiment by tuning Hyperparameter to get the optimal result.  
[Applied ML/Deep Learning is a highly iterative process]



# Deep Learning Hands-On:

During the rest of the workshop, we will implement the theoretical concept we learned so far.

Please get the python codes from the following GitHub repository:

[https://github.com/ShaonBhattaShuvo/Deep-Learning-Workshop/blob/master/Workshop%20\(Part%201\)/WorkshopDL\\_\(Part1\).py](https://github.com/ShaonBhattaShuvo/Deep-Learning-Workshop/blob/master/Workshop%20(Part%201)/WorkshopDL_(Part1).py)

# Some useful contents came in handy to prepare the lecture:

1. <https://machinelearningmastery.com/what-is-deep-learning/>
2. <https://www.mathworks.com/discovery/deep-learning.html>
3. <https://www.analyticsvidhya.com/blog/2017/04/comparison-between-deep-learning-machine-learning/>
4. <http://content.time.com/time/interactive/0,31813,2048601,00.html>
5. <https://www.cs.toronto.edu/~tijmen/csc321/>
6. <https://cs.nyu.edu/~yann/talks/lecun-ranzato-icml2013.pdf>
7. <https://www.analyticsvidhya.com/blog/2020/01/fundamentals-deep-learning-activation-functions-when-to-use-them/>
8. <https://www.sebastianraschka.com/faq/docs/diff-perceptron-adaline-neuralnet.html>
9. <https://www.coursera.org/specializations/deep-learning#courses>
10. <https://www.udemy.com/course/artificial-intelligence-az/>
11. <https://www.udemy.com/course/machinelearning/>
12. <https://www.udemy.com/course/the-data-science-course-complete-data-science-bootcamp/>
13. <https://towardsdatascience.com/understanding-backpropagation-algorithm-7bb3aa2f95fd>
14. [http://neuralnetworksanddeeplearning.com/chap5.html#the\\_vanishing\\_gradient\\_problem](http://neuralnetworksanddeeplearning.com/chap5.html#the_vanishing_gradient_problem)
15. [https://ml-cheatsheet.readthedocs.io/en/latest/activation\\_functions.html](https://ml-cheatsheet.readthedocs.io/en/latest/activation_functions.html)
16. <http://www.deeplearningbook.org/>
17. <https://mlfromscratch.com/activation-functions-explained/#/>