

Documentation: Raspberry Pi Pico W

Overview

The Raspberry Pi Pico W is a microcontroller board developed by the Raspberry Pi Foundation. It builds on the original Raspberry Pi Pico by adding wireless connectivity, making it suitable for Internet of Things (IoT) applications, robotics, and embedded systems. Its combination of low power consumption, powerful processing capabilities, and versatility makes it an excellent choice for a variety of projects.

Technical Specifications

Physical Characteristics

- Dimensions: 51mm x 21mm x 1mm
- Weight: Approximately (6 grams) (without headers)

Processor

- Dual-core Arm Cortex-M0+ processor running up to (133 MHz)
- Built-in Floating-Point Unit (FPU) for efficient mathematical operations

Memory

- 264 KB SRAM for efficient runtime memory management
- 2 MB onboard flash memory for program and data storage

Connectivity

- Wi-Fi: IEEE 802.11n (2.4 GHz) provided via Infineon CYW43439 chip
- Secure communication support with protocols like WPA2

GPIO Pins (Total 40 pins)

- 26 multifunctional GPIO pins, configurable for:
- Digital Input/Output
- I2C, SPI, UART, PWM, ADC functionality
- Includes support for up to 16 PWM channels

Power Supply

- Operates with an input voltage of 1.8V to 5.5V
- Can be powered via micro-USB or an external power source
- Low power consumption ideal for battery-operated applications

Programming Support

- Languages supported:
- C and C++: High-performance and low-level control
- MicroPython and CircuitPython: For ease of use and rapid prototyping
- SDKs available for streamlined development



Additional Features

- Onboard antenna for reliable Wi-Fi communication
- Can function as both an Access Point (AP) and a Wi-Fi client
- Built-in Real-Time Clock (RTC) for time-based applications

Advantages

1. Cost-Effective: Affordable price point with powerful features.
2. Compact and Lightweight: Suitable for portable or space-constrained applications.
3. Versatility: Multifunctional GPIO pins support various peripherals.
4. Programming Flexibility: Can be programmed in multiple languages with extensive community support.
5. Low Power Consumption: Suitable for battery-operated and low-energy projects.
6. Wireless Connectivity: Reliable onboard Wi-Fi enhances its use in IoT applications.

Disadvantages

1. Limited Flash Memory: Only 2 MB onboard flash might be insufficient for complex projects.
2. No RTOS: Lacks a built-in Real-Time Operating System for advanced real-time applications.
3. No Native Hardware for Drones: Unlike dedicated flight controllers, it lacks optimized hardware for motor control and stabilization.
4. Limited ADC Channels: Only three ADC inputs, which may restrict analog signal processing.

Suitability for Kalman Filter Implementation

The Raspberry Pi Pico W is well-suited for implementing a Kalman filter, particularly in applications requiring sensor fusion (e.g., drones and robotics).

Key Points

1. Processing Power:

- The dual-core Arm Cortex-M0+ processor can handle real-time calculations, including matrix operations.
- The built-in FPU enables efficient floating-point arithmetic, crucial for Kalman filters.

2. Programming Libraries:

- uKalman: A lightweight Python library for Kalman filters.
- Custom C/C++ implementations for optimized performance.

3. IMU Integration:

- Easily interfaces with IMU sensors like MPU-6050 for obtaining accelerometer and gyroscope data.

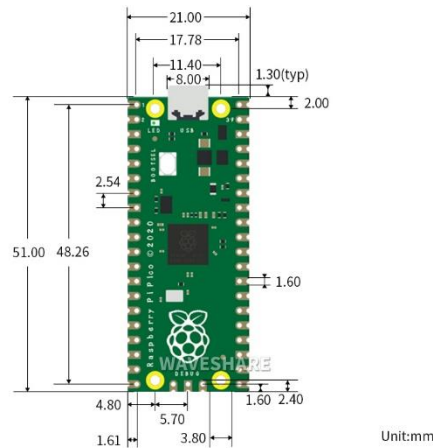
-Facilitates real-time filtering to improve data accuracy and reduce noise.

4. Real-Time Sampling:

-Supports I2C communication for high-speed data acquisition from sensors.

-Ensure a sampling rate of at least 100 Hz for optimal filter performance.

DIMENSION OF RASPBERRY PI PICO W



RASPBERRY PI PICO W PINOUT CHART

RP2040

■	Power
■	Ground
■	UART / UART (default)
■	GPIO, PIO, and PWM
■	ADC
■	SPI / SPI (default)
■	I2C / I2C (default)
■	System Control
■	Debugging

Infineon 43439

■	GPIO
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