Computer Fundamentals

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Introduction

Types of DT

Array

Stack

Queue

Linked Lists

Tree and Graph

Hashing

Search & Sort

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- Publications: 216 in Books, Book Chapters, Journals and in Proceedings of International and National Conferences







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Unit 4: Data Structures

- Primitive and composite data types
- Arrays, stacks, queues, linked lists
- Binary trees, B-trees
- Hashing techniques
- Linear Search, Binary Search
- Bubble Sort



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Hashing Data Structure

- Hashing is an important Data Structure which is designed to use a special function called the Hash function which is used to map a given value with a particular key for faster access of elements. The efficiency of mapping depends of the efficiency of the hash function used.
- Invented by Hans Peter Luhn , an IBM Scientis (1953)





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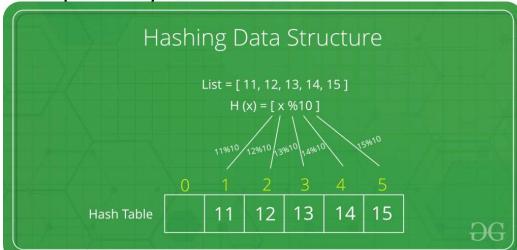
Tree and Graph

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Hashing Example

- Let a hash function H(x) maps the value at the index **x%10** in an Array.
- For example if the list of values is [11,12,13,14,15] it will be stored at positions {1,2,3,4,5} in the array or Hash table respectively.





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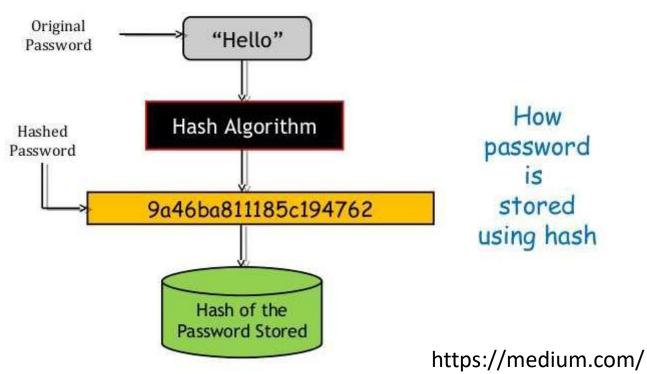
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Application: Hashing Password





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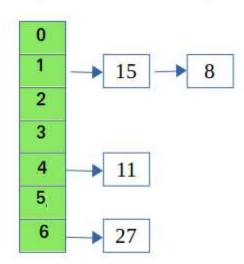
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Let's say hash table with 7 buckets (0, 1, 2, 3, 4, 5, 6)

Keys arrive in the Order (15, 11, 27, 8)



hashIndex = key % noOfBuckets

In computing, the **modulo operation** returns the remainder or signed remainder of a division, after one number is divided by another (called the **modulus** of the **operation**).





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hash key = key % number of slots in the table

[0] 72

Assume a table with 8 slots:

Hash key = key % table size

[1]

[2] 18

[3] 43

[4] 36

[5]

[6] 6

[7]





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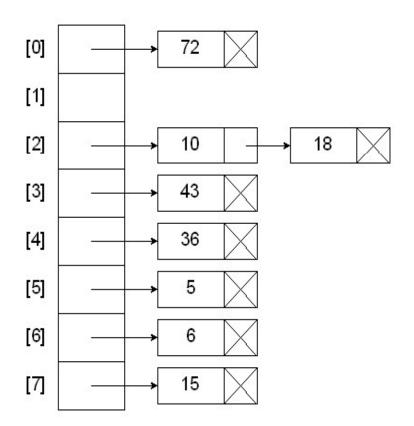
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Hashing with chains

Hash key = key % table size







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Linear Search

- The most basic type of searching algorithm.
- **Sequentially moves** through the data looking for a matching value.
- It **begins with the first** element, checking it every data until you find what you're looking for.
- In complexity terms this is an O(n) search.
- The time taken to search the list is in parallel with the size of the list.



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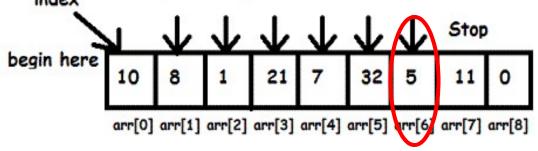
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go through these positions, until element found and then stop index



Element to search: 5





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Binary Search

- Binary search is an efficient algorithm for finding an item from a sorted list of items.
- It works by repeatedly dividing in half the portion of the list that could contain the item, until you've narrowed down the possible locations to just one.

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Binary Search

The following is our sorted array and let us assume that we need to search the location of value 31 using binary search.



- First, we shall determine half of the array by using this formula –
- mid = low + (high low) / 2
- Here it is, 0 + (9 0) / 2 = 4 (integer value of 4.5).
- So, 4 is the mid of the array.



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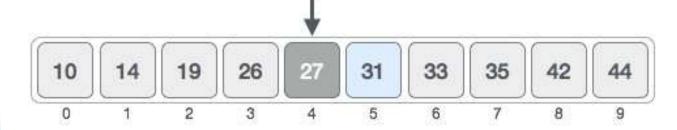
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Binary Search

 Now we compare the value stored at location 4, with the value being searched, i.e. 31.



- The value at location 4 is 27, which is not a match
- As the value is greater than 27 and we have a sorted array, so we also know that the target value must be in the upper portion of the array.



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The current situation is like this.



- We change our low to mid + 1 and find the new mid value again.
- low = mid + 1
- New mid = low + (high low) / 2
- Our new mid is 7.
- Compare the value stored at location 7 with our target value 31.





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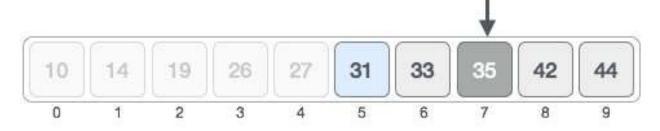
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The current situation is like this.



- The value stored at location 7 is not a match, rather it is more than what we are looking for.
- So, the value must be in the lower part from this location.



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The current situation is like this.



- Hence, we calculate the mid again. This time it is 5.
- compare the value stored at location 5 with our target value. We find that it is a match.





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Binary Search

- Procedure binary_search
- $A \leftarrow \text{sorted array}$,
- $n \leftarrow \text{size of array}$
- $x \leftarrow \text{value to be searched}$
- Set Low= 1,
- Set High = n
- while x not found
 - if High< Low EXIT: x does not exists.
 - set mid= Low + (High Low) / 2
 - if A[mid] < x set Low = Mid + 1
 - if A[mid] > x set High = mid 1
 - if A[mid] = x then exit
- end while
- end procedure



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Bubble Sort

- It is the simplest sorting algorithm that works by repeatedly swapping the adjacent elements if they are in wrong order.
- First Pass:
 (51428) -> (15428)
- Here, algorithm compares the first two elements, and swaps since 5 > 1.
- (1**54**28) -> (1**45**28), Swap since 5 > 4
- (14**52**8) -> (14**25**8), Swap since 5 > 2
- (14258) -> (14258), Now, since these elements are already in order (8 > 5), algorithm does not swap them.



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Second Pass:

- **■** (**14**258) -> (**14**258)
- (14258) -> (12458), Swap since 4 > 2
- (12**45**8) -> (12**45**8)
- (124**58**) -> (124**58**)
- Now, the array is already sorted, but our algorithm does not know if it is completed.
- The algorithm needs one whole pass without any swap to know it is sorted.



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Third Pass:

- **■** (**12**458) -> (**12**458)
- **■** (1**24**58) -> (1**24**58)
- (12**45**8) -> (12**45**8)
- **■** (124**58**) -> (124**58**)



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```
Algorithm 2: Improved Bubble Sort
```

```
Data: Input array A//
Result: Sorted A[]
int i, j, k;
indicator = 1;
N = length(A);
for j = 1; j \leq (N-1) \wedge indicator == 1; j + + do
   indicator = 0;
   for i = 1 to N-1; i++ do
      if A[i] > A[i+1] then
          temp = A/i;
          A[i] = A[i+1];
          A[i+1] = temp;
          indicator = 1;
      end
   end
end
```

https://www.baeldung.com



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Main References

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