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- 1. Write a C program to define 3 different threads with the following purposes where N is the input
 - Thread A-To run a loop and return the sum of first N prime numbers
 - Thread B & C should run in parallel. One prints "Thread 1 running" every 2 seconds, and the other prints "Thread 2 running" every 3 seconds for 100 seconds.

PROGRAM:

```
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>
#include <unistd.h>
#include <time.h>
// Function to check if a number is prime
int is prime(int num) {
  if (num < 2) return 0;
  for (int i = 2; i * i \le num; i++) {
    if (num \% i == 0)
       return 0:
  return 1;
// Thread A: Calculate sum of first N prime numbers
void* threadA func(void* arg) {
  int N = *(int*)arg;
  int count = 0, num = 2, sum = 0;
  while (count \leq N) {
    if (is prime(num)) {
       sum += num;
       count++;
     }
    num++;
  printf("Thread A: Sum of first %d prime numbers is %d\n", N, sum);
  pthread exit(NULL);
// Thread B: Print message every 2 seconds for 100 seconds
void* threadB func(void* arg) {
  time t start = time(NULL);
  while (time(NULL) - start < 100) {
     printf("Thread 1 running\n");
     sleep(2);
  pthread exit(NULL);
```

```
// Thread C: Print message every 3 seconds for 100 seconds
void* threadC func(void* arg) {
  time t start = time(NULL);
  while (time(NULL) - start \leq 100) {
    printf("Thread 2 running\n");
    sleep(3);
  pthread_exit(NULL);
int main() {
  int N;
  printf("Enter value for N: ");
  scanf("%d", &N);
  pthread t threadA, threadB, threadC;
  // Create threads
  pthread create(&threadA, NULL, threadA func, &N);
  pthread create(&threadB, NULL, threadB func, NULL);
  pthread create(&threadC, NULL, threadC func, NULL);
  // Wait for threads to finish
  pthread join(threadA, NULL);
  pthread join(threadB, NULL);
  pthread join(threadC, NULL);
  return 0;
```

OUTPUT:

```
Enter value for N: 5
Thread A: Sum of first 5 prime numbers is 28
Thread 1 running
Thread 2 running
Thread 1 running
Thread 2 running
Thread 1 running
Thread 2 running
Thread 1 running
Thread 1 running
Thread 1 running
Thread 1 running
Thread 2 running
Thread 2 running
Thread 2 running
Thread 1 running
```

- 2. In the above program,
 - > add signal handling for SIGINT (etc) and prevent termination.
 - Convert the above threads to individual functions and note down the time taken and the flow of execution

PROGRAM:

```
#include <stdio.h>
#include <stdlib.h>
#include <pthread.h>
#include <unistd.h>
#include <signal.h>
#include <time.h>
// Global control flag for threads
volatile sig atomic t keep running = 1;
// Signal handler for SIGINT (Ctrl + C)
void sigint handler(int sig) {
  printf("\nSIGINT received. Ignoring and continuing execution...\n");
  keep running = 0;
// Function to check if a number is prime
int is prime(int num) {
  if (num < 2) return 0;
  for (int i = 2; i * i \le num; i++) {
     if (num \% i == 0)
       return 0;
  return 1;
// Thread A: Computes sum of first N prime numbers
void* threadA func(void* arg) {
  int N = *(int*)arg;
  int count = 0, num = 2, sum = 0;
  printf("Thread A: Starting computation of prime numbers...\n");
  while (count < N && keep running) {
    if (is prime(num)) {
       sum += num;
       count++;
    num++;
  if (keep running)
```

```
printf("Thread A: Sum of first %d prime numbers is %d\n", N, sum);
  else
    printf("Thread A: Interrupted. Partial sum = %d\n", sum);
  pthread_exit(NULL);
// Thread B: Prints message every 2 seconds for 100 seconds
void* threadB func(void* arg) {
  time t start = time(NULL);
  printf("Thread B: Started...\n");
  while (keep running && time(NULL) - start < 100) {
    printf("Thread 1 running\n");
     sleep(2);
  printf("Thread B: Finished.\n");
  pthread exit(NULL);
// Thread C: Prints message every 3 seconds for 100 seconds
void* threadC func(void* arg) {
  time t start = time(NULL);
  printf("Thread C: Started...\n");
  while (keep running && time(NULL) - start < 100) {
    printf("Thread 2 running\n");
    sleep(3);
  }
  printf("Thread C: Finished.\n");
  pthread exit(NULL);
int main() {
  int N:
  pthread t threadA, threadB, threadC;
  // Set up signal handler
  signal(SIGINT, sigint handler);
  // Get input
  printf("Enter the value of N (for prime sum): ");
  scanf("%d", &N);
  // Start real-time tracking
  time t begin = time(NULL);
```

```
// Create threads
pthread_create(&threadA, NULL, threadA_func, &N);
pthread_create(&threadB, NULL, threadB_func, NULL);
pthread_create(&threadC, NULL, threadC_func, NULL);

// Wait for threads to finish
pthread_join(threadA, NULL);
pthread_join(threadB, NULL);
pthread_join(threadC, NULL);

// End time and calculate duration
time_t end = time(NULL);
double elapsed_time = difftime(end, begin);
printf("Main: Total execution time = %.2f seconds\n", elapsed_time);

return 0;
}
```

OUTPUT:

```
Enter the value of N (for prime sum): 10
Thread B: Started...
Thread 1 running
Thread C: Started...
Thread 2 running
Thread A: Starting computation of prime numbers...
Thread A: Sum of first 10 prime numbers is 129
Thread 1 running
Thread 2 running
Thread 1 running
Thread 2 running
Thread 1 running
Thread 1 running
Thread 2 running
Thread 1 running
SIGINT received. Ignoring and continuing execution...
Thread C: Finished.
Thread B: Finished.
Main: Total execution time = 12.00 seconds
...Program finished with exit code 0
Press ENTER to exit console.
```

3. Know about the following topics and explore them (Write a note on your understandings)
Areas for exploration,

1. Child Process – fork()

- fork() is a system call in Unix/Linux that creates a new process by duplicating the calling process.
- The new process is called a child, and the original is the parent.
- After a successful fork():
 - o The parent receives the child's PID.
 - o The child receives 0.
- If return value is $> 0 \rightarrow Parent$, $== 0 \rightarrow Child$, $< 0 \rightarrow Error$ (fork failed)
- Both processes continue executing from the point where fork() was called, but independently.

Example:

```
pid_t pid = fork();

if (pid == 0) {
    printf("Child Process\n");
} else if (pid > 0) {
    printf("Parent Process, Child PID = %d\n",
pid);
} else {
    printf("Process Failed\n");
}
```

2. Handling Common Signals

• Signals are asynchronous notifications sent to a process to notify it of events (e.g., termination request, invalid memory access).

Common Signals:

- SIGINT Ctrl+C (interrupt)
- SIGTERM Terminate gracefully
- SIGKILL Force kill (cannot be caught)
- SIGSEGV Invalid memory access (segmentation fault)
- SIGFPE- Floating Point Exception

- SIGILL- Illegal Instruction
- SIGABRT- Abort

Signal Handling: using the signal() or sigaction() function.

Example:

```
void handler(int sig) {
   printf("Caught signal %d\n", sig);
}
signal(SIGINT, handler);
```

This allows program to intercept and handle signals instead of terminating unexpectedly.

3. Exploring Different Kernel Crashes

Kernel crashes (also called kernel panics) occur when the Linux kernel encounters a fatal error it cannot recover from.

- ➤ Common Causes: Faulty drivers, Null pointer dereference in kernel space, Buffer overflows, Race conditions, Stack overflows, Deadlocks
- > Symptoms: System freeze or reboot and Panic logs in /var/log/kern.log or dmesg
- ➤ Tools for Analysis: dmesg: Check kernel ring buffer, kdump: Capture kernel crash dumps, gdb with kernel symbols: Debug the crash
- ➤ Preventive Measures: By Using proper locking mechanism, by Validating memory access and by Testing kernel modules thoroughly

4. Time Complexity

Time complexity measures how the runtime of an algorithm increases with input size. Analysing Time complexity helps in selecting the most efficient algorithm for large input sizes and optimizing program performance.

Common Notations:

- O(1) Constant time
- O(log n) Logarithmic time
- O(n) Linear time
- $O(n^2)$ Quadratic time
- $O(2^n)$ Exponential time

Example:

A loop running n times is O(n). A nested loop on n elements is $O(n^2)$.

5. Mutex/Spinlock:

Feature	Mutex	Spinlock
Waiting Behaviour	Puts thread to sleep if lock is	Busy-waits (keeps checking until
	unavailable	lock is free)
CPU Usage While	Low (since thread sleeps)	High (uses CPU cycles while
Waiting		spinning)
Context Switching	Yes (can cause overhead)	No (remains in same context)
Lock Hold Duration	Suitable for longer critical	Suitable for very short critical
	sections	sections
Fairness	Can be fair (depends on	May cause starvation (no
	implementation)	queuing)
Power Consumption	Lower	Higher (CPU is active while
		spinning)
Performance	Better for multitasking	Better for real-time or low-
	systems	latency tasks
Use Case Example	File access, I/O operations	Low-level kernel locks, short ops
		in SMP systems