$$\hat{\theta} = \underset{i=1}{\operatorname{argmin}} \underbrace{Z}_{i} di \left( y_{i} - z_{i}^{T} \theta \right)$$

$$\hat{\theta} = \underset{i=1}{\operatorname{argmin}} \underbrace{Z}_{i} d_{i} (y_{i} - z_{i}^{T} \theta)$$

$$J(\theta) = \sum_{i=1}^{N} di \left( y_i - x_i^T \theta \right)^2$$

$$= (y - x\theta)^{T} D (y - x\theta) ; D = \begin{bmatrix} d_{1} & 0 & \cdots \\ 0 & d_{2} & \cdots \end{bmatrix}$$

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$$= (y^{T} - \theta^{T} x^{T})(Dy - Dx\theta)$$

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$$J(\theta) = y^T O y - 2y^T D^T \times \theta + \theta^T \times D \times \theta$$

$$J(\theta) = y^T O y - 2y^T D^T X \theta + \theta^T X^T D X \theta$$

$$\frac{\partial J(b)}{\partial \theta} = 0 \Rightarrow \frac{\partial}{\partial \theta} \left( -2y^T O^T y \Theta \right) + \frac{\partial}{\partial \theta} \Theta^T x^T O x \Theta = 0$$

$$\Rightarrow 2x^{T}0y = 2x^{T}0x\theta$$

$$\hat{\Theta} = (x^T D x)^T x^T D y$$