## Davidson

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## 1 Davidson Algorithm

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The Davidson algorithm is an efficient way to find a number of the lowest (or highest) valued eigenvalues of a large, diagonally dominant matrix. The general goal of the algorithm is to solve the eigenvalue problem for the matrix in question in a gradually growing subspace of orthonormal vectors and hope the eigenvector that corresponds to the lowest (or highest) valued eigenvalue exists in the span of this subspace. The main steps are:

- 1. Guess an orthonormal basis of vectors with dimension greater than the number of eiegenvalues you are solving for
- 2. Calculate the residue vector and check for convergence. The residue vector is the vector left over after trying to solve the eiegenvalue problem with the guess vectors
- 3. Calculate the correction vector based on the residue vector and the approximate eigenvalue pairs
- 4. Add the correction vectors to your orthonormal subspace and repeat starting from step 2

The written function can be seen below.

```
In [1]: import math
        import numpy as np
        def Davidson(H_func, H_diag, neig):
                                                  #input Direct Method Hamiltonian, Diagonal of E
                                                      #number of vectors in initial sample space
                a = 8
                tol = 1e-8
                n = len(H_diag)
                                                        #set of test unit vectors in initial samp
                t = np.eye(n,a)
                V = np.zeros((n,a))
                                                   #array to store sample space
                for i in range(a):
                                                   #input test vectors into sample space matrix
                        V[:,i] = t[:,i]
                                                  #initialize old and new eigenvalue guesses, "I
                theta_old = np.zeros(neig)
                theta_new = np.ones(neig)
                count = 1
                                                  #keep track of number of iterations
```

```
while np.linalg.norm(theta_old-theta_new) > tol:
        theta_old = theta_new
                                   #step theta
        V,R = np.linalg.qr(V)
                                     #use python's QR decomp. to ensure sample s
        HV = np.zeros((n,a*count))
        for i in range(a*count):
                HV[:,i] = H_func(V[:,i])
        VHV = np.dot(V[:,:(a*count)].T,HV) #build matrix in subspace
        theta,s = np.linalg.eig(VHV)
                                            #diagonalize
        index = np.argsort(theta)
                                       #sort eigenvalues and eigenvectors
        theta = theta[index]
        s = s[:,index]
        V = np.c_{V,np.zeros((n,a))}
                                            #grow sample space matrix
        for i in range(a):
                                          #loop through test vectors
                test = np.dot(V[:,:(a*count)],s[:,i])
                                                             #change basis of en
                r = H_func(test) - theta[i]*test
                                                      #calculate residue vecto
                q = -(1/H_diag[i] - 1/theta[i])*r
                                                        #calculate correction v
                V[:,(i+(a*count))] = q
                                                              #add correction ve
        theta_new = theta[:neig]
                                                        #update quesses to eigen
        count = count + 1
return theta_new
```

To test the algorithm, I made a test script that constructed a diagonally dominant matrix and computed the 4 lowest valued eigenvalues and compared the calculation time to the eiegenvalue solver in numpy.

```
In [6]: import numpy as np
        import Davidson as D
        import time
        #Build diagonally dominant Hamiltonian and Direct method function of Hamiltonian
        H = np.zeros((n,n))
        r = range(n)
        for i in r:
                H[i,i] = i+1
                                    #take diagonal elements to be increasing integer values
                                            #take off diagonal elements to be decreasing in order
                for j in r[(i+1):]:
                        H[i,j] = (10**(i-j+1))
        H = (H.T + H)/2
                                 #make direct method function
        def A(v):
                return np.dot(H,v)
        #Davidson
        start_davidson = time.time()
        E = D.Davidson(A, np.diag(H), 4)
```

```
end_davidson = time.time()

start_numpy = time.time()

print("Davidson = ", E,":",end_davidson-start_davidson, "seconds")

#Numpy

start_numpy = time.time()

E,V = np.linalg.eig(H)
E = np.sort(E)

end_numpy = time.time()

print("Numpy = ", E[:4],":",end_numpy - start_numpy, "seconds")

Davidson = [0.78251653 1.9679405 2.99718315 3.9998414] : 0.030191659927368164 seconds
Numpy = [0.78251653 1.9679405 2.99718315 3.9998414] : 9.659271717071533 seconds
```

Running on the virtual machine on my personal computer, the Davidson algorithm calculated the 4 lowest eigenvalues of a 1500x1500 diagonally dominant matrix with a high degree of accuracy in almost 0.03 seconds, compared to numpy in almost 10. Not to bad (if you ignore the fact numpy calculated the entire eigenvalue spectrum).