Motor

+ present_velocity: double
+ target_voltage: double
+ present_voltage: double
+ margin_of_error: double
+ target_velocity: double

+ drive() : double

PID

- Kp: double
- Ki: double
- Kd: double
- dt: double
- prev_error: double
- integral: double
- max_voltage: double
- min_voltage: double

+ calculate() : double