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1 # Sapan Sharma, 6352819, COSC 4P80
2 import os
3 import numpy as np
4 import random
5 from scipy.stats import shapiro
6 from scipy.stats import ttest_ind
7 from sklearn.utils import shuffle
8 from sklearn.model_selection import train_test_split
9 import matplotlib.pyplot as plt
10 import tensorflow as tf
11 from tensorflow import keras
12 import pandas as pd
13 import statsmodels.api as sm
14 from statsmodels.formula.api import ols
15
16 Data2019 = os.path.join(os.getcwd(), "Data2019") # it will get path from current directory of folder
17 GridEyeData = os.path.join(os.getcwd(), "GridEyeData")
18
19 # Loading all files from disk to numpy arrays to process data. --Warning-- only tested on a windows machine.
20 # numpy arrays are loaded from files without first 2 lines of header
21 # First column(0) of thermistor reading is removed from array on axis = 1
22 control_nothing = np.delete(np.genfromtxt(os.path.join(Data2019, "control", "nothing") , skip_header = 2), 0, 1)
23 indoors_none_blank =np.delete(np.genfromtxt(os.path.join(GridEyeData, "indoors", "none", "blank.txt") , skip_header = 2), 0, 1)
24 indoors_single_1foot =np.delete(np.genfromtxt(os.path.join(GridEyeData, "indoors", "single", "1foot.txt") , skip_header = 2), 0, 1)
25 indoors_single_3feet =np.delete(np.genfromtxt(os.path.join(GridEyeData, "indoors", "single", "3feet.txt") , skip_header = 2), 0, 1)
26 indoors_single_8feet =np.delete(np.genfromtxt(os.path.join(GridEyeData, "indoors", "single", "8feet.txt") , skip_header = 2), 0, 1)
27 indoors_two_3foot =np.delete(np.genfromtxt(os.path.join(GridEyeData, "indoors", "two", "3foot.txt") , skip_header = 2), 0, 1)
28 indoors_three_3feet =np.delete(np.genfromtxt(os.path.join(GridEyeData, "indoors", "three", "3feet.txt") , skip_header = 2), 0, 1)
29 distance_1p1ft =np.delete(np.genfromtxt(os.path.join(Data2019, "distance", "1p1ft") , skip_header = 2), 0, 1)
30 control_1p3ft =np.delete(np.genfromtxt(os.path.join(Data2019, "control", "1p3ft") , skip_header = 2), 0, 1)
31 distance_1p6ft =np.delete(np.genfromtxt(os.path.join(Data2019, "distance", "1p6ft") , skip_header = 2), 0, 1)
32 qty_2p3ft = np.delete(np.genfromtxt(os.path.join(Data2019, "qty", "2p3ft") , skip_header = 2), 0, 1)
33 qty_3p3ft = np.delete(np.genfromtxt(os.path.join(Data2019, "qty", "3p3ft") , skip_header = 2), 0, 1)
34 outdoors_nothingo =np.delete(np.genfromtxt(os.path.join(Data2019, "outdoors", "nothingo") , skip_header = 2), 0, 1)
35 outdoors_none_blank =np.delete(np.genfromtxt(os.path.join(GridEyeData, "outdoors", "none", "blank.txt") , skip_header = 2), 0, 1)
36 outdoors_1p1fto =np.delete(np.genfromtxt(os.path.join(Data2019, "outdoors", "1p1fto") , skip_header = 2), 0, 1)
37 outdoors_single_1foot =np.delete(np.genfromtxt(os.path.join(GridEyeData, "outdoors", "single", "1foot.txt") , skip_header = 2), 0, 1)
38 outdoors_1p3fto =np.delete(np.genfromtxt(os.path.join(Data2019, "outdoors", "1p3fto") , skip_header = 2), 0, 1)
39 outdoors_single_6feet =np.delete(np.genfromtxt(os.path.join(GridEyeData, "outdoors", "single", "6feet.txt") , skip_header = 2), 0)

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39 , 1)

40 # creating labels for each file according to the information provided in the file and storing into a ndarray
41 # Labels are as:
42 # "Location": [{"Outdoor": 0, "Indoor": 1},
43 # "Subject Quantity": [{"None": 0, "Single":1, "Two": 2, "Three": 3},
44 # "Presence": [{"Absence": 0, "Presence": 1},
45 # "Distance": [{"Dist 1": 0, "Dist 3": 1, "Dist 6/8": 2}

46 # label_control_nothing = np.tile([1,0,0,np.nan], (control_nothing.shape[0],1))
47 label_indoors_none_blank = np.tile([1,0,0,np.nan], (indoors_none_blank.shape[0],1))
48 label_indoors_single_1foot = np.tile([1,1,1,0], (indoors_single_1foot.shape[0],1))
49 label_indoors_single_3feet = np.tile([1,1,1,1], (indoors_single_3feet.shape[0],1))
50 label_indoors_single_8feet = np.tile([1,1,1,2], (indoors_single_8feet.shape[0],1))
51 label_indoors_two_3foot = np.tile([1,2,1,1], (indoors_two_3foot.shape[0],1))
52 label_indoors_three_3feet = np.tile([1,3,1,1], (indoors_three_3feet.shape[0],1))
53 label_distance_1p1ft = np.tile([np.nan,1,1,0], (distance_1p1ft.shape[0],1))
54 label_distance_1p3ft = np.tile([np.nan,1,1,1], (distance_1p3ft.shape[0],1))
55 label_distance_1p6ft = np.tile([np.nan,1,1,2], (distance_1p6ft.shape[0],1))
56 label_qty_2p3ft = np.tile([np.nan,2,1,1], (qty_2p3ft.shape[0],1))
57 label_qty_3p3ft = np.tile([np.nan,3,1,1], (qty_3p3ft.shape[0],1))
58 label_outdoors_nothingo = np.tile([0,0,0,np.nan], (outdoors_nothingo.shape[0],1))
59 label_outdoors_none_blank = np.tile([0,0,0,np.nan], (outdoors_none_blank.shape[0],1))
60 label_outdoors_1p1fto = np.tile([0,1,1,0], (outdoors_1p1fto.shape[0],1))
61 label_outdoors_single_1foot = np.tile([0,1,1,0], (outdoors_single_1foot.shape[0],1))
62 label_outdoors_1p3fto = np.tile([0,1,1,1], (outdoors_1p3fto.shape[0],1))
63 label_outdoors_single_6feet = np.tile([0,1,1,2], (outdoors_single_6feet.shape[0],1))

64 # dictionary to find out class name from a given attribute like distance or location
65 # print(class_categories_names["Distance"][1])#instead of 1 goes prediction of neural net using model.predict_classes(X)
66 class_categories_names = {
67     "Location": [{"Outdoor": "Indoor"}, {"Indoor": "Outdoor"}],
68     "Subject Quantity": [{"None": "None", "Single": "Single", "Two": "Two", "Three": "Three"}],
69     "Presence": [{"Absence": "Absence", "Presence": "Presence"}],
70     "Distance": [{"Dist 1": "Dist 1", "Dist 3": "Dist 3", "Dist 6/8": "Dist 6/8"}]
71 }
72
73
74
75
76 # creating datasets and labels to use for MLP models. Datasets and labels are created according to the identified
77 # files which answers the required questions. Like dist_in_1_dataset uses all files which have 1 object indoors with
78 # different distance so it is used to classify distance of object indoors.
79
80 # concatenates different datasets along 0 axis
81 # concatenates different labels along 0 axis and choose only label which answers question and is required from label

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82 # arr and converts to integer as previously these arrays had np.nan values. (conversion for cross entropy loss function)
83
84 dist_in_1_dataset = np.concatenate((indoors_single_1foot,indoors_single_3feet,indoors_single_8feet), axis = 0)
85 dist_in_1_label = np.concatenate((label Indoors_single_1foot, label Indoors_single_3feet, label Indoors_single_8feet), axis = 0
86 )[: ,3]. astype(int)
87 dist_unknown_dataset = np.concatenate((distance_1p1ft, control_1p3ft, distance_1p6ft), axis = 0)
88 dist_out_dataset = np.concatenate((label_distance_1p1ft, label_control_1p3ft, label_distance_1p6ft), axis = 0)
89 dist_out_label = np.concatenate((label_outdoors_1p1fto, outdoors_single_1foot, outdoors_1p3fto, outdoors_single_6feet), axis = 0)
90 presence_in_dataset = np.concatenate((control_nothing, indoors_none_blank, indoors_single_1foot,indoors_single_3feet,
91 indoors_single_8feet, indoors_two_3foot, indoors_three_3feet), axis = 0)
92 presence_in_label = np.concatenate((label_control_nothing, label Indoors_none_blank, label Indoors_single_1foot,
93 label Indoors_single_3feet, label Indoors_single_8feet, label Indoors_two_3foot, label Indoors_three_3feet), axis = 0)[: ,2]. astype
94 (int)
95 quantity_in_label = np.concatenate((label_control_nothing, label Indoors_none_blank, label Indoors_single_1foot,
96 label Indoors_single_3feet, label Indoors_single_8feet, label Indoors_two_3foot, label Indoors_three_3feet), axis = 0)[:,1]. astype
97 (int)
98 location_dataset = np.concatenate((control_nothing, indoors_none_blank, indoors_single_1foot,indoors_single_3feet,
99 outdoors_single_8feet, indoors_two_3foot, outdoors_1p3fto, outdoors_single_6feet), axis = 0)
100 location_label = np.concatenate((label_control_nothing, label Indoors_none_blank, label Indoors_single_1foot,
101 label Indoors_single_3feet, label Indoors_single_8feet, label Indoors_two_3foot, label Indoors_three_3feet,
102 label_outdoors_nothingo, label_outdoors_none_blank, label_outdoors_1p1fto, label_outdoors_single_1foot, label_outdoors_1p3fto,
103 def preprocess(X,y):
104
105 # pre-thresholding(clipping)- any data above 1000 is divided by 10 to prevent overexposure to radiation,
106 # overexposure affects the ability to adjust weights (find features) in the dataset.
107 np.divide(X, 10, out = X, where = X > 1000)
108 # normalization- perform min max feature scaling on data to bring them in a range of [0,1]

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109     max_v = np.max(X)
110     min_v = np.min(X)
111     X = np.array([(s - min_v) / (max_v - min_v) for s in X])
112     # shuffle the dataset in unison so that the labels and samples remain in same order
113     # shuffling will help neural network to process different instances as files are concatenated.
114     X, y = shuffle(X, y, random_state = 66)
115     # split dataset and labels into train(75%) and test(25%) for each using train test split function from sklearn.
116     X_train, X_test, y_train, y_test = train_test_split(X, y, shuffle=False)
117
118     return X_train, X_test, y_train, y_test
119
120
121     # get train test split of dataset and labels, get data after clipping, get data after normalization and shuffle. pheWW--
122     dist_in_1_dataset_train, dist_in_1_dataset_test, dist_in_1_label_train, dist_in_1_label_test = preprocess(dist_in_1_dataset,
123     dist_in_1_label)
124     dist_unknown_dataset_train, dist_unknown_dataset_test, dist_unknown_label_train, dist_unknown_label_test = preprocess(
125     dist_unknown_dataset, dist_unknown_label)
126     dist_out_dataset_train, dist_out_dataset_test, dist_out_label_train, dist_out_label_test = preprocess(
127     dist_out_label)
128     presence_in_dataset_train, presence_in_dataset_test, presence_in_label_train, presence_in_label_test = preprocess(
129     presence_in_dataset, presence_in_label)
130     presence_out_dataset_train, presence_out_dataset_test, presence_out_label_train, presence_out_label_test = preprocess(
131     presence_out_dataset, presence_out_label)
132     qty_in_dataset_train, qty_in_dataset_test, qty_in_label_train, qty_in_label_test = preprocess(qty_in_dataset, qty_in_label)
133     qty_unknown_dataset_train, qty_unknown_dataset_test, qty_unknown_label_train, qty_unknown_label_test = preprocess(
134     qty_unknown_dataset, qty_unknown_label)
135     location_dataset_train, location_dataset_test, location_label_train, location_label_test = preprocess(location_dataset,
136     location_label)
137
138     # user can input most hyperparameters to the function
139     def build_model_GD(n_hidden, n_neurons_list, activation_function, user_learning_rate, user_momentum, n_outputs, user_loss=""
140         sparse_categorical_crossentropy", output_activation="softmax"):
141         tf.keras.backend.clear_session() # to clear previous values and weights from tf backend
142         i = 0 # index to get value of neurons from neuron list
143         model = keras.models.Sequential() # adds layers sequentially
144         model.add(keras.layers.InputLayer(input_shape=[64,])) # input layer with shape (none, 64) where none is a batch axis

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144     for layer in range(n_hidden): # to create user given number of hidden layers
145         model.add(keras.layers.Dense(n_neurons_list[i], activation=activation_function))
146         i += 1
147     model.add(keras.layers.Dense(n_outputs, activation=output_activation)) # output layer with output function sigmoid or softmax
148     # initializing stochastic gradient descent optimizer which computes gradient descent step in its tape tree.
149     optimizer = keras.optimizers.SGD(learning_rate=user_learning_rate, momentum=user_momentum)
150     # if binary label classification calculate false positives and false negatives
151     if output_activation == "sigmoid":
152         metrics_list = ["accuracy", tf.keras.metrics.FalsePositives(), tf.keras.metrics.FalseNegatives()]
153     else:
154         metrics_list = ["accuracy"] # otherwise just accuracy
155         # compiling the model where random weights and bias weights are set loss function, gradient descent is initialized and metrics
156         # to calculate are loaded
157         model.compile(loss=user_loss, metrics=metrics_list, optimizer=optimizer)
158
159     # sparse categorical cross entropy loss and softmax output activation function unless different values passed
160     # sigmoid output activation function and binary crossentropy if labels are binary (yes or no/ presence or absence)
161     # softmax output activation function for the multi-classes which are exclusive and sparse categorical crossentropy loss function
162     # for sparse labels with target class index like 0,1,2,3 for multi-class output.
163
164     # user can input most hyperparameters to the function
165
166     def build_model_RMS(n_hidden, n_neurons_list, activation_function, user_learning_rate, user_momentum, n_outputs, user_rho = 0.9,
167         user_loss="sparse_categorical_crossentropy", output_activation="softmax"):
168         tf.keras.backend.clear_session() # to clear previous values and weights from tf backend
169         j = 0
170         model = keras.models.Sequential()
171         model.add(keras.layers.InputLayer(input_shape=[64, ]))
172         for layer in range(n_hidden):
173             model.add(keras.layers.Dense(n_neurons_list[j], activation=activation_function))
174             j += 1
175         model.add(keras.layers.Dense(n_outputs, activation=output_activation))
176         # RMSprop optimizer which is a variation for learning which maintains a moving average of square of gradients and divide the
177         # gradient by the root of that average.
178         # this adaptive learning rate method of gradient descent provides an alternative to classical stochastic gradient descent
179         # implemented above.
180         optimizer = keras.optimizers.RMSprop(learning_rate=user_learning_rate, momentum=user_momentum, rho=user_rho)
181         # Accuracy calculates accuracy according to the context of loss. If loss is binary cross entropy then it calculates how often
182         # predictions match binary labels.
183         # If loss is sparse categorical cross entropy then it calculates how often predictions matches integer labels.

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181 # FalsePositives class calculates the number of false positives and FalseNegatives class calculates the number of false
182 negatives.
183 # if binary label classification calculate false positives and false negatives
184 if output_activation == "sigmoid":
185     metrics_list = ["accuracy", tf.keras.metrics.FalsePositives(), tf.keras.metrics.FalseNegatives()]
186 else:
187     metrics_list = ["accuracy"] # otherwise just accuracy
188 model.compile(loss=user_loss, metrics=metrics_list, optimizer=optimizer)
189
190 def main():
191     print("Please ignore red warning, those are for GPU which is not connected in the env. And make sure inputs are correct as
192 there is no try catch block.")
193     print("Sample input for Gradient Descent: 1,2,20,10,relu,0.1,0,9,20.. Sample input for RMSprop: 2,2,20,10,relu,0.0009,0.9,0.9,
194 20..")
195     test_no = int(input("Do you want to perform ANOVA Test on different hyperparameters, if no enter 1. Otherwise, Enter number of
196 variants: "))
197     df_GD = []
198     df_RMS = []
199     for i in range(test_no):
200         print()
201         model_no = int(input("Enter 1 for Gradient Descent, and 2 for RMSprop: "))
202         n_hidden_v = int(input("Enter number of hidden Layer for test: "))
203         n_neurons_list_v = []
204         for i in range(n_hidden_v):
205             s = int(input("Enter number of neurons for "+str(i+1)+" hidden Layer: "))
206             n_neurons_list_v.append(s)
207         activation_function_v = input("Activation function for hidden layer: ")
208         if model_no == 1:
209             user_learning_rate_GD = float(input("Enter learning rate for Gradient Descent: "))
210             user_momentum_GD = float(input("Enter momentum for Gradient Descent: "))
211             user_rho_v = float(input("Enter rho value for RMSprop (Optimum: 0.3-0.9): "))
212             user_learning_rate_RMS = float(input("Enter learning rate for RMSprop (Optimum: 0.001-0.01): "))
213             user_momentum_RMS = float(input("Enter momentum for RMSprop (Optimum: 0.7-0.9): "))
214             epochs_v = int(input("Enter number of epochs (give 20): "))
215             if model_no == 2:
216                 user_rho_v = float(input("Enter rho value for RMSprop (Optimum: 0.7-0.9): "))
217                 subject = "# model_dist_in_1_dataset classifies 3 classes Dist 1': 0; Dist 3': 1; Dist 8': 2 for predicting distance indoor with 1
218                 subject = "# model_dist_unknown_dataset classifies 3 classes Dist 1': 0; Dist 3': 1; Dist 6': 2 for predicting distance unknown"

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218 location with 1 subject
219 # model_dist_out_dataset classifies 3 classes Dist 1': 0; Dist 3': 1; Dist 6': 2 for predicting distance outdoor with
220 different subject
221 # model_presence_in_dataset classifies binary label classes Presence: 0; Absence: 1; predicts if subject is present or
222 absent indoors
223 # model_presence_out_dataset classifies binary label Presence: 0; Absence: 1; predicts if subject is present or absent
224 outdoors
225 # model_location_dataset classifies binary label classes outdoor:0; Indoor:1; for predicting the location of the subject
226 irrespective of quantity or distance
227
228 if model_no == 1:
229     model_dist_in_1_dataset_GD = build_model_GD(n_hidden=n_hidden_v, n_neurons_list=n_neurons_list_v, activation_function=
activation_function_v, user_learning_rate=user_learning_rate_GD, user_momentum=user_momentum_GD, n_outputs=3, user_loss="sparse_categorical_crossentropy", output_activation="softmax")
230     print("Training Stats of dist_in_1_dataset_GD")
231     history_dist_in_1_dataset_GD = model_dist_in_1_dataset_GD.fit(dist_in_1_dataset_train, dist_in_1_label_train, verbose=
2, epochs=epochs_v)
232     print()
233     model_dist_unknown_dataset_GD = build_model_GD(n_hidden=n_hidden_v, n_neurons_list=n_neurons_list_v, activation_function=
activation_function_v, user_learning_rate=user_learning_rate_GD, user_momentum=user_momentum_GD, n_outputs=3, user_loss="sparse_categorical_crossentropy", output_activation="softmax")
234     print("Training Stats of dist_unknown_dataset_GD")
235     history_dist_unknown_dataset_GD = model_dist_unknown_dataset_GD.fit(dist_unknown_dataset_train,
dist_unknown_label_train, verbose=2, epochs=epochs_v)
236     print()
237     model_dist_out_dataset_GD = build_model_GD(n_hidden=n_hidden_v, n_neurons_list=n_neurons_list_v, activation_function=
activation_function_v, user_learning_rate=user_learning_rate_GD, user_momentum=user_momentum_GD, n_outputs=3, user_loss="sparse_categorical_crossentropy", output_activation="softmax")
238     print("Training Stats of dist_out_dataset_GD")
239     history_dist_out_dataset_GD = model_dist_out_dataset_GD.fit(dist_out_dataset_train, dist_out_label_train, verbose=2,
epochs=2, epochs=epochs_v)
240     print()
241     model_presence_in_dataset_GD = build_model_GD(n_hidden=n_hidden_v, n_neurons_list=n_neurons_list_v, activation_function=
activation_function_v, user_learning_rate=user_learning_rate_GD, user_momentum=user_momentum_GD, n_outputs=1, user_loss="binary_crossentropy", output_activation="sigmoid")
242     print("Training Stats of presence_in_dataset_GD")
243     history_presence_in_dataset_GD = model_presence_in_dataset_GD.fit(presence_in_dataset_train, presence_in_label_train,
verbose=2, epochs=epochs_v)

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243 activation_function_v, user_learning_rate=user_learning_rate_GD, user_momentum=user_momentum_GD, n_outputs=1, user_loss=""
binary_crossentropy, output_activation="sigmoid")
244 print("Training Stats of presence_out_dataset_GD")
245 history_presence_out_dataset_GD = model_presence_out_dataset_GD.fit(presence_out_dataset_train,
246 presence_out_label_train, verbose=2, epochs=epochs_v)
247 print()
248 model_qty_in_dataset_GD = build_model_GD(n_hidden=n_hidden_v, n_neurons_list=n_neurons_list_v, activation_function=
activation_function_v, user_learning_rate=user_learning_rate_GD, user_momentum=user_momentum_GD, n_outputs=4, user_loss=""
sparse_categorical_crossentropy, output_activation="softmax")
249 print("Training Stats of qty_in_dataset_GD")
250 history_qty_in_dataset_GD = model_qty_in_dataset_GD.fit(qty_in_dataset_train, qty_in_label_train, verbose=2, epochs=epochs_v)
251 print()
252 model_qty_unknown_dataset_GD = build_model_GD(n_hidden=n_hidden_v, n_neurons_list=n_neurons_list_v, activation_function=
activation_function_v, user_learning_rate=user_learning_rate_GD, user_momentum=user_momentum_GD, n_outputs=4, user_loss=""
sparse_categorical_crossentropy, output_activation="softmax")
253 print("Training Stats of qty_unknown_dataset_GD")
254 history_qty_unknown_dataset_GD = model_qty_unknown_dataset_GD.fit(qty_unknown_dataset_train, qty_unknown_label_train,
verbose=2, epochs=epochs_v)
255 print()
256 model_location_dataset_GD = build_model_GD(n_hidden=n_hidden_v, n_neurons_list=n_neurons_list_v, activation_function=
activation_function_v, user_learning_rate=user_learning_rate_GD, user_momentum=user_momentum_GD, n_outputs=1, user_loss=""
binary_crossentropy, output_activation="sigmoid")
257 print("Training Stats of location_dataset_GD:")
258 history_location_dataset_GD = model_location_dataset_GD.fit(location_dataset_train, location_label_train, verbose=2,
epochs=epochs_v)
259 print("Model evaluations on test data set: ")
260 evaluate_dist_in_1_dataset_train_GD = model_dist_in_1_dataset_GD.evaluate(dist_in_1_dataset_test,
dist_in_1_label_test)
261 evaluate_dist_unknown_dataset_train_GD = model_dist_unknown_dataset_GD.evaluate(dist_unknown_dataset_test,
dist_unknown_label_test)
262 evaluate_dist_out_dataset_train_GD = model_dist_out_dataset_GD.evaluate(dist_out_dataset_test, dist_out_label_test)
263 evaluate_presence_in_dataset_train_GD = model_presence_in_dataset_GD.evaluate(presence_in_dataset_test,
presence_in_label_test)
264 evaluate_presence_out_dataset_train_GD = model_presence_out_dataset_GD.evaluate(presence_out_dataset_test,
presence_out_label_test)
265 evaluate_qty_in_dataset_train_GD = model_qty_in_dataset_GD.evaluate(qty_in_dataset_test, qty_in_label_test)
266 evaluate_qty_unknown_dataset_train_GD = model_qty_unknown_dataset_GD.evaluate(qty_unknown_dataset_test,
qty_unknown_label_test)
267 evaluate_location_dataset_train_GD = model_location_dataset_GD.evaluate(location_dataset_test, location_label_test)
268 print()
269 print("Hyperparameters for this run: Model"+str(model_no)+"_Hidden:"+str(n_hidden_v)+"_Neurons"+str(n_neurons_list_v)+"

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269 "LR"+str(user_learning_rate_6D)+"_M"+str(user_momentum_6D))
270
271     if model_no == 2:
272         model_dist_in_1_dataset_RMS = build_model_RMS(n_hidden=n_hidden_v,n_neurons_list=n_neurons_list_v,activation_function=
activation_function_v,user_learning_rate=user_learning_rate_RMS,user_momentum=user_momentum_RMS, user_rho=user_rho_v, n_outputs=3,
user_loss= "sparse_categorical_crossentropy", output_activation="softmax")
273         print("Training Stats of dist_in_1_dataset_RMS")
274         history_dist_in_1_dataset_RMS = model_dist_in_1_dataset_RMS.fit(dist_in_1_dataset_train, dist_in_1_label_train,
verbose=2,epochs=epochs_v)
275         print()
276         model_dist_unknown_dataset_RMS = build_model_RMS(n_hidden=n_hidden_v,n_neurons_list=n_neurons_list_v,
activation_function=activation_function_v,user_learning_rate=user_learning_rate_RMS,user_momentum=user_momentum_RMS, user_rho=
user_rho_v,n_outputs=3,user_loss= "sparse_categorical_crossentropy", output_activation="softmax")
277         print("Training Stats of dist_unknown_dataset_RMS")
278         history_dist_unknown_dataset_RMS = model_dist_unknown_dataset_RMS.fit(dist_unknown_dataset_train,
dist_unknown_label_train, verbose=2,epochs=epochs_v)
279         print()
280         model_dist_out_dataset_RMS = build_model_RMS(n_hidden=n_hidden_v,n_neurons_list=n_neurons_list_v,activation_function=
activation_function_v,user_learning_rate=user_learning_rate_RMS,user_momentum=user_momentum_RMS, user_rho=user_rho_v,n_outputs=3,
user_loss= "sparse_categorical_crossentropy", output_activation="softmax")
281         print("Training Stats of dist_out_dataset_RMS")
282         history_dist_out_dataset_RMS = model_dist_out_dataset_RMS.fit(dist_out_dataset_train, dist_out_label_train, verbose=2,
epochs=epochs_v)
283         print()
284         model_presence_in_dataset_RMS = build_model_RMS(n_hidden=n_hidden_v,n_neurons_list=n_neurons_list_v,
activation_function=activation_function_v,user_learning_rate=user_learning_rate_RMS,user_momentum=user_momentum_RMS, user_rho=
user_rho_v,n_outputs=1,user_loss= "binary_crossentropy",output_activation="sigmoid")
285         print("Training Stats of presence_in_dataset_RMS")
286         history_presence_in_dataset_RMS = model_presence_in_dataset_RMS.fit(presence_in_dataset_train,presence_in_label_train
, verbose=2,epochs=epochs_v)
287         print()
288         model_presence_out_dataset_RMS = build_model_RMS(n_hidden=n_hidden_v,n_neurons_list=n_neurons_list_v,
activation_function=activation_function_v,user_learning_rate=user_learning_rate_RMS,user_momentum=user_momentum_RMS, user_rho=
user_rho_v,n_outputs=1,user_loss= "binary_crossentropy",output_activation="sigmoid")
289         print("Training Stats of presence_out_dataset_RMS")
290         history_presence_out_dataset_RMS = model_presence_out_dataset_RMS.fit(presence_out_dataset_train,
presence_out_label_train, verbose=2,epochs=epochs_v)
291         print()
292         model_qty_in_dataset_RMS = build_model_RMS(n_hidden=n_hidden_v,n_neurons_list=n_neurons_list_v,activation_function=
activation_function_v,user_learning_rate=user_learning_rate_RMS,user_momentum=user_momentum_RMS, user_rho=user_rho_v,n_outputs=4,
user_loss= "sparse_categorical_crossentropy", output_activation="softmax")
293         print("Training Stats of qty_in_dataset_RMS")
294         history_qty_in_dataset_RMS = model_qty_in_dataset_RMS.fit(qty_in_dataset_train, qty_in_label_train, verbose=2,epochs=2,epochch=

```

```

294 epochs_v)
295     print()
296     model_qty_unknown_dataset_RMS = build_model_RMS(n_hidden=n_hidden_v, n_neurons_list=n_neurons_list_v,
297 activation_function=activation_function_v, user_learning_rate=user_learning_rate_RMS, user_momentum=RMS, user_rho=
298 user_rho_v, n_outputs=4, user_loss= "sparse_categorical_crossentropy" , output_activation="softmax")
299     history_qty_unknown_dataset_RMS = model_qty_unknown_dataset_RMS.fit(qty_unknown_dataset_train, qty_unknown_label_train
300     , verbose=2, epochs=epochs_v)
301     print()
302     model_location_dataset_RMS = build_model_RMS(n_hidden=n_hidden_v, n_neurons_list=n_neurons_list_v,activation_function=
303 activation_function_v, user_learning_rate=user_learning_rate_RMS, user_momentum=user_momentum_RMS, user_rho=user_rho_v, n_outputs=1,
304 user_loss="binary_crossentropy",output_activation="sigmoid")
305     print("Training Stats of location_dataset_RMS:")
306     history_location_dataset_RMS = model_location_dataset_RMS.fit(location_dataset_train, location_label_train, verbose=2,
307 epochs=epochs_v)
308     print()
309     print("Model evaluations on test data set: ")
310     evaluate_dist_in_1_dataset_test_RMS = model_dist_in_1_dataset.evaluate( dist_in_1_dataset_test,
311 dist_in_1_label_test)
312     evaluate_dist_unknown_dataset_train_RMS = model_dist_unknown_dataset_RMS.evaluate(dist_unknown_dataset_test,
313 dist_unknown_label_test)
314     evaluate_dist_out_dataset_train_RMS = model_dist_out_dataset_RMS.evaluate(dist_out_dataset_test, dist_out_label_test)
315     evaluate_presence_in_dataset_train_RMS = model_presence_in_dataset_RMS.evaluate(presence_in_dataset_test,
316 presence_in_label_test)
317     evaluate_presence_out_dataset_train_RMS = model_presence_out_dataset_RMS.evaluate(presence_out_dataset_test,
318 presence_out_label_test)
319     evaluate_qty_in_dataset_train_RMS = model_qty_in_dataset_RMS.evaluate(qty_in_dataset_test, qty_in_label_test)
320     evaluate_qty_unknown_dataset_train_RMS = model_qty_unknown_dataset_RMS.evaluate(qty_unknown_dataset_test,
321 qty_unknown_label_test)
322     evaluate_location_dataset_train_RMS = model_location_dataset_RMS.evaluate(location_dataset_test, location_label_test)
323     print()
324     print("Hyperparameters for this run: Model"+str(model_no)+"_Hidden:"+str(n_hidden_v)+"_Neurons"+str(n_neurons_list_v)+"
325 " _LR"+str(user_learning_rate_RMS)+"_M"+str(user_momentum_RMS))
326     if test_no > 1:
327         if model_no == 1:
328             test_name = "GD"+"_"+str(n_hidden_v)+"_"+str(n_neurons_list_v)+"_"+str(user_learning_rate_GD)+"_"+str(
329 user_momentum_GD)
330             GD_1 = (evaluate_dist_in_1_dataset_train_GD[1],
331 evaluate_dist_unknown_dataset_train_GD[1],
332 evaluate_dist_out_dataset_train_GD[1],
333 evaluate_presence_in_dataset_train_GD[1]
334 evaluate_presence_out_dataset_train_GD[1],
335 )

```

```

324     evaluate_qty_in_dataset_train_GD[1],
325     evaluate_qty_unknown_dataset_train_GD[1],
326     evaluate_location_dataset_train_GD[1],
327
328     df_GD[test_name] = GD_1
329
330     test_name = "RMS"+"_"+str(n_hidden_V)+"_"+str(n_neurons_list_V)+"_"+str(user_learning_rate_RMS)+"_"+str(
331         user_momentum_RMS)
332
333     RMS_1 = (evaluate_dist_in_1_dataset_train_RMS[1],
334             evaluate_dist_unknown_dataset_train_RMS[1],
335             evaluate_dist_out_dataset_train_RMS[1],
336             evaluate_presence_in_dataset_train_RMS[1],
337             evaluate_presence_out_dataset_train_RMS[1],
338             evaluate_qty_in_dataset_train_RMS[1],
339             evaluate_qty_unknown_dataset_train_RMS[1],
340             evaluate_location_dataset_train_RMS[1],)
341
342     df_RMS[test_name] = RMS_1
343
344     # doing statistical tests
345     if model_no == 1:
346         experiment1 = pd.DataFrame(df_GD)
347         experiment1.index.name = 'Dataset No'
348         print()
349         print("Accuracy of all tests in- Gradient_hiddenLayers_neuronsList_LearningRate_Momentum: ")
350         print()
351         print(experiment1.describe()) # mean, std. dev, IQ ranges, min, max
352         print()
353         fig1, ax1 = plt.subplots() # boxplot for initial reference
354         ax1.set_title('Plot')
355         ax1.boxplot(experiment1)
356         plt.show()
357
358         # shapiro test
359         # testing null hypothesis if data is normally distributed.
360         # if p-value greater than 0.05 it is, otherwise reject the hypothesis
361         print("Shapiro test")
362         for col, val in experiment1.iteritems():
363             for col, val in experiment1.iteritems():
364                 print(col, end=' ')
365                 stat, p = shapiro(val)
366                 print('stats=%4f, p=%4f' % (stat,p))

```

```

366 # ANOVA test
367 # Hypothesis that mean of all datasets are not statistically different from each other.
368 # Hypothesis holds if p-value>0.05
369 # Otherwise there exist a better mean of all which can be found with T-test
370 # Last minute bug
371 print()
372 print("ANOVA test")
373 ana_model = ols('experiment1.iloc[:,0]~experiment1.iloc[:,1]+experiment1.iloc[:,2]', experiment1).fit()
374 anova_table = sm.stats.anova_lm(ana_model, typ=2)
375 print(anova_table)

376 # t-test, our hypothesis that means are same no statistical advantage over any parameter.
377 # p-value > 0.05 we don't have statistical evidence to 2 comparisons have different means, hypothesis stands
378 # if p-value less than 0.05 there is statistical evidence that one of the mean is better, hypothesis is rejected.
379 print()
380 print("t-tests")
381 t1 = ttest_ind(experiment1.iloc[:,0], experiment1.iloc[:,1], equal_var=False)
382 t2 = ttest_ind(experiment1.iloc[:,1], experiment1.iloc[:,2], equal_var=False)
383 t3 = ttest_ind(experiment1.iloc[:,0], experiment1.iloc[:,2], equal_var=False)
384 print(t1)
385 print(t2)
386 print(t3)
387 print()
388 print()
389 # then whichever average value of accuracy is higher if hypothesis is rejected is chosen so we get better hyper-
390 parameters
391 if t1[1]< 0.005 or t2[1]< 0.005 or t3[1]< 0.005:
392     print("Statistically better mean available")
393 else:
394     print("No statistically better mean")

395
396
397 if model_no == 2:
398     experiment2 = pd.DataFrame(df_RMS)
399     experiment2.index.name = 'Dataset No'
400     print()
401     print("Accuracy of all tests in- Gradient_hiddenLayers_neuronsList_LearningRate_Momentum: ")
402     print()
403     print(experiment2)
404     print()
405     print(experiment2.describe())
406     print()
407     print()

```

```

408     fig1, ax1 = plt.subplots()
409     ax1.set_title('Plot')
410     ax1.boxplot(experiment2)
411     plt.show()
412
413
414     # Shapiro test
415     # testing null hypothesis if data is normally distributed.
416     # if p-value greater than 0.05 it is, otherwise reject the hypothesis
417     print("Shapiro test")
418     for col, val in experiment2.iteritems():
419         for col, val in experiment2.iteritems():
420             stat, p = shapiro(val)
421             print('stats=% .4f, p=% .4f' % (stat, p))
422
423
424     # ANOVA test
425     # Hypothesis that mean of all datasets are not statistically different from each other.
426     # Hypothesis holds if p-value>0.05
427     # Otherwise there exist a better mean of all which can be found with T-test
428     # Last minute bug
429     print("ANOVA test")
430     ana_model = ols('experiment2.iloc[:,0]~experiment2.iloc[:,1]+experiment2.iloc[:,2]', experiment2).fit()
431     anova_table = sm.stats.anova_lm(ana_model, typ=2)
432     print(anova_table)
433     # t-test, our hypothesis that means are same no statistical advantage over any parameter.
434     # p-value > 0.05 we don't have statistical evidence to 2 comparisons have different means, hypothesis stands
435     # if p-value less than 0.05 there is statistical evidence that one of the mean is better, hypothesis is rejected.
436     print()
437     print("t-tests")
438     t1 = ttest_ind(experiment2.iloc[:,0], experiment2.iloc[:,1], equal_var=False)
439     t2 = ttest_ind(experiment2.iloc[:,1], experiment2.iloc[:,2], equal_var=False)
440     t3 = ttest_ind(experiment2.iloc[:,0], experiment2.iloc[:,2], equal_var=False)
441     print(t1)
442     print(t2)
443     print(t3)
444     print()
445     # then whichever average value of accuracy is higher if hypothesis is rejected is chosen so we get better hyper-
parameters
446     if t1[1]< 0.005 or t2[1]< 0.005 or t3[1]< 0.005:
447         print("Statistically better mean available: ")
448     else:
449         print("No statistically better mean")

```

```
450  
451  
452 if __name__ == '__main__' :  
453     main()  
454
```