

Notes: Nevanlinna analytical Continuation Method

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(Dated: November 23, 2021)

Abstract

This is the abstract.

CONTENTS

I. The analytic continuation problem	2
II. How to solve?	2
III. Nevanlinna analytic continuation method	2
A. Schur Algorithm	3
B. Generalized Schur Algorithm	4
C. Interpolation of Green's functions	5
IV. Hardy basis optimization	7
A. Conformal transforms	7
1. The linear fractional transform	7
2. The Mobius transform	7
References	8

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I. THE ANALYTIC CONTINUATION PROBLEM

The analytic continuation problem seeks to extract real frequency dynamical information from imaginary-time correlation functions $G(\tau)$ data. Technically, this is a highly nontrivial task[1]. To see this, we use the relation between $G(\tau)$ and $A(\omega)$ [1, 2]:

$$G(\tau) = \int_{-\infty}^{\infty} d\omega \frac{e^{-\tau\omega}}{1 - \lambda e^{-\beta\omega}} A(\omega) = \int_{-\infty}^{\infty} d\omega K(\tau, \omega) A(\omega) \quad (1)$$

where $K(\tau, \omega) = \frac{e^{-\tau\omega}}{1 - \lambda e^{-\beta\omega}}$ is the kernel, $\lambda = \pm 1$ for bosons/fermions respectively. One may consider to solve the problem by firstly discretize τ and ω and get:

$$G(\tau_i) = \sum_{j=1}^{N_\omega} K_{ij} A(\omega_j) \quad (2)$$

Then do SVD decomposition of rectangular matrix K , write $K_{ij} = U_{il} \lambda_l V_{lj}$. Finally the spectral function reads

$$A(\omega_j) = \sum_{l=1}^{N_\tau} \frac{1}{\lambda_l} V_{lj} \sum_{i=1}^{N_\omega} G(\tau_i) U_{il} \quad (3)$$

It seems fine at the first glance. However, if we consider the properties of $K(\tau, \omega)$, we would notice that it is highly singular since it is exponentially small for large $|\omega|$, so small errors $G(\tau)$ would be amplified by exponentially small λ_l . This problem is well-known ill-posed[3, 4] and enormous efforts have been made[].

II. HOW TO SOLVE?

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Here we introduce the recently developed Nevanlinna analytic continuation method[5].

III. NEVANLINNA ANALYTIC CONTINUATION METHOD

The Nevanlinna analytic continuation method[5] is an interpolation method. The key step is to build the conformal mappings from the open upper half of the complex plane \mathcal{C}^+ to a closed unit disk $\bar{\mathcal{D}}$ in the complex plane and make use of the Schur algorithm [6–8] to do the interpolate.

A. Schur Algorithm

Schur Algorithm was introduced by I. Schur[9] in Section 1 of Ref.[6]. Here we list the main results we need while for a detailed introduction, see Ref.[8].

A Schur class(\mathcal{S}) consists of the Schur functions, which are the [holomorphic functions](#) from the open unit disk \mathcal{D} to the closed unit disk $\bar{\mathcal{D}}$. For a given Schur function $s_0(z)$, the Schur algorithm defines a set of $\{s_j(z) \in \mathcal{S}\}_{0 \leq j < \infty}$ starting from $s_0(z)$ by the recurrence relation:

$$zs_{j+1}(z) = \frac{s_j(z) - \gamma_j}{1 - \gamma_j^* s_j(z)} \quad (4)$$

where $s_j \in \mathcal{S}$ and $\gamma_j \equiv s_j(0)$ are called Schur parameters and $|\gamma_j| \leq 1$.

On the other hand, given an arbitrary strictly contractive sequence of Schur parameters $\{\gamma_0, \gamma_1, \dots, \gamma_j, \dots\} \subset \mathcal{D}$, one can construct a unique Schur function $s_0(z)$ by means of a continued fraction algorithm. In which we use the inverse relation of eq. (4)

$$s_j(z) = \frac{\gamma_j + zs_{j+1}(z)}{1 + \gamma_j^* zs_j(z)} \quad (5)$$

to construct the n -th Schur approximant, which we will denote by $s_0(z; \gamma_0, \gamma_1, \dots, \gamma_n)$. Namely, we write:

$$s_n(z; \gamma_n) = \gamma_n \quad (6)$$

$$s_j(z; \gamma_j, \gamma_{j+1}, \dots, \gamma_n) = \frac{\gamma_j + zs_{j+1}(z; \gamma_{j+1}, \dots, \gamma_n)}{1 + \gamma_j^* zs_{j+1}(z; \gamma_{j+1}, \dots, \gamma_n)} \quad (7)$$

where $j = n-1, n-2, \dots, 1, 0$.

Given the initial data consisting of N points $\{\mathcal{Y}_0, \mathcal{Y}_1, \dots, \mathcal{Y}_{N-1}\} \subset \mathcal{D}$ and target data $\{\gamma_0, \gamma_1, \dots, \gamma_{N-1}\} \subset \mathcal{D}$, we can find a holomorphic function $s(z) : \mathcal{D} \rightarrow \bar{\mathcal{D}}$ such that $s(\mathcal{Y}_j) = \gamma_j$ for all j by combining eq. (6), eq. (7) and the linear fractional transform $\xi(z, \mathcal{Y}_j) = \frac{z - \mathcal{Y}_j}{1 - z\mathcal{Y}_j^*}$:

$$s_{N-1}(z; \gamma_{N-1}) = \frac{\gamma_{N-1} + \xi(z, \mathcal{Y}_{N-1})s_N(z)}{1 + \gamma_{N-1}^* \xi(z, \mathcal{Y}_{N-1})s_N(z)} \quad (8)$$

$$s_j(z; \gamma_j, \gamma_{j+1}, \dots, \gamma_N) = \frac{\gamma_j + \xi(z, \mathcal{Y}_j)s_{j+1}(z; \gamma_{j+1}, \dots, \gamma_N)}{1 + \gamma_j^* \xi(z, \mathcal{Y}_j)s_{j+1}(z; \gamma_{j+1}, \dots, \gamma_N)} \quad (9)$$

where $j = N-2, N-3, \dots, 1, 0$ and $s_0(z) \equiv s(z)$. In eq. (8), we notice that there is an degrees of freedom to choose an arbitrary $s_N(z) \in \mathcal{S}$, eq. (6) correponds the special case $s_{n+1}(z) = 0$.

G. Pick and R. Nevanlinna studied the interpolation problem independently in 1917[10] and 1919[11] respectively, showing that an interpolating function exists if and only if the Pick matrix

$$P_{jk} = \frac{1 - \gamma_k^* \gamma_j}{1 - \mathcal{Y}_j^* \mathcal{Y}_k} \quad (10)$$

is positive semi-definite. Furthermore, the function $s(z)$ is unique if and only if the Pick matrix has zero determinant. It is called the [the Nevanlinna–Pick theorem](#).

B. Generalized Schur Algorithm

Schur algorithm can be modified to expand all contractive functions($\in \mathcal{B}$)[12], which are holomorphic functions mapping from the upper half plane \mathcal{C}^+ to $\bar{\mathcal{D}}$.

Given the initial data consisting of N points $\{\mathcal{Y}_0, \mathcal{Y}_1, \dots, \mathcal{Y}_{N-1}\} \subset \mathcal{C}^+$ and target data $\{\gamma_0, \gamma_1, \dots, \gamma_{N-1}\} \subset \bar{\mathcal{D}}$, in order to find a holomorphic function $\theta(z) \in \mathcal{B}$ such that $\theta(\mathcal{Y}_j) = \gamma_j$ for all j , we should make use of the Mobius transform $h(z, \mathcal{Y}) = \frac{z - \mathcal{Y}}{z - \mathcal{Y}^*}$ which maps $\mathcal{C}^+/\bar{\mathcal{C}}^+$ to $\mathcal{D}/\bar{\mathcal{D}}$, which means it establishes a one-to-one correspondence of $\theta(z)$ to a schur function $s(z)$ with:

$$\theta(h^{-1}(z, \mathcal{Y})) = s(z), \text{ or } s(h(z, \mathcal{Y})) = \theta(z) \quad (11)$$

We denote $h(z, \mathcal{Y}_j)$ as $h_j(z)$ form now on.

The recursion relation between $\theta_j(z)$ and the next contractive function $\theta_{j+1}(z)$ can be easily build as follows. From eq. (11), we have:

$$s_j(0) = \theta_j(h_j^{-1}(0)) = \theta_j(\mathcal{Y}_j) = \gamma_j \quad (12)$$

Let $\theta_{j+1}(z) = s_{j+1}(h_j(z))$, then use the recursion relation eq. (4), we have:

$$z\theta_{j+1}(h_j^{-1}(z)) = \frac{\theta_j(h_j^{-1}(z)) - \gamma_j}{1 - \gamma_j^* \theta_j(h_j^{-1}(z))} \stackrel{\text{def}}{=} \phi_j(h_j^{-1}(z)) \quad (13)$$

Form the first and the third terms of eq. (13) we have:

$$\phi_j(h_j^{-1}(z)) = z\theta_{j+1}(h_j^{-1}(z)) = h_j(h_j^{-1}(z))\theta_{j+1}(h_j^{-1}(z)) \quad (14)$$

replace $h_j^{-1}(z)$ with $z \in \mathcal{D}$ by $z \in \mathcal{C}^+$, we have

$$\phi_j(z) = h_j(z)\theta_{j+1}(z) \quad (15)$$

We can read from eq. (15) that $\phi_j(z) \in \mathcal{B}$ and $\phi_j(\mathcal{Y}_j) = 0$.

Form the second and the third terms of eq. (13) we can read:

$$\phi_j(z) = \frac{\theta_j(z) - \gamma_j}{1 - \gamma_j^* \theta_j(z)} \quad (16)$$

Together with eq. (15) we get the recursion relation between $\theta_j(z)$ and $\theta_{j+1}(z)$:

$$\theta_j(z) = \frac{\phi_j(z) + \gamma_j}{\gamma_j^* \phi_j(z) + 1} = \frac{h_j(z) \theta_{j+1}(z) + \gamma_j}{\gamma_j^* h_j(z) \theta_{j+1}(z) + 1} \quad (17)$$

The recursive final $\theta(z)$ can conveniently be written in a matrix form:

$$\theta(z)[z; \theta_N(z)] = \frac{a(z) \theta_N(z) + b(z)}{c(z) \theta_N(z) + d(z)} \quad (18)$$

where

$$\begin{pmatrix} a(z) & b(z) \\ c(z) & d(z) \end{pmatrix} = \prod_{j=1}^{N-1} \begin{pmatrix} h_j(z) & \gamma_j \\ \gamma_j^* h_j(z) & 1 \end{pmatrix} \quad (19)$$

Like in eq. (6), there is a also freedom to choose $\theta_N(z)$.

C. Interpolation of Green's functions

The retarded Green's function $G^R(\omega + i\eta)$ and the Masubara Green's function $G(i\omega_n)$ can be expressed consistently by replacing the variables $i\omega_n$ and $\omega + i\eta$ with a single complex variable z . $G(z)$ is analytic in the upper half plane \mathcal{C}^+ . Our problem is that once we have Masubara frequencies $\{i\omega_n\} \subset \mathcal{C}^+$ and target data $\{G(i\omega_n)\} \subset \mathcal{C}$, where \mathcal{C} is the complex plane, how can we get interpolate them and get the holomorphic function $G(z) : \mathcal{C}^+ \rightarrow \mathcal{C}$?

Based on the knowledge of Schur algorithm, if we can find a one-to-one correspondence of $G(z)$ and a contractive function $\theta(z) \in \mathcal{B}$, then we can futher generalize the algorithm in section III B.

To do this, we firstly introduce the Nevanlinna functions $f(z) \in \mathcal{N}$. In complex analysis, a Nevanlinna function is a complex function that is analytic in the open upper half plane \mathcal{C}^+ and has non-negative imaginary part, i.e., maps into $\bar{\mathcal{C}}^+$ (the overline denotes inclusion of the boundary). The invertible Möbius transform $h(z) = \frac{z-i}{z+i}$ maps Nevanlinna functions one to one to contractive functions:

$$\theta(z) = h(f(z)), \text{ or } f(z) = h^{-1}(\theta(z)) \quad (20)$$

Given the initial data consisting of N points $\{\mathcal{Y}_0, \mathcal{Y}_1, \dots, \mathcal{Y}_{N-1}\} \subset \mathcal{C}^+$ and target data $\{C_0, C_1, \dots, C_{N-1}\} \subset \bar{\mathcal{C}}$, The only thing we needed is to let γ_j in eq. (17) be $\gamma_j \equiv h(C_j)$.

Moreover, the corresponding Pick matrix is generalized to:

$$P_{jk} = \frac{1 - h(C_k)^* h(C_j)}{1 - h(\mathcal{Y}_j)^* h(\mathcal{Y}_k)} \quad (21)$$

The aforementioned conformal mappings are shown in fig. 1.

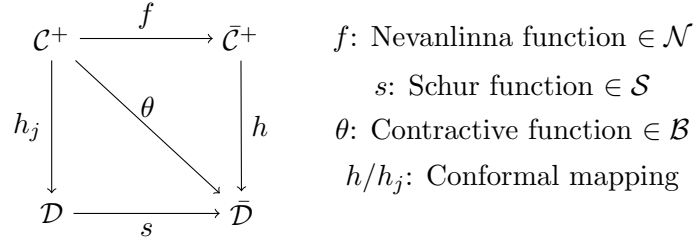


FIG. 1. Conformal mappings

Now we are ready to discuss the Green's functions. The Lehmann representation of Green's function $G(z)$ is:

$$G(z) = \frac{1}{Z} \sum_{nm} |A_{nm}|^2 \frac{e^{-\beta E_n} \pm e^{-\beta E_m}}{z - E_m + E_n} \quad (22)$$

where the "+" sign is for fermionic Green's functions and "-" sign is for bosonic Green's functions.

In fermionic case, if we take $z = x + iy$ with $y > 0$, i.e. $z \in \mathcal{C}^+$, we can easily prove that $\text{Im}G(z) \leq 0$. Therefore $-G(z) \in \mathcal{N}$ is a Nevanlinna function.

While the bosonic case is less trivial. The imaginary part of bosonic Green's function is:

$$\text{Im}G(z) = \frac{1}{Z} \sum_{nm} \frac{y |A_{nm}|^2 e^{-\beta E_m}}{(x - E_m + E_n)^2 + y^2} [(1 - e^{\beta(E_m - E_n)})] \quad (23)$$

which is negative when $E_m > E_n$ and positive when $E_m < E_n$. We can construct a $\tilde{G}(z)$ like:

$$\tilde{G}(z) = \frac{1}{Z} \sum_{nm} \frac{|A_{nm}|^2}{z - E_m + E_n} \frac{e^{-\beta E_n} - e^{-\beta E_m}}{E_m - E_n} \quad (24)$$

and $-\tilde{G}(z) \in \mathcal{N}$ is a Nevanlinna function.

IV. HARDY BASIS OPTIMIZATION

Appendix A: Conformal transforms

1. The linear fractional transform

The linear fractional transform is:

$$\xi(z, \mathcal{Y}) = \frac{z - \mathcal{Y}}{1 - z\mathcal{Y}^*} \quad (\text{A1})$$

It is a one to one mapping of the open unit disk \mathcal{D} onto itself and a one to one mapping of the unit circle \mathcal{T} . It maps point \mathcal{Y} to the center of \mathcal{D} .

2. The Mobius transform

The mapping from $\mathcal{C}^+/\bar{\mathcal{C}}^+$ to $\mathcal{D}^+/\bar{\mathcal{D}}^+$ is called Mobius transform. It has the form:

$$h(z, \mathcal{Y}) = \frac{z - \mathcal{Y}}{z - \mathcal{Y}^*} \quad (\text{A2})$$

where $\mathcal{Y} \in \bar{\mathcal{C}}^+$ and $\mathcal{Y} \neq 0$. We can easily prove that $|h(z, \mathcal{Y})| \leq 1$ for $z \in \bar{\mathcal{C}}^+$ and $|h(z, \mathcal{Y})| = 1$ if z is real. $h(z, \mathcal{Y})$ maps $\mathcal{Y} \in \bar{\mathcal{C}}^+$ to the center of the unit disk \mathcal{D} and the real axis as the edge of $\bar{\mathcal{D}}$, the rest part of upper half complex plane is wrapped inside the unit disk. If $\tilde{z} \in \mathcal{D}$, the inverse transform is:

$$h^{-1}(\tilde{z}, \mathcal{Y}) = \frac{\mathcal{Y} - \tilde{z}\mathcal{Y}^*}{1 - \tilde{z}} \quad (\text{A3})$$

Angin one can prove $\text{Im}h^{-1}(\tilde{z}, \mathcal{Y}) = (\text{Im}\mathcal{Y})(1 - |\tilde{z}|^2) > 0$.

Proof of $|h(z, \mathcal{Y})| \leq 1$ for $z \in \bar{\mathcal{C}}^+$ and $|h(z, \mathcal{Y})| = 1$ if z is real. We already know that $\text{Im}z \geq 0, \text{Im}\mathcal{Y} > 0$.

$$\begin{aligned} |h(z, \mathcal{Y})|^2 &= \frac{z - \mathcal{Y}}{z - \mathcal{Y}^*} \frac{z^* - \mathcal{Y}^*}{z^* - \mathcal{Y}} = \frac{|z|^2 + |\mathcal{Y}|^2 - z\mathcal{Y}^* - z^*\mathcal{Y}}{|z|^2 + |\mathcal{Y}|^2 - z\mathcal{Y} - z^*\mathcal{Y}^*} \\ &= \frac{|z|^2 + |\mathcal{Y}|^2 - 2(\text{Re}z\text{Re}\mathcal{Y} + \text{Im}z\text{Im}\mathcal{Y})}{|z|^2 + |\mathcal{Y}|^2 - 2(\text{Re}z\text{Re}\mathcal{Y} - \text{Im}z\text{Im}\mathcal{Y})} \end{aligned} \quad (\text{A4})$$

If $\text{Im}z = 0$, $|h(z, \mathcal{Y})|^2 = 1$. If $\text{Im}z > 0$, $|h(z, \mathcal{Y})|^2 < 1$. And we notice that if $\text{Im}\mathcal{Y} = 0$, we

map all points in $\bar{\mathcal{C}}$ to point 1 except for point \mathcal{Y} itself.

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