

2) Verify the

$B = \{ (2, 3, 4, 2), (4, 0, -4, 28), (3, 4, 5, 5) \}$
is linearly independent or not.

Sol.

Let c_1, c_2, c_3 be scalars consider

$$c_1(2, 3, 4, 2) + c_2(4, 0, -4, 28) + c_3(3, 4, 5, 5) = (0, 0, 0, 0)$$

$$\cancel{2c_1} + \cancel{4c_2} + (2c_1, 3c_1, 4c_1, 2c_1) + (4c_2, 0c_2, -4c_2, 28c_2) + (3c_3, 4c_3, 5c_3, 5c_3) = (0, 0, 0, 0)$$

$$\left. \begin{aligned} 2c_1 + 4c_2 + 3c_3 &= 0 \\ 3c_1 + 0c_2 + 4c_3 &= 0 \\ 4c_1 + (-4c_2) + 5c_3 &= 0 \\ 2c_1 + 28c_2 + 5c_3 &= 0 \end{aligned} \right\} \textcircled{2}$$

$$A = \begin{bmatrix} 2 & 4 & 3 \\ 3 & 0 & 4 \\ 4 & -4 & 5 \\ 2 & 28 & 5 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 4 & 3 \\ 3 & 0 & 4 \\ 6 & 0 & 8 \\ 2 & 28 & 5 \end{bmatrix}$$

$$= \begin{bmatrix} 2 & 4 & 3 \\ 3 & 0 & 4 \\ 0 & -8 & -1 \\ 0 & 24 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 4 & 3 \\ 3 & 0 & 4 \\ 0 & -8 & -1 \\ 0 & 0 & -1 \end{bmatrix}$$

$\rho(A) = 3 = \text{No. of unknowns.}$

\therefore The system has unique Solu which is a trivial Solu.

Hence the vectors are linearly independent vectors.

PART - B

Q1) Show

Solu:

$$B = \{(3, 3, 3), (3, -3, 3), (0, 3, 3)\}$$

i) To show that the elements of B are linearly independent, consider.

$$c_1(3, 3, 3) + c_2(3, -3, 3) + c_3(0, 3, 3) = (0, 0, 0)$$

$$(3c_1, 3c_1, 3c_1) + (3c_2, -3c_2, 3c_2) + (0c_3, 3c_3, 3c_3) = (0, 0, 0)$$

$$3c_1 + 3c_2 + 0c_3 = 0$$

$$3c_1 + (-3c_2) + 3c_3 = 0$$

$$3c_1 + 3c_2 + 3c_3 = 0$$

$$\begin{aligned} |A| &= \begin{vmatrix} 3 & 3 & 0 \\ 3 & -3 & 3 \\ 3 & 3 & 3 \end{vmatrix} = 3(-9-9) - 3(9+9) \\ &= 3 \times (-18) - 3 \times (18) \\ &= -54 - 54 = -108 \end{aligned}$$

$$|A| = -108$$

$\therefore \rho(A) = 3 = \text{No. of unknowns.}$

The system (i) has unique soln.

ii) To show that B spans $V_3(R)$ consider $(x, y, z) \in V_3(R)$

$$(x, y, z) = (3c_1 + 3c_2 + 0c_3, 3c_1 - 3c_2 + 3c_3, 3c_1 + 3c_2 + 3c_3)$$

$$3c_1 + 3c_2 + 0c_3 = x$$

$$3c_1 + (-3c_2) + 3c_3 = y$$

$$3c_1 + 3c_2 + 3c_3 = z$$

Augmented matrix:-

$$[A : B] = \begin{bmatrix} 3 & 3 & 0 & : & x \\ 3 & -3 & 3 & : & y \\ 3 & 3 & 3 & : & z \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 0 & : & x/3 \\ 1 & -1 & 1 & : & y/3 \\ 1 & 1 & 1 & : & z/3 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 0 & : & x/3 \\ 1 & -1 & 1 & : & y/3 \\ 0 & 2 & 1 & : & z/3 + y/3 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 0 & : & x/3 \\ 2 & 0 & 1 & : & y/3 + x/3 \\ 2 & 0 & 2 & : & z/3 + y/3 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 1 & 0 & : & x/3 \\ 2 & 0 & 1 & : & y/3 + x/3 \\ 0 & 0 & 1 & : & (z/3 + y/3) - y/3 - x/3 \end{bmatrix}$$

$$\rho(A) = \rho([A : B]) = 3 = \text{No. of unknowns}$$

$$c_3 = z_3 - x_3 \quad \Rightarrow 3c_1 = z - x$$

$$2c_1 + c_3 = y_3 + x_3$$

$$2c_1 = y_3 + x_3 - z_3 + x_3$$

$$2c_1 = y_3 + 2x_3 - z_3$$

$$c_1 + c_2 = x_3$$

$$c_2 = x_3 - c_1 = x_3 - \frac{y}{6} - \frac{x}{3} + \frac{z}{6}$$

$$c_2 = \frac{z}{6} - \frac{y}{6}$$

i.e every vector of $V_3(R)$ is generated
by the elements of B .
as,

$$(x, y, z) = \left(\frac{y}{6} + \frac{x}{3} - \frac{z}{6}\right)(3, 3, 3) + \left(\frac{z}{6} - \frac{y}{6}\right)(3, 3, 3) + \left(\frac{z}{3} - \frac{x}{3}\right)(0, 3, 3)$$

$\therefore B$ spans $V_3(R)$

$$\text{i.e } V_3(R) = \langle B \rangle$$

$\therefore B$ form a basis for $V_3(R)$

PART C

Q2) Determine

Sol: Consider 3 possible vectors namely: -

$$\vec{v}_1 = \begin{bmatrix} -1 \\ 4 \\ -3 \end{bmatrix} \quad \vec{v}_2 = \begin{bmatrix} 5 \\ 2 \\ 1 \end{bmatrix} \quad \vec{v}_3 = \begin{bmatrix} 3 \\ -4 \\ -7 \end{bmatrix}$$

To have $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ as orthogonal we must have

$\{\vec{v}_1, \vec{v}_2\}$, $\{\vec{v}_1, \vec{v}_3\}$ & $\{\vec{v}_2, \vec{v}_3\}$ be orthogonal

$$\therefore \vec{v}_1 \cdot \vec{v}_2 = (-1) \times 5 + 4 \times 2 + (-3) \times 1$$

$$= -5 + 8 - 3 = 0$$

$$\vec{v}_2 \cdot \vec{v}_3 = 5 \times 3 + 2 \times (-4) + 1 \times (-7)$$

$$= 15 - 8 - 7 = 0$$

$$\vec{v}_1 \cdot \vec{v}_3 = (-1) \times 3 + 4 \times (-4) + (-3) \times (-7)$$

$$= -3 + (-16) + 21 = 2$$

Since $\vec{v}_1 \cdot \vec{v}_3 \neq 0$

$\therefore \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is not an orthogonal set.

Q3) $\{(2, -7, -1), (-6, -3, 9), (3, 1, -1)\}$

Let 3 possible vectors be

$$\vec{v}_1 = \begin{bmatrix} 2 \\ -7 \\ -1 \end{bmatrix} \quad \vec{v}_2 = \begin{bmatrix} -6 \\ -3 \\ 9 \end{bmatrix} \quad \vec{v}_3 = \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix}$$

$$\vec{v}_1 \cdot \vec{v}_2 = 2 \times (-6) + (-7) \times (-3) + (-1) \times 9 = -12 + 21 - 9$$

$$= 0$$

$$\vec{v}_1 \cdot \vec{v}_2 = (-6 \times 3) + (-8 \times 1) + (9 \times -1) \\ = -18 - 8 + (-9) \\ = -35$$

1. Since $\vec{v}_1 \cdot \vec{v}_2 \neq 0$.
 \therefore the given $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is not orthogonal.

iii) $\{(3, -2, 1, 3)^T, (-1, 3, -3, 4)^T, (3, 8, 7, 0)^T\}$
 Let the 3 possible vector be

$$\vec{v}_1 = \begin{bmatrix} 3 \\ -2 \\ 1 \\ 3 \end{bmatrix} \quad \vec{v}_2 = \begin{bmatrix} -1 \\ 3 \\ -3 \\ 4 \end{bmatrix} \quad \vec{v}_3 = \begin{bmatrix} 3 \\ 8 \\ 7 \\ 0 \end{bmatrix}$$

Consider 3 diff. pairs $\{\vec{v}_1, \vec{v}_2\}, \{\vec{v}_1, \vec{v}_3\}, \{\vec{v}_2, \vec{v}_3\}$

$$\vec{v}_1 \cdot \vec{v}_2 = -3 - 6 - 3 + 12 \\ = 0$$

$$\vec{v}_1 \cdot \vec{v}_3 = 9 - 16 + 7 = 0$$

$$\vec{v}_2 \cdot \vec{v}_3 = (-1 \times 3) + (3 \times 8) + (-3 \times 7) \\ = -3 + 24 - 21 = 0$$

Since each pair of distinct vector is orthogonal and $\neq 0$

$\therefore \{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$ is an orthogonal set.

~~PART~~
PART - D

Q2)

$$A = \begin{bmatrix} 1 & 8 & 0 \\ 2 & 1 & 0 \\ 0 & -6 & 1 \end{bmatrix}$$

Soln:

$$\text{Let } \vec{x}_1 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \quad \vec{x}_2 = \begin{bmatrix} 8 \\ 1 \\ -6 \end{bmatrix} \quad \vec{x}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\vec{v}_1 = \vec{x}_1 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$$

$$\begin{aligned} \vec{v}_2 &= \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 = \begin{bmatrix} 8 \\ 1 \\ -6 \end{bmatrix} - \frac{10}{5} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} 8 \\ 1 \\ -6 \end{bmatrix} - \begin{bmatrix} 2 \\ 4 \\ 0 \end{bmatrix} \end{aligned}$$

$$\vec{v}_2 = \begin{bmatrix} 6 \\ -3 \\ -6 \end{bmatrix}$$

$$\vec{v}_2' = 4 \vec{v}_2 = 4 \begin{bmatrix} 6 \\ -3 \\ -6 \end{bmatrix} = \begin{bmatrix} 24 \\ -12 \\ -24 \end{bmatrix}$$

$$\vec{v}_3 = \vec{x}_3 - \frac{\vec{x}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{x}_3 \cdot \vec{v}_2'}{\vec{v}_2' \cdot \vec{v}_2'} \vec{v}_2'$$

$$\vec{v}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} - \frac{0}{5} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} - \frac{0}{100} \begin{bmatrix} 24 \\ -12 \\ -24 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\vec{v}_1 = \begin{bmatrix} 0 \\ 3 \\ -6 \end{bmatrix} = 3 \begin{bmatrix} 0 \\ 1 \\ -2 \end{bmatrix}$$

$$\vec{v}_2 = \begin{bmatrix} 6 \\ -3 \\ -6 \end{bmatrix} = 3 \begin{bmatrix} 2 \\ -1 \\ -2 \end{bmatrix}$$

$$\vec{v}_3 = \vec{v}_3 - \frac{\vec{v}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{v}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2 =$$

$$= \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} - 0 - \frac{(-6)}{81} \begin{bmatrix} 6 \\ -3 \\ -6 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} + \frac{2}{27} \begin{bmatrix} 6 \\ -3 \\ -6 \end{bmatrix}$$

=

Now normalize the vectors $\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$
to obtain ~~$\{\vec{v}_1, \vec{v}_2, \vec{v}_3\}$~~ $\{\vec{u}_1, \vec{u}_2, \vec{u}_3\}$

$$\vec{u}_1 = \frac{\vec{v}_1}{\|\vec{v}_1\|} = \begin{bmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \\ 0 \end{bmatrix}$$

$$\vec{u}_2 = \frac{\vec{v}_2}{\|\vec{v}_2\|} = \begin{bmatrix} 6/9 \\ -3/9 \\ -6/9 \end{bmatrix}$$

$$\vec{u}_3 = \frac{\vec{v}_3}{\|\vec{v}_3\|} = \begin{bmatrix} 0.59 \\ -0.2981 \\ 0.7453 \end{bmatrix}$$

$$Q = [\vec{u}_1 \quad \vec{u}_2 \quad \vec{u}_3]$$

$$R = Q^T A$$