

PHYS 5319-001: Math Methods in Physics III Linear Algebra Package

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Linear Algebra Basic

Scalar a, c

• Vector
$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

• Matrix
$$A = \begin{pmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{pmatrix}$$

Here the basis is *n*-dimension (*n* could be any positive integer). The elements could be real or complex.

Some usual operations

rescale a vector (for a constant c): c

$$c\mathbf{x} = \begin{pmatrix} cx_1 \\ \vdots \\ cx_n \end{pmatrix}$$

- addition: x + cy = z
- sum $s = \sum_{i=1}^{n} x_i$
- find the maximum (return the index)
- scalar product $\langle x|y\rangle$ or x^Ty
- matrix-vector Ax = y
- Matrix-matrix AB = C

C(i,j)=0 $(M^{n} = 1, n$ $C(i) = C(j + A_{im})$ end Bmj

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LAPACK: Linear Algebra PACKage

- Developed by netlib: https://www.netlib.org/
- LAPACK is written in Fortran 90
- Some of them are ported to python/MATLAB
- e.g. for Python (scipy.linalg.lapack) for MATLAB:

Linear Algebra

Linear equations, eigenvalues, singular values, decomposition, matrix operations, matrix structure

- Including Basic Linear Algebra Subprograms (BLAS)
- & EISPACK

LEVEL 1

Single

single precision

- <u>SROTG</u> setup Givens rotation
- <u>SROTMG</u> setup modified Givens rotation
- <u>SROT</u> apply Givens rotation
- SROTM apply modified Givens rotation
- SSWAP swap x and y
- SSCAL $x = a^*x$ rescal a vector
- SCOPY copy x into y
- SAXPY y = a*x + y vector addition
- SDOT dot product
- SDSDOT dot product with extended precision accumulation
- SNRM2 Euclidean norm
- SCNRM2- Euclidean norm
- SASUM sum of absolute values
- ISAMAX index of max abs value

LEVEL 2

Single

- <u>SGEMV</u> matrix vector multiply
- <u>SGBMV</u> banded matrix vector multiply
- SSYMV symmetric matrix vector multiply
- SSBMV symmetric banded matrix vector multiply
- SSPMV symmetric packed matrix vector multiply
- STRMV triangular matrix vector multiply
- STBMV triangular banded matrix vector multiply
- STPMV triangular packed matrix vector multiply
- STRSV solving triangular matrix problems
- STBSV solving triangular banded matrix problems
- STPSV solving triangular packed matrix problems
- SGER performs the rank 1 operation A := alpha*x*y' + A
- SSYR performs the symmetric rank 1 operation A := alpha*x*x' + A
- SSPR symmetric packed rank 1 operation A := alpha*x*x' + A
- SSYR2 performs the symmetric rank 2 operation, A := alpha*x*y' + alpha*y*x' + A
- SSPR2 performs the symmetric packed rank 2 operation, A := alpha*x*y' + alpha*y*x' + A

 $y = \alpha Ax + \beta y$

LEVEL 3

Single

<u>SGEMM</u> - matrix matrix multiply

- $C = \alpha AB + \beta C$
- <u>SSYMM</u> symmetric matrix matrix multiply
- SSYRK symmetric rank-k update to a matrix
- SSYR2K symmetric rank-2k update to a matrix
- STRMM triangular matrix matrix multiply
- STRSM solving triangular matrix with multiple right hand sides

Complex

<u>CGEMM</u> - matrix matrix multiply

 $\mathbf{C} = \alpha \mathbf{A}^{\dagger} \mathbf{B} + \beta \mathbf{C}$

- <u>CSYMM</u> symmetric matrix matrix multiply
- <u>CHEMM</u> hermitian matrix matrix multiply
- <u>CSYRK</u> symmetric rank-k update to a matrix
- <u>CHERK</u> hermitian rank-k update to a matrix
- CSYR2K symmetric rank-2k update to a matrix
- CHER2K hermitian rank-2k update to a matrix
- <u>CTRMM</u> triangular matrix matrix multiply
- CTRSM solving triangular matrix with multiple right hand sides

Linear algebra equations

• *n-dim*: unknown $\{x_1, x_2, ..., x_3\}$ satisfying

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

.

$$a_{n1}x_1 + a_{n2}x_2 + \dots + a_{nn}x_n = b_n$$

simply,

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

m = n

where a_{ij} and b_i are constants, i = 1, 2, ..., m, j = 1, 2, ..., n.

or

$$Ax = b$$

Solving linear algebra equations

$$Ax = b$$

Decomposition: A = LU

$$L = \begin{bmatrix} * & 0 & 0 & \dots & 0 \\ * & * & 0 & \dots & 0 \\ * & * & * & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ * & * & * & \dots & * \end{bmatrix} \qquad U = \begin{bmatrix} * & * & * & \dots & * \\ 0 & * & * & \dots & * \\ 0 & 0 & * & \dots & * \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & * \end{bmatrix} \qquad U : \text{ upper triangular, } elements $\{\beta_{ij}\}$$$

L: lower triangular,

elements $\{\beta_{ij}\}$

So,
$$Ax = (LU)x = L(Ux) = b$$



Let $Ux \equiv y$

Solve Ly = b first for y, then Ux = y for x, by taking advantage of Δ :

$$y_1 = b_1/\alpha_{11}, \quad y_2 = \frac{1}{\alpha_{22}}[b_2 - \alpha_{21}y_1], \dots \qquad y_i = \frac{1}{\alpha_{ii}} b_i - \sum_{j=1}^{i-1} \alpha_{ij}y_j$$

$$x_n = \frac{y_n}{\beta_{nn}}, \longrightarrow x_i = \frac{1}{\beta_{ii}} \left[y_i - \sum_{j=i+1}^n \beta_{ij} x_j \right]^{\mathsf{L}}$$

LAPACK: LU factorization for Ax = b

Get A = PLU

L:unit lower triangular

where P is an integer array, the permutation matrix

```
dgesv()
                                                       N,
subroutine dgesv (integer
                  integer
                                                       NRHS,
                  double precision, dimension( lda, '
                  integer
                                                       LDA,
                  integer, dimension(*)
                                                       IPIV,
                  double precision, dimension( ldb, * )
                                                       LDB,
                  integer
                  integer
                                                       INFO
```

Schrödinger Equations

$$i\hbarrac{\partial}{\partial t}\Psi(x,t)=\left[-rac{\hbar^2}{2m}rac{\partial^2}{\partial x^2}+V(x,t)
ight]\Psi(x,t)$$

If V independent of t, separation of variables, $\Psi(x,t) = f(t)\varphi(x)$

Stationary Schrödinger equation $\widehat{H}\varphi(x) = E\varphi(x)$

where
$$\widehat{H} = -\frac{\hbar^2}{2m} \frac{\partial^2}{\partial x^2} + V(x)$$
. Bound state $E \to E_n$, $\{\varphi_n\}$

On the other hand,

$$\psi(x,t) = \hat{U}(t)\psi(x,0)$$

$$i\hbar \frac{\partial \hat{U}\psi(x,0)}{\partial t} = \mathcal{H}\hat{U}\psi(x,0) \rightarrow i\hbar \frac{\partial \hat{U}}{\partial t} = \mathcal{H}\hat{U}$$

$$\rightarrow \hat{U}(t) = e^{-i\mathcal{H}t/\hbar} \rightarrow \psi(x,t) = e^{-i\hat{H}t/\hbar}$$

$$\rightarrow \quad \hat{U}(t) = e^{-i\mathcal{H}t/\hbar} \qquad \rightarrow \quad \psi(x,t) = e^{-i\hat{H}t/\hbar}\psi(x,0)$$

For any initial state
$$\psi(x,0) = \sum_{n} a_n \varphi_n(x)$$

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$$\psi(x,0) = \sum_{n} a_n \varphi_n(x)$$
, $\psi(x,0) = \sum_{n} a_n \varphi_n(x)$

$$\psi(x,t) = \underbrace{e^{-\frac{i\widehat{H}t}{\hbar}}}_{n}\psi(x,0) = \sum_{n} a_{n}e^{\frac{-i\widehat{H}t}{\hbar}}\varphi_{n}(x) = \sum_{n} \underbrace{a_{n}e^{\frac{-iE_{n}t}{\hbar}}}_{n}\varphi_{n}(x)$$

The above is still quantum mechanics. Now, just technically, let's "absorb" *i* in *t*:

$$\psi(x,\Delta t) = e^{-\frac{\widehat{H}\Delta t}{\hbar}}\psi(x,0) = \sum_{n} a_{n} e^{\frac{-E_{n}\Delta t}{\hbar}}\varphi_{n}(x) = \sum_{n} \widetilde{a}_{n}\varphi_{n}(x)$$

- If we don't now the eigenstates of H, we can start with a trial wavefunction (normalized), $\psi(x, 0)$.
- Apply on it repeatedly, each time normalized. \tilde{a}_0 will grow.
- Eventually we'll get the ground state: $\tilde{\psi}(x,0) \rightarrow \varphi_0$