1. Study of the Existing Code

The uart_tx_sense project from the VSDSquadron_FM repository integrates a UART transmitter with a sensor interface module on the FPGA. The Verilog code is structured with the following key modules:

Key Components:

1. top.v (Top-Level Module):

• UART Transmission:

o This module triggers UART transmission when sensor input data is available.

• Clock Division:

Generates a lower-frequency clock from the 12 MHz main oscillator, typically 9600
 Hz, using a counter.

• Sensor Interfacing:

 Receives digital signal inputs (intended from a sensor) and passes the value for UART transmission.

LED Indicator:

 Uses RGB LED logic or single LED pin as output indicator upon data capture or transmission events.

2. uart_tx_8n1.v (UART Transmitter):

• Transmission Protocol:

o Implements 8N1 protocol (8-bit data, no parity, 1 stop bit).

• State Machine Control:

o Controls the transitions between idle, start bit, data transmission, and stop bit states.

• Trigger-Based Sending:

o Waits for a senddata signal before initiating UART transmission.

3. Pin Constraint File (.pcf):

Defines pin locations for:

o UART TX: Pin 14

Clock: Pin 20

Sensor Input: Assigned appropriately (based on design, e.g., Pin 18)

LED Output: Pin 39 (or equivalent)

4. Makefile:

- Automation of Flow:
 - o Handles synthesis, place and route, and bitstream generation.
 - Uses yosys, nextpnr-ice40, icepack, and iceprog tools.
 - o Supports terminal setup using picocom.

Implementation Steps

Hardware Setup:

1. FPGA and Sensor Connection:

- Connect the ultrasonic sensor's output to the FPGA input pin defined in the constraint file.
- Connect FPGA to PC using a USB cable (for power and UART).

2. UART Connection:

• Ensure the uart_tx pin is connected to a USB-to-Serial converter (if not inbuilt).

3. Serial Terminal Setup:

• Use picocom or similar to observe the UART data:

sudo picocom -b 9600 /dev/ttyUSB0

Synthesis & Upload

1. Compile and Generate Bitstream:

Run the following command in the terminal:

<mark>make</mark>

2. Upload to FPGA:

Flash the FPGA with:

sudo make flash

4. Testing & Verification

Test Procedure:

1. Open Serial Terminal:

o Launch terminal using picocom.

2. Sensor Stimulation:

o Activate the ultrasonic sensor or simulate its digital signal.

3. Observe UART Data:

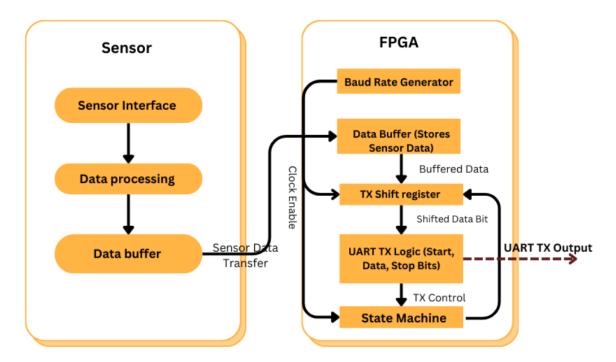
o Check if sensor-triggered values are transmitted to the serial terminal.

Expected Outcome:

• Sensor-triggered values are seen as characters/bytes on the serial monitor.

5.Block diagram:

FPGA-BASED SENSOR DATA UART TRANSMITTER



6)Circuit diagram:

