

Numerical approach to analyse physical system

Industrial training (7PH192)



By

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Outlines

1. Introduction to Euler's method, Euler-Cromer method
2. Physical system (Simple pendulum, damped and a damped, driven)
3. Summary
4. References

Euler's method and Euler-Cromer method

Euler's method is a numerical method to solve first order differential equation with given initial value. There is a problem with Euler's method for oscillatory motion who solved it is Cromer.

Physical system

1. Simple pendulum ,with damping and with damping and forcing

Simple pendulum

The swinging of a pendulum is governed by the equation

$$d^2 x/dt^2 + (g/L) \sin(x) = 0$$

$x = \theta$, $y = \omega$

Euler scheme

- (i) Plot of x versus time (using Euler scheme)

Euler-Cromer scheme

- (ii) Plot of x versus time
- (iii) Plot of x versus y

With dmping

$$d^2 x/dt^2 + (g/L) \sin(x) + \beta * dx/dt = 0$$

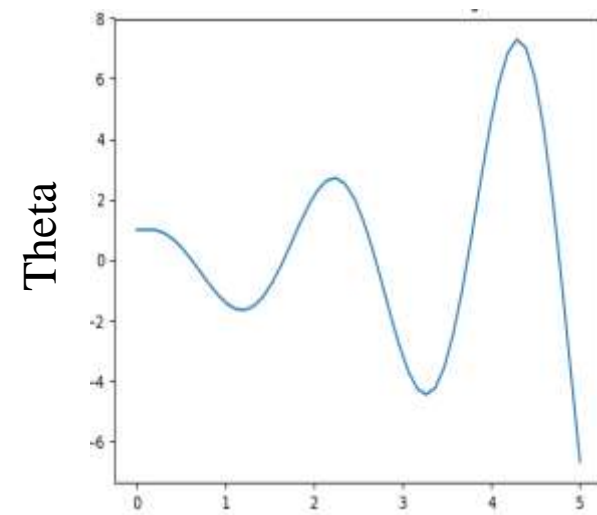
β = damping parameter

- (iv) Plot of θ versus time
- (v) Plot of Ω versus time

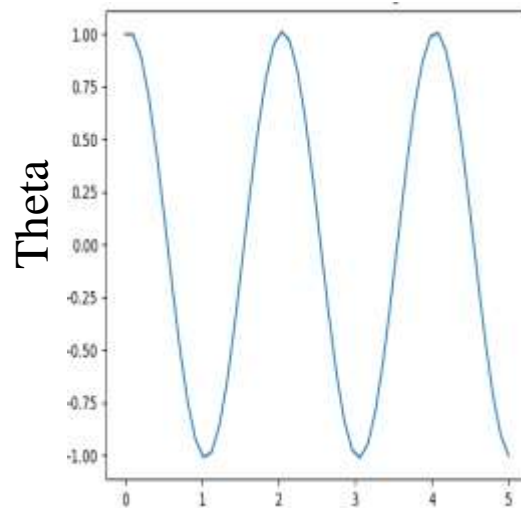
With damping and driving force

$$d^2 x/dt^2 + (g/L) \sin(x) + \beta * dx/dt = A \cos(\omega t)$$

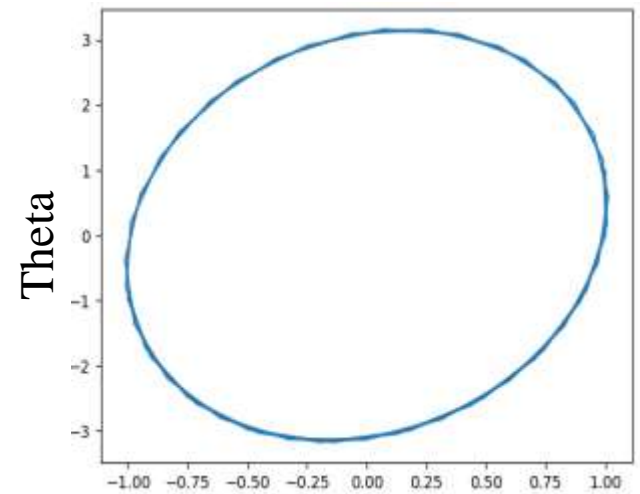
- (vi) Plot of θ versus time



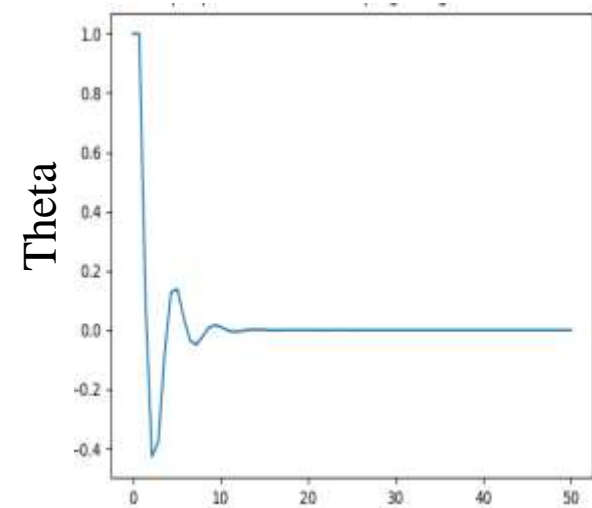
Time
(i)



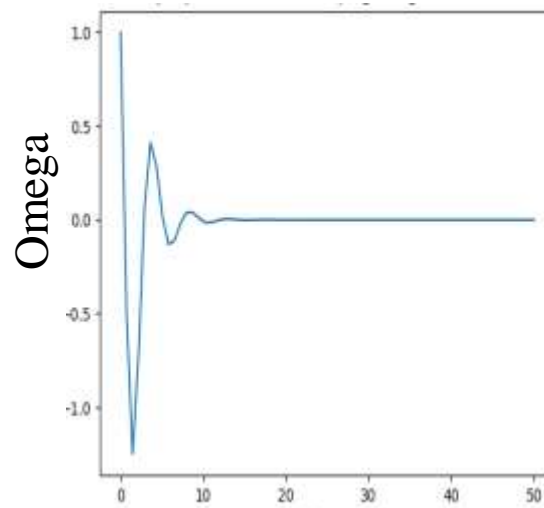
Time
(ii)



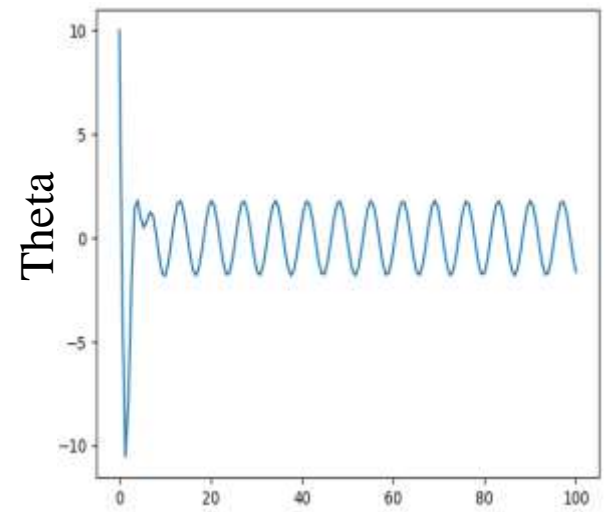
Omega
(iii)



Time
(iv)



Time
(v)



Time
(vi)

Summary

- For any oscillatory motion , the energy of Euler's solution increases with time.
- Problem with Euler's solution is fixed by Cromer by the position x_i and velocity v_i at step i to find the position x_{i+1} .

References

1. Rubin H. Landau Manuel J. Paez Cristian C. Bordeianu Computational Physics
2. E. Ward Cheney, David R. Kincaid Numerical Mathematics and Computing, Sixth Edition
3. S S SASTRY Introductory methods of numerical analysis
4. Paul L DeVries A first course in computational physics
5. Steven E. Koonin Computational physics,

Code

```
import numpy as np
from matplotlib import pyplot as plt
l=1,g=1,t0=0,x0=1,y0=1,tf=5,n=50
deltat=(tf-t0)/(n-1)
t=np.linspace(t0,tf,n)
y=np.zeros([n])
y[0]=y0
x=np.zeros([n])
x[0]=x0
for i in range(1,n):
    y[i]=y[i-1]+deltat*x[i] #y=theta
    for i in range(1,n):
        x[i]=x[i-1]-(g/l)*y[i-1] #x=omega
for i in range(n):
    for i in range(n):
        print(y[i],x[i])
    plt.xlabel("time")
    plt.ylabel("omega")
    plt.plot(t,x)
    plt.show()
```


Thank you!