

CRC (16 bit) error detection

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```
#include <stdio.h>
```

```
char m[50], g[50], r[50], q[50], tmp[50];
```

```
void caltrans(int n)
```

```
{ int i, k=0;
```

```
  for (i=n-16; i<n; i++)
```

```
    m[i] = ((int) m[i]-48) * ((int) r[k++]-48) + 48;
```

```
    m[i] = '\0';
```

```
}
```

```
void crc(int n)
```

```
{ int i, j;
```

```
  for (i=0; i<n; i++)
```

```
    tmp[i] = m[i];
```

```
  for (i=0; i<16; i++)
```

```
    r[i] = m[i];
```

```
  printf ("In intermediate remainder is\n");
```

```
  for (i=0; i<n-16; i++)
```

```
{ if (r[0] == '1')
```

```
  { q[i] = '1';
```

```
    calram(i);
```

```
  }
```

```
  else
```

```
  { q[i] = '0';
```

```
    shift(i);
```

```
  }
```

```
  r[16] = m[i+16];
```

```

r[17] = '\0';
printf("\n remainder %d : %d", i1, r);
for (j=0; j<17; j++)
    temp[j] = r[j];
}
q[n-16] = '\0';
}

```

```

void calram()

```

```

{
    int i, j;
    for (i=0; i<16; i++)
        r[i-1] = ((int)temp[i]-48) ^ ((int)q[i]-48) + 48;
}

```

```

void shift()

```

```

{
    int i;
    for (i=0; i<=16; i++)
        r[i+1] = r[i];
}

```

```
int main()
```

```
{
```

```
    int n, i=0;
```

```
    char ch, flag=0;
```

```
    printf ("Enter the frame bits:");
```

```
    while ((ch = getc(stdin)) != '\n')
```

```
        m[i++] = ch;
```

```
        i++;
```

```
    for (i=0; i<16; i++)
```

```
        m[n++] = '0';
```

```
        m[n] = '\0';
```

```
    printf ("Message after appending 16 zeros: %s", m);
```

```
    for (i=0; i<16; i++)
```

```
        g[i] = '0';
```

```
    g[0] = g[4] = g[11] = g[16] = '1'; g[17] = '\0';
```

```
    printf ("In generator: %s", g);
```

```
    crc(n);
```

```
    printf ("Xm quotient: %s", q);
```

```
    caltram(n);
```

```
    printf ("transmitted frame: %s", m);
```

```
    printf ("Enter transmitted frame:");
```

```
    scanf ("%s", m);
```

```
    printf ("CRC checking\n");
```

```
    crc(n);
```

```
    printf ("In last remainder: %s", r);
```

```
    for (i=0; i<16; i++)
```

```
    { if (r[i] != '0')
```

```
        flag=1;
```


else

continue;

}

if (flag == 2)

printf ("Error during transmission");

else

printf ("Received frame is correct");

}