02 Linear Regression from Scratch

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```
[1]: %matplotlib inline
  import torch
  from matplotlib import pyplot as plt
  import random
```

1 Linear Regression from Scratch

- This notebook shows how linear regression can be implemented (almost) from scratch. This will involve:
 - Creating a dataset.
 - Defining a linear regression model.
 - Initializing the model parameters (weights and bias).
 - Defining a loss function.
 - Implementing an optimization algorithm (minibatch stochastic gradient descent).
 - Executing the training loop:
 - * Computing the gradient of the loss with respect to the parameters (using automatic differentiation).
 - * Updating the parameters based on this gradient.
- PyTorch already implements many of these steps, as the next notebook will show.

2 Creating the Dataset

- We will create a simple dataset to serve as an example.
- Our goal will be to find the parameters that we used to create this dataset, as if we did not know them.
- The training dataset $(\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(n)}, y^{(n)})$ is composed of n = 1000 examples.
- Each observation $\mathbf{x}^{(i)}$ is a 2-dimensional vector whose features are sampled from a standard normal distribution.
- We will use a design matrix X to represent the observations (without an extra column filled with ones).
- The target vector $\mathbf{y} = [y^{(1)}, \dots, y^{(n)}]^T$ will be given by

$$\mathbf{y} = \mathbf{X}\mathbf{w} + b + \epsilon,$$

where $\mathbf{w} = [2, -3.4]^T$ and b = 4.2 are the true model parameters, and ϵ is an *n*-dimensional noise vector whose elements are sampled from a normal distribution with standard deviation 0.01

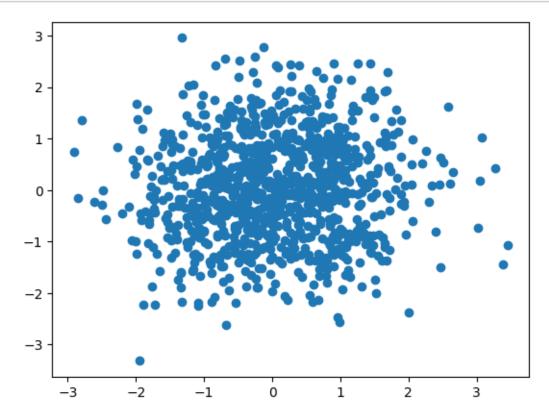
• If the noise vector ϵ were zero, we would only need three examples to find the true parameters.

```
[2]: def synthetic_data(w, b, num_examples):
    """Generate y = Xw + b + noise."""
    X = torch.normal(0, 1, (num_examples, len(w)))
    y = torch.mm(X, w) + b
    y += torch.normal(0, 0.01, y.size())
    return X, y
[3]: true w = torch tensor([[2], [-3, 4]])
```

```
[3]: true_w = torch.tensor([[2], [-3.4]])
    true_b = torch.tensor(4.2)
    features, labels = synthetic_data(true_w, true_b, 1000)
    print(features.size())
    print(labels.size())
```

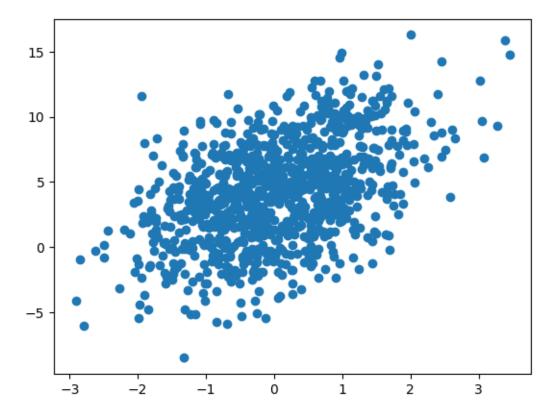
torch.Size([1000, 2])
torch.Size([1000, 1])

```
[4]: # Scatter plot of the observations
plt.scatter(features[:, 0], features[:, 1]);
```

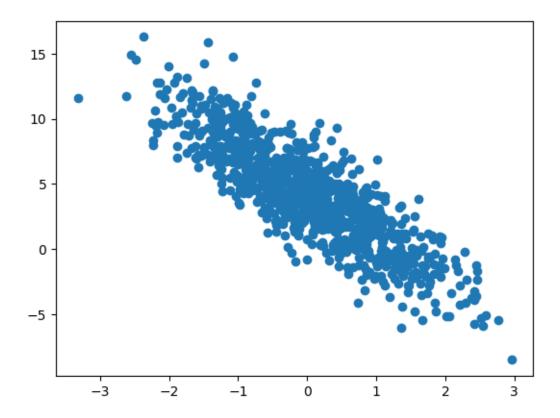


[5]: # Scatter plot of the first features against the targets. Note the positive occurrelation.

plt.scatter(features[:, 0], labels);



[6]: # Scatter plot of the second features against the targets. Note the negative plt.scatter(features[:, 1], labels);



3 Generating batches

- In order to implement minibatch stochastic gradient descent, we need to generate batches of examples.
- In Python, this can be accomplished using a generator.
- The generator data_iter defined below yields a minibatch (a pair of features/labels) each time it is asked for a next element. After the first element is requested, recall that data_iter will resume from yield.

```
[7]: def data_iter(batch_size, features, labels):
    num_examples = len(features)
    indices = list(range(num_examples))
    # The order of examples is randomized once
    random.shuffle(indices)
    for i in range(0, num_examples, batch_size):
        batch_indices = torch.tensor(indices[i: min(i + batch_size,_u
num_examples)])
    yield features[batch_indices], labels[batch_indices]

# Shows first minibatch
```

```
batch_size = 10
for X, y in data_iter(batch_size, features, labels):
    print(f'Features:\n {X}')
    print(f'Labels:\n {y}')
    break
```

Features:

```
tensor([[-2.0636, -0.9750],
        [-1.4682, -0.7159],
        [0.4561, 0.5953],
        [-0.1997, 0.3594],
        [-0.5797, 1.4050],
        [-0.6102, -0.4021],
        [-0.1985, 0.7836],
        [0.3694, -0.3172],
        [-0.4626, 1.1817],
        [ 1.1429, -1.6776]])
Labels:
tensor([[ 3.3835],
        [ 3.6897],
        [3.0818],
        [ 2.5736],
        [-1.7425],
        [4.3405],
        [ 1.1258],
        [6.0209],
        [-0.7439],
        [12.1844]])
```

• PyTorch implements its own highly efficient data iterators that are also able to deal with datasets stored in files.

4 Defining the Model

- Recall that linear regression supposes that the target vector y is given by $\mathbf{y} = \mathbf{X}\mathbf{w} + b$
- Recall that broadcasting can be used to add the bias b to each element of the vector $\mathbf{X}\mathbf{w}$.

```
[8]: def linreg(X, w, b):
    """The linear regression model: y = Xw + b
    X: [num_of_examples, num_of_feat]
    w: [num_of_feat, 1]
    b: scalar
    y: [num_of_examples, 1]"""
    return torch.mm(X, w) + b
```

5 Initializing Model Parameters

- Minibatch stochastic gradient descent requires that the parameters are initialized.
- Since the parameters can be initialized arbitrarily, we will sample each element of the weights from a normal distribution with standard deviation 0.01. We will initialize the bias to zero.
- Note that we request PyTorch to keep track of gradients with respect to w and b.

```
[9]: w = torch.normal(0, 0.01, size=(2,1), requires_grad=True)
b = torch.zeros(1, requires_grad=True)
```

6 Defining the Loss Function

• We can define the squared loss function as follows.

```
[10]: def squared_loss(y_hat, y):
    """Squared_loss."""
    return torch.mean((y_hat - y) ** 2 / 2)
```

7 Defining the Optimization Algorithm

- Although the linear regression problem has an analytic solution, minibatch stochastic gradient descent will also be used for neural networks.
- The following code applies the minibatch stochastic gradient descent update given a set of parameters, a learning rate, and a batch size.
- Note that we do not wish to track gradients of the update operation.

```
[11]: def sgd(params, lr):
    """Minibatch stochastic gradient descent."""
    with torch.no_grad():
        for param in params:
            param -= lr * param.grad
            param.grad.zero_()
```

8 Training Loop

- During each **epoch**:
 - Execute one iteration per minibatch.
 - During each iteration:
 - * Obtain the minibatch.
 - * Compute predictions and loss using the current model (forward pass).
 - * Compute the gradients of the loss with respect to model parameters (backward pass).
 - * Update the model parameters.

```
[12]: # Hyperparameters
      num_epochs = 3
      lr = 0.5
      print('\nInitial parameters:')
      print(w)
      print(b)
      print()
      # Training loop
      for epoch in range(num_epochs):
          for X, y in data iter(batch size, features, labels): # Minibatch: `X` and I
       \hookrightarrow ^{\sim}y
              y_hat = linreg(X, w, b) # Prediction for the minibatch
              1 = squared_loss(y_hat, y) # Loss for the minibatch
              1.backward() # Compute gradient of `l` with respect to [`w`, `b`]
              sgd([w, b], lr) # Update parameters using this gradient
          # After each epoch, computes the loss for the entire training dataset
          with torch.no_grad():
              train_1 = squared_loss(linreg(features, w, b), labels)
              print(f'Epoch: {epoch + 1}. Loss: {float(train_l):f}')
      print('\nLearned parameters:')
      print(w)
      print(b)
      print('\nTrue parameters:')
      print(true_w)
      print(true_b)
     Initial parameters:
     tensor([[-0.0074],
              [ 0.0161]], requires_grad=True)
     tensor([0.], requires_grad=True)
     Epoch: 1. Loss: 0.000060
     Epoch: 2. Loss: 0.000061
     Epoch: 3. Loss: 0.000052
     Learned parameters:
     tensor([[ 1.9997],
              [-3.3993]], requires_grad=True)
     tensor([4.1980], requires_grad=True)
```

9 Evaluation

• Because we created the dataset, we can evaluate our success by comparing the true parameters with the learned parameters.

10 [Storing this notebook as a pdf]