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Source Code
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#include <Wire.h>
#include <RTClib.h>
#include "HX711.h"
RTC DS3231 rtc;
                     // Real-time clock object
const int triggerPin = 9; // Ultrasonic sensor trigger pin
const int echoPin = 10; // Ultrasonic sensor echo pin
const int weightDataPin = A1; // Weight sensor data pin
const int weightClockPin = A2; // Weight sensor clock pin
const int methaneSensorPin = A3; // Methane gas sensor analog pin
const int co2SensorPin = A4; // CO2 gas sensor analog pin
HX711 scale; // Weight sensor object
const int thresholdDistance = 20; // Threshold distance for ultrasonic sensor (in cm)
const float thresholdWeight = 100.0; // Threshold weight for weight sensor (in grams)
const int thresholdMethaneValue = 500; // Threshold methane gas sensor value (adjust as needed)
const int thresholdCO2Value = 800; // Threshold CO2 gas sensor value (adjust as needed)
void setup() {
Serial.begin(9600); // Initialize serial communication
                  // Initialize the Wire library for I2C communication
Wire.begin();
                 // Start RTC module using the default Wire library
rtc.begin();
pinMode(triggerPin, OUTPUT); // Set trigger pin as output
 pinMode(echoPin, INPUT); // Set echo pin as input
```

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scale.begin(weightDataPin, weightClockPin); // Initialize weight sensor
 scale.set_scale(); // Calibrate the weight sensor
scale.tare(); // Reset the scale to 0
}
void loop() {
long duration, distance;
 digitalWrite(triggerPin, LOW);
 delayMicroseconds(2);
 digitalWrite(triggerPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(triggerPin, LOW);
 duration = pulseIn(echoPin, HIGH);
 distance = duration * 0.034 / 2;
 DateTime now = rtc.now();
float weight = scale.get_units(); // Read weight sensor data in grams
int methaneValue = analogRead(methaneSensorPin); // Read methane gas sensor data
int co2Value = analogRead(co2SensorPin); // Read CO2 gas sensor data
if (distance <= thresholdDistance && weight >= thresholdWeight &&
   methaneValue >= thresholdMethaneValue && co2Value >= thresholdCO2Value &&
   now.hour() == 12) {
  // Your logic here for garbage collection
}
if (now.second() % 2 == 0) {
 // Simulate some action if needed
}
```

```
Serial.print("Distance: ");
Serial.print(distance);
Serial.print(" cm | Weight: ");
Serial.print(weight);
Serial.print(" g | Methane Value: ");
Serial.print(methaneValue);
Serial.print(" | CO2 Value: ");
Serial.print(co2Value);
Serial.print(" | Time: ");
Serial.println(now.timestamp());

delay(1000); // Delay for stability
}
```