

# CHAPTER 2

## ARTIFICIAL NEURAL NETWORKS: AN INTRODUCTION

“Principles of Soft Computing, 2<sup>nd</sup> Edition”

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# Back Propagation Algorithm

To derive a convenient expression for  $\frac{\partial E_d}{\partial net_j}$

We consider two cases in turn:

- Case 1, where unit  $j$  is an output unit for the network, and
- Case 2, where unit  $j$  is an internal unit of the network.

# Back Propagation Algorithm

## Case 1: Training Rule for Output Unit Weights

- Just as  $wji$  can influence the rest of the network only through  $net_j$ ,  $net_j$  can influence the network only through  $o_j$ . Therefore, we can invoke the chain rule again to write,

$$\begin{aligned}\frac{\partial E_d}{\partial net_j} &= \frac{\partial E_d}{\partial o_j} \frac{\partial o_j}{\partial net_j} & \frac{\partial E_d}{\partial o_j} &= \frac{\partial}{\partial o_j} \frac{1}{2} \sum_{k \in \text{outputs}} (t_k - o_k)^2 & \frac{\partial o_j}{\partial (net_j)} &= \frac{\partial \sigma(net_j)}{\partial (net_j)} & \frac{\partial \sigma(x)}{\partial (x)} &= \sigma(x) (1 - \sigma(x)) \\ & & & & &= \sigma(net_j) (1 - \sigma(net_j)) \\ & & & & &= o_j (1 - o_j) \\ \frac{\partial E_d}{\partial o_j} &= \frac{\partial}{\partial o_j} \frac{1}{2} (t_j - o_j)^2 \\ &= \frac{1}{2} 2(t_j - o_j) \frac{\partial (t_j - o_j)}{\partial o_j} \\ &= -(t_j - o_j) \\ \frac{\partial E_d}{\partial net_j} &= -(t_j - o_j) o_j (1 - o_j)\end{aligned}$$

# Back Propagation Algorithm

## Case 1: Training Rule for Output Unit Weights

$$\Delta w_{ji} = -\eta \frac{\partial E_d}{\partial w_{ji}}$$

$$\frac{\partial E_d}{\partial net_j} = -(t_j - o_j) o_j(1 - o_j)$$

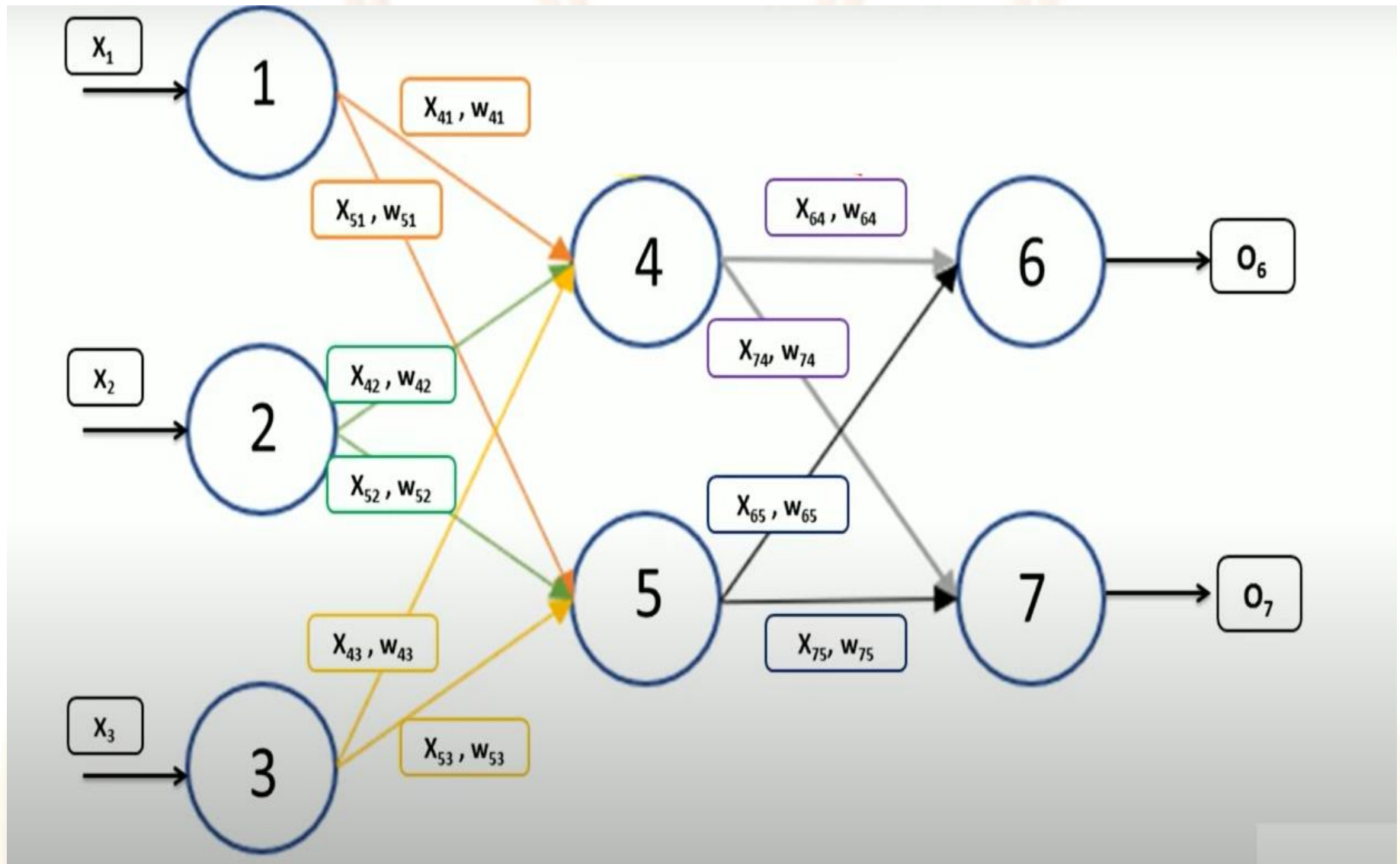
$$\Delta w_{ji} = -\eta \frac{\partial E_d}{\partial net_j} x_{ji}$$

$$\Delta w_{ji} = \eta \underline{(t_j - o_j) o_j(1 - o_j)} x_{ji}$$

$$\delta_j = (t_j - o_j) o_j(1 - o_j)$$

$$\Delta w_{ji} = \eta \delta_j x_{ji}$$

# Back Propagation Algorithm



# Back Propagation Algorithm

## Case 2: Training Rule for Hidden Unit Weights

$$\frac{\partial E_d}{\partial net_j} = \sum_{k \in \text{Downstream}(j)} \frac{\overset{\checkmark}{\partial E_d}}{\overset{\checkmark}{\partial net_k}} \frac{\overset{\checkmark}{\partial net_k}}{\partial net_j}$$

$$= \sum_{k \in \text{Downstream}(j)} \boxed{-\delta_k} \frac{\partial net_k}{\partial net_j}$$

$$= \sum_{k \in \text{Downstream}(j)} -\delta_k \frac{\overset{\checkmark}{\partial net_k}}{\partial o_j} \frac{\partial o_j}{\partial net_j}$$

$$= \sum_{k \in \text{Downstream}(j)} -\delta_k \underline{w_{kj}} \frac{\partial o_j}{\partial net_j}$$

$$= \sum_{k \in \text{Downstream}(j)} -\delta_k w_{kj} o_j (1 - o_j)$$

$$\frac{\partial E_d}{\partial net_j} = -\underline{(t_j - o_j) o_j (1 - o_j)}$$

$$\delta_j = (t_j - o_j) o_j (1 - o_j)$$

$$\frac{\partial net_k}{\partial o_j} = \frac{\partial x_{kj} w_{kj}}{\partial o_j} = \frac{\partial o_j w_{kj}}{\partial o_j}$$

$$\frac{\partial o_j}{\partial (net_j)} = \frac{\partial \sigma(net_j)}{\partial (net_j)}$$

$$= \sigma(net_j) (1 - \sigma(net_j))$$

$$= o_j (1 - o_j)$$

# Back Propagation Algorithm

## Case 2: Training Rule for Hidden Unit Weights

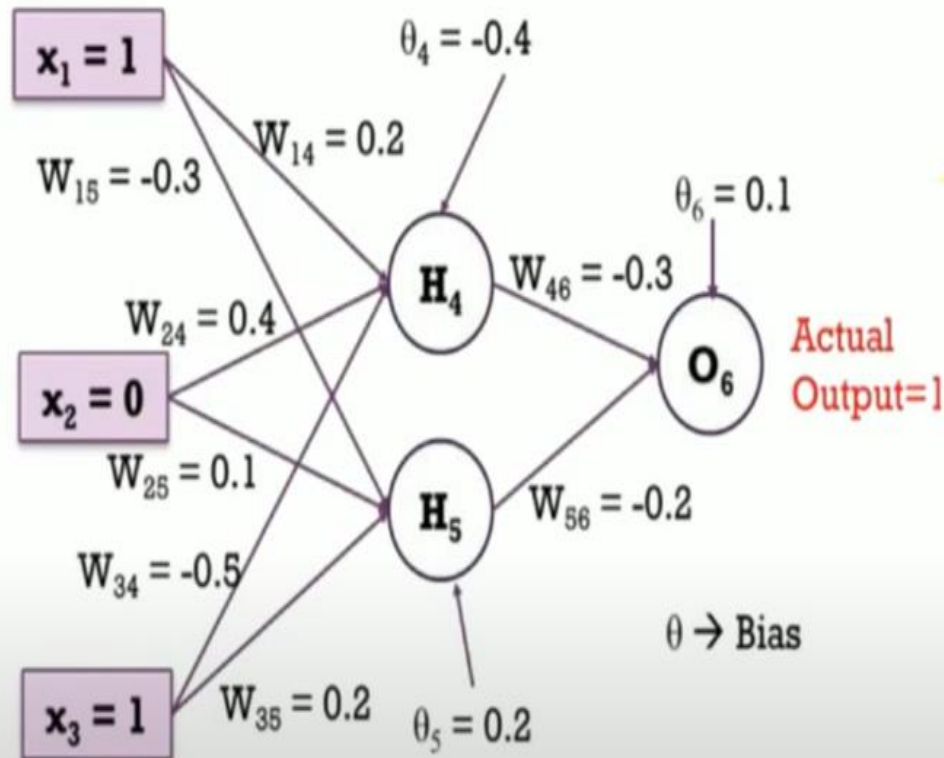
$$\Delta w_{ji} = -\eta \frac{\partial E_d}{\partial net_j} x_{ji} \quad \frac{\partial E_d}{\partial net_j} = \sum_{k \in \text{Downstream}(j)} \underline{-\delta_k} \underline{w_{kj}} \underline{o_j(1 - o_j)}$$

$$\Delta w_{ji} = \eta o_j(1 - o_j) \sum_{k \in \text{Downstream}(j)} \delta_k w_{kj} x_{ji}$$

$$\Delta w_{ji} = \eta \underline{\delta_j} x_{ji} \quad \underline{\delta_j} = o_j(1 - o_j) \sum_{k \in \text{Downstream}(j)} \delta_k w_{kj}$$



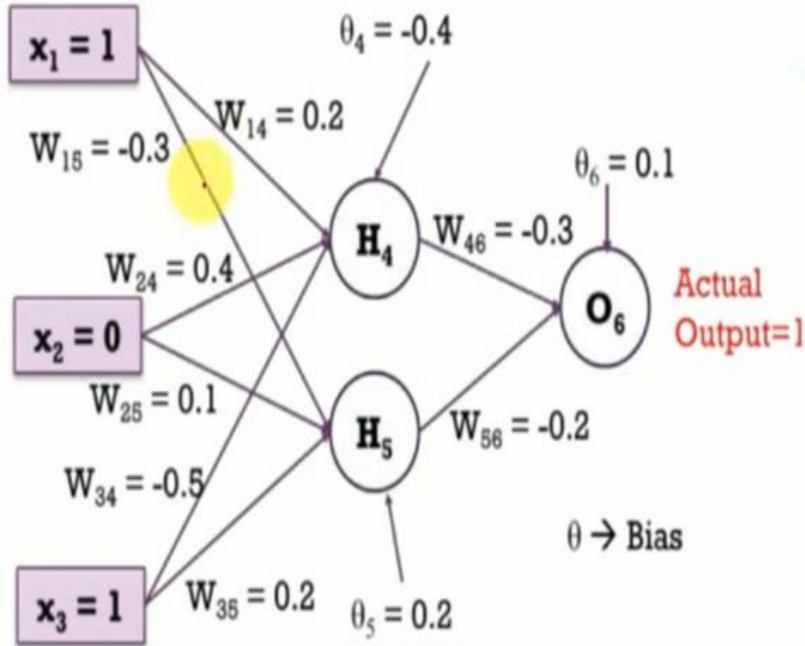
# Back Propagation Algorithm Example



Assume that the neurons have a sigmoid activation function, perform a forward pass and a backward pass on the network. Assume that the actual output of  $y$  is 1 and learning rate is 0.9. Perform another forward pass.



# Back Propagation Algorithm Example



$$\text{Error} = y_{\text{target}} - y_6 = 0.526$$

- Forward Pass: Compute output for  $y_4$ ,  $y_5$  and  $y_6$ .

$$a_j = \sum_i (w_{ij} * x_i) \quad y_j = F(a_j) = \frac{1}{1 + e^{-a_j}}$$

$$\begin{aligned} a_4 &= (w_{14} * x_1) + (w_{24} * x_2) + (w_{34} * x_3) + \theta_4 \\ &= (0.2 * 1) + (0.4 * 0) + (-0.5 * 1) + (-0.4) = -0.7 \\ O(H_4) &= y_4 = f(a_4) = \frac{1}{1 + e^{0.7}} = 0.332 \end{aligned}$$

$$\begin{aligned} a_5 &= (w_{15} * x_1) + (w_{25} * x_2) + (w_{35} * x_3) + \theta_5 \\ &= (-0.3 * 1) + (0.1 * 0) + (0.2 * 1) + (0.2) = 0.1 \\ O(H_5) &= y_5 = f(a_5) = \frac{1}{1 + e^{-0.1}} = 0.525 \end{aligned}$$

$$\begin{aligned} a_6 &= (w_{46} * H_4) + (w_{56} * H_5) + \theta_6 \\ &= (-0.3 * 0.332) + (-0.2 * 0.525) + 0.1 = -0.105 \\ O(O_6) &= y_6 = f(a_6) = \frac{1}{1 + e^{0.105}} = 0.474 \end{aligned}$$

# Back Propagation Algorithm Example

- Each weight changed by:

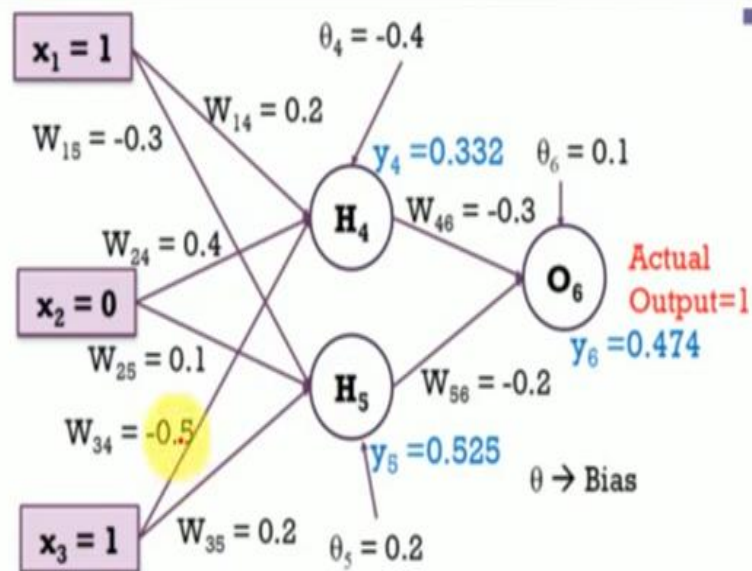
$$\Delta w_{ji} = \eta \delta_j o_i$$

$$\delta_j = o_j(1 - o_j)(t_j - o_j) \quad \text{if } j \text{ is an output unit}$$

$$\delta_j = o_j(1 - o_j) \sum_k \delta_k w_{kj} \quad \text{if } j \text{ is a hidden unit}$$

- where  $\eta$  is a constant called the learning rate
- $t_j$  is the correct teacher output for unit  $j$
- $\delta_j$  is the error measure for unit  $j$

# Back Propagation Algorithm Example



Compute new weights

$$\Delta w_{ji} = \eta \delta_j o_i$$

$$\Delta w_{46} = \eta \delta_6 y_4 = 0.9 * 0.1311 * 0.332 = 0.03917 \checkmark$$

$$w_{46}(\text{new}) = \Delta w_{46} + w_{46}(\text{old}) = 0.03917 + (-0.3) = -0.261$$

$$\Delta w_{14} = \eta \delta_4 x_1 = 0.9 * -0.0087 * 1 = -0.0078$$

$$w_{14}(\text{new}) = \Delta w_{14} + w_{14}(\text{old}) = -0.0078 + 0.2 = 0.192$$

- Backward Pass: Compute  $\delta_4, \delta_5$  and  $\delta_6$ .

For output unit:

$$\delta_6 = y_6(1-y_6)(y_{\text{target}} - y_6) = 0.474 * (1-0.474) * (1-0.474) = \underline{0.1311}$$

For hidden unit:

$$\delta_5 = y_5(1-y_5) w_{56} * \delta_6 = 0.525 * (1 - 0.525) * (-0.2 * 0.1311) = \underline{-0.0065}$$

$$= y_4(1-y_4) w_{46} * \delta_6$$

$$= 0.332 * (1 - 0.332) * (-0.3 * 0.1331) = \underline{-0.0087}$$



# Back Propagation Algorithm Example

- Similarly, update all other weights

i	j	$w_{ij}$	$\delta_i$	$x_i$	$\eta$	Updated $w_{ij}$
4	6	-0.3	0.1311	0.332	0.9	-0.261
5	6	-0.2	0.1311	0.525	0.9	-0.138
1	4	0.2	-0.0087	1	0.9	0.192
1	5	-0.3	-0.0065	1	0.9	-0.306
2	4	0.4	-0.0087	0	0.9	0.4
2	5	0.1	-0.0065	0	0.9	0.1
3	4	-0.5	-0.0087	1	0.9	-0.508
3	5	0.2	-0.0065	1	0.9	0.194

# Back Propagation Algorithm Example

- Similarly, update bias weights

$\theta_j$	Previous $\theta_j$	$\delta_j$	$\eta$	Updated $\theta_j$
$\Theta_6$	0.1	0.1311	0.9	0.218
$\Theta_5$	0.2	-0.0065	0.9	0.194
$\Theta_4$	-0.4	-0.0087	0.9	-0.408