

Appendix E

Denotational semantics of Sodium

Revision 1.1—26 Apr 2016

Introduction

This document is the formal specification of the semantics of Sodium, an FRP system based on the concepts from Conal Elliott's paper "Push-Pull FRP." The code in this document is in Haskell, and a basic understanding of Haskell is required to understand it. Most readers won't need this information, but people interested in FRP semantics and developers of FRP systems will find it useful. Note that this has nothing to do with the Haskell implementation of Sodium. The executable version of this specification can be found at <https://github.com/SodiumFRP/sodium/blob/master/denotational/>.

Revision history

- 1.0 (19 May 2015)—First version
- 1.1 (24 July 2015)—The times for streams changed to increasing instead of nondecreasing so that multiple events per time are no longer representable
- 1.1 (8 Oct 2015, 26 Apr 2016)—Minor corrections; no semantic change

Data types

Sodium has two data types:

- `Stream a`—A sequence of events, equivalent to Conal's `Event`
- `Cell a`—A value that changes over time, equivalent to Conal's `Behavior`

We replace Conal's term *event occurrence* with *event*.

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Primitives

We define a type `T` representing time that is a total order. For the `Split` primitive, we need to extend that definition to be hierarchical such that for any time `t` we can add children numbered with natural numbers that are all greater than `t` but smaller than any greater sibling of `t`. In the executable version, we have used the type

```
type T = [Int]
```

with comparison defined such that early list elements have precedence over later ones.

Sodium has 16 primitives. Primitives marked with `*` are non-primitive, because they can be defined in terms of other primitives:

- `Never :: Stream a`
- `MapS :: (a → b) → Stream a → Stream b`
- `Snapshot* :: (a → b → c) → Stream a → Cell b → Stream c`
- `Merge :: Stream a → Stream a → (a → a → a) → Stream a`
- `Filter :: (a → Bool) → Stream a → Stream a`
- `SwitchS :: Cell (Stream a) → Stream a`
- `Execute :: Stream (Reactive a) → Stream a`
- `Updates :: Cell a → Stream a`
- `Value :: Cell a → T → Stream a`
- `Split :: Stream [a] → Stream a`
- `Constant* :: a → Cell a`
- `Hold :: a → Stream a → T → Cell a`
- `MapC :: (a → b) → Cell a → Cell b`
- `Apply :: Cell (a → b) → Cell a → Cell b`
- `SwitchC :: Cell (Cell a) → T → Cell a`
- `Sample :: Behavior a → T → a`

`Reactive` is a helper monad that's equivalent to `Reader T`. It represents a computation that's executed at a particular instant in time. Its declaration is as follows:

```
data Reactive a = Reactive { run :: T → a }
```

`Execute` works with this monad. In the Haskell implementation, `Reactive` is part of the public interface of Sodium used to construct the four primitives that take a `T` argument representing the time when that primitive was constructed: `Value`, `Hold`, `SwitchC`, and `Sample`. Most languages don't support monads, so they instead use a concept of transactions, but the meaning is the same. The output values of those four primitives can never be sampled before the time `t` they were constructed, for these reasons:

- The public interface only allows `Value`, `Hold`, `SwitchC`, and `Sample` to be

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constructed through `Reactive`.

- The time at which the simulation is sampled is always increasing.
- The public interface only allows `Reactive` to be resolved once the simulation has reached time `t`.
- The public interface only allows streams and cells to be sampled at the current simulation time.

We define semantic domains $S\ a$ and $C\ a$ for streams and cells:

- `type S a = [(T, a)]` for increasing `T` values
- `type C a = (a, [(T, a)])` for increasing `T` values

$S\ a$ represents a list of time/value pairs describing the events of the stream. $C\ a$ represents (initial value, steps) for the cell: the initial value pertains to all times before the first step, and the time/value pairs give the discrete steps in the cell's value.

We define these semantic functions to transform streams and cells to their semantic domains:

```
occs :: Stream a → S a
steps :: Cell a → C a
```

$C\ a$ is different than Conal Elliott's semantic domain for behavior, which was

```
type B a = T → a
```

The reason for this choice is that it makes `Updates` and `Value` possible, and it allows the cell variant of `switch` to take `Cell (Cell a)` as its argument instead of `Cell a → Stream (Cell a)`, effectively decoupling it from stepper/hold functionality. Something roughly equivalent to Conal's `switcher` can be defined as follows, if we posit that `[0]` is the smallest possible value of `T`:

```
switcher :: Cell a → Stream (Cell a) → Cell a
switcher c s = SwitchC (Hold c s [0]) [0]
```

We can derive Conal's $B\ a$ from $C\ a$ with an `at` function:

```
at :: C a → T → a
at (a, sts) t = last (a : map snd (filter (\(tt, a) → tt < t) sts))
```

Test cases

Now we'll give the definitions of the semantic functions `occs` and `steps` for each primitive, with test cases to show things are working as expected. `MkStream` is the inverse of `occs`, constructing a `Stream a` from an $S\ a$. We use it to feed input into our test cases.

Never

```
Never :: Stream a
```

A stream that never fires:

```
occs Never = []
```

TEST CASES

See figure E.1.

```
let s = Never
```

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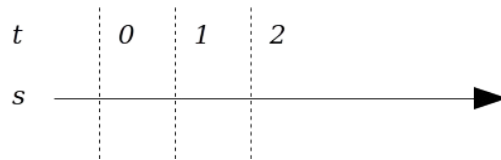


Figure E.1 Never test

MapS

`MapS :: (a → b) → Stream a → Stream b`

Map a function over a stream:

`occs (MapS f s) = map (\(t, a) → (t, f a)) (occs s)`

TEST CASES

See figure E.2.

```
let s1 = MkStream [([0], 5), ([1], 10), ([2], 12)]
let s2 = MapS (1+) s1
```

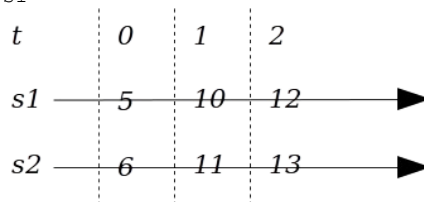


Figure E.2 MapS test

Snapshot

`Snapshot :: (a → b → c) → Stream a → Cell b → Stream c`

Capture the cell's observable value as at the time when the stream fires:

`occs (Snapshot f s c) = map (\(t, a) → (t, f a (at stsb t))) (occs s)`
 where `stsb = steps c`

Note: Snapshot is non-primitive. It can be defined in terms of MapS, Sample, and Execute:

`snapshot2 f s c = Execute (MapS (\a → f a <$> sample c) s)`

NOTE To make it easier to see the underlying meaning, we're diagramming cells in their "cooked" form with the observable values it would give us and vertical lines to indicate the steps, not directly in their B a representation of initial value and steps.

TEST CASES

See figure E.3.

```
let c = Hold 3 (MkStream [([1], 4), ([5], 7)]) [0]
let s1 = MkStream [([0], 'a'), ([3], 'b'), ([5], 'c')]
let s2 = Snapshot (flip const) s1 c
```

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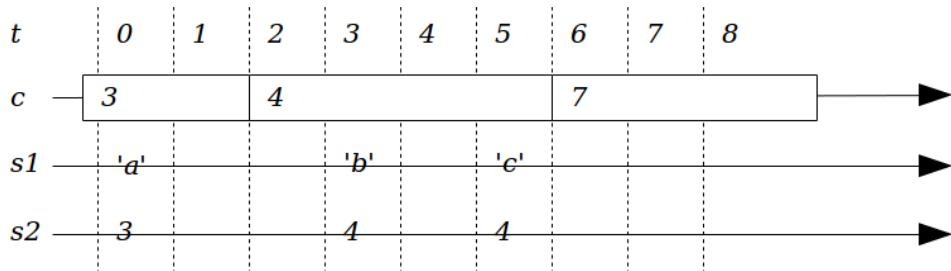


Figure E.3 Snapshot test

Merge

```
Merge :: Stream a → Stream a → (a → a → a) → Stream a
```

Merge the events from two streams into one. A stream can have simultaneous events, meaning two or more events with the same value t , which have an order. $s3$ in the following diagram gives an example. Merge is left-biased, meaning for time t , events originating in the left input event are output before ones from the right:

```
occs (Merge sa sb) = coalesce f (knit (occs sa) (occs sb))
  where knit ((ta, a):as) bs@((tb, _):_) | ta <= tb = (ta, a) : knit as bs
        knit as@((ta, _):_) ((tb, b):bs) = (tb, b) : knit as bs
        knit as bs = as ++ bs
coalesce :: (a → a → a) → S a → S a
coalesce f ((t1, a1):(t2, a2):as) | t1 == t2 = coalesce f ((t1, f a1
a2):as)
coalesce f (ta:as) = ta : coalesce f as
coalesce f [] = []
```

TEST CASES

See figure E.4.

```
let s1 = MkStream [([0], 0), ([2], 2)]
let s2 = MkStream [([1], 10), ([2], 20), ([3], 30)]
let s3 = Merge s1 s2 (+)
```

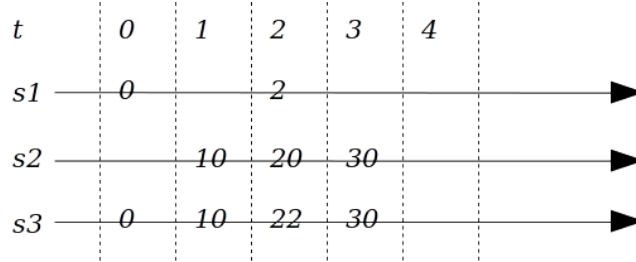


Figure E.4 Merge test

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Filter

```
Filter :: (a → Bool) → Stream a → Stream a
```

Filter events by a predicate:

```
occs (Filter pred s) = filter (\(t, a) → pred a) (occs s)
```

TEST CASES

See figure E.5.

```
let s1 = MkStream [([0], 5), ([1], 6), ([2], 7)]
let s2 = Filter odd s1
```

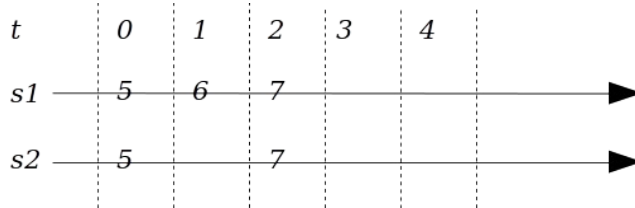


Figure E.5 Filter test

SwitchS

```
SwitchS :: Cell (Stream a) → Stream a
```

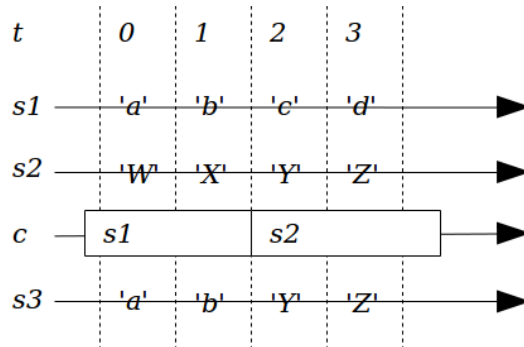
Act like the stream that is the current value of the cell:

```
occs (SwitchS c) = scan Nothing a sts
  where (a, sts) = steps c
        scan mt0 a0 ((t1, a1):as) =
          filter (\(t, a) → maybe True (t >) mt0 && t <= t1) (occs a0)
          ++ scan (Just t1) a1 as
        scan mt0 a0 [] =
          filter (\(t, a) → maybe True (t >) mt0) (occs a0)
```

TEST CASES

See figure E.6.

```
let s1 = MkStream [([0], 'a'), ([1], 'b'), ([2], 'c'), ([3], 'd')]
let s2 = MkStream [([0], 'W'), ([1], 'X'), ([2], 'Y'), ([3], 'Z')]
let c = Hold s1 (MkStream [([1], s2)]) [0]
let s3 = SwitchS c
```



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Figure E.6 SwitchS test

Execute

```
Execute :: Stream (Reactive a) → Stream a
```

Unwrap the `Reactive` helper monad value of the occurrences, passing it the time of the occurrence. This is commonly used when we want to construct new logic to activate with `SwitchC` or `SwitchS`:

```
occs (Execute s) = map (\(t, ma) → (t, run ma t)) (occs s)
```

TEST CASES

See figure E.7.

```
let s1 = MkStream [[0], return 'a']]
let s2 = Execute s1
```

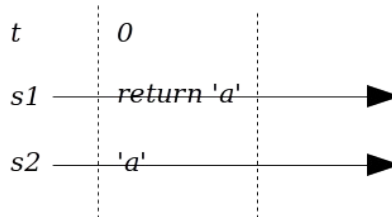


Figure E.7 Execute test

Updates

```
Updates :: Cell a → Stream a
```

A stream representing the steps in a cell, which breaks the principle of non-detectability of cell steps. Updates must therefore be treated as operational primitives, for use only in defining functions that don't expose cell steps to the caller. If the cell had been the `Hold` of stream s , it would be equivalent to `Coalesce (flip const) s`.

```
occs (Updates c) = sts
  where (_, sts) = steps c
```

TEST CASES

See figure E.8.

```
let c = Hold 'a' (MkStream [[1], 'b'], ([3], 'c')) [0]
let s = Updates c
```

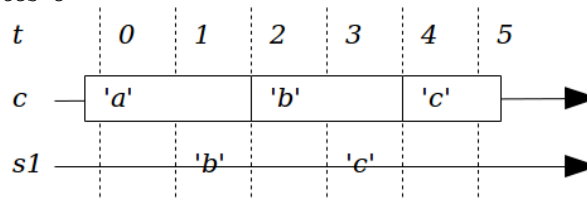


Figure E.8 Updates test

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Value

```
Value :: Cell a → T → Stream a
```

Like `Updates`, except it also fires once with the current cell value at the time `t0` when it's constructed. Also like `Updates`, `Value` breaks the non-detectability of cell steps and so is treated as an operational primitive:

```
occs (Value c t0) = coalesce (flip const) ((t0, a) : sts)
  where (a, sts) = chopFront (steps c) t0
chopFront :: C a → T → C a
chopFront (i, sts) t0 = (at (i, sts) t0, filter (\(t, a) → t >= t0) sts)
```

Note that `Value` has the property that it can create an event occurrence out of nothing. It's possible to argue that it's reconstructing an event occurrence that we can prove exists—the one that drives the `Execute` that must have executed this instance of `Value`. It's the same event occurrence that `Sample` implies the existence of if it's seen as being based on `Snapshot`.

TEST CASES

See figure E.9

```
let c = Hold 'a' (MkStream [([1], 'b'), ([3], 'c')]) [0]
let s = Value c [0]
```

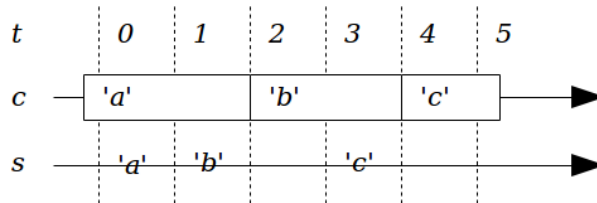


Figure E.9 Value test 1

See figure E.10

```
let c = Hold 'a' (MkStream [([0], 'b'), ([1], 'c'), ([3], 'd')]) [0]
let s = Value c [0]
```

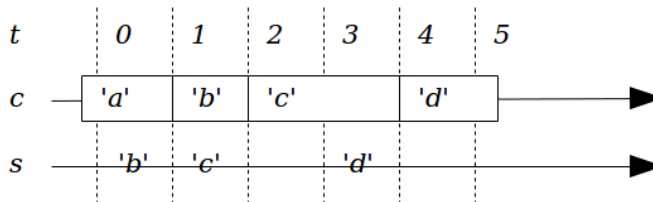


Figure E.10 Value test 2

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Split

`Split :: Stream [a] → Stream a`

Put the values into newly created child time steps:

```
occs (Split s) = concatMap split (coalesce (++) (occs s))
  where split (t, as) = zipWith (\n a → (t++[n], a)) [0..] as
```

TEST CASES

See figure E.11.

```
let s1 = MkStream [([0], ['a', 'b']), ([1], ['c'])]
let s2 = Split s1
```

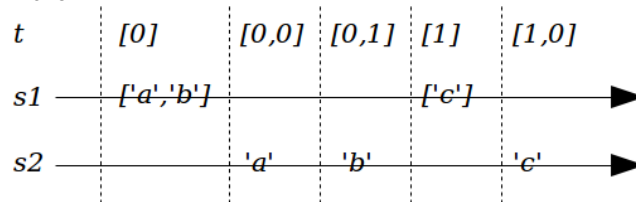


Figure E.11 Split test

Constant

`Constant :: a → Cell a`

A cell with an initial value but no steps:

```
steps (Constant a) = (a, [])
```

Note that `Constant` is non-primitive. It can be defined in terms of `Hold` and `Never`.

TEST CASES

See figure E.12.

```
let c = Constant 'a'
```

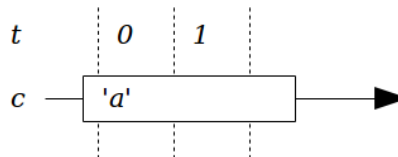


Figure E.12 Constant test

Hold

`Hold :: a → Stream a → T → Cell a`

A cell with an initial value of `a` and the specified steps, ignoring any steps before specified `t0`:

```
steps (Hold a s t0) = (a, coalesce (flip const)
  (filter (\(t, a) → t >= t0) (occs s)))
```

We coalesce to maintain the invariant that step times in `C a` are increasing. Where input events are simultaneous, the last is taken. Events before `t0` are discarded.

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TEST CASES

See figure E.13.

```
let c = Hold 'a' (MkStream [([1], 'b'), ([3], 'c')]) [0]
```

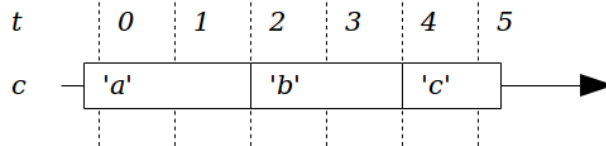


Figure E.13 Hold test

MapC

```
MapC :: (a → b) → Cell a → Cell b
```

Map a function over a cell:

```
steps (MapC f c) = (f a, map \ (t, a) → (t, f a)) sts)
  where (a, sts) = steps c
```

TEST CASES

See figure E.14.

```
let c1 = Hold 0 (MkStream [([2], 3), ([3], 5)]) [0]
let c2 = MapC (1+) c1
```

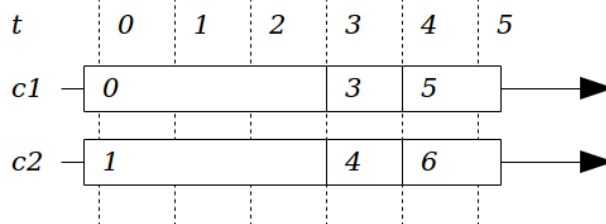


Figure E.14 MapC test

Apply

```
Apply :: Cell (a → b) → Cell a → Cell b
```

Applicative “apply” operation, as the basis for function lifting:

```
steps (Apply cf ca) = (f a, knit f fsts a asts)
  where (f, fsts) = steps cf
        (a, asts) = steps ca
        knit _ ((tf, f):fs) a as@((ta, _):_)
          | tf < ta = (tf, f a) : knit f fs a as
        knit f fs@((tf, _):_) _ ((ta, a):as)
          | tf > ta = (ta, f a) : knit f fs a as
        knit _ ((tf, f):fs) _ ((ta, a):as)
          | tf == ta = (tf, f a) : knit f fs a as
        knit _ ((tf, f):fs) a [] = (tf, f a) : knit f fs a []
        knit f [] _ ((ta, a):as) = (ta, f a) : knit f [] a as
        knit _ [] _ [] = []
```

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Note the “no glitch” rule: where both cells are updated in the same time t , we output only one output step.

TEST CASES

See figure E.15.

```
let cf = Hold (0+) (MkStream [([1], (5+)), ([3], (6+))]) [0]
let ca = Hold (100 :: Int) (MkStream [([1], 200), ([2], 300),
                                     ([4], 400)]) [0]
```

```
let cb = Apply cf ca
```

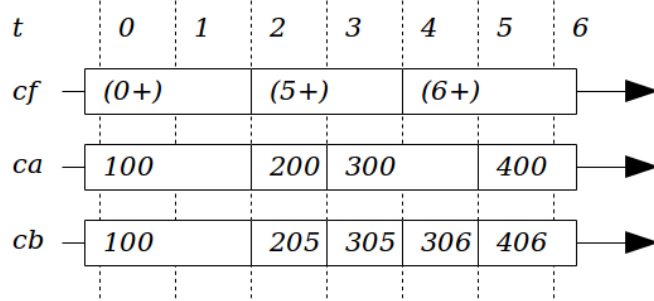


Figure E.15 Apply test

SwitchC

```
SwitchC :: Cell (Cell a) → T → Cell a
```

Act like the current cell that's contained in the cell:

```
steps (SwitchC c t0) = (at (steps (at (steps c) t0)) t0,
  coalesce (flip const) (scan t0 a sts))
  where (a, sts) = steps c
        scan t0 a0 ((t1, a1):as) =
          let (b, stsb) = normalize (chopBack
                                     (chopFront (steps a0) t0) t1)
          in ((t0, b) : stsb) ++ scan t1 a1 as
        scan t0 a0 [] =
          let (b, stsb) = normalize (chopFront (steps a0) t0)
          in ((t0, b) : stsb)
        normalize :: C a → C a
        normalize (_, (t1, a) : as) | t1 == t0 = (a, as)
        normalize as = as
        chopBack :: C a → T → C a
        chopBack (i, sts) tEnd = (i, filter (\(t, a) → t < tEnd) sts)
```

The purpose of `normalize` is to get rid of simultaneousness returned by `chopFront` where the first step occurs at the chop point t_0 . It discards the initial value and replaces that with the first step value. This is different than how `Value` uses `chopFront`: in that case, we keep the simultaneous events.

TEST CASES

See figure E.16.

```
let c1 = Hold 'a' (MkStream [([0], 'b'), ([1], 'c')],
```

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```

let c2 = Hold 'V' (MkStream [([0], 'W'), ([1], 'X'),
                             ([2], 'Y'), ([3], 'Z')]) [0]
let c3 = Hold c1 (MkStream [([1], c2)]) [0]
let c4 = SwitchC c3 [0]

```

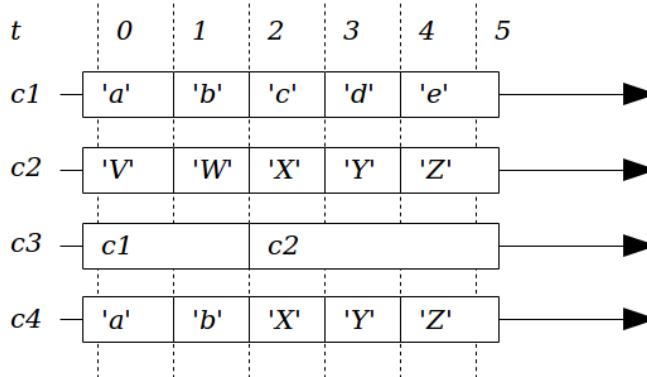


Figure E.16 SwitchC test 1

See figure E.17.

```

let c1 = Hold 'a' (MkStream [([0], 'b'), ([1], 'c'), ([2], 'd'),
                             ([3], 'e')]) [0]
let c2 = Hold 'W' (MkStream [([1], 'X'), ([2], 'Y'), ([3], 'Z')]) [0]
let c3 = Hold c1 (MkStream [([1], c2)]) [0]
let c4 = SwitchC c3 [0]

```

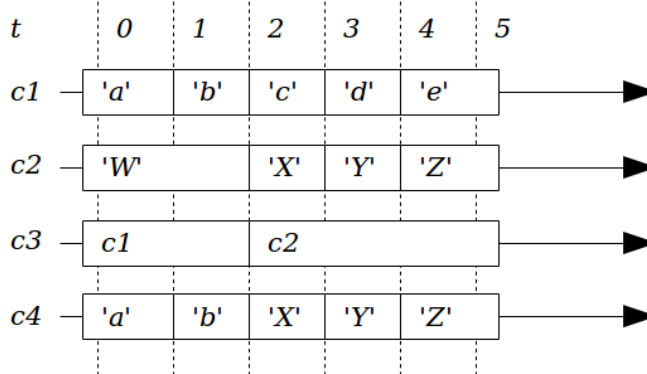


Figure E.17 SwitchC test 2

See figure E.18.

```

let c1 = Hold 'a' (MkStream [([0], 'b'), ([1], 'c'),
                             ([2], 'd'), ([3], 'e')]) [0]
let c2 = Hold 'X' (MkStream [([2], 'Y'), ([3], 'Z')]) [0]

```

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```
let c3 = Hold c1 (MkStream [([1], c2)]) [0]
let c4 = SwitchC c3 [0]
```

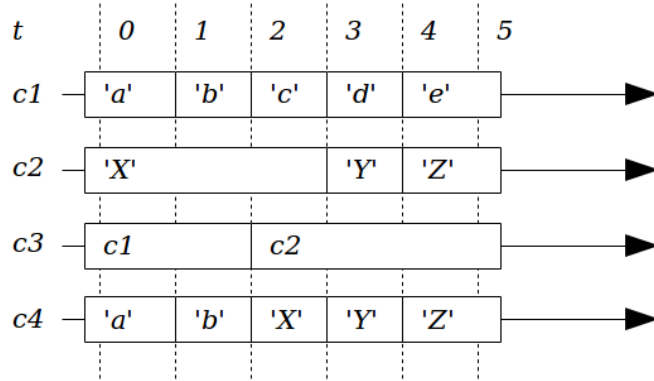


Figure E.18 SwitchC test 3

See figure E.19.

```
let c1 = Hold 'a' (MkStream [([0], 'b'), ([1], 'c'),
                             ([2], 'd'), ([3], 'e')]) [0]
let c2 = Hold 'V' (MkStream [([0], 'W'), ([1], 'X'),
                             ([2], 'Y'), ([3], 'Z')]) [0]
let c3 = Hold '1' (MkStream [([0], '2'), ([1], '3'),
                             ([2], '4'), ([3], '5')]) [0]
let c4 = Hold c1 (MkStream [([1], c2), ([3], c3)]) [0]
let c5 = SwitchC c4 [0]
```

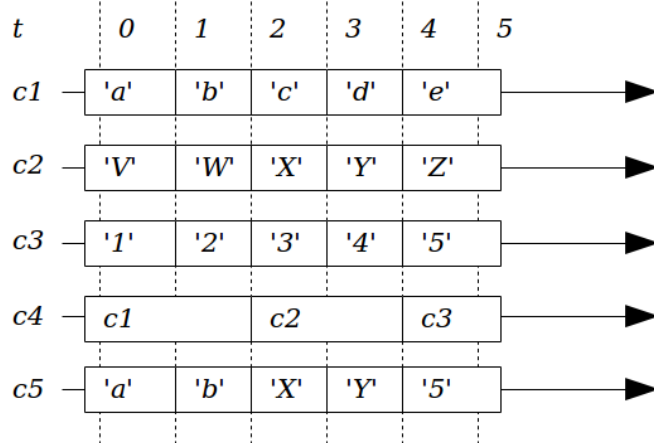


Figure E.19 SwitchC test 4

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Sample

Sample :: Cell a → T → a

Extract the observable value of the cell at time t:

sample :: Cell a → Reactive a

sample c = Reactive (at (steps c))

TEST CASES

See figure E.20.

```
let c = Hold 'a' (MkStream [([1], 'b')]) [0]
let a1 = run (sample c) [1]
let a2 = run (sample c) [2]
```

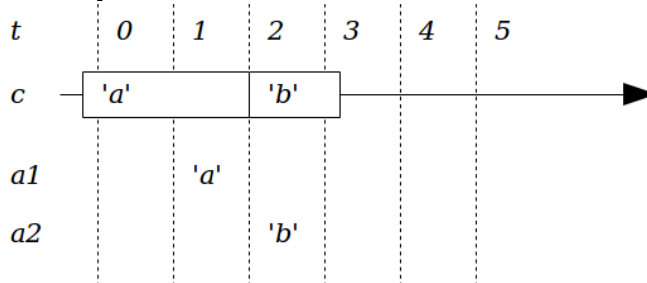


Figure E.20 Sample test

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