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% SOM routine
% uses the following scripts or functions:
% vec2pat(), pat2vec()
% find_closest_cluster()
% alphafnc(i,j,ictr,jctr,time)
% view_all_pattern_responses()
% eval_test_patterns

% clear; % delete all memory
% clc; % clear windows screen
% clf; % clear figure screen
% shg; % put figure screen on top of all screens

% load in training patterns
load scrambled_blobs

% shuffle the random number generator
rng 'shuffle'

% find the size and number of these patterns
[npats,nrows,ncols]=size(scrambled_blobs);

% image represented as a vector has this many elements
vecdim=nrows*ncols;

% the maximum number of epochs
MAX_NUM_ITERS = 100000;

% the maximum learning rate
MAX_ALPHA = 0.5;

% the minimum learning rate
MIN_ALPHA = 0.01;

% specify cluster grid dimensions
nclustrows=8;
nclustcols=8;

% initial neighborhood radius
MAX_RADIUS = (max(nclustrows, nclustcols)/2);

clusters=zeros(nclustrows,nclustcols,vecdim);

% seeds all clusters with random values between 0 and 1
for i=1:nclustrows
    for j=1:nclustcols
        clusters(i, j, :) = rand(vecdim,1);
    end
end

% initialize sample pattern matrix
scrambled_pats = zeros(npats,vecdim);

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% normalize each training pattern
for ipat=1:npat
    temp=pat2vec(squeeze(scrambled_blobs(ipat,:,:)));
    temp=temp/norm(temp);
    scrambled_pats(ipat,:)=temp;
end

% view decoding of 3 test patterns, I, H and X
% I, H and X will be unrecognizable at this point
eval_test_patterns;

% Now, train the clusters.
% draw from input pattern vector pool at random--
% find closest cluster, which is indexed by ibest, jbest
% update both the best-fit cluster as well as its neighbors
% neighborhood operator should shrink over time to influence fewer neighbors
% max influence of a training pattern may also decrease over time

% initialize the current iteration and display counter
curr_iter=0;
display_counter=0;

% initialize the neighborhood function vector
neighborhood = zeros(nclustrows, nclustcols);

% this is our radius decay time constant
r_time_constant = MAX_NUM_ITERS/log(MAX_RADIUS);

% set as infinite loop (and halt w/ control-C); or, put cap on "time" for max iterations
while curr_iter <= MAX_NUM_ITERS
    % calculate the neighborhood radius at this time
    % exponential decay
    % curr_radius = MAX_RADIUS * exp(-curr_iter/r_time_constant);
    % linear decay
    curr_radius = MAX_RADIUS * (1 - curr_iter/MAX_NUM_ITERS);

    % find the variance of the neighborhood
    variance = curr_radius ^ 2;

    % calculate the learning rate at this time
    if curr_iter > 0
        %power series decay
        %curr_alpha = MAX_ALPHA*((0.005/MAX_ALPHA)^(curr_iter/MAX_NUM_ITERS));
        %linear decay
        %curr_alpha = 1/curr_iter;
        %exponential decay
        curr_alpha = MAX_ALPHA * exp(-curr_iter/MAX_NUM_ITERS);
    else
        curr_alpha = 1;
    end

    % make sure learning rate is at least the minimum
    if curr_alpha < MIN_ALPHA
        curr_alpha = MIN_ALPHA;
    end
end

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end

% pick a pattern at random
rand_ipat=ceil(rand*npats);

% extract the corresponding vector and transpose it to be a column
training_features=squeeze(scrambled_pats(rand_ipat,:))';

% for the selected pattern, find which cluster is most similar.
% identify this cluster in terms of its grid location, ictr,jctr
[ictr,jctr]=find_best_matching_cluster(training_features,clusters);

% calculate the neighborhood function values for each cluster
for i=1:nclustrows
    for j=1:nclustcols
        % this cluster is the winner and has best neighborhood
        % influence
        if i == ictr && j == jctr
            neighborhood(i,j)=1;
            continue
        else
            % these clusters have a scaled neighborhood influence
            % Gaussian Neighborhood
            dist_from_bmu=(ictr - i)^2 + (jctr - j)^2;
            neighborhood(i,j)=exp(-dist_from_bmu/(2*variance));
            % Epanechnikov Neighborhood
            % dist_from_bmu = pdist([ictr,jctr;i,j], 'euclidean');
            % neighborhood(i,j)=max(0,1-(curr_radius-dist_from_bmu)^2);
            % Cut Gaussian Neighborhood
            dist_from_bmu = pdist([ictr,jctr;i,j], 'euclidean');
            if dist_from_bmu < curr_radius
                neighborhood(i,j)=exp(-dist_from_bmu/(2*variance));
            else
                neighborhood(i,j)=0;
            end
        end
    end
end

% update the bmu cluster and its neighbors
for i=1:nclustrows
    for j=1:nclustcols
        % grab the feature vector of the current cluster
        curr_features = squeeze(clusters(i,j,:));

        updated_features=curr_features + curr_alpha*neighborhood(i,j)*...
            (training_features-curr_features);

        % normalize the newly calculated cluster features
        norm_features = norm(updated_features);
        if norm_features > 0
            updated_features = updated_features/norm_features;
        end
    end
end

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        clusters(i,j,:) = updated_features;
    end
end

% review results after each 1000 pattern updates
if (display_counter>=1000)
    fprintf('updating graphs at iteration: %d\n', curr_iter);

    % pause to let gui update graphs
    pause(3);

    % are clusters performing decoding? Check cluster responses to I, H
    % and X scrambled test patterns
    view_all_pattern_responses(scrambled_pats,clusters);

    eval_test_patterns
    display_counter=0;

    % save cluster results to file clusters.mat
    save('clusters','clusters');
end

% increment the iteration and display counter by 1
curr_iter=curr_iter+1;
display_counter=display_counter+1;
end

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