

ELEC 424/553

Mobile & Embedded Systems

Lecture 18
systemd, computer vision

Install php while you are waiting:

- **sudo apt update**
 - (NOT UPGRADE!!)
- **sudo apt install php**
- **sudo apt install python3-opencv**

If on Mac, also install XQuartz

If on Windows, install MobaXTerm

The Goal

- Learn how to use the device tree
 - Project 2
- Learn about general operation of kernel (and more)
 - Midterm
- (optionally) Learn how to use Rust
 - (optional) Assignment 3
- Put everything together by building an advanced mobile & embedded system
 - Final Project (with project 3 as a milestone towards the final project)
- This is a lot
- But with diligence, you can be done before the end of the last day of classes

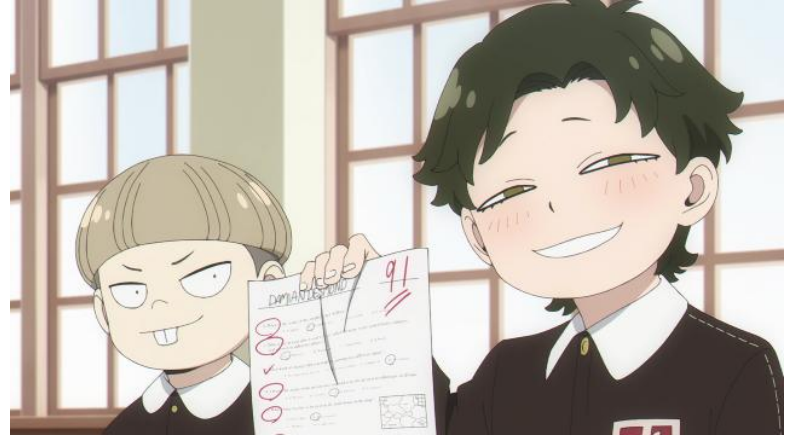
Housekeeping - Project 2

- Due this Friday Nov 3 at 11:59pm
 - ONLY in person demos allowed
 - Demo and help times:
 - Before and after class
 - Joe's office hours Tuesday 3-4pm in Duncan Hall 2098
 - Lucy's office hours Wednesday 5:30-6:30pm in Ryon B10
 - Friday 3-5pm in Ryon B10
- Any questions?

Project 2 Demo

Housekeeping - Midterm

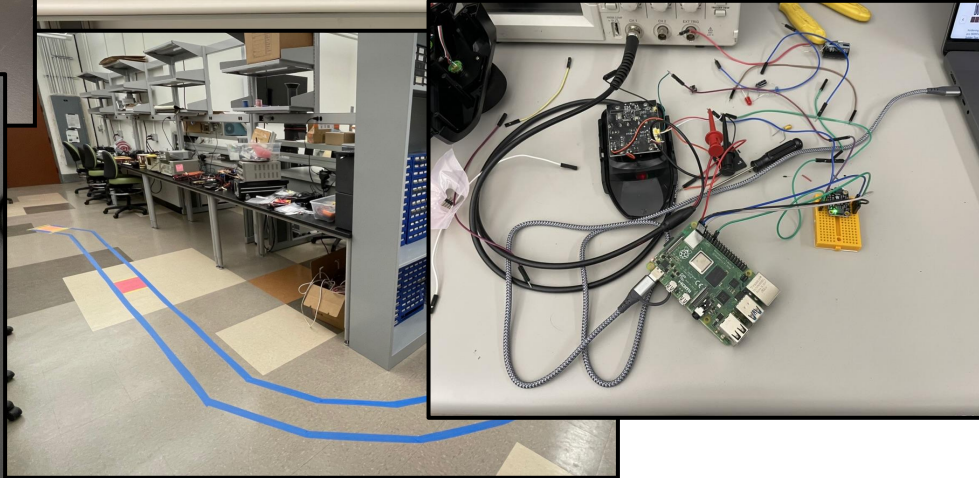
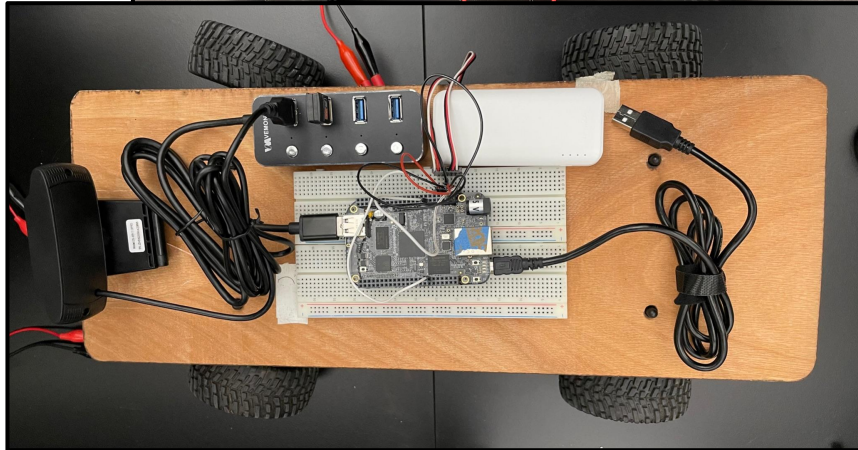
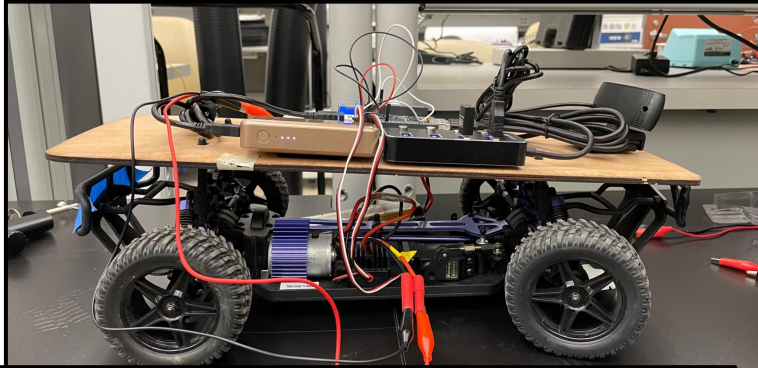
- **Midterm released Monday Nov 6**
 - Topics to be sent out today or tomorrow
 - 30 questions, 1 hour
 - All multiple choice/true or false/etc
 - Entirely in Canvas, online
 - Due Sunday Nov 13 at 11:59pm
 - Open slides, notes taken during class, assignments, projects
 - NOT open internet
- NO lecture Wed Nov 8, I will be on zoom to help with any midterm question clarification during class time [zoom link to be announced on Canvas]



Housekeeping - (optional) Assignment 3

- Assignment 3 optional
 - Can replace lowest assignment or project score - your choice
- Rust programming
- Keep an eye out for announcements on posting and due date

Housekeeping - Final Project



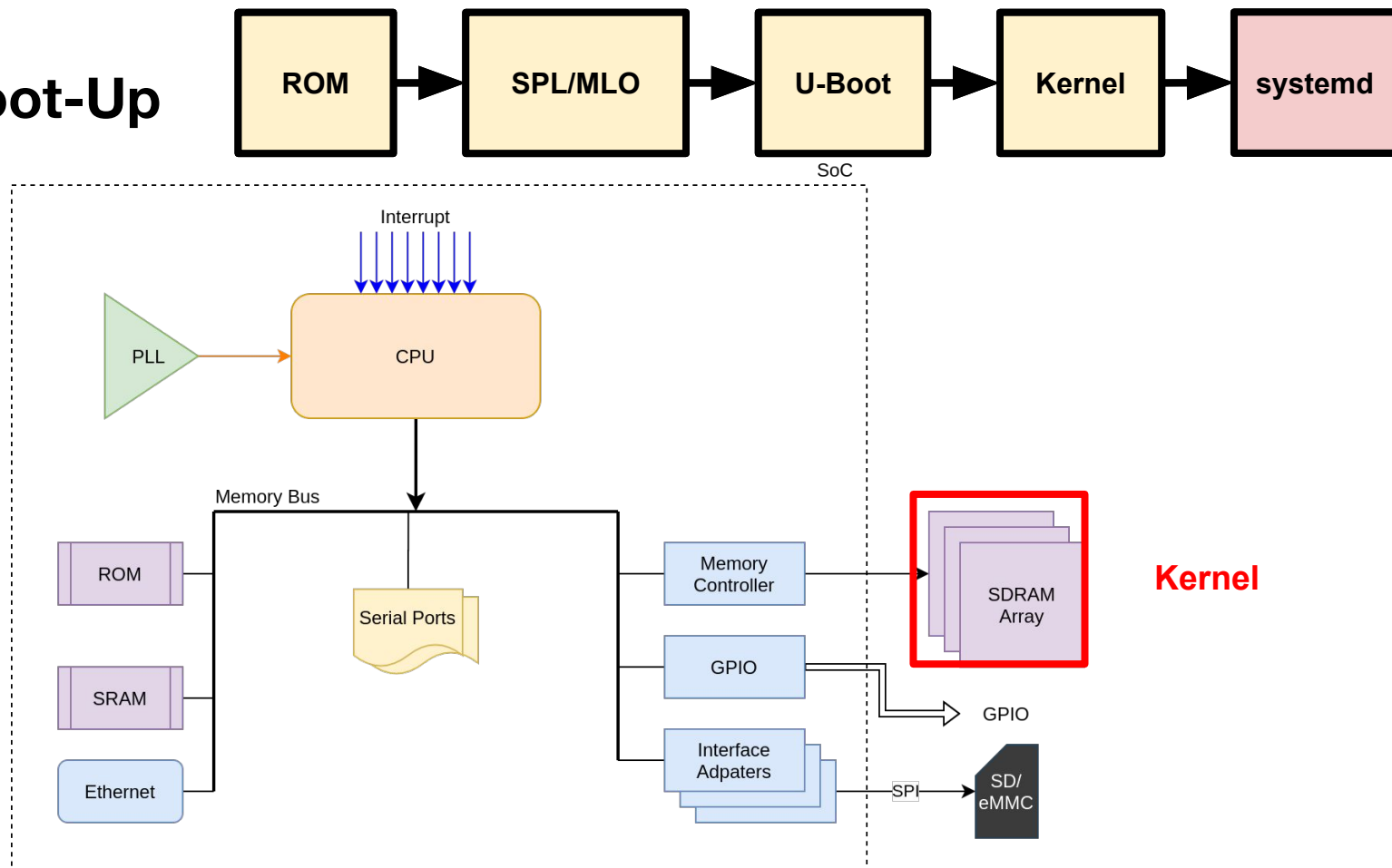
Housekeeping - Final Project

- Due last day of classes - Friday Dec 1 at 11:59pm
- Goal: Webcam-based lane-keeping RC car
- Project 3 as a milestone - Due date to be announced, likely Tuesday Nov 14
- Teams of 4 [both for final project and project 3]
 - Teams must be exclusively undergraduate students or graduate students, not both
 - Sign up [here](#) by end of this Wed Nov 1
- Graduate students: ML

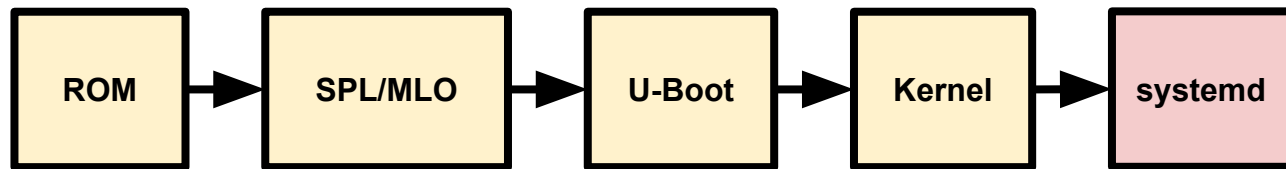
5 Minutes For Team Discussion

Link to final project team sign up has been posted in Canvas announcement

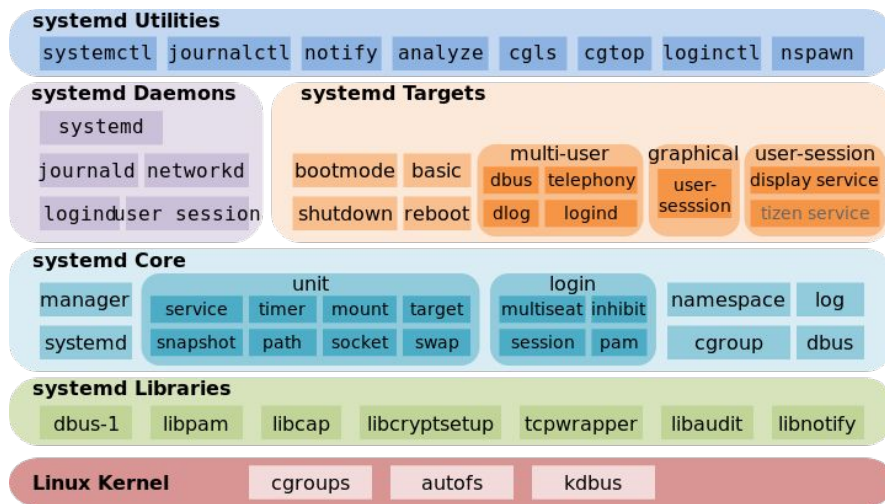
SoC & Boot-Up



[● ◀] systemd



- System & service manager
- d stands for daemon (in Unix fashion)
- Init process (daemon) PID 1
 - Universal common ancestor of all processes
- Parallelism
- *Controversial*



Carla Schroder, "Understanding and Using Systemd". URL:
<https://www.linux.com/training-tutorials/understanding-and-using-systemd/>

A Word From Our Best Friend

(language warning)



<https://en.wikipedia.org/wiki/XML#Criticism>

“bug reports have been basically ignored in some cases”

systemd / systemd Public

Sponsor Notifications Star 8.6k Fork 2.7k

<> Code Issues 1.5k Pull requests 160 Actions Projects 1 Security Insights

Pinned issues

TEST-50-DISSECT: Failed to set up mount namespaces: No such ...
#17469 opened on Oct 27, 2020 by mrc0mmand
Open 7

is:issue is:open Labels 189 Milestones 2 New issue

1,528 Open 6,510 Closed

Author Label Projects Milestones Assignee Sort

networkd not reloading / reconfiguring new addresses on interface bug network 1 25
#21113 opened 19 hours ago by wak-google

Question: Is it possible to use both After= and Before= options towards the same unit (service) together in systemd service?
#21110 opened yesterday by Alexander-Shukaev

systemd / systemd Public

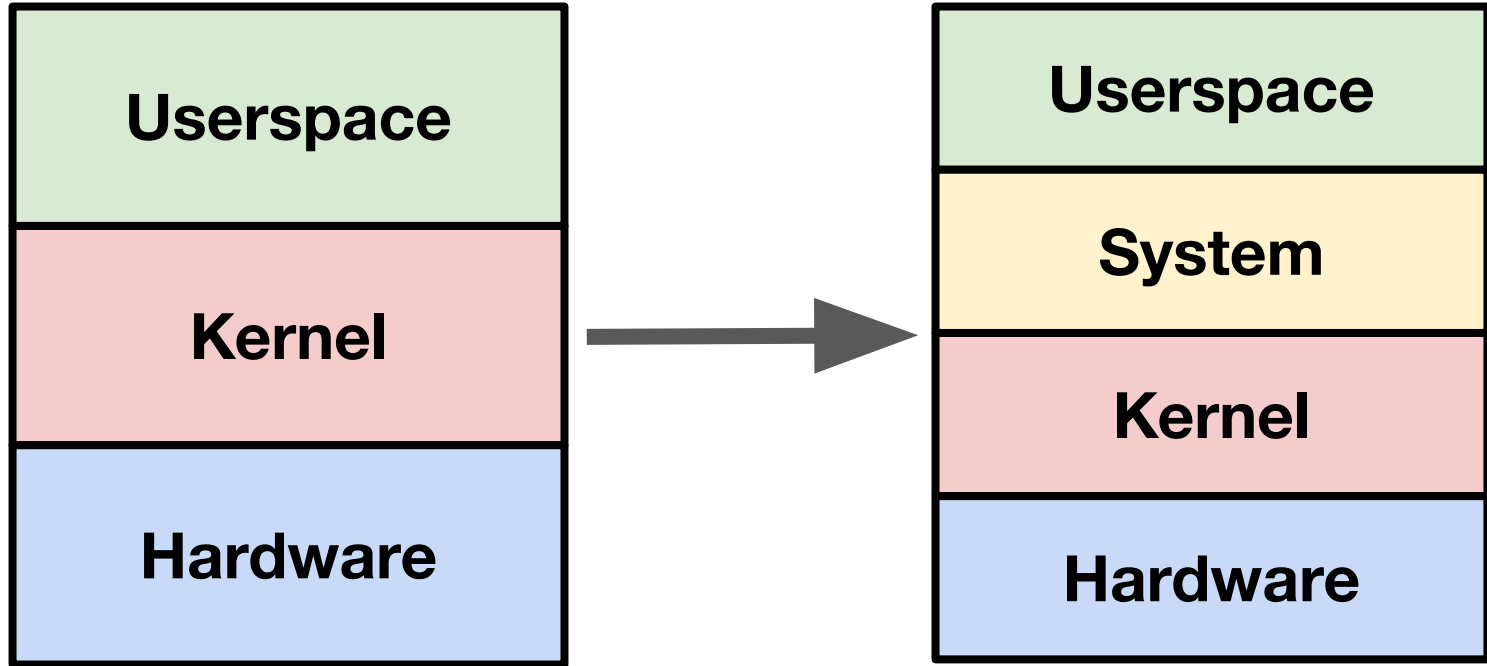
<> Code Issues 1.5k Pull requests 160

is:pr is:open

160 Open 12,847 Closed

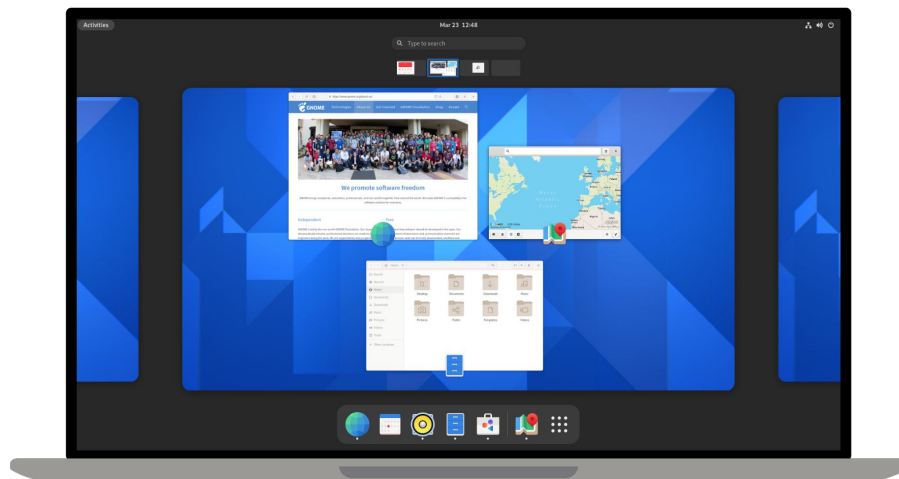
Author Label Projects Milestones

A Change In The Winds



Example of Userspace Depending On Supposed System Layer

- GNOME
- From Nov. 2012 meeting notes:
 - ‘- No hard compile time dep on systemd for "basic functionality"
 - example of basic functionality: active session tracking
 - example of non-basic functionality: power management’



<https://www.gnome.org/>

Adoption of systemd By Distributions

Fedora 15	May, 2011
openSUSE 12.2	September, 2012
CentOS 7.14.04	April, 2014
Red Hat Enterprise Linux 7.0	June, 2014
SUSE Linux Enterprise Server 12	October, 2014
Debian 8	April, 2015
Ubuntu 15.05	April, 2015

Motivation

- Automated service management
 - Start
 - Stop
 - Restarting
 - Autorestarting
- Windows has long history of service management
- MacOS has launched

Joe Show launchd

Terminal

top

man top

q

top -o +pid

What Can systemd Do For Us?

- We can create a service
- Webcam streaming
- Web server
- Can start automatically on system boot

What Can systemd Do For Us?

- We can create a service
- **Webcam streaming**
 - We won't do this, but we will get a preview of computer vision
 - This is a side story but also an appetizer
- Web server
- Can start automatically on system boot

Select image and copy to Pi

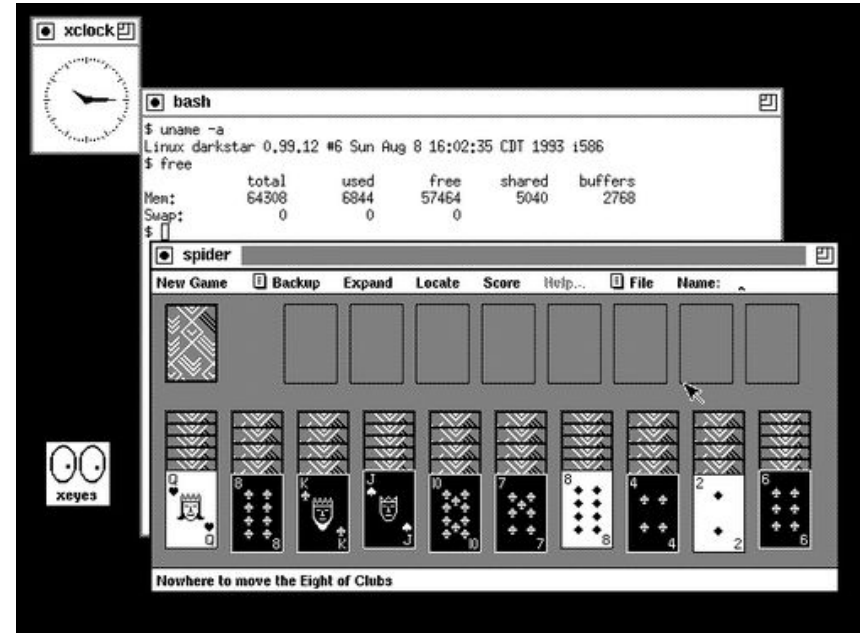
```
cd Downloads
```

```
scp img.jpg pi@raspberrypi.local:~/
```


Remember?

1992: A Big Year for Linux

- X Window System ported to Linux
 - First GUI on Linux



<https://doublslash.com/blog/2013/05/11/linux-user-base-is-below-1-and-it-is-changing/>

Login To Pi With X Forwarding

```
cd Downloads
```

```
scp img.jpg pi@raspberrypi.local:~/
```

openCV

```
# Modified from: https://www.geeksforgeeks.org/python-grayscale-of-images-using-opencv/
# import opencv
import cv2

# Load the input image
image = cv2.imread('img.jpg')
cv2.imshow('Original', image)
cv2.waitKey(0)

# Use the cvtColor() function to grayscale the image
gray_image = cv2.cvtColor(image, cv2.COLOR_BGR2GRAY)

cv2.imshow('Grayscale', gray_image)
cv2.waitKey(0)

# Window shown waits for any key pressing event
cv2.destroyAllWindows()
```

openCV - Edge detection

```
# Edge detection
```

```
edges = cv2.Canny(image=gray_image, threshold1=100, threshold2=200)
```

```
cv2.imshow('Edges', edges)
```

```
cv2.waitKey(0)
```

v4l2

- Video 4 Linux 2
- Video capture API for Linux
- Works with a variety of webcams
- `v4l2-ctl -h`
- `v4l2-ctl --list-devices`
- `v4l2-ctl --all`
- `V4l2-ctl --set-ctrl=brightness=200`

v4l2 (2)

- `v4l2-ctl --list-formats`
- `v4l2-ctl --set-fmt-video=width=1920,height=1080,pixelformat=1`
- `v4l2-ctl --all`

What Can systemd Do For Us?

- We can create a service
- **Webcam streaming**
- Web server
- Can start automatically on system boot

What Can systemd Do For Us?

- We can create a service
- Webcam streaming
- **Web server**
- Can start automatically on system boot

Exercise 14 Code: web3

Creating a Service - My Modified Example From Benjamin Morel On Medium

- Let's make a simple web server
- `nano server.php`

```
<?php
```

```
$sock = socket_create(AF_INET, SOCK_DGRAM, SOL_UDP);  
socket_bind($sock, '0.0.0.0', 10000);
```

```
for (;;) {  
    socket_recvfrom($sock, $message, 1024, 0, $ip, $port);  
    $reply = str_rot13($message);  
    socket_sendto($sock, $reply, strlen($reply), 0, $ip, $port);  
    $reply2 = str_rot13($reply);  
    socket_sendto($sock, $reply2, strlen($reply2), 0, $ip, $port);  
}
```

Try Out The Server

- Run the server:
 - **php server.php**
- *You may need to install php:*
 - ***sudo apt update***
 - ***NOT UPGRADE!!***
 - ***sudo apt install php***
 - ***(again) php server.php***
- From a different terminal:
 - **nc -u 127.0.0.1 10000**

Let's Make This a **Service** (Runs In Background) Managed By systemd

- Make a service file in the location for system services:
 - **sudo nano /etc/systemd/system/rot13.service**
- Put configuration details in file:

```
[Unit]
Description=ROT13 demo service
After=network.target
StartLimitIntervalSec=0

[Service]
Type=simple
Restart=always
RestartSec=1
User=pi
ExecStart=/usr/bin/env php /path/to/server.php

[Install]
WantedBy=multi-user.target
```

What Do All These Configuration Details Mean?

[Unit] ([link](#) to explanations for this section)

Description=ROT13 demo service

After=network.target

StartLimitIntervalSec=0

[Service] ([link](#) to explanations for this section)

Type=simple

Restart=always

RestartSec=1

User=debian

ExecStart=/usr/bin/env php **/path/to/server.php**

[Install] ([link](#) to explanations for this section)

WantedBy=multi-user.target ([special note](#))

The Service Exists - Let's Get It Started

- `systemctl -h`
- `man systemctl`
- Stop current server from running if it is: **control+c**
- `systemctl start rot13`
- `nc -u 127.0.0.1 10000`

Taking Your Service To The Next Level: On Boot

- Making service autostart when Pi powered on:
 - **`systemctl enable rot13`**
- Undoing autostart:
 - **`systemctl disable rot13`**

Taking Your Service To The Next Level: On Boot

- Waiting for something else to happen
 - E.g., MySQL server needs to be alive before service
 - **After=mysql.service**
- The services dies! (*exits*)
 - No autorestart by default
 - **Restart=always**
 - **on-failure** in place of **always** causes autorestart for exit status $\neq 0$

Taking Your Service To The Next Level: Patience

- Autorestart has default delay of 100ms
- Can change to (for example) 2 seconds:
 - **RestartSec=2**
- But wait, there's more!
- If >5 autorestart failures occur in <10s, systemd throws in the towel
- Who did this?
 - **StartLimitBurst=5**
 - **StartLimitIntervalSec=10**