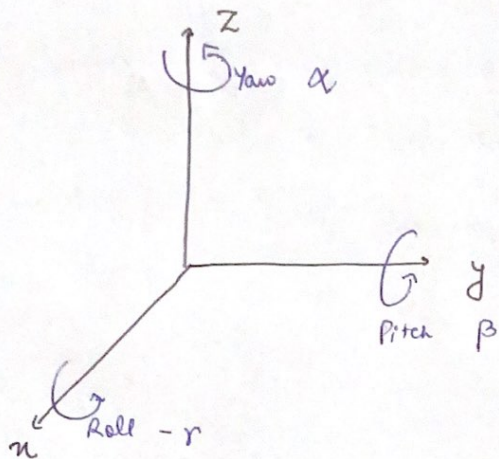


Yaw, Roll, Pitch



$$R_z(\alpha) = \begin{bmatrix} \cos \alpha & -\sin \alpha & 0 \\ \sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_y(\beta) = \begin{bmatrix} \cos \beta & 0 & \sin \beta \\ 0 & 1 & 0 \\ -\sin \beta & 0 & \cos \beta \end{bmatrix}$$

$$R_x(r) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos r & -\sin r \\ 0 & \sin r & \cos r \end{bmatrix}$$

$$R(\alpha, \beta, \gamma) = R(\alpha) \cdot R(\beta) \cdot R(\gamma) =$$

$$\begin{bmatrix} \cos \alpha \cos \beta & \cos \alpha \sin \beta \sin \gamma - \sin \alpha \cos \gamma & \cos \alpha \sin \beta \cos \gamma + \sin \alpha \sin \gamma \\ \sin \alpha \cos \beta & \sin \alpha \sin \beta \sin \gamma + \cos \alpha \cos \gamma & \sin \alpha \sin \beta \cos \gamma - \cos \alpha \sin \gamma \\ -\sin \beta & \cos \beta \sin \gamma & \cos \beta \cos \gamma \end{bmatrix}$$

For an arbitrary matrix such as :

$$\begin{bmatrix} r_{11} & r_{12} & r_{13} \\ r_{21} & r_{22} & r_{23} \\ r_{31} & r_{32} & r_{33} \end{bmatrix}$$

Solving for each angle yields :

$$\alpha = \tan^{-1}(r_{21}/r_{11})$$

$$\gamma = \tan^{-1}(r_{32}/r_{33})$$

$$\beta = \tan^{-1}\left(\frac{-r_{31}}{\sqrt{r_{32}^2 + r_{33}^2}}\right)$$

Since, it will all lie b/w $[0, 2\pi]$ bc of arctangents :

$$\alpha = 2(r_{21}, r_{11})$$

$$\beta = 2(-r_{31}, \sqrt{r_{32}^2 + r_{33}^2})$$

$$\gamma = 2(r_{32}, r_{33})$$