# 5004 Homework 2

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# Question 1:

1. Let  $T: \mathbb{R}^3 \to \mathbb{R}^2$  be a linear transformation. If T satisfies

$$T \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$
, and  $T \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$ ,

then find

 $T \begin{bmatrix} 8 \\ 3 \\ 7 \end{bmatrix}$ 

.

### Answer

We know that

$$2\begin{bmatrix} 1\\0\\-1 \end{bmatrix} + 3\begin{bmatrix} 2\\1\\3 \end{bmatrix} = \begin{bmatrix} 2\\0\\-2 \end{bmatrix} + \begin{bmatrix} 6\\3\\9 \end{bmatrix} = \begin{bmatrix} 8\\1\\7 \end{bmatrix}$$

So in conclusion,

$$2T \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + 3T \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} = 2 \begin{bmatrix} 2 \\ 3 \end{bmatrix} + 3 \begin{bmatrix} -1 \\ 0 \end{bmatrix} = \begin{bmatrix} 4-3 \\ 6+0 \end{bmatrix} = \begin{bmatrix} 1 \\ 6 \end{bmatrix}$$

## Question 2:

2. Find the Jacobian matrix of the following vector-valued multi-variable functions.

(a)  $f: \mathbb{R}^n \to \mathbb{R}^m$  is defined by  $f(\boldsymbol{x}) = A\boldsymbol{x} - \boldsymbol{b}$ , where  $\boldsymbol{x} \in \mathbb{R}^n$ ,  $\boldsymbol{A} \in \mathbb{R}^{m \times n}$ ,  $\boldsymbol{b} \in \mathbb{R}^n$ .

(b)  $f: \mathbb{R}^n \to \mathbb{R}^n$  is defined by  $f(\boldsymbol{x}) = \boldsymbol{x} \boldsymbol{x}^T \boldsymbol{a}$ , where  $\boldsymbol{x} \in \mathbb{R}^n$ ,  $\boldsymbol{a} \in \mathbb{R}^n$ .

#### Answer

Assume that:

$$\mathbf{A}_i = [A_{ij}]_{j=1}^n, \mathbf{A}_i \in \mathbb{R}^n$$
$$b_i = \mathbf{b}_i, b_i \in \mathbb{R}$$
$$f_i(\mathbf{x}) = \langle \mathbf{A}_i, \mathbf{x} \rangle - b_i$$

We know that:

$$f(oldsymbol{x}) = oldsymbol{A} oldsymbol{x} - oldsymbol{b}$$
  $f(oldsymbol{x}) = egin{bmatrix} f_1(oldsymbol{x}) & dots \ f_n(oldsymbol{x})^T \ dots \ 
abla f_n(oldsymbol{x})^T \end{bmatrix}$   $Df(oldsymbol{x}) = egin{bmatrix} oldsymbol{X} f_1(oldsymbol{x})^T \ dots \ 
abla f_n(oldsymbol{x})^T \end{bmatrix}$   $Df(oldsymbol{x}) = egin{bmatrix} oldsymbol{A}_n^T \ dots \ oldsymbol{A}_n^T \ dots \ oldsymbol{A}_n^T \ \end{pmatrix} = oldsymbol{A}$ 

We know that Jacobian matrix is the differentiation of  $f: \mathbb{R}^n \to \mathbb{R}^m$ . So In conclusion, the Jacobian matrix is A.

(b) Assume that:

$$m{X} = m{x} m{x}^T = [x_i x_j]_{i=1,j=1}^{n,n}, m{X} \in \mathbb{R}^{n \times n}$$
 $m{X}_i = [x_i x_j]_{j=1}^n, m{X}_i \in \mathbb{R}^n$ 
 $f_i(m{x}) = \langle m{X}_i, m{a} \rangle$ 

if i = k

$$\frac{\partial f_i}{x_k} = \sum_{j=1}^n x_j a_j + x_k a_k$$

if  $i \neq k$ 

$$\frac{\partial f_i}{\partial x_k} = x_i a_k$$

$$f(\boldsymbol{x}) = \begin{bmatrix} f_1(\boldsymbol{x}) \\ \vdots \\ f_n(\boldsymbol{x}) \end{bmatrix}$$

$$Df(\boldsymbol{x}) = \begin{bmatrix} \nabla f_1(\boldsymbol{x})^T \\ \vdots \\ \nabla f_n(\boldsymbol{x})^T \end{bmatrix} = \begin{bmatrix} x_1 a_1 & x_1 a_2 & \cdots & x_1 a_n \\ \vdots & \vdots & \cdots & \vdots \\ x_n a_1 & x_n a_2 & \cdots & x_n a_n \end{bmatrix} + \begin{bmatrix} \sum_{j=1}^n x_j a_j & 0 & \cdots & 0 \\ \vdots & \vdots & \cdots & \vdots \\ 0 & 0 & \cdots & \sum_{j=1}^n x_j a_j \end{bmatrix} = \boldsymbol{x} \boldsymbol{a}^T + (\boldsymbol{x}^T \boldsymbol{a}) \boldsymbol{I}$$

# Question 3:

3. Let  $f: \mathbb{R}^2 \to \mathbb{R}$ ,  $g: \mathbb{R}^2 \to \mathbb{R}^2$ ,  $g(x,y) = (x^2y, x-y)$  and  $h = f \circ g = f(g(x,y))$ . Find  $\frac{\partial h}{\partial x}|_{x=2,y=-1}$  if  $\frac{\partial f}{\partial x}|_{x=2,y=-1} = 3$  and  $\frac{\partial f}{\partial y}|_{x=2,y=-1} = -2$ . (Hint: use the chain rule)

#### Answer:

We know that:

$$g_1(x,y) = x^2 y$$

$$g_2(x,y) = x - y$$

$$h(x,y) = f(g_1(x,y), g_2(x,y))$$

$$\frac{\partial h}{\partial x} = \frac{\partial f}{\partial x} \frac{\partial g_1}{\partial x} + \frac{\partial f}{\partial y} \frac{\partial g_2}{\partial x}$$

$$\frac{\partial h}{\partial x}|_{x=1,y=2} = 3 \frac{\partial g_1}{\partial x} - 2 \frac{\partial g_2}{\partial x} = 3 * (2xy)|_{x=2,y=-1} - 2 * 1 = -14$$

## Question 4:

Let  $f(t) = f_1(t) * f_2(t)$  be the convolution of two functions  $f_1(t)$  and  $f_2(t)$  on  $\mathbb{R}$ , i.e.,

$$f(t) = \int_{-\infty}^{+\infty} f_1(t-s) f_2(s) ds$$

Let  $a, a_1, a_2$  be real number.

(i) Prove the following identity:

$$f_1(t-a) * f_2(t) = f_1(t) * f_2(t-a) = f(t-a).$$

(ii) Prove the following identity:

$$f_1(t-a_1) * f_2(t-a_2) = f(t-a_1-a_2).$$

#### Answer:

(i) Prove  $f_1(t-a) * f_2(t) = f(t-a)$ :

$$f(t-a) = \int_{-\infty}^{+\infty} f_1(t-s-a) f_2(s) ds$$

$$f'_1(t) = f_1(t-a)$$

$$f(t-a) = \int_{-\infty}^{+\infty} f'_1(t-s) f_2(s) ds = f'_1(t) * f_2(t) = f_1(t-a) * f_2(t)$$

Prove  $f_1(t) * f_2(t - a) = f(t - a)$ :

$$f(t-a) = \int_{-\infty}^{+\infty} f_1(t-s-a)f_2(s)ds$$

$$f'_2(t) = f_2(t-a)$$

$$f(t-a) = \int_{-\infty}^{+\infty} f_1(t-(s+a))f_2(s)d(s+a) = \int_{-\infty}^{+\infty} f_1(t-(s+a))f'_2(s+a)d(s+a)$$

$$= \int_{-\infty}^{+\infty} f_1(t-u)f'_2(u)du$$

$$= f_1(t) * f'_2(t)$$

$$= f_1(t) * f_2(t-a)$$

(ii)

$$f_1(t - a_1) * f_2(t - a_2) = \int_{-\infty}^{+\infty} f_1(t - a_1 - s) f_2(s - a_2) ds$$

$$= \int_{-\infty}^{+\infty} f_1(t - a_1 - s) f_2(s - a_2) d(s - a_2)$$

$$= \int_{-\infty}^{+\infty} f_1(t - a_1 - a_2 - (s - a_2)) f_2(s - a_2) d(s - a_2)$$

$$= \int_{-\infty}^{+\infty} f_1(t - (a_1 + a_2) - u) f_2(u) du$$

$$= f(t - a_1 - a_2).$$

## Question 5:

5. Let  $V_1$  and  $V_2$  be two Hilbert spaces with the inner products  $\langle \cdot, \cdot \rangle_{V_1}$ , and  $\langle \cdot, \cdot \rangle_{V_2}$ , respectively. Let  $T \in \mathcal{L}(V_1, V_2)$ , i.e.,  $T: V_1 \to V_2$  be a bounded linear operator.

(a) Let  $S: V_2 \to V_1$  be an operator satisfying  $\langle T\boldsymbol{x}, \boldsymbol{y} \rangle_{V_2} = \langle \boldsymbol{x}, S\boldsymbol{y} \rangle_{V_1}$  for any  $\boldsymbol{x} \in V_1$  and  $\boldsymbol{y} \in V_2$ . Prove that S is a bounded linear operator. (Consequently, S is the adjoint of T, i.e.,  $S = T^*$ )

- (b) Prove that  $(T^*)^* = T$ .
- (c) Prove that  $||T|| = ||T^*||$ .

#### Answer

We know

$$\|\mathbf{A}\mathbf{x}\|_{V_2} \le \|\mathbf{A}\| \|\mathbf{x}\|_{V_1} \tag{1}$$

We know, by using Cauchy–Schwarz inequality and (1):

$$\langle Tx, y 
angle_{V_2} \leq \|Tx\|_{V_2} \|y\|_{V_2} \leq \|T\| \|x\|_{V_1} \|y\|_{V_2}$$

We choose x as Sy

$$egin{aligned} \langle m{T}m{S}m{y},m{y}
angle_{V_2} &= \langle m{S}m{y},m{S}m{y}
angle_{V_1} = \|m{S}m{y}\|_{V_1}^2 \leq \|m{T}m{S}m{y}\|_{V_2}\|m{y}\|_{V_2} \leq \|m{T}\|\|m{S}m{y}\|_{V_1}\|m{y}\|_{V_2} \ &\|m{S}m{y}\|_{V_1} \leq \|m{T}\|\|m{y}\|_{V_2} \leq \infty \end{aligned}$$

Thus, S is a bounded linear operator.

(b) We know:

$$egin{aligned} \langle oldsymbol{T}oldsymbol{x},oldsymbol{y}
angle_{V_2} &= \langle oldsymbol{x},oldsymbol{T}^*oldsymbol{y}
angle_{V_1} \ \langle oldsymbol{T}oldsymbol{x},oldsymbol{y}
angle_{V_1} &= \langle (oldsymbol{T}^*)^*oldsymbol{x},oldsymbol{y}
angle_{V_2} \ oldsymbol{T} &= (oldsymbol{T}^*)^* \end{aligned}$$

(c) Proof of

$$\|oldsymbol{T}\| = \sup_{\|oldsymbol{y}\|=1} \|oldsymbol{T}oldsymbol{y}\| = \sup_{\|oldsymbol{y}\|=1} \sup_{\|oldsymbol{x}\|=1} \langle oldsymbol{x}, oldsymbol{T}oldsymbol{y}
angle$$

By using Cauchy Schwarz inequality

$$egin{aligned} \langle oldsymbol{x}, oldsymbol{T} oldsymbol{y} 
angle & \leq \|oldsymbol{x}\| \|oldsymbol{T} oldsymbol{y}\| \ & \|oldsymbol{T} oldsymbol{y}\| & = \sup_{\|oldsymbol{y}\| = 1} \langle oldsymbol{x}, oldsymbol{T} oldsymbol{y} 
angle \ & \|oldsymbol{T}\| = \sup_{\|oldsymbol{y}\| = 1} \|oldsymbol{T} oldsymbol{y}\| & = \sup_{\|oldsymbol{y}\| = 1} \sup_{\|oldsymbol{x}\| = 1} \langle oldsymbol{x}, oldsymbol{T} oldsymbol{y} 
angle \ & \|oldsymbol{T}\| = \sup_{\|oldsymbol{y}\| = 1} \|oldsymbol{x}\| oldsymbol{x} oldsymbol{y} \ & \|oldsymbol{T} oldsymbol{y}\| & = \sup_{\|oldsymbol{y}\| = 1} \|oldsymbol{x}\| oldsymbol{x} oldsymbol{y} \ & \|oldsymbol{T} oldsymbol{y}\| & \|oldsymbol{T} oldsymbol{y}\| & \|oldsymbol{x}\| oldsymbol{y} \ & \|oldsymbol{T} oldsymbol{y}\| & \|oldsymbol{T} oldsymbol{y}\| & \|oldsymbol{T} oldsymbol{y}\| & \|oldsymbol{y}\| & \|oldsymbol{y}\|$$

Then

$$\begin{split} \|\boldsymbol{T}^*\| &= \sup_{\|\boldsymbol{y}\|=1} \|\boldsymbol{T}^*\boldsymbol{y}\| = \sup_{\|\boldsymbol{y}\|=1} \sup_{\|\boldsymbol{x}\|=1} \langle \boldsymbol{x}, \boldsymbol{T}^*\boldsymbol{y} \rangle \\ &= \sup_{\|\boldsymbol{y}\|=1} \sup_{\|\boldsymbol{x}\|=1} \langle \boldsymbol{T}\boldsymbol{x}, \boldsymbol{y} \rangle = \sup_{\|\boldsymbol{x}\|=1} \sup_{\|\boldsymbol{x}\|=1} \langle \boldsymbol{T}\boldsymbol{x}, \boldsymbol{y} \rangle = \sup_{\|\boldsymbol{x}\|=1} \|\boldsymbol{T}\boldsymbol{x}\| = \|\boldsymbol{T}\| \end{split}$$

In conclusion,  $\|T^*\| = \|T\|$ 

## Question 6:

Consider the vector space  $\ell_{\infty}$  equipped with the norm  $\|\cdot\|_{\infty}$ . Define the operator  $T:\ell_{\infty}\to\ell_{\infty}$  by  $T(\{x_n\}_{n\in\mathbb{N}})=\{y_n\}_{n\in\mathbb{N}}$  where  $y_n=x_{n+1}$ .

- (a) Prove that T is a linear operator.
- (b) Prove that T is a bounded operator.
- (c) Prove that ||T|| = 1.

### Answer