## MSBD 5007 HW1

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# Question1

Given two vectors  $\mathbf{a} = [a_0, a_1, \dots, a_{N-1}]$  and  $\mathbf{b} = [b_0, b_1, \dots, b_{N-1}]^T$ , their *circular convolution* is defined by

$$(\boldsymbol{a} \circledast \boldsymbol{b})_k = \sum_{j=0}^{N-1} a_j b_{k-j}, k = 0, 1, \cdots, N-1,$$

where  $\boldsymbol{b}$  is extended periodically, i.e.,  $b_{k-j} = b_{(k-j)+N}$  if  $-N \leq k-j \leq -1$ . Let  $\boldsymbol{f}, \boldsymbol{g}$ , and  $\boldsymbol{h}$  be vectors in  $\mathbb{R}^N$ . Prove that the circular convolution satisfies:

- (a)  $\mathbf{f} \circledast \mathbf{g} = \mathbf{g} \circledast \mathbf{f}$ .
- (b)  $\mathbf{f} \circledast (\mathbf{g} \circledast \mathbf{h}) = (\mathbf{f} \circledast \mathbf{g}) \circledast \mathbf{h}$ .

(a)

$$(f \circledast g)_{k}$$

$$= \sum_{j=0}^{N-1} f_{j}g_{k-j}$$

$$= \sum_{j=k+1}^{N-1} f_{j}g_{k-j} + \sum_{j=0}^{k} f_{j}g_{k-j}$$

$$= \sum_{j=k+1}^{N-1} f_{j}g_{N+k-j} + \sum_{j=0}^{k} f_{j}g_{k-j}$$

$$= \sum_{i=k+1}^{N-1} f_{N+k-i}g_{i} + \sum_{j=0}^{k} f_{j}g_{k-j}$$

$$= \sum_{i=k+1}^{N-1} g_{i}f_{k-i} + \sum_{i=0}^{k} f_{k-i}g_{i}$$

$$= \sum_{i=k+1}^{N-1} g_{i}f_{k-i} + \sum_{i=0}^{k} g_{i}f_{k-i}$$

$$= \sum_{i=0}^{N-1} g_{i}f_{k-i}$$

$$= (g \circledast f)_{k}$$

Therefore, we can conclude that:  $f \circledast g = g \circledast f$ .

(b)

$$(\boldsymbol{f} \circledast (\boldsymbol{g} \circledast \boldsymbol{h}))_{k} = (\boldsymbol{f} \circledast (\boldsymbol{h} \circledast \boldsymbol{g}))_{k}$$

$$= \sum_{j=0}^{N-1} f_{j} (\boldsymbol{h} \circledast \boldsymbol{g})_{k-j}$$

$$= \sum_{j=0}^{N-1} f_{j} \sum_{i=0}^{N-1} h_{i} g_{k-j-i}$$

$$= \sum_{j=0}^{N-1} \sum_{i=0}^{N-1} f_{j} h_{i} g_{k-j-i}$$

$$= \sum_{i=0}^{N-1} \sum_{j=0}^{N-1} f_{j} h_{i} g_{k-j-i}$$

$$= \sum_{i=0}^{N-1} h_{i} \sum_{j=0}^{N-1} f_{j} g_{k-j-i}$$

$$= \sum_{i=0}^{N-1} h_{i} (\boldsymbol{f} \circledast \boldsymbol{g})_{k-j}$$

$$= (\boldsymbol{h} \circledast (\boldsymbol{f} \circledast \boldsymbol{g}))_{k}$$

$$= ((\boldsymbol{f} \circledast \boldsymbol{g}) \circledast \boldsymbol{h})_{k}$$

Therefore, we can conclude that:  $f \circledast (g \circledast h) = (f \circledast g) \circledast h$ .

## Question2

Let 
$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 3 \\ 1 & 2 & 1 \\ -3 & -1 & 2 \end{bmatrix}$$
 be a  $3 \times 3$  matrix.

(a) Find the LU decomposition of the matrix  $\boldsymbol{A}$ . The final result will look like this:

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & 0 \\ l_{21} & 0 & 0 \\ l_{31} & l_{32} & 1 \end{bmatrix} \begin{bmatrix} u_{11} & u_{12} & u_{13} \\ 0 & u_{22} & u_{23} \\ 0 & 0 & u_{33} \end{bmatrix}$$

(b) Use the result in (a) to solve the system:

$$2x_1 - x_2 + 3x_3 = 3$$
$$x_1 + 2x_2 + x_3 = 4$$
$$-3x_1 - x_2 + 2x_3 = 5$$

(a)

$$\begin{bmatrix} 2 & -1 & 3 \\ 1/2 & 5/2 & -1/2 \\ -3/2 & -5/2 & 13/2 \end{bmatrix}_{k=1}$$

$$\begin{bmatrix} 2 & -1 & 3 \\ 1/2 & 5/2 & -1/2 \\ -3/2 & -1 & 6 \end{bmatrix}_{k=2}$$

From this, we can get:

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ -3/2 & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 & 3 \\ 0 & 5/2 & -1/2 \\ 0 & 0 & 6 \end{bmatrix}$$

(b)

From (a), we know:

$$\begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ -3/2 & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 & 3 \\ 0 & 5/2 & -1/2 \\ 0 & 0 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$$

Assume LUx = b as Ly = b, s.t.: From (a), we know:

$$\begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ -3/2 & -1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$$

From these, we can solve:

$$y_1 = 3$$
$$y_2 = 5/2$$
$$y_3 = 12$$

s.t.

$$\begin{bmatrix} 2 & -1 & 3 \\ 0 & 5/2 & -1/2 \\ 0 & 0 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ 5/2 \\ 12 \end{bmatrix}$$

From these, we can solve:

$$x_1 = -4/5$$
$$x_2 = 7/5$$
$$x_3 = 2$$

# Question3

Let  $\mathbf{A} \in \mathbb{R}^{n \times n}$  be a tri-diagonal matrix (i.e.  $a_{ij} = 0$  if |i-j| > 1). The pattern of nonzero entries is illustrated below:

$$\begin{bmatrix} \times & \times & & & & \\ \times & \times & \times & & & \\ & \ddots & \ddots & \ddots & \\ & & \times & \times & \times \end{bmatrix}$$

Develop an algorithm with complexity O(n) to compute the LU decomposition of A, assuming all the pivots are non-zero.

#### Algorithm 1 Update Matrix Elements

- 1:  $\mathbf{for} \ k = 1 \ \text{to n } \mathbf{do}$
- $2: \qquad a_{k,k+1} \leftarrow \frac{a_{k,k+1}}{a_{k,k}}$
- 3:  $a_{k+1,k+1} \leftarrow a_{k+1,k+1} a_{k,k+1} \cdot a_{k+1,k}$
- 4: end for

## Question4

To accelerate matrix multiplications, the *Coppersmith Winograd* algorithm reduces the number of scalar multiplications by cleverly reformulating the inner product. Assume that n is even and define, for any vector  $x \in \mathbb{R}^n$ ,

$$f(\mathbf{x}) = \sum_{i=1}^{n/2} x_{2i-1} x_{2i}$$

. (a) Prove that for all vectors  ${\pmb x}, {\pmb y} \in \mathbb{R}^n,$  the inner product can be re-expressed as

$$\mathbf{x}^T \mathbf{y} = \sum_{i=1}^{n/2} ((x_{2i-1} + y_{2i})(x_{2i} + y_{2i-1})) - f(\mathbf{x}) - f(\mathbf{y}).$$

(b) Now consider the matrix product C = AB, where  $A, Bin\mathbb{R}^{n\times n}$ . Devise an algorithm to compute C using  $\frac{n^3}{2} + O(n^2)$  scalar multiplications. Note: A standard matrix multiplication requires  $n^3$  scalar multiplications. By combining this method

Note: A standard matrix multiplication requires  $n^3$  scalar multiplications. By combining this method with other techniques, one can obtain the Coppersmith Winograd algorithm, which has an asymptotic complexity of  $O(n^{2.375})$ .

(a)

$$\sum_{i=1}^{n/2} ((x_{2i-1} + y_{2i})(x_{2i} + y_{2i-1}))$$

$$= \sum_{i=1}^{n/2} x_{2i-1}x_{2i} + y_{2i}x_{2i} + x_{2i-1}y_{2i-1} + y_{2i}y_{2i-1}$$

$$= \sum_{i=1}^{n/2} x_{2i-1}x_{2i} + \sum_{i=1}^{n/2} y_{2i}x_{2i} + \sum_{i=1}^{n/2} x_{2i-1}y_{2i-1} + \sum_{i=1}^{n/2} y_{2i}y_{2i-1}$$

$$= \mathbf{x}^T \mathbf{y} + f(\mathbf{x}) + f(\mathbf{y})$$

So we can conclude that:

$$\mathbf{x}^T \mathbf{y} = \sum_{i=1}^{n/2} ((x_{2i-1} + y_{2i})(x_{2i} + y_{2i-1})) - f(\mathbf{x}) - f(\mathbf{y}).$$

(b)