

# MSBD5007 Optimization and Matrix Computation

## Homework 5

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1. Find explicit formulas for the projection of  $y \in \mathbb{R}^n$  onto the following non-empty, closed, and convex sets  $S \subset \mathbb{R}^n$ , respectively.

- (a) The unit  $\infty$ -norm ball

$$S = \{x \in \mathbb{R}^n \mid \|x\|_\infty \leq 1\}.$$

- (b) The closed halfspace

$$S = \{x \in \mathbb{R}^n \mid a^T x \leq b\},$$

where  $a \in \mathbb{R}^n$ ,  $a \neq 0$ , and  $b \in \mathbb{R}$  are given.

2. Consider the optimization problem in  $x = (x_1, x_2, x_3) \in \mathbb{R}^3$ :

$$\begin{aligned} \min_{x \in \mathbb{R}^3} & \frac{1}{2}(x_1^2 + 4x_2^2 + 9x_3^2) - (4x_1 + 2x_2), \\ \text{s.t.} \quad & x_1 + x_2 + x_3 = 3, \\ & x_i \geq 0, \quad i = 1, 2, 3. \end{aligned}$$

- (a) Write down the KKT conditions (stationarity, feasibility, complementary slackness).
  - (b) Solve the KKT system to find the optimal solution  $x^*$ , the Lagrange multiplier  $\lambda^*$  for the equality constraint, and the multipliers  $\mu^* = (\mu_1, \mu_2, \mu_3)$  for the inequality constraints.
3. We wish to compute the projection of  $y \in \mathbb{R}^n$  onto the unit  $\ell_1$  ball, i.e. solve

$$\begin{aligned} \min_{x \in \mathbb{R}^n} & \frac{1}{2} \|x - y\|_2^2 \\ \text{s.t.} \quad & \|x\|_1 \leq 1. \end{aligned}$$

- (a) Derive the Lagrange dual problem and show it can be written as

$$\max_{\lambda \geq 0} d(\lambda), \quad d(\lambda) = \sum_{i=1}^n h_\lambda(y_i) - \lambda,$$

where  $h_\lambda : \mathbb{R} \rightarrow \mathbb{R}$  is the so-called Huber's function (which is a smooth function consisting of a quadratic and two linear pieces) defined by

$$h_\lambda(t) = \begin{cases} \frac{1}{2}t^2, & |t| \leq \lambda, \\ \lambda|t| - \frac{1}{2}\lambda^2, & |t| \geq \lambda. \end{cases}$$

- (b) Prove that strong duality holds.
  - (c) Find the optimal dual multiplier  $\lambda^*$ .
  - (d) Give an expression of the projection in terms of  $\lambda^*$ .
4. Let  $S \subseteq \mathbb{R}^n$  be a nonempty, closed, convex set, and let  $\|\cdot\|_2$  denote 2-norm. The projection of any point  $y \in \mathbb{R}^n$  onto  $S$  is defined by

$$\mathcal{P}_S(y) = \arg \min_{x \in S} \|x - y\|_2.$$

Prove that the projection  $\mathcal{P}_S : \mathbb{R}^n \rightarrow S$  is nonexpansive: for all  $x, y \in \mathbb{R}^n$ ,

$$\|\mathcal{P}_S(x) - \mathcal{P}_S(y)\|_2 \leq \|x - y\|_2.$$

## 1 Answer

### 1.1 (1)

#### 1.1.1 (a)

We know the projection:

$$\mathcal{P}_S(y) = \arg \min_{x \in S} \|\mathbf{x} - \mathbf{y}\|_2.$$

We consider

$$\min_{\mathbf{x} \in \mathbb{S}} \|\mathbf{x} - \mathbf{y}\|_2$$

This means:

$$\min_{\mathbf{x} \in \mathbb{S}} \sum_{i=1}^n (x_i - y_i)^2$$

We can solve for each component  $x_i$  independently:

$$\min_{x_i \in [-1, 1]} (x_i - y_i)^2$$

This is just the Euclidean projection of a scalar onto the interval  $[-1, 1]$ , which gives:

$$x_i = \min(\max(y_i, -1), 1)$$

and

$$\mathbf{x} = [x_i]_1^n$$

### 1.1.2 (b)

We know the projection:

$$\mathcal{P}_S(y) = \arg \min_{\mathbf{x} \in S} \|\mathbf{x} - \mathbf{y}\|_2$$

$$\mathcal{L}(\mathbf{x}, \lambda) = \frac{1}{2} \|\mathbf{x} - \mathbf{y}\|_2^2 + \lambda(\mathbf{a}^T \mathbf{x} - b), \quad \lambda \geq 0$$

We know the KKT conditions:

$$\begin{aligned} \nabla_{\mathbf{x}} \mathcal{L} &= \mathbf{x} - \mathbf{y} + \lambda \mathbf{a} = 0 \\ \mathbf{x}^* &= \mathbf{y} - \lambda \mathbf{a} \end{aligned}$$

and

$$\begin{aligned} \mathbf{a}^T \mathbf{x}^* &\leq b \\ \mathbf{a}^T (\mathbf{y} - \lambda \mathbf{a}) &\leq b \\ \mathbf{a}^T \mathbf{y} - \lambda \|\mathbf{a}\|^2 &\leq b \\ \lambda &\geq \frac{\mathbf{a}^T \mathbf{y} - b}{\|\mathbf{a}\|^2} \end{aligned}$$

and we know:

$$\begin{aligned} \lambda(\mathbf{a}^T \mathbf{x} - b) &= 0 \\ \lambda(\mathbf{a}^T \mathbf{y} - \lambda \|\mathbf{a}\|^2 - b) &= 0 \end{aligned}$$

So we get  $\lambda = \max(0, \frac{\mathbf{a}^T \mathbf{y} - b}{\|\mathbf{a}\|^2})$

So we can get

$$\mathcal{P}_S(\mathbf{y}) = \mathbf{y} - \max(0, \frac{\mathbf{a}^T \mathbf{y} - b}{\|\mathbf{a}\|^2}) \mathbf{a}$$

## 1.2 (2)

### 1.2.1 (a)

We can write the Lagrangian Function:

$$\mathcal{L}(x, \lambda, \mu) = \frac{1}{2}(x_1^2 + 4x_2^2 + 9x_3^2) - (4x_1 + 2x_2) - \lambda(x_1 + x_2 + x_3 - 3) - \sum_{i=1}^3 \mu_i x_i$$

$$\begin{aligned}
\nabla_x \mathcal{L} &= 0 \\
x_1 - 4 - \lambda - \mu_1 &= 0 \\
4x_2 - 2 - \lambda - \mu_2 &= 0 \\
9x_3 - \lambda - \mu_3 &= 0
\end{aligned}$$

$$\begin{aligned}
x_1 + x_2 + x_3 &= 3 \\
x_i &\geq 0
\end{aligned}$$

$$\begin{aligned}
\mu_i &\geq 0 \\
\mu_i x_i &= 0
\end{aligned}$$

### 1.2.2 (b)

We need to do analysis of the solution first.

$$\begin{aligned}
x_1 > 0, x_2 > 0, x_3 > 0 &\quad \text{invalid} \\
x_1 = 0, x_2 > 0, x_3 > 0 &\quad \text{invalid} \\
x_1 > 0, x_2 = 0, x_3 > 0 &\quad \text{invalid} \\
x_1 > 0, x_2 > 0, x_3 = 0 &\quad \text{valid}
\end{aligned}$$

if  $x_3 = 0$ , we know  $\mu_1 = 0, \mu_2 = 0$ . Therefore, we get:

$$\begin{aligned}
x_1 &= \lambda + 4 \\
x_2 &= \frac{\lambda + 2}{4} \\
\mu_3 &= -\lambda
\end{aligned}$$

We know  $x_1 + x_2 = 3$ .

$$\begin{aligned}
\lambda + 4 + \frac{\lambda + 2}{4} &= 3 \\
\lambda &= -\frac{6}{5}
\end{aligned}$$

s.t.

$$x_1 = \frac{14}{5}$$

$$x_2 = \frac{1}{5}$$

$$x_1 = 0$$

$$\mu_3 = \frac{6}{5}$$

Therefore, we can conclude:

$$x_1 = \frac{14}{5}$$

$$x_2 = \frac{1}{5}$$

$$x_1 = 0$$

$$\mu_1 = 0$$

$$\mu_2 = 0$$

$$\mu_3 = \frac{6}{5}$$

$$\lambda = -\frac{6}{5}$$

**1.3 (3)**

**1.3.1 (a)**