## MSBD 5007 HW2

#### RONG Shuo

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## Question1

Determine the convexity of the following functions, where  $x \in \mathbb{R}^n$  and  $X \in \mathbb{S}^n_{++}$  (the set of symmetric positive definite matrices). Justify your answer.

- (a)  $f(\mathbf{x}) = \log(e^{x_1} + e^{x_2} + \dots + e^{x_n}).$
- (b)  $f(\mathbf{X}) = \operatorname{logdet}(\mathbf{X})$ .

#### Answer

(a)

$$\nabla f(\mathbf{x}) = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \cdots, \frac{\partial f}{\partial x_n}\right)$$

$$\frac{\partial f}{\partial x_i} = \frac{1}{e^{x_1} + e^{x_1} + \cdots + e^{x_1}} \times \frac{\partial}{\partial x_i} (e^{x_1} + e^{x_2} + \cdots + e^{x_n})$$

$$= \frac{e^{x_i}}{e^{x_1} + e^{x_2} + \cdots + e^{x_n}}$$

Therefore,

$$\nabla f(\mathbf{x}) = \left(\frac{e^{x_1}}{\sum_{i=1}^n e^{x_i}}, \frac{e^{x_2}}{\sum_{i=1}^n e^{x_i}}, \cdots, \frac{e^{x_1}}{\sum_{i=n}^n e^{x_i}}\right)$$

We know,

$$\begin{aligned} \boldsymbol{H}_{ij} &= \frac{\partial^2 f}{\partial x_i \partial y_i} \\ \boldsymbol{H}_{ii} &= \frac{\partial^2 f}{\partial x_i} (\frac{e^{x_i}}{S}) = \frac{e^{x_i} (S - e^{x_i})}{S^2} \text{ if } i = j \\ \boldsymbol{H}_{ij} &= -\frac{e^{x_i} e^{x_j}}{S^2} \text{ if } i \neq j \\ \nabla^2 f(\boldsymbol{x}) &= \frac{1}{S} \text{diag}(\boldsymbol{e}) - \frac{1}{S^2} \boldsymbol{e} \boldsymbol{e}^T \end{aligned}$$

where  $e = (e^{x_1}, e^{x_2}, \dots, e^{x_n})^T$ , and  $S = \sum_{i=1}^n e^{x_i}$ 

$$\begin{split} & \boldsymbol{z} \nabla^2 f(\boldsymbol{x}) \boldsymbol{z}^T = \frac{1}{S} \sum_{i=1}^n e^{x_i} z_i^2 - \frac{1}{S^2} (\sum_{i=1}^n e^{x_i} z_i)^2 \\ & (\sum_{i=1}^n e^{x_i} z_i)^2 \le (\sum_{i=1}^n e^{x_i} z_i^2) (\sum_{i=1}^n e^{x_i}) \\ & \frac{1}{S} \sum_{i=1}^n e^{x_i} z_i^2 \ge \frac{1}{S^2} (\sum_{i=1}^n e^{x_i} z_i)^2 \\ & \boldsymbol{z} \nabla^2 f(\boldsymbol{x}) \boldsymbol{z}^T \ge 0 \end{split}$$

Thus, we prove that Hessian is positive semi-definite, so we can conclude f(x) is convex.

(b)

Let  $X \in \mathbb{S}^n_{++}$  and  $V \in \mathbb{S}^n$ , we define  $g(t) = \operatorname{logdet}(X + tV)$ , where X + tV is symmetric, positive and definite.

$$g(t) = \operatorname{logdet}(\boldsymbol{X} + t\boldsymbol{V})$$

$$= \operatorname{logdet}(\boldsymbol{X}^{\frac{1}{2}}(\boldsymbol{I} + t\boldsymbol{X}^{-\frac{1}{2}}\boldsymbol{V}\boldsymbol{X}^{-\frac{1}{2}})\boldsymbol{X}^{\frac{1}{2}})$$

$$= \operatorname{logdet}\boldsymbol{X} + \operatorname{logdet}(\boldsymbol{I} + t\boldsymbol{\Lambda})$$

$$= \operatorname{logdet}\boldsymbol{X} + \sum_{i=1}^{n} \operatorname{log}(1 + t\lambda_{i})$$

where  $\lambda_i$  is the eigenvalues of  $\Lambda$ 

$$g''(t) = \sum_{i=1}^{n} \frac{-\lambda_i^2}{(1+t\lambda_i)^2} \le 0$$

Thus  $g''(t) \leq 0$  for all t where X + tV is symmetric, positive and definite, so g(t) is concave. Since g(t) is concave for any direction, f(X) = logdet X is concave on  $\mathbb{S}^n_{++}$ .

#### Question2

Consider the linear system  $\mathbf{A}\mathbf{x} = \mathbf{b}$ , with  $\mathbf{A} = \begin{bmatrix} 2 & 1 \\ 1 & 4 \end{bmatrix}$  and  $\mathbf{b} \in \begin{bmatrix} 2 \\ -4 \end{bmatrix}$ , and the initial guess  $\mathbf{x}_0 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ .

- (a) Present the first two update iterations using the steepest descent algorithm.
- (b) Present the first two updated iterations using the conjugate gradient algorithm.

#### Answer

(a)

We know if we want use steepest descent algorithm to solve the linear system, we need:

$$\alpha_k = \frac{\boldsymbol{r}_k^T \boldsymbol{r}_k}{\boldsymbol{r}_k^T \boldsymbol{A} \boldsymbol{r}_k}$$

where  $\mathbf{r}_{k+1} = \mathbf{r}_k - \alpha_k \mathbf{A} \mathbf{r}_k$ 

$$r_0 = \boldsymbol{b} - \boldsymbol{A}\boldsymbol{x}_0 = \begin{bmatrix} 2\\ -4 \end{bmatrix}$$

$$\alpha_0 = \frac{5}{14}$$

$$\boldsymbol{x}_1 = \begin{bmatrix} 0\\ 0 \end{bmatrix} + \frac{5}{14} \begin{bmatrix} 2\\ 4 \end{bmatrix} = \begin{bmatrix} \frac{5}{7}\\ -\frac{10}{7} \end{bmatrix}$$

$$\boldsymbol{r}_1 = \begin{bmatrix} 0\\ 0 \end{bmatrix} - \frac{5}{14} \begin{bmatrix} 2\\ 4 \end{bmatrix} = \begin{bmatrix} 2\\ 1 \end{bmatrix}$$

next iteration:

$$\alpha_1 = \frac{5}{16}$$

$$x_2 = \begin{bmatrix} \frac{5}{7} \\ -\frac{1}{20} \end{bmatrix} + \frac{5}{16} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{75}{56} \\ -\frac{125}{112} \end{bmatrix}$$

$$r_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix} - \frac{5}{16} \begin{bmatrix} 5 \\ 6 \end{bmatrix} = \begin{bmatrix} \frac{7}{16} \\ -\frac{14}{16} \end{bmatrix}$$

In conclusion,  $\boldsymbol{x}_1 = \begin{bmatrix} \frac{5}{7} \\ -\frac{1}{10} \end{bmatrix} \boldsymbol{x}_2 = \begin{bmatrix} \frac{75}{56} \\ -\frac{125}{112} \end{bmatrix}$ 

(b)

#### Question3

Let  $f: \mathbb{R}^n \to \mathbb{R}$  be a twice continuously differentiable functions. Suppose that for every  $\boldsymbol{x} \in \mathbb{R}^n$ , the eigenvalues of the Hessian matrix  $\nabla^2 f(\boldsymbol{X})$  lie uniformly in the interval [m, M] with  $0 < m \le M < \infty$ .

Prove that:

- (a) The function f has a unique global minimizer  $x^*$ .
- (b) For all  $x \in \mathbb{R}^n$ , the following inequality holds:

$$\frac{1}{2M} \|\nabla f(x)\|^2 \le f(x) - f(x^*) \le \frac{1}{2m} \|\nabla f(x)\|^2$$

# Question4

Consider the optimization problem  $\min_{\boldsymbol{x} \in \mathbb{R}^n} f(\boldsymbol{x})$ , where  $f : \mathbb{R}^n \to \mathbb{R}$  is a continuously differentiable function. To develop a weighted gradient descent method, let  $\boldsymbol{W} \in \mathbb{R}^{n \times n}$  be a symmetric positive definite (SPD) matrix. Denote by  $\boldsymbol{W}^{\frac{1}{2}}$  the unique SPD square root of  $\boldsymbol{W}$  (i.e.,  $(\boldsymbol{W}^{\frac{1}{2}})^2 = \boldsymbol{W}$ ) and by  $\boldsymbol{W}^{-\frac{1}{2}}$  its inverse. Given the current iterate  $\boldsymbol{x}^{(k)}$ , define the next iterate  $\boldsymbol{x}^{(k+1)}$  as the solution of the following constrained optimization problem:

$$\min_{\boldsymbol{x} \in \mathbb{R}^n} f(\boldsymbol{x}^{(k)}) + \langle \nabla f(\boldsymbol{x}^{(k)}), \boldsymbol{x} - \boldsymbol{x}^{(k)} \rangle$$
subject to  $\|\boldsymbol{W}^{\frac{1}{2}}(\boldsymbol{x} - \boldsymbol{x}^{(k)})\|_2 \le \alpha_k \|\boldsymbol{W}^{-\frac{1}{2}} \nabla f(\boldsymbol{x}^{(k)})\|_2$ 

where  $\alpha_k > 0$  is a step-size parameter.

Answer the following questions:

- (a) Derive an explicit formula for  $\boldsymbol{x}^{(k+1)}$
- (b) Prove that  $\bar{x}^{(k+1)}$  is equivalently the unique minimizer of the unconstrained quadratic problem:

$$\min_{oldsymbol{x} \in \mathbb{R}^n} \left\{ 
abla f(oldsymbol{x}^{(k)}) + \langle f(oldsymbol{x}^{(k)}), oldsymbol{x} - oldsymbol{x}^{(k)} 
angle + rac{1}{2lpha_k} \|oldsymbol{W}^{rac{1}{2}}(oldsymbol{x} - oldsymbol{x}^{(k)})\|_2^2 
ight\}$$