MSBD 5007 HW2

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Question1

Let
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 1 & 0 \\ 1 & 1 & 2 & 1 \\ 1 & 0 & 1 & 2 \\ 0 & 1 & 1 & 1 \end{bmatrix}$$
 and $\mathbf{b} = \begin{bmatrix} 6 \\ 5 \\ 7 \\ 4 \end{bmatrix}$. Use the QR factorization to solve the least square problem:

$$\min_{oldsymbol{x} \in \mathbb{R}^4} \|oldsymbol{A}oldsymbol{x} - oldsymbol{b}\|_2^2.$$

- (a)
- (b)

Question2

Find the best rank-1 approximation with respect to the Frobenius norm to the matrix.

$$\mathbf{A} = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix}$$

Question3

Let X and Y be two matrices of dimensions $m \times n$. Consider the optimization problem

$$\min_{Q \in \mathbb{R}^{m \times n}} \| \boldsymbol{X} - \boldsymbol{Q} \boldsymbol{Y} \|_F \text{ subject to } \boldsymbol{Q}^T \boldsymbol{Q} = \boldsymbol{I}_m.$$

, where $\|\dot\|_F$ denotes the Frobenius norm and I_m . is the $m \times n$ identity matrix. This problem aries when we want to align two datasets \boldsymbol{X} and \boldsymbol{Y} up to an orthogonal linear transformation. Prove that the solution is given by $\boldsymbol{Q} = \boldsymbol{U}\boldsymbol{V}^T$, where $\boldsymbol{U}\boldsymbol{\Sigma}\boldsymbol{V}^T$ is the singular value decomposition of $\boldsymbol{X}\boldsymbol{Y}^T$, i.e. $\boldsymbol{X}\boldsymbol{Y}^T = \boldsymbol{U}\boldsymbol{\Sigma}\boldsymbol{V}^T$.

Question4

Let $A \in \mathbb{R}^{m \times n}$ be a matrix with $m \geq n$ and full column rank, i.e., rank(A) = n. A Given rotation matrix $G_{i,j,\theta} \in \mathbb{R}^{n \times n}$ (for indices $1 \leq i \leq j \leq n$) is defined by

$$oldsymbol{G}_{i,j, heta} = egin{bmatrix} oldsymbol{I}_{i-1} & & & & & & \\ & & \cos(heta) & & & -\sin(heta) & & \\ & & oldsymbol{I}_{j-i-1} & & & & \\ & & \sin(heta) & & & \cos(heta) & & \\ & & oldsymbol{I}_{n-j} \end{bmatrix}$$

where I_k denotes the $k \times k$ identity matrix, and all unspecified entries are zero. Equivalently, $G_{i,j,\theta}$ is identical to the identity matrix except for the four entries in its *i*th and *j*th rows and columns:

$$g_{ii} = cos\theta, g_{ij} = -sin\theta, g_{jj} = cos\theta.$$

Answer the following questions:

(a) Prove that $G_{i,j,\theta}$ is an orthogonal matrix, i.e. show that

$$G_{i,j,\theta}^T G_{i,j,\theta} = \mathbf{I}_n.$$

(b) Let $v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \in \mathbb{R}$. Prove that for any indices i, j with $1 \le i < j \le n$, there exists an angle θ

such that

$$\boldsymbol{G}_{i,j,\theta}\boldsymbol{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_{i-1} \\ \sqrt{v_i^2 + v_j^2} \\ v_{i+1} \\ \vdots \\ v_{j-1} \\ 0 \\ v_{j+1} \\ \vdots \\ v_n \end{bmatrix}$$

In other words, show that the Given rotation can eliminate the jth entry of v by affecting only the ith and jth components.

(c) An $m \times n$ **A** is called an *upperHessenbergmatrix* if

$$a_{ij} = 0$$
 whenever $i - j > 2$.

For $m \geq n$, the pattern of nonzero entries in **A** is depicted as

$$\begin{bmatrix} \times & \times & \dots & \times \\ \times & \times & \dots & \times \\ 0 & \times & \ddots & \vdots \\ \vdots & \ddots & \ddots & \times \\ \vdots & \ddots & \ddots & \times \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & \dots & 0 \end{bmatrix}$$

Since A already contains many zeros in its lower triangular portion, the standard Householder QR algorithm can be optimized. Develop an algorithm using Givens rotations to compute the QR decomposition of an upper Hessenberg matrix A. Your algorithm should achieve a computational cost of $O(n^2)$ for the reduced (economy-size) QR factorization and O(mn) for the full QR factorization.

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