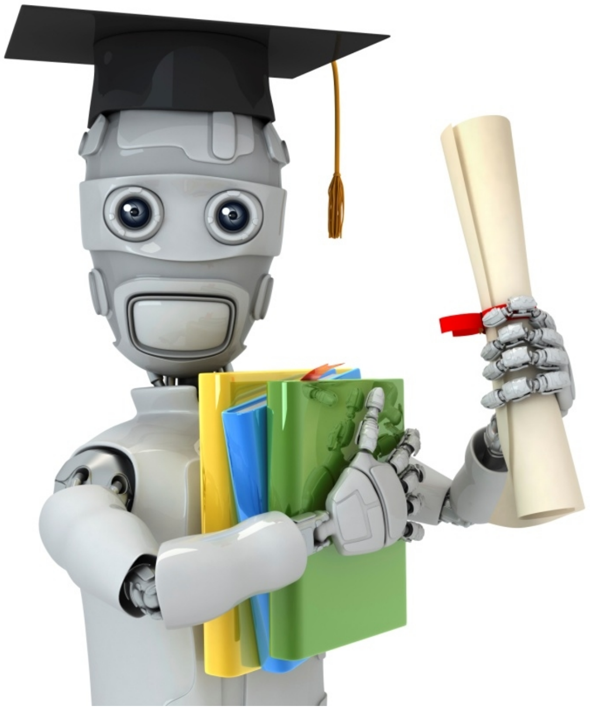
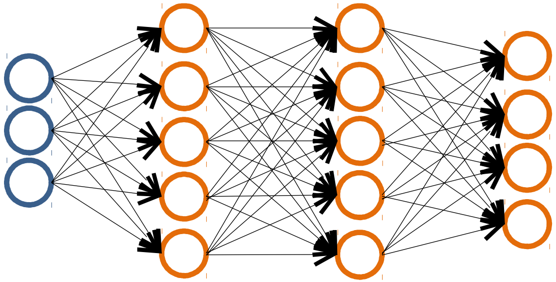


Neural Networks: Learning

Cost function

Machine Learning

Neural Network (Classification)



Layer 1 Layer 2 Layer 3 Layer 4

$\{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \ldots, (x^{(m)}, y^{(m)})\}$

$L =$ total no. of layers in network

$s_l =$ no. of units (not counting bias unit) in layer l

Binary classification

$y = 0 \text{ or } 1$

1 output unit

Multi-class classification (K classes)

$y \in \mathbb{R}^K$ E.g. $\begin{bmatrix}1\\0\\0\\0\end{bmatrix}$, $\begin{bmatrix}0\\1\\0\\0\end{bmatrix}$, $\begin{bmatrix}0\\0\\1\\0\end{bmatrix}$, $\begin{bmatrix}0\\0\\0\\1\end{bmatrix}$

pedestrian car motorcycle truck

K output units

Cost function

Logistic regression:

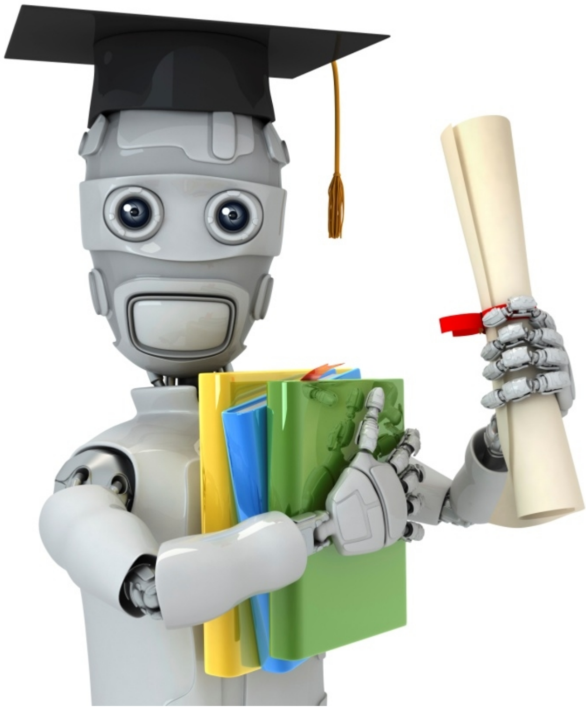
$$J(\theta) = -\frac{1}{m}\left[\sum_{i=1}^{m} y^{(i)} \log h_\theta(x^{(i)}) + (1-y^{(i)})\log(1-h_\theta(x^{(i)}))\right] + \frac{\lambda}{2m}\sum_{j=1}^{n}\theta_j^2$$

Neural network:

$$h_\Theta(x) \in \mathbb{R}^K \quad (h_\Theta(x))_i = i^{th} \text{ output}$$

$$J(\Theta) = -\frac{1}{m}\left[\sum_{i=1}^{m}\sum_{k=1}^{K} y_k^{(i)} \log(h_\Theta(x^{(i)}))_k + (1-y_k^{(i)})\log(1-(h_\Theta(x^{(i)}))_k)\right]$$

$$+\frac{\lambda}{2m}\sum_{l=1}^{L-1}\sum_{i=1}^{s_l}\sum_{j=1}^{s_{l+1}}(\Theta_{ji}^{(l)})^2$$



Machine Learning

Neural Networks: ~~Learning~~

Backpropagation algorithm

Gradient computation

$$J(\Theta) = -\frac{1}{m}\left[\sum_{i=1}^{m}\sum_{k=1}^{K} y_k^{(i)} \log h_\theta(x^{(i)})_k + (1 - y_k^{(i)}) \log(1 - h_\theta(x^{(i)})_k)\right]$$
$$+\frac{\lambda}{2m}\sum_{l=1}^{L-1}\sum_{i=1}^{s_l}\sum_{j=1}^{s_{l+1}}(\Theta_j^{(l)})^2$$

$$\min_{\Theta} J(\Theta)$$

Need code to compute:

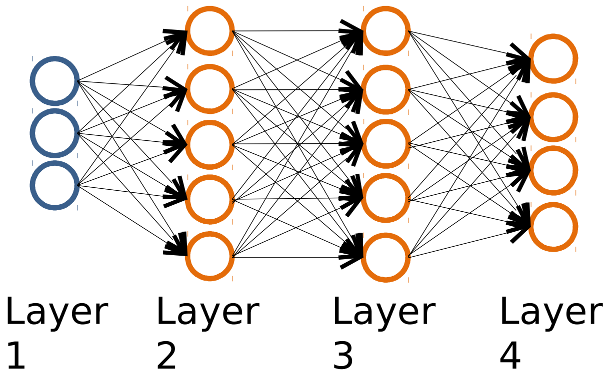
- $J(\Theta)$
- $\frac{\partial}{\partial \Theta_{ij}^{(l)}} J(\Theta)$

Gradient computation

Given one training example (x, y):

Forward propagation:

$$a^{(1)} = x$$
$$z^{(2)} = \Theta^{(1)} a^{(1)}$$
$$a^{(2)} = g(z^{(2)}) \quad (\text{add } a_0^{(2)})$$
$$z^{(3)} = \Theta^{(2)} a^{(2)}$$
$$a^{(3)} = g(z^{(3)}) \quad (\text{add } a_0^{(3)})$$
$$z^{(4)} = \Theta^{(3)} a^{(3)}$$
$$a^{(4)} = h_\Theta(x) = g(z^{(4)})$$



Gradient computation: Backpropagation algorithm

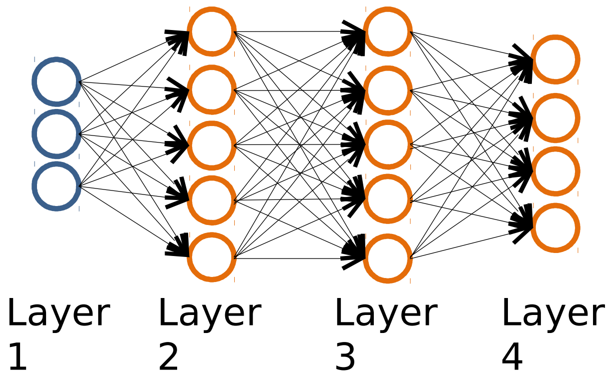
Intuition: $\delta_j^{(l)} =$ "error" of node j in layer l.

For each output unit (layer L = 4)

$$\delta_j^{(4)} = a_j^{(4)} - y_j$$

$$\delta^{(3)} = (\Theta^{(3)})^T \delta^{(4)} .* g'(z^{(3)})$$

$$\delta^{(2)} = (\Theta^{(2)})^T \delta^{(3)} .* g'(z^{(2)})$$



Backpropagation algorithm

Training set $\{(x^{(1)}, y^{(1)}), \ldots, (x^{(m)}, y^{(m)})\}$

Set $\triangle_{ij}^{(l)} = 0$ (for all l, i, j).

For $i = 1 \text{ to } m$

Set $a^{(1)} = x^{(i)}$

Perform forward propagation to compute $a^{(l)}$ for $l = 2, 3, \ldots, L$

Using $y^{(i)}$, compute $\delta^{(L)} = a^{(L)} - y^{(i)}$

Compute $\delta^{(L-1)}, \delta^{(L-2)}, \ldots, \delta^{(2)}$

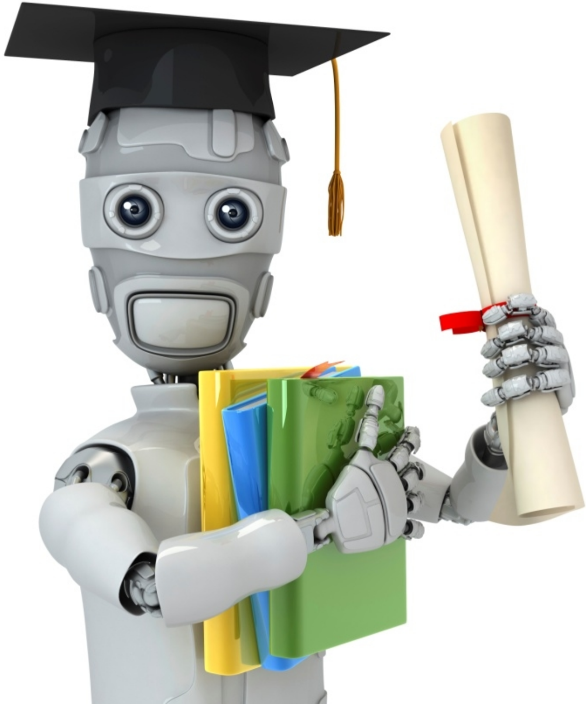
$$\triangle_{ij}^{(l)} := \triangle_{ij}^{(l)} + a_j^{(l)} \delta_i^{(l+1)}$$

$$D_{ij}^{(l)} := \frac{1}{m} \triangle_{ij}^{(l)} + \lambda \Theta_{ij}^{(l)} \text{ if } j \neq 0$$

$$D_{ij}^{(l)} := \frac{1}{m} \triangle_{ij}^{(l)} \quad \text{if } j = 0$$

$$\frac{\partial}{\partial \Theta_{ij}^{(l)}} J(\Theta) = D_{ij}^{(l)}$$

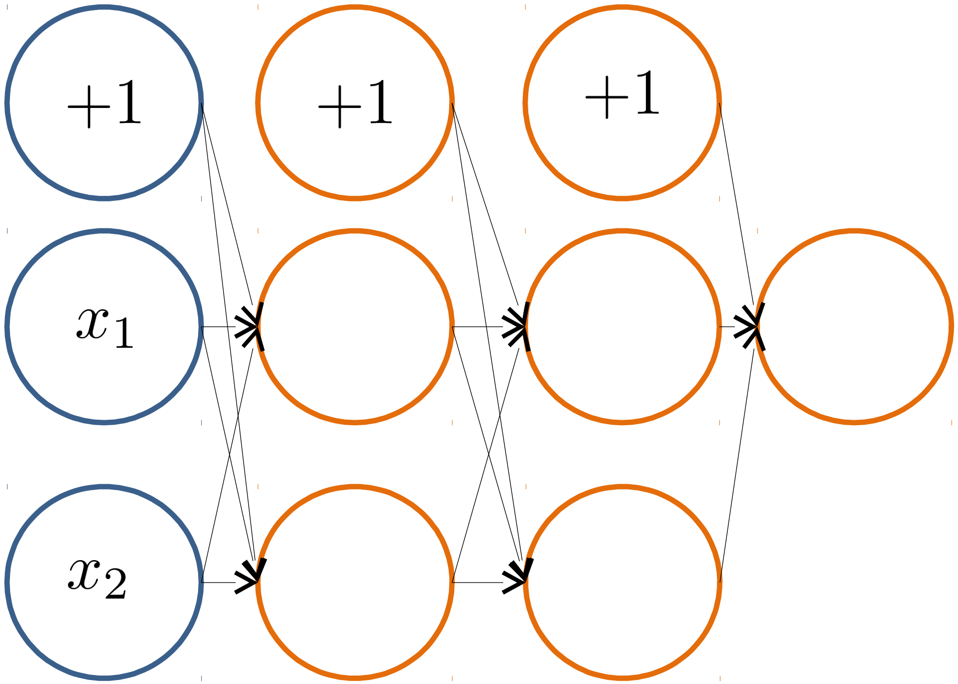
Derivative



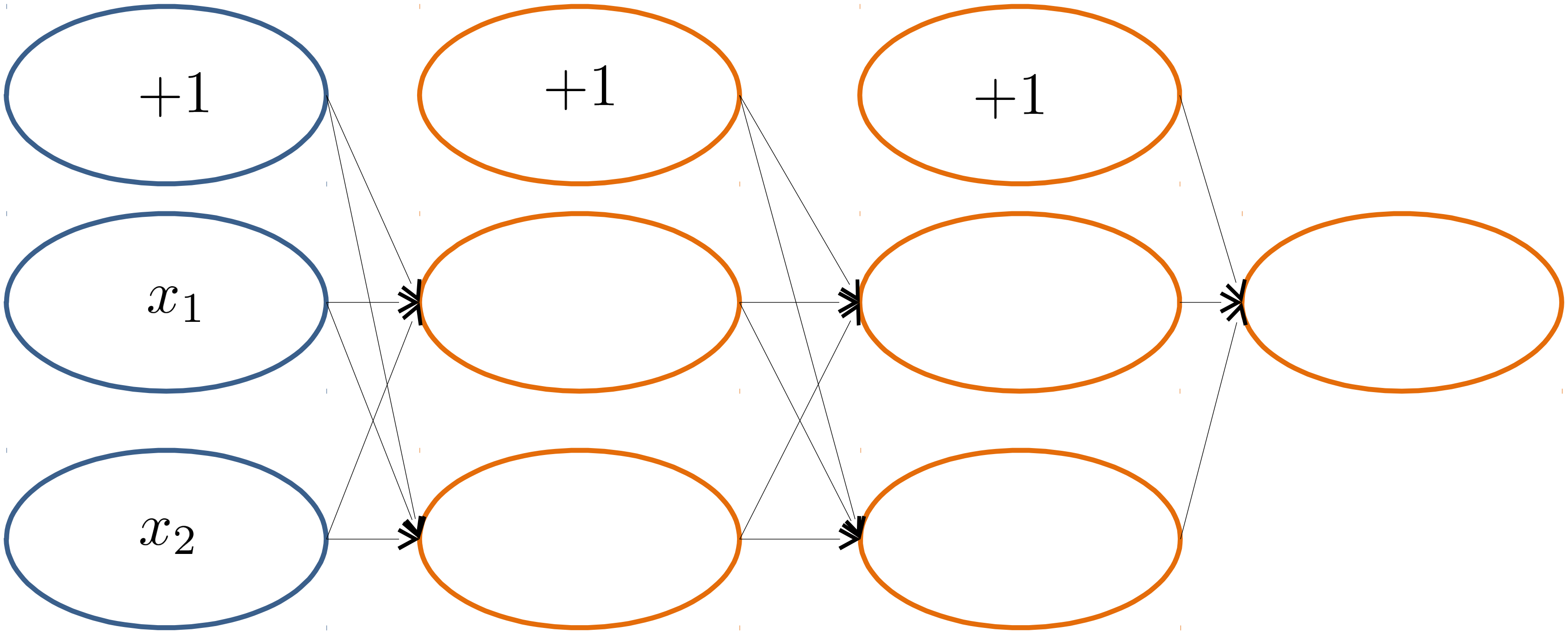
Machine Learning

Neural Networks: ~~Learning~~ Backpropagation intuition

Forward Propagation



Forward Propagation



What is backpropagation doing?

$$J(\Theta) = -\frac{1}{m}\left[\sum_{i=1}^{m} y^{(i)} \log(h_\Theta(x^{(i)})) + (1-y^{(i)})\log(1-(h_\Theta(x^{(i)})))\right]$$
$$+\frac{\lambda}{2m}\sum_{l=1}^{L-1}\sum_{i=1}^{s_l}\sum_{j=1}^{s_{l+1}}(\Theta_{ji}^{(l)})^2$$

Focusing on a single example $x^{(i)}$, $y^{(i)}$, the case of 1 output unit, and ignoring regularization ($\lambda = 0$),

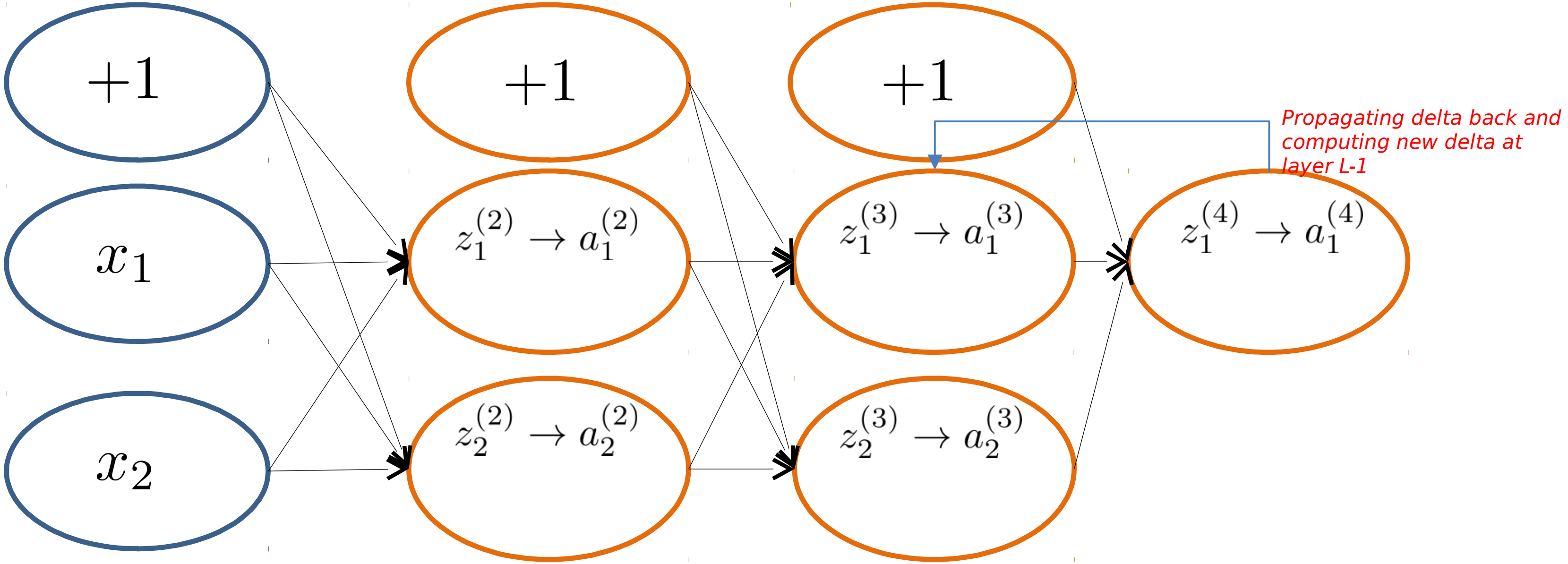
You can think of cost function as a mean square error function to get a better intuition of back propogation algorithm

$$\text{cost(i)} = y^{(i)} \log h_\Theta(x^{(i)}) + (1-y^{(i)}) \log h_\Theta(x^{(i)})$$

(Think of $\text{cost(i)} \approx (h_\Theta(x^{(i)}) - y^{(i)})^2$)

I.e. how well is the network doing on example i?

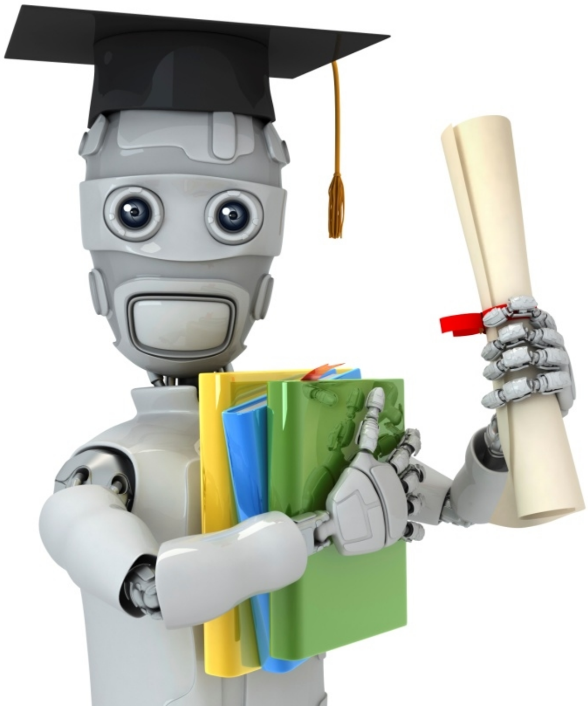
Forward Propagation



$\delta_j^{(l)}$ = “error” of cost for $a_j^{(l)}$ (unit j in layer l).

Formally, $\delta_j^{(l)} = \frac{\partial}{\partial z_j^{(l)}} \text{cost}(i)$ (for $j \geq 0$), where

$$\text{cost}(\text{i}) = y^{(i)} \log h_\Theta(x^{(i)}) + (1 - y^{(i)}) \log h_\Theta(x^{(i)})$$



Neural Networks: Learning

Implementation note: Unrolling parameters

Machine Learning

Advanced optimization

```
function [jVal, gradient] = costFunction(theta)
    ...
optTheta = fminunc(@costFunction, initialTheta, options)
```

Neural Network (L=4):

$\Theta^{(1)}, \Theta^{(2)}, \Theta^{(3)}$ - matrices (`Theta1, Theta2, Theta3`)

$D^{(1)}, D^{(2)}, D^{(3)}$ - matrices (`D1, D2, D3`)

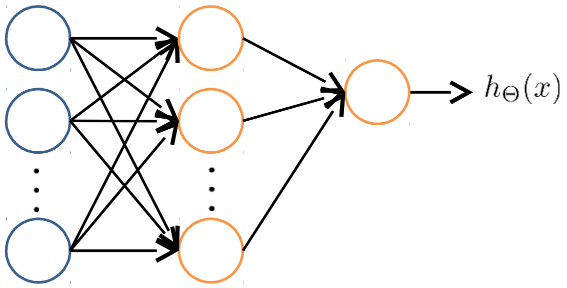
"Unroll" into vectors

Example

$s_1 = 10, s_2 = 10, s_3 = 1$

$\Theta^{(1)} \in \mathbb{R}^{10\times 11}, \Theta^{(2)} \in \mathbb{R}^{10\times 11}, \Theta^{(3)} \in \mathbb{R}^{1\times 11}$

$D^{(1)} \in \mathbb{R}^{10\times 11}, D^{(2)} \in \mathbb{R}^{10\times 11}, D^{(3)} \in \mathbb{R}^{1\times 11}$




```
thetaVec = [ Theta1(:); Theta2(:); Theta3(:)];
DVec = [D1(:); D2(:); D3(:)];

Theta1 = reshape(thetaVec(1:110),10,11);
Theta2 = reshape(thetaVec(111:220),10,11);
Theta3 = reshape(thetaVec(221:231),1,11);
```

Learning Algorithm

Have initial parameters $\Theta^{(1)}, \Theta^{(2)}, \Theta^{(3)}$.

Unroll to get `initialTheta` to pass to

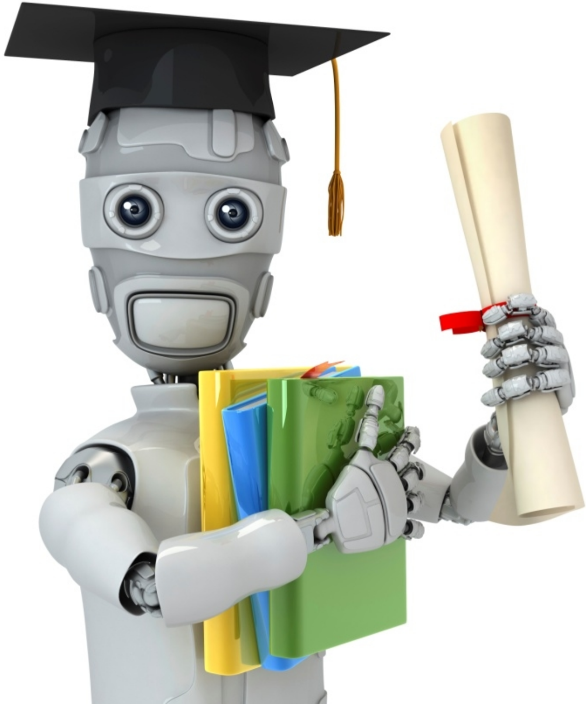
```
fminunc(@costFunction, initialTheta, options)
```

```
function [jval, gradientVec] = costFunction(thetaVec)
```

From `thetaVec`, get $\Theta^{(1)}, \Theta^{(2)}, \Theta^{(3)}$.

Use forward prop/back prop to compute $D^{(1)}, D^{(2)}, D^{(3)}$ and $J(\Theta)$.

Unroll $D^{(1)}, D^{(2)}, D^{(3)}$ to get `gradientVec`.

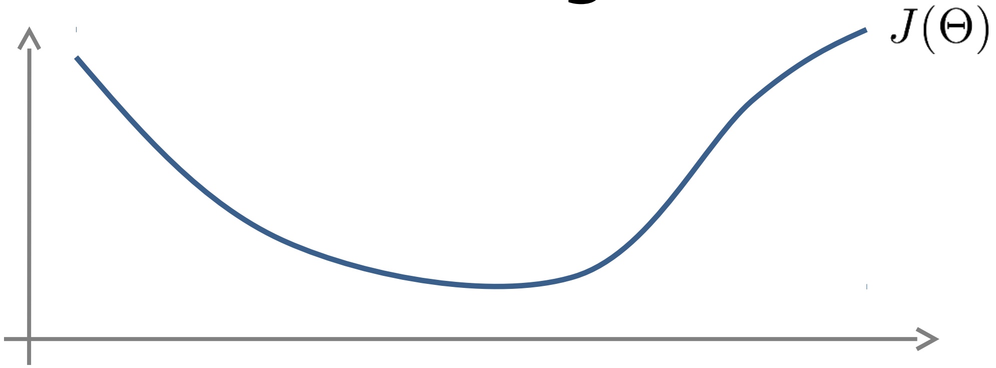


Machine Learning

Neural Networks: Learning

Gradient checking

Numerical estimation of gradients



More accurate

Implement: **gradApprox = (J(theta + EPSILON) – J(theta – EPSILON)) /(2*EPSILON)**

Parameter vector θ

$\theta \in \mathbb{R}^n$ (E.g. θ is "unrolled" version of $\Theta^{(1)}, \Theta^{(2)}, \Theta^{(3)}$)

$\theta = \theta_1, \theta_2, \theta_3, \dots, \theta_n$

$$\frac{\partial}{\partial\theta_1} J(\theta) \approx \frac{J(\theta_1+\epsilon,\theta_2,\theta_3,\dots,\theta_n) - J(\theta_1-\epsilon,\theta_2,\theta_3,\dots,\theta_n)}{2\epsilon}$$

$$\frac{\partial}{\partial\theta_2} J(\theta) \approx \frac{J(\theta_1,\theta_2+\epsilon,\theta_3,\dots,\theta_n) - J(\theta_1,\theta_2-\epsilon,\theta_3,\dots,\theta_n)}{2\epsilon}$$

$$\vdots$$

$$\frac{\partial}{\partial\theta_n} J(\theta) \approx \frac{J(\theta_1,\theta_2,\theta_3,\dots,\theta_n+\epsilon) - J(\theta_1,\theta_2,\theta_3,\dots,\theta_n-\epsilon)}{2\epsilon}$$

```
for i = 1:n,
    thetaPlus = theta;
    thetaPlus(i) = thetaPlus(i) + EPSILON;
    thetaMinus = theta;
    thetaMinus(i) = thetaMinus(i) – EPSILON;
    gradApprox(i) = (J(thetaPlus) – J(thetaMinus))
                /(2*EPSILON);
end;
```

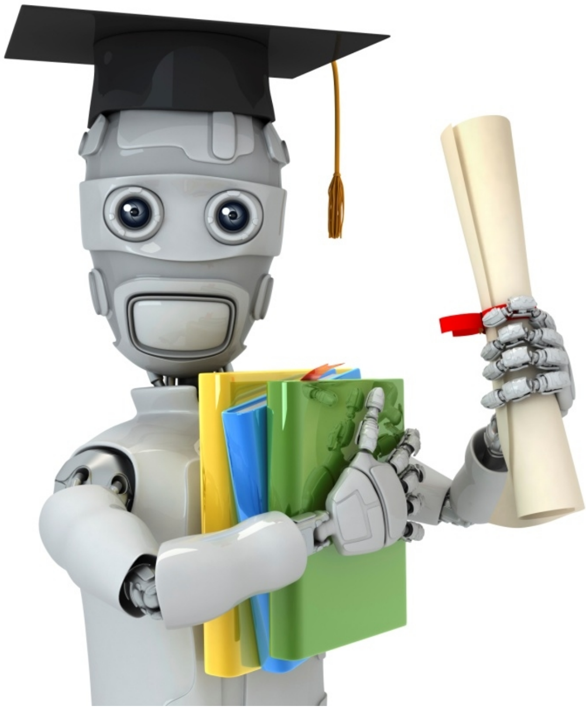
Check that `gradApprox ≈ DVec`

Implementation Note:

- Implement backprop to compute **DVec** (unrolled $D^{(1)}, D^{(2)}, D^{(3)}$).
- Implement numerical gradient check to compute **gradApprox**.
- Make sure they give similar values.
- Turn off gradient checking. Using backprop code for learning.

Important:

- Be sure to disable your gradient checking code before training
  your classifier. If you run numerical gradient



Machine Learning

Neural Networks: Learning

Random initialization

Initial value of Θ

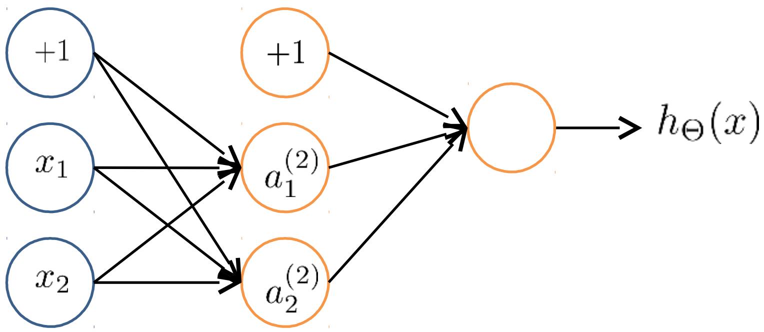
For gradient descent and advanced optimization method, need initial value for Θ.

```
optTheta = fminunc(@costFunction,
initialTheta, options)
```

Consider gradient descent

Set `initialTheta = zeros(n,1)` ?

Zero initialization



$$\Theta_{ij}^{(l)} = 0 \text{ for all } i, j, l.$$

After each update, parameters corresponding to inputs going into each of two hidden units are identical.

Random initialization: Symmetry breaking

Initialize each $\Theta_{ij}^{(l)}$ to a random value in $[-\epsilon, \epsilon]$

(i.e. $-\epsilon \leq \Theta_{ij}^{(l)} \leq \epsilon$)

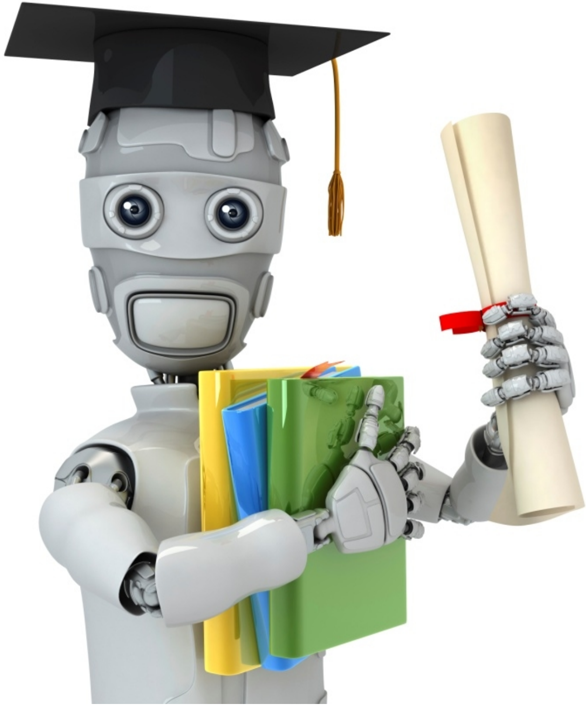
E.g.

```
Theta1 =  rand(10,11)*(2*INIT_EPSILON)
      - INIT_EPSILON;

Theta2 =  rand(1,11)*(2*INIT_EPSILON)
   - INIT_EPSILON;
```

Neural Networks: ~~Learning~~

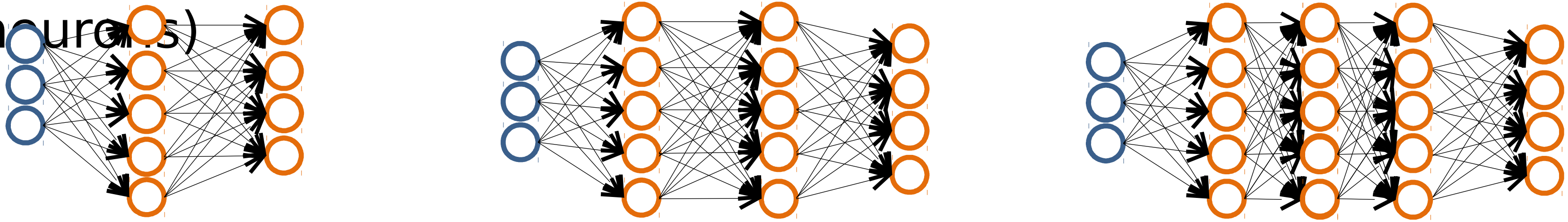
Putting it together



Machine Learning

Training a neural network

Pick a network architecture (connectivity pattern between neurons)



No. of input units: Dimension of features $x^{(i)}$

No. output units: Number of classes

Reasonable default: 1 hidden layer, or if >1 hidden layer, have same no. of hidden units in every layer (usually the more the better)

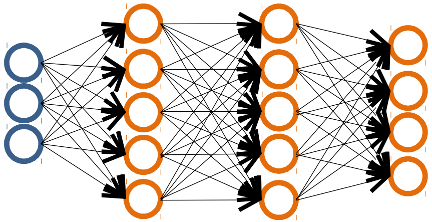
Training a neural network

1. Randomly initialize weights
2. Implement forward propagation to get $h_\Theta(x^{(i)})$ for any $x^{(i)}$
3. Implement code to compute cost function $J(\Theta)$
4. Implement backprop to compute partial derivatives $\frac{\partial}{\partial\Theta^{(l)}_{jk}} J(\Theta)$

```
for i = 1:m
```

Perform forward propagation and backpropagation using example $(x^{(i)}, y^{(i)})$

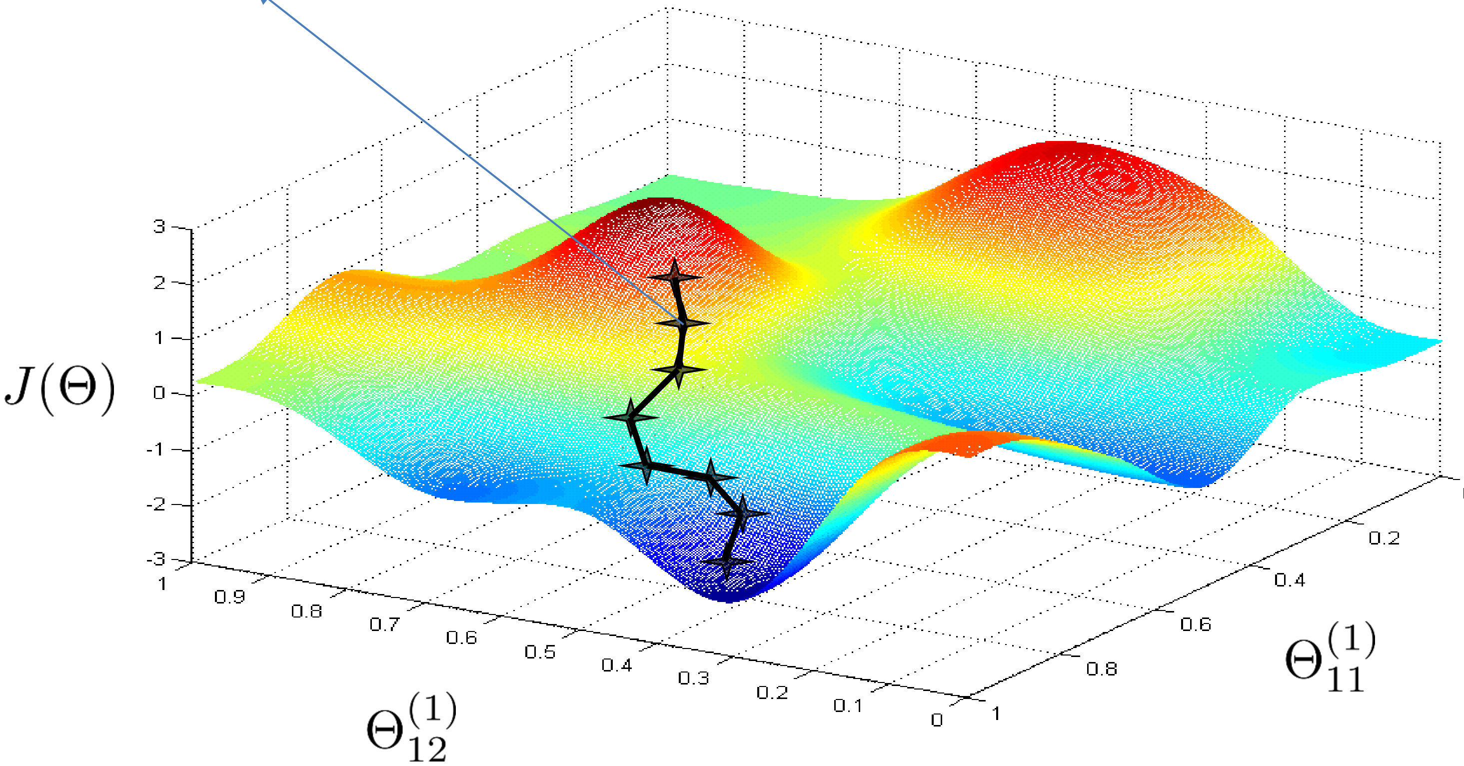
(Get activations $a^{(l)}$ and delta terms $\delta^{(l)}$ for $l = 2, \ldots, L$).

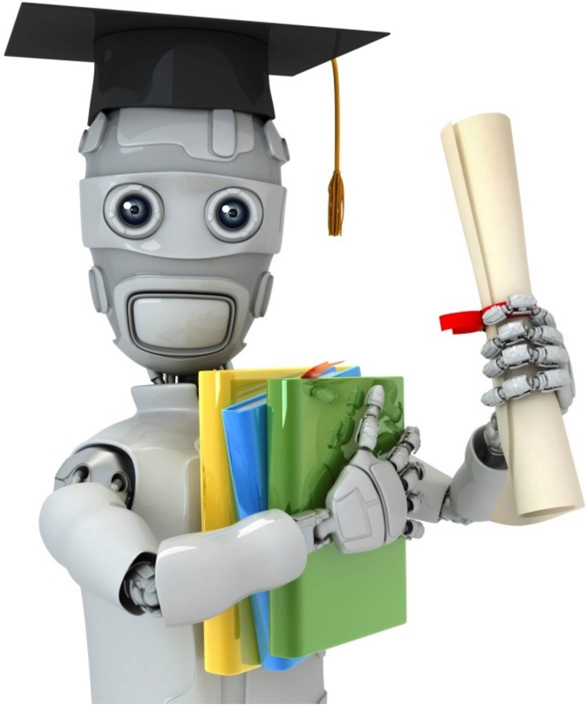


Training a neural network

5. Use gradient checking to compare $\frac{\partial}{\partial\Theta_{jk}^{(l)}}J(\Theta)$ computed using backpropagation vs. using numerical estimate of gradient of $J(\Theta)$. Then disable gradient checking code.
6. Use gradient descent or advanced optimization method with backpropagation to try to minimize $J(\Theta)$ as a function of parameters Θ

ck Propagation computing direction of gradient,
adient descent goes down hill until we reach gobal optimum





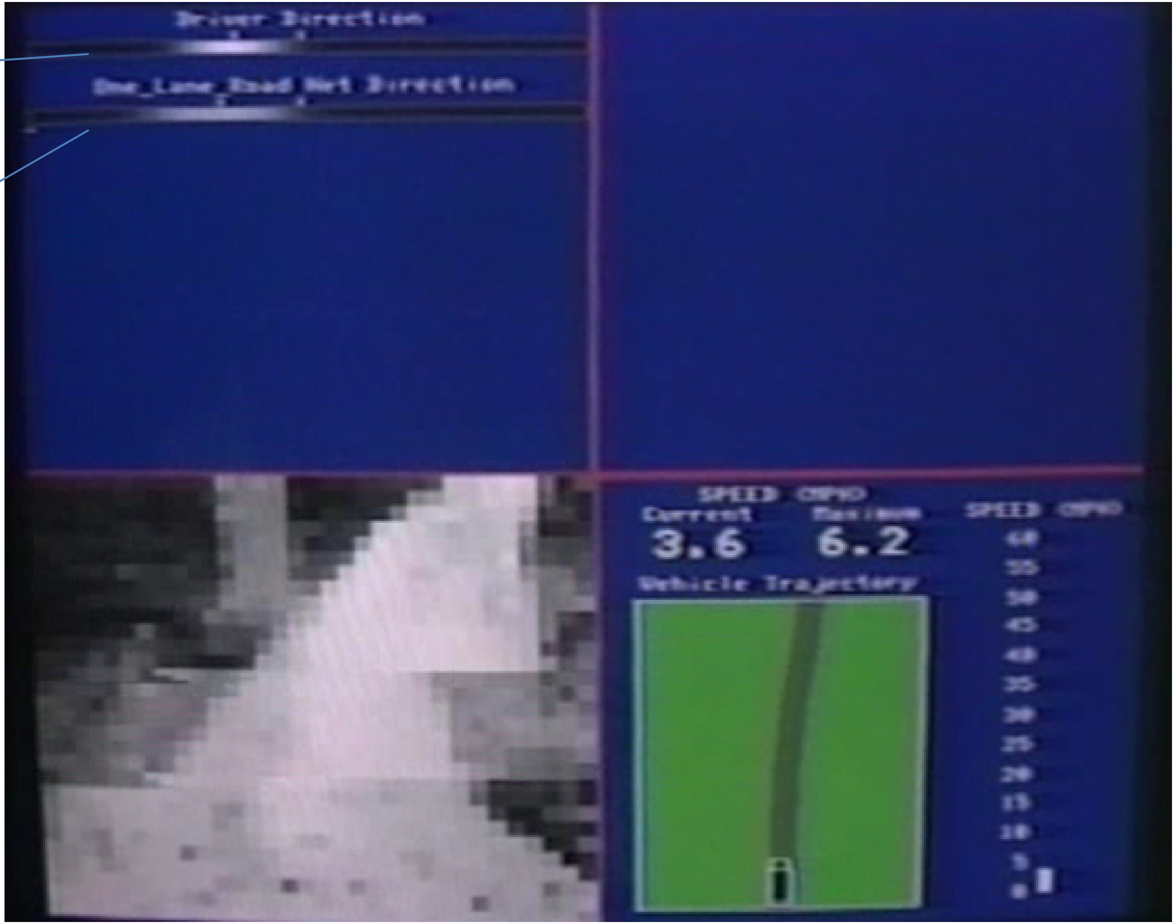
Machine Learning

Neural Networks: Learning

Backpropagation example: Autonomous driving (optional)

Direction choosen by human driver

Direction selected by learning algorithm



Courtesy of Dean Pomerleau]