

# CS 8803 – O01: Artificial Intelligence for Robotics

## Mini Project: Runaway Robot

### Fall 2018

#### Project Specifications

Your task is to complete Parts 1–4 in the “Runaway Robot” project on Udacity. While you may use the Udacity IDE to test your code against some test cases, you must submit your code to Canvas for grading using the Assignments link in the canvas navigation bar.

We will run your code against 10 test cases per part to grade your work. Each test case is worth 2.5 points, so there is a maximum of 100 points. We will run your code once per test case; passing a test case is worth 2.5 point, and failing a test case is worth 0 points.

The parameters for the test cases will satisfy the following constraints:

- $-20.0 \leq \text{target\_starting\_position\_x} \leq 20.0$
- $-20.0 \leq \text{target\_starting\_position\_y} \leq 20.0$
- $-\text{math.pi} \leq \text{target\_starting\_heading} < \text{math.pi}$
- $10 \leq \text{abs}(\text{target\_period}) \leq 50$
- $1.0 \leq \text{target\_speed} \leq 5.0$
- $-20.0 \leq \text{hunter\_starting\_position\_x} \leq 20.0$
- $-20.0 \leq \text{hunter\_starting\_position\_y} \leq 20.0$
- $-\text{math.pi} \leq \text{hunter\_starting\_heading} < \text{math.pi}$

*target\_period* will be an integer. It represents the number of time steps required for the robot to make one complete cycle.

A positive value for *target\_period* means that the robot will move counterclockwise; a negative value means the robot will move clockwise.

The standard deviation of the Gaussian applied to the target's measurements will be 0 in Part 1, 0.05 times the target's speed in Parts 2–4.

The hunter bot (if present) will have a max speed twice that of the target in Part 3 and 0.99 that of the target in Part 4.

#### The requirements for passing a test case are:

- Part 1: Identifies the position of the target within a distance of  $0.02 * \text{target\_speed}$  using at most **10** calls to `estimate_next_pos`
- Part 2: Identifies the position of the target within a distance of  $0.02 * \text{target\_speed}$  using at most 1000 calls to `estimate_next_pos`
- Parts 3&4: Puts the hunter within a distance of  $0.02 * \text{target\_speed}$  of the target using at most 1000 calls to `next_move`
- All Parts: The code takes a maximum of 5 seconds per test case; taking longer than 5 seconds will result in the failure of the test case
- All Parts: No exceptions are raised; any exception raised during the execution of a test case will result in the failure of the test case

As you will only upload the studentMain files in your submission, any changes you make to `robot.py` or `matrix.py` will not be seen. If you want to modify those classes for your submission, include the classes in the appropriate studentMainN.py files (and don't import `robot` or `matrix`). You're also welcome to use any other libraries that are accepted in the Udacity interface (e.g. `numpy`).

The submission must consist of Python 2.7 files labeled `studentMain1.py`, `studentMain2.py`, `studentMain3.py`, and `studentMain4.py`. Do not zip, tar, or archive the files together. Files that do not follow this format will receive a penalty of -20 pts.

Your `studentMainN.py` files should execute NO code when they are imported. (i.e. comment out any testing code you may have, we only want to test the `estimate_next_pos` or `next_move` function.) They should also **NOT** display a GUI or Visualization when we import them or call your function under test. If we have to manually edit your code to comment out your own testing harness or visualization you will receive a -20 point penalty.

Additionally, you may use any packages that are accepted in the Udacity interface, but any code that does not run in the Udacity interface will receive no credit. This includes using Python 3, packages not available in Python 2.7, or packages not recognized by the Udacity IDE. You can always check your packages work by uploading them to the Udacity IDE and seeing whether an error is raised.

### **Testing Your Code**

On Canvas, we have posted a testing suite similar to the one we'll be using for grading the Runaway Robot project. To use the testing suite, put `testing_suite_full.py` into the same directory as the `studentMainN.py` files (and `robot.py` and `matrix.py` if you are using the default versions), then run `python testing_suite_full.py`

In the testing suite, we've provided 10 premade test cases. We will use 10 other, secret test cases to score your project. You should ensure that your code consistently succeeds on each of the given test cases as well as on a wide range of other test cases of your own design, as we will only run your code once per graded test case.

### **Academic Integrity**

You must write the code for this project alone. While you may make limited usage of outside resources, keep in mind that you must cite any such resources you use in your work (for example, you should use comments to denote a snippet obtained from StackOverflow).

You must not use anybody else's code for this project in your work. We will use code-similarity detection software to identify suspicious code, and we will refer any potential incidents to the Office of Student Integrity for investigation. Moreover, you must not post your work on a publicly accessible repository; this could also result in an Honor Code violation [if another student turns in your code]. (Consider using the GT provided Github repository or a repo such as Bitbucket that doesn't default to public sharing.)