Shayan Riyaz

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STATEMENT

Research and Development Engineer with a robust background in Algorithm Engineering. Technical background includes algorithm design, data science, data analysis, Machine/Deep Learning (M/DL), Digital Signal Processing (DSP), embedded systems, software engineering, computer vision, and statistics. Proficient with experiment design, presentations, project management, report writing, and research planning.

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EXPERIENCE

Stroke Dx, Senior Software R&D Engineer,

Los Angeles, CA, 2025 - Present

- Lead Software Engineer responsible for algorithm research, development, and documentation.
- Researching computational pipeline development for automated stroke classification:
- Transforming eddy current damping sensor based raw electromagnetic impedance data into 3D diagnostic visualizations for differentiating ischemic vs. hemorrhagic stroke subtypes.

Masimo Corporation, Algorithm Engineer II,

Irvine, CA, 2020 - 2025

- Led a team of 3 engineers to deploy the PPG-based AFib detection project for a <u>hospital wearable</u>.
 - Optimized computation and memory overhead in Python/C machine learning algorithms.
 - Applied model-based development and design control for algorithms under IEC 62304 compliance.
 - Collaborated with clinicians to draft IRB (Institutional Review Board) protocols for FDA validation.
- Led the design of a novel low-power and memory heart sound detector for the next-gen Masimo Centroid
 - Achieved a **96% F1 score** using conditional probability, peak and cluster detection, and state machines.
 - O Designed FIR filters in C and Python for gain and phase requirements.
- Achieved a Root Mean Square error of ±2.9% in detecting real-time activities such as steps, falls, and gait, utilizing accelerometer, gyroscope, and GPS data, in a four-engineer team, matching competitor accuracy.
 - O Combined signal processing (IIR, FFT, cross-correlation) and Machine Learning (logistic regression and K-Neighbors) in C/C++, Python, and MATLAB for wearable activity detection.
- Achieved 98% PPV and 99% specificity in sleep cycle classification for wrist wearables by incorporating neural networks in PyTorch with time-series and categorical data, deployed in C, JavaScript, Python, and SQL.

Human Performance and Robotics Laboratory, Research Assistant,

Long Beach, CA, 2019 - 2020

- Successfully developed a <u>real-time simulation framework</u> integrating IMU data with biomechanical models to estimate vertical ground reaction forces across multiple dynamic tasks.
 - Lead data validation by **resampling**, **filtering**, **and synchronizing** force plate and IMU data.
- Developed a Deep Learning glove controller with <u>CyberSens</u>, integrating IMUs, Arduino, I2C, and vibration motors. Modeled in TensorFlow Python, firmware in C, deployed in ONNX in C#.

EDUCATION	
California State University - Long Beach, Bachelor of Science , EE	2017 - 2019
De Anza College, Transfer, Electrical Engineering (EE)	2015 - 2017
SKILLS	
Languages: C, C++, JavaScript, Matlab, Python, SQL	
Frameworks/Libraries: Dash, Django, OpenCV, PyTorch, React, SciKitLearn, TensorFlow	
Systems/Applications: Arduino, AWS S3, Elastic, Confluence, Docker, Linux, Simulink, Tableau Methodologies: Agile, Six Sigma (White), GitLab, JIRA, CI/CD Practices	

PUBLICATIONS

A. Recinos, J. Abella, **S. Riyaz**, E. Demircan "Real-Time Vertical Ground Reaction Force Estimation in a Unified Simulation Framework Using Inertial Measurement Unit Sensors" MDPI (2020).