

Many of the slides in this lecture are either from or adapted from slides provided by the authors of the textbook "Computer Systems: A Programmer's Perspective," 2nd Edition and are provided from the website of Carnegie-Mellon University, course 15-213, taught by Randy Bryant and David O'Hallaron in Fall 2010. These slides are indicated "Supplied by CMU" in the notes section of the slides.

Cache Performance Metrics

- · Miss rate
 - fraction of memory references not found in cache (misses / accesses)
 - = 1 hit rate
 - typical numbers (in percentages):
 - » 3-10% for L1
 - » can be quite small (e.g., < 1%) for L2, depending on size, etc.
- Hit time
 - time to deliver a line in the cache to the processor
 - » includes time to determine whether the line is in the cache
 - typical numbers:
 - » 1-2 clock cycles for L1
 - » 5-20 clock cycles for L2
- · Miss penalty
 - additional time required because of a miss
 - » typically 50-200 cycles for main memory (trend: increasing!)

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Let's Think About Those Numbers

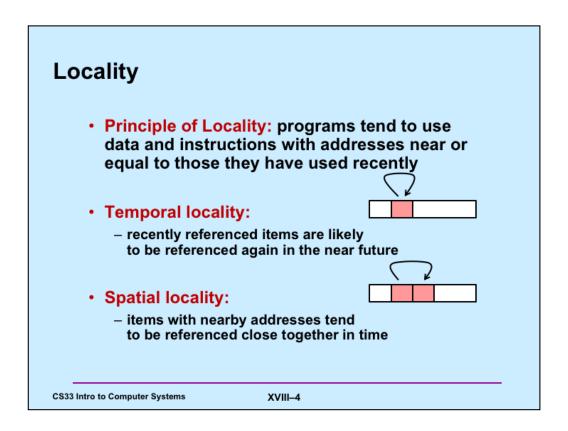
- · Huge difference between a hit and a miss
 - could be 100x, if just L1 and main memory
- Would you believe 99% hit rate is twice as good as 97%?
 - consider:
 cache hit time of 1 cycle
 miss penalty of 100 cycles
 - average access time:

```
97% hits: .97 * 1 cycle + 0.03 * 100 cycles ≈ 4 cycles
99% hits: .99 * 1 cycle + 0.01 * 100 cycles ≈ 2 cycles
```

This is why "miss rate" is used instead of "hit rate"

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Locality Example

```
sum = 0;
for (i = 0; i < n; i++)
    sum += a[i];
return sum;</pre>
```

· Data references

 reference array elements in succession (stride-1 reference pattern)

Spatial locality

- reference variable sum each iteration Temporal locality

Instruction references

- cycle through loop repeatedly Temporal locality

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Qualitative Estimates of Locality

- Claim: being able to look at code and get a qualitative sense of its locality is a key skill for a professional programmer
- Question: does this function have good locality with respect to array a?

```
int sum_array_rows(int a[M][N]) {
   int i, j, sum = 0;

for (i = 0; i < M; i++)
      for (j = 0; j < N; j++)
            sum += a[i][j];
   return sum;
}</pre>
```

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Quiz 1

Does this function have good locality with respect to array a?

- a) yes
- b) no

```
int sum_array_cols(int a[M][N]) {
   int i, j, sum = 0;

for (j = 0; j < N; j++)
   for (i = 0; i < M; i++)
      sum += a[i][j];
   return sum;
}</pre>
```

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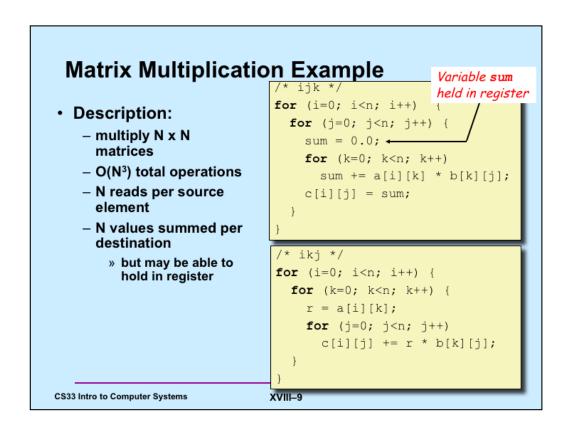
Writing Cache-Friendly Code

- · Make the common case go fast
 - focus on the inner loops of the core functions
- Minimize the misses in the inner loops
 - repeated references to variables are good (temporal locality)
 - stride-1 reference patterns are good (spatial locality)

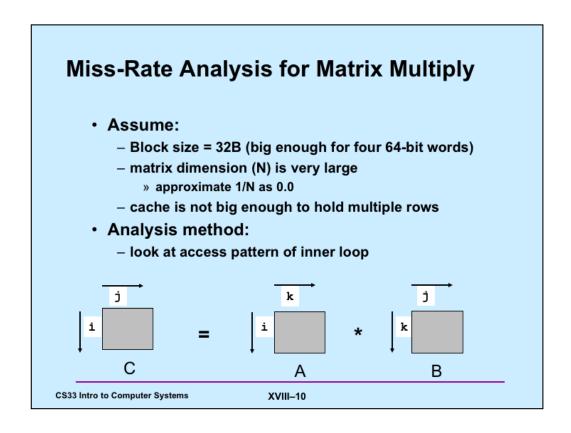
Key idea: our qualitative notion of locality is quantified through our understanding of cache memories

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Based on slides supplied by CMU.



Layout of C Arrays in Memory (review)

- · C arrays allocated in row-major order
 - each row in contiguous memory locations
- · Stepping through columns in one row:

```
- for (i = 0; i < N; i++)
sum += a[0][i];
```

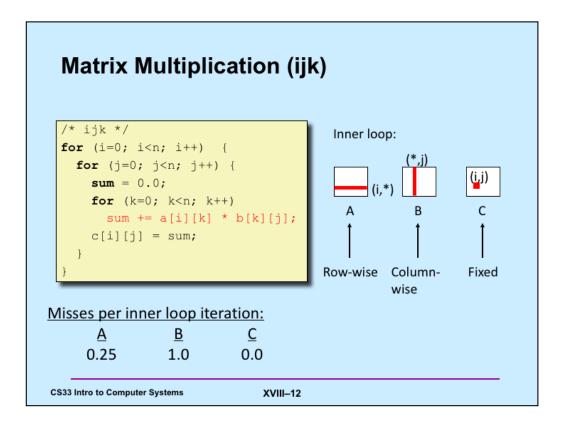
- accesses successive elements
- if block size (B) > 4 bytes, exploit spatial locality
 - » compulsory miss rate = 4 bytes / B
- Stepping through rows in one column:

```
- for (i = 0; i < n; i++)
sum += a[i][0];</pre>
```

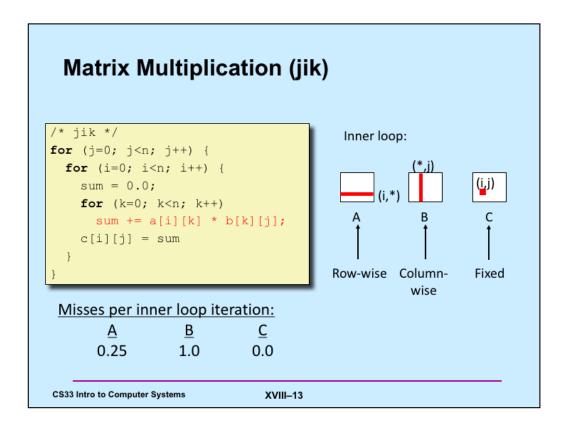
- accesses distant elements
- no spatial locality!
 - » compulsory miss rate = 1 (i.e. 100%)

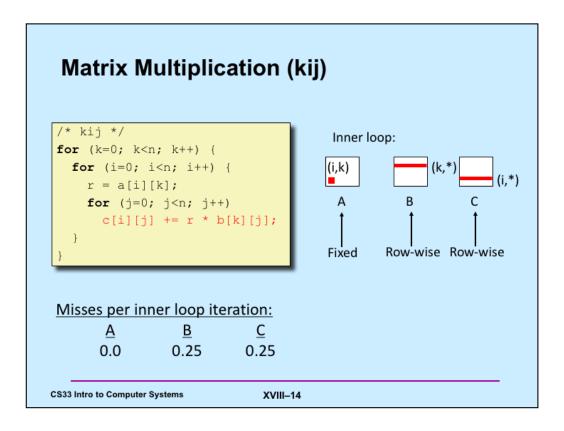
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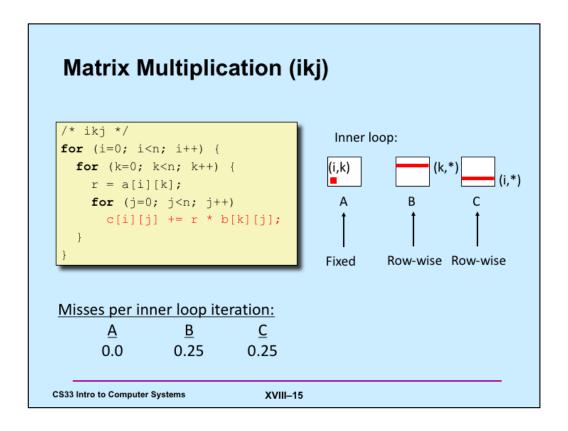
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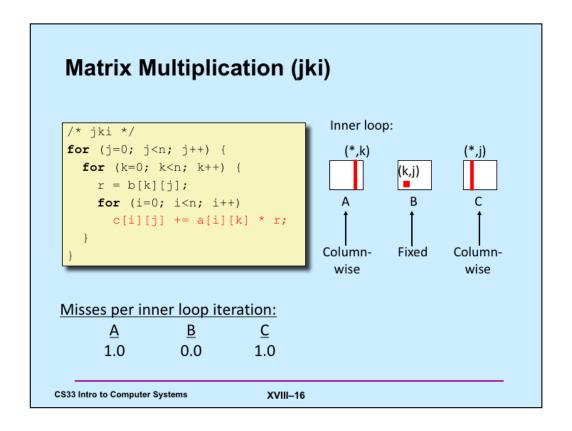


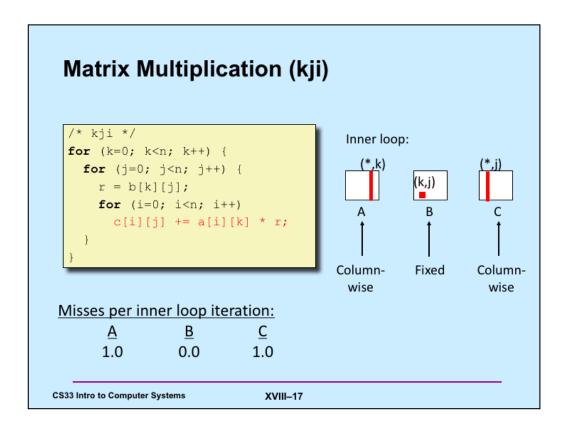
Assume we are multiplying arrays of doubles, thus each element is eight bytes long, and thus a cache line holds four matrix elements.



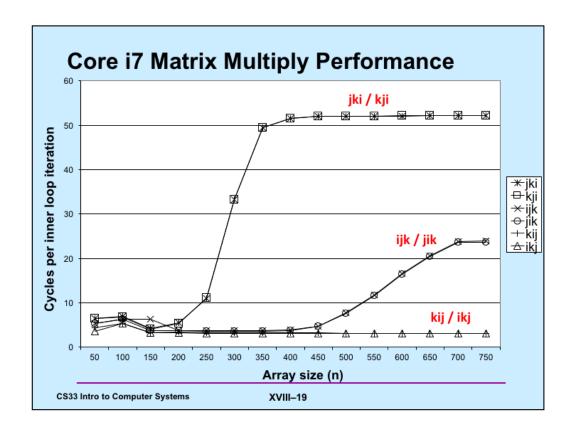


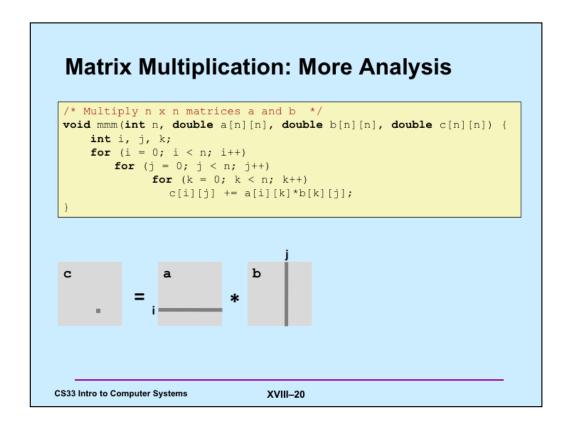




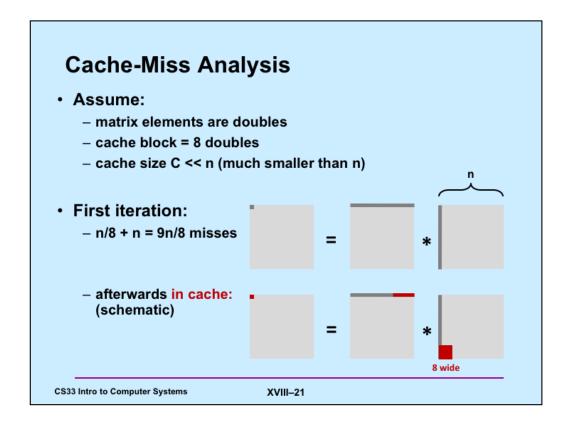


```
Summary of Matrix Multiplication
        for (i=0; i<n; i++)
          for (j=0; j<n; j++) {
                                                ijk (& jik):
           sum = 0.0;
                                                 • 2 loads, 0 stores
           for (k=0; k<n; k++)
            sum += a[i][k] * b[k][j];
                                                 • misses/iter = 1.25
           c[i][j] = sum;
        for (k=0; k<n; k++)
         for (i=0; i<n; i++) {</pre>
                                                kij (& ikj):
          r = a[i][k];
                                                 • 2 loads, 1 store
          for (j=0; j<n; j++)
                                                 • misses/iter = 0.5
           c[i][j] += r * b[k][j];
        for (j=0; j<n; j++)
         for (k=0; k<n; k++) {
                                                jki (& kji):
           r = b[k][j];
                                                 • 2 loads, 1 store
           for (i=0; i<n; i++)
                                                 • misses/iter = 2.0
            c[i][j] += a[i][k] * r;
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```

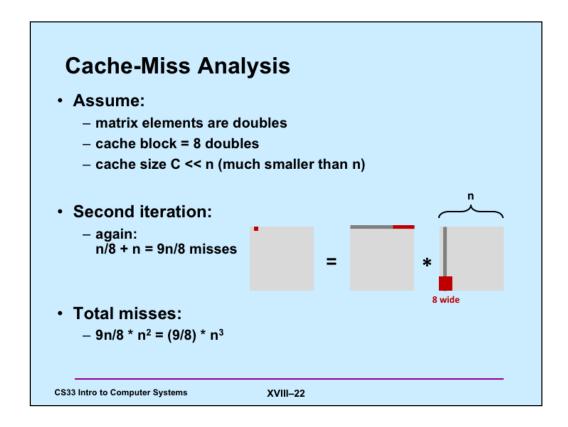




We're now going to look at a somewhat different approach towards better cache utilization.



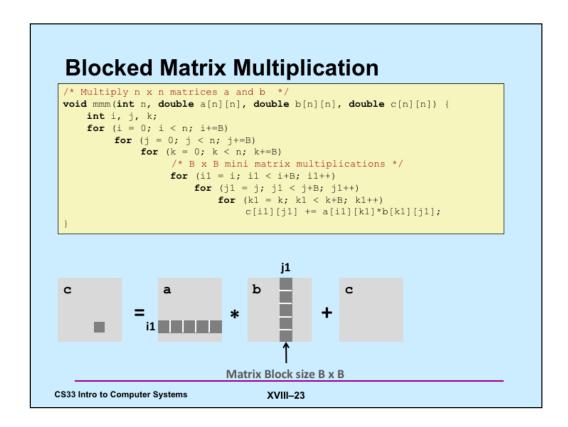
Using the ijk approach, there will be n/8 misses when accessing the first row of A and n misses when accessing the first column of B. After the first iteration of the inner loop, what's shown in red is in the cache.



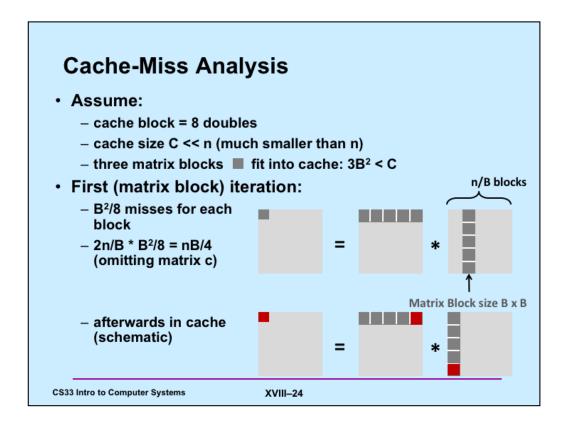
For the second iteration of the inner loop, there will again be 9n/8 cache misses. What's shown in red will be in cache when the iteration completes.

Continuing this analysis, we can see that the total number of misses is $(9/8)n^3$.

But keep in mind that after each iteration, there's a fair amount in the cache that won't be used.

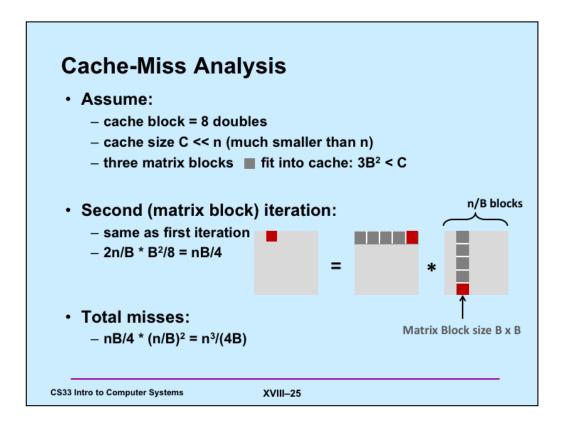


Keeping in mind what was left over in the cache after each iteration, as shown in the previous two slides, let's reorganize the computation into six nested loops, rather than three. The outer loops are as before, except that at each iteration they increase by some constant B. They are effectively breaking up the matrix into "mini matrices" of size BxB. We had three additional inner loops to compute the products of these mini matrices.



Each mini matrix is B x B in size. Each reference to memory fetches an entire cache block (of 8 8-byte double-precision floating-point values). Thus with eight memory fetches, we bring an entire mini matrix into the cache. We assume the cache is large enough to hold three of these mini matrices, thus the computation of the product of two of them can be done in the cache.

We now repeat our previous analysis, this time with the mini matrices



Summary

- No blocking: (9/8) * n³
 Blocking: 1/(4B) * n³
- Suggest largest possible block size B, but limit 3B² < C!
- · Reason for dramatic difference:
 - matrix multiplication has inherent temporal locality:
 - » input data: 3n2, computation 2n3
 - » every array element used O(n) times!
 - but program has to be written properly

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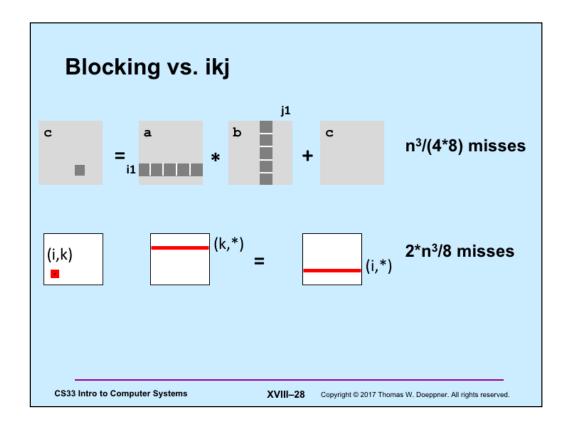
Quiz 2

What is the smallest value of B (in 8-byte doubles) for which the cache-miss analysis works?

- a) 1
- b) 2
- c) 4
- d) 8

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On sunlab machines, the cache-block size is 64 bytes, or 8 doubles. For the blocked-matrix approach, if we have B=8, then the expected number of misses is $n^3/32$. For the ikj approach, each reference to memory fetches 8 doubles, thus there are cache misses on 1/8 of the references to matrix elements. The inner loop is executed n^3 times, with two references per iteration. Thus the expected number of misses is $n^3/4$.

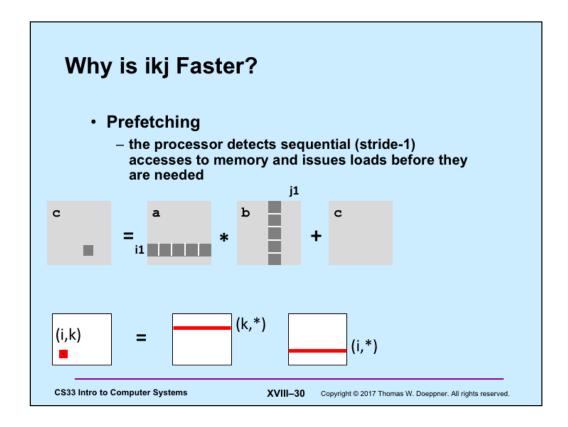
Blocking vs. ikj

```
$ ./matmult ikj
ikj: .608 secs
$ ./matmult Blocked
Blocked: .880 secs
```

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When run on sunlab machines for 1024x1024 matrices, the "ikj" approach to matrix multiplication out performs the blocked approach by around 30%.



The ikj approach provides ample opportunities for prefetching, which the blocking approach does not. The processor does such a good job with prefetching that the delays due to cache misses are very much reduced. While there may be a cache miss on an array element, the fetching of the element from memory has already been started and thus the delay is short.

Concluding Observations

- Programmer can optimize for cache performance
 - organize data structures appropriately
 - take care in how data structures are accesses
 - » nested loop structure
 - » blocking is a general technique
- · All systems favor "cache-friendly code"
 - getting absolute optimum performance is very platform specific
 - » cache sizes, line sizes, associativities, etc.
 - can get most of the advantage with generic code
 - » keep working set reasonably small (temporal locality)
 - » use small strides (spatial locality)

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