

CS 33

Memory Hierarchy II

Most of the slides in this lecture are either from or adapted from slides provided by the authors of the textbook “Computer Systems: A Programmer’s Perspective,” 2nd Edition and are provided from the website of Carnegie-Mellon University, course 15-213, taught by Randy Bryant and David O’Hallaron in Fall 2010. These slides are indicated “Supplied by CMU” in the notes section of the slides.

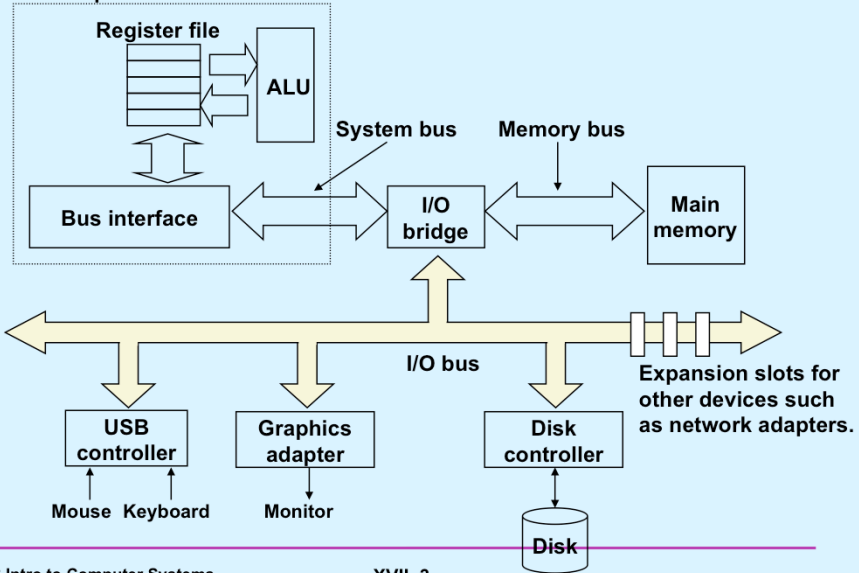
Logical Disk Blocks

- **Modern disks present a simpler abstract view of the complex sector geometry:**
 - the set of available sectors is modeled as a sequence of b-sized **logical blocks** (0, 1, 2, ...)
- **Mapping between logical blocks and actual (physical) sectors**
 - maintained by hardware/firmware device called disk controller
 - converts requests for logical blocks into (surface, track, sector) triples
- **Allows controller to set aside spare cylinders for each zone**
 - accounts for the difference in “formatted capacity” and “maximum capacity”

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I/O Bus

CPU chip



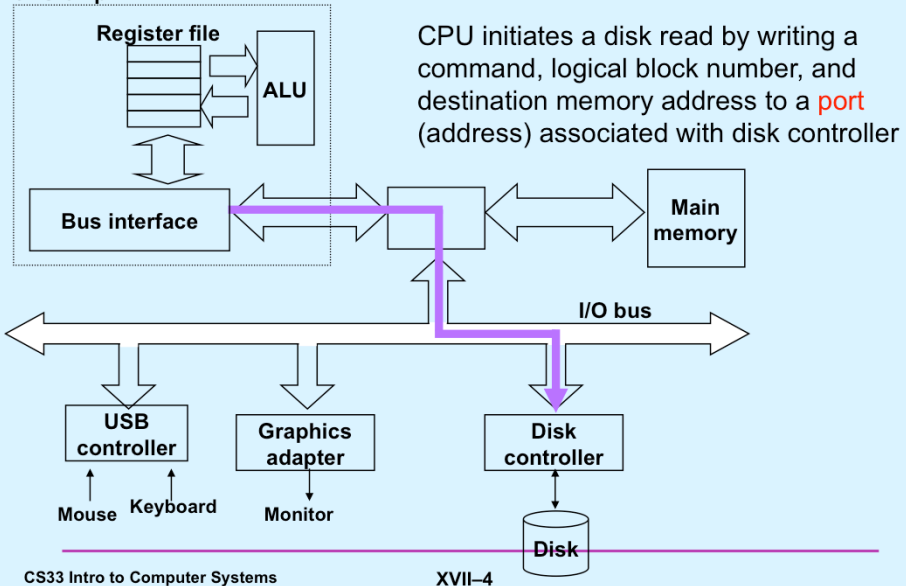
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Reading a Disk Sector (1)

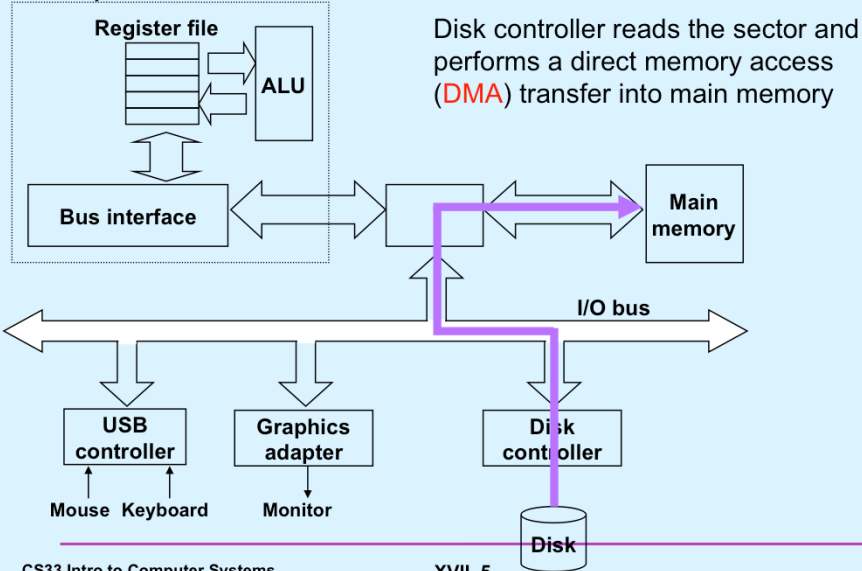
CPU chip



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Reading a Disk Sector (2)

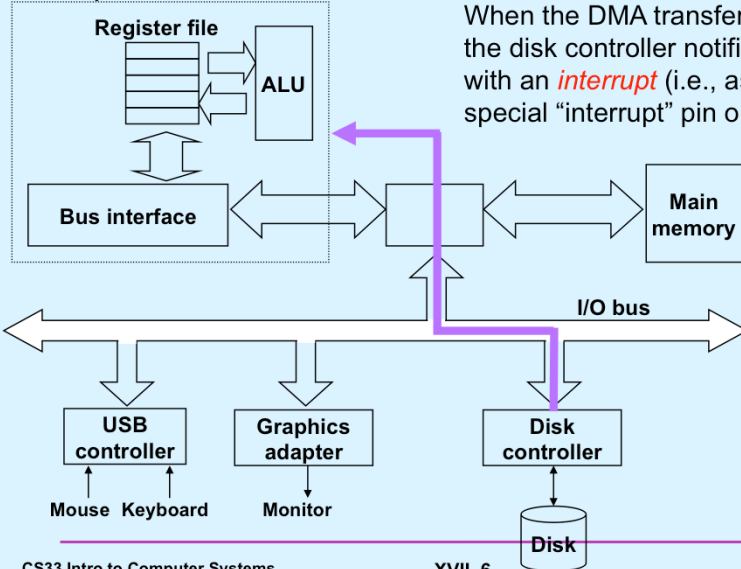
CPU chip



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Reading a Disk Sector (3)

CPU chip

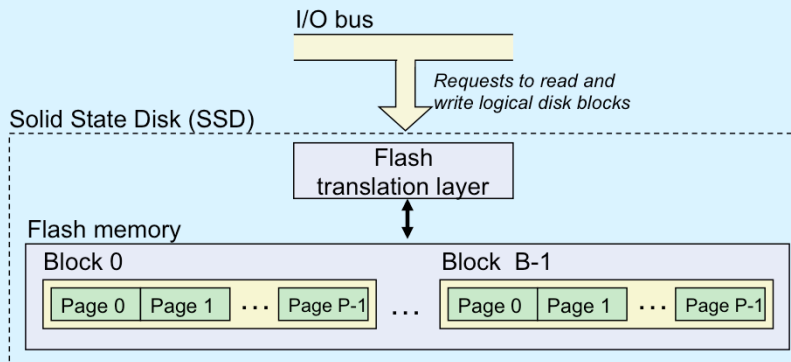


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Solid-State Disks (SSDs)



- **Pages:** 512KB to 4KB; **blocks:** 32 to 128 pages
- Data read/written in units of pages
- Page can be written only after its block has been erased
- A block wears out after 100,000 repeated writes

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SSD Performance Characteristics

Sequential read tput	250 MB/s	Sequential write tput	170 MB/s
Random read tput	140 MB/s	Random write tput	14 MB/s
Random read access	30 us	Random write access	300 us

- **Why are random writes so slow?**
 - erasing a block is slow (around 1 ms)
 - modifying a page triggers a copy of all useful pages in the block
 - » find a used block (new block) and erase it
 - » write the page into the new block
 - » copy other pages from old block to the new block

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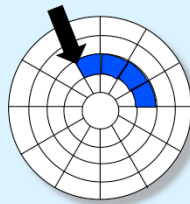
SSD Tradeoffs vs Rotating Disks

- **Advantages**
 - no moving parts → faster, less power, more rugged
- **Disadvantages**
 - have the potential to wear out
 - » mitigated by “wear-leveling logic” in flash translation layer
 - » e.g. Intel X25 guarantees 1 petabyte (10^{15} bytes) of random writes before they wear out
 - in 2010, about 100 times more expensive per byte
- **Applications**
 - MP3 players, smart phones, laptops
 - beginning to appear in desktops and servers

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Reading a File on a Rotating Disk

- **Suppose the data of a file are stored on consecutive disk sectors on one track**
 - this is the best possible scenario for reading data quickly
 - » single seek required
 - » single rotational delay
 - » all sectors read in a single scan

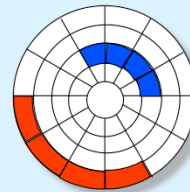


Quiz 1

We have two files on the same (rotating) disk. The first file's data resides in consecutive sectors on one track, the second in consecutive sectors on another track. It takes a total of t seconds to read all of the first file then all of the second file.

Now suppose the files are read concurrently, perhaps a sector of the first, then a sector of the second, then the first, then the second, etc. Compared to reading them sequentially, this will take

- a) less time
- b) about the same amount of time
- c) more time



Quiz 2

You've replaced the rotating disk on your computer with a solid-state disk. The data of the two files are again in consecutive locations. Suppose it still takes a total of t seconds to read the first file then the second. Suppose it took u seconds to read the two files concurrently on the rotating disk. It takes v seconds to read them concurrently on the SSD.

- a) $v < u$ (faster on the SSD)
- b) $v \approx u$ (about the same)
- c) $v > u$ (slower on the SSD)

Storage Trends

SRAM

Metric	1980	1985	1990	1995	2000	2005	2010	2010:1980
\$/MB	19,200	2,900	320	256	100	75	60	320
access (ns)	300	150	35	15	3	2	1.5	200

DRAM

Metric	1980	1985	1990	1995	2000	2005	2010	2010:1980
\$/MB	8,000	880	100	30	1	0.1	0.06	130,000
access (ns)	375	200	100	70	60	50	40	9
typical size (MB)	0.064	0.256	4	16	64	2,000	8,000	125,000

Disk

Metric	1980	1985	1990	1995	2000	2005	2010	2010:1980
\$/MB	500	100	8	0.30	0.01	0.005	0.0003	1,600,000
access (ms)	87	75	28	10	8	4	3	29
typical size (MB)	1	10	160	1,000	20,000	160,000	1,500,000	1,500,000

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CPU Clock Rates

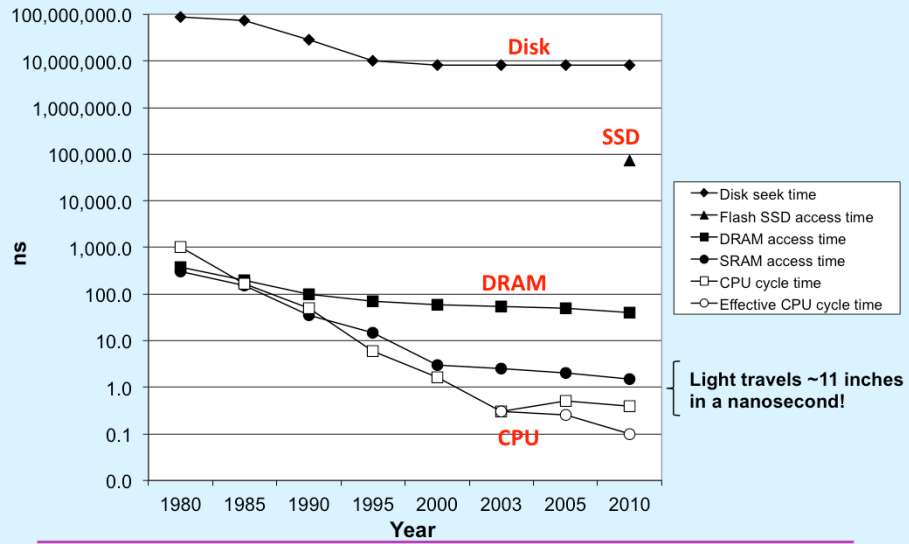
Inflection point in computer history
when designers hit the “Power Wall”

	1980	1990	1995	2000	2003	2005	2010	2010:1980
CPU	8080	386	Pentium	P-III	P-4	Core 2	Core i7	---
Clock rate (MHz)	1	20	150	600	3300	2000	2500	2500
Cycle time (ns)	1000	50	6	1.6	0.3	0.50	0.4	2500
Cores	1	1	1	1	1	2	4	4
Effective cycle time (ns)	1000	50	6	1.6	0.3	0.25	0.1	10,000

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The CPU-Memory Gap

The gap widens between DRAM, disk, and CPU speeds



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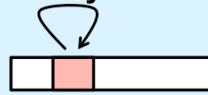
Locality to the Rescue!

The key to bridging this CPU-Memory gap is a fundamental property of computer programs known as **locality**

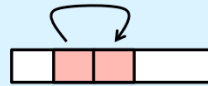
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Locality

- **Principle of Locality:** programs tend to use data and instructions with addresses near or equal to those they have used recently



- **Temporal locality:**
 - recently referenced items are likely to be referenced again in the near future



- **Spatial locality:**
 - items with nearby addresses tend to be referenced close together in time

Locality Example

```
sum = 0;
for (i = 0; i < n; i++)
    sum += a[i];
return sum;
```

- **Data references**

- reference array elements in succession (stride-1 reference pattern) **Spatial locality**
- reference variable `sum` each iteration **Temporal locality**

- **Instruction references**

- reference instructions in sequence. **Spatial locality**
- cycle through loop repeatedly **Temporal locality**

Qualitative Estimates of Locality

- **Claim:** being able to look at code and get a qualitative sense of its locality is a key skill for a professional programmer
- **Question:** does this function have good locality with respect to array *a*?

```
int sum_array_rows(int a[M][N]) {  
    int i, j, sum = 0;  
  
    for (i = 0; i < M; i++)  
        for (j = 0; j < N; j++)  
            sum += a[i][j];  
    return sum;  
}
```

Quiz 3

Does this function have good locality with respect to array a?

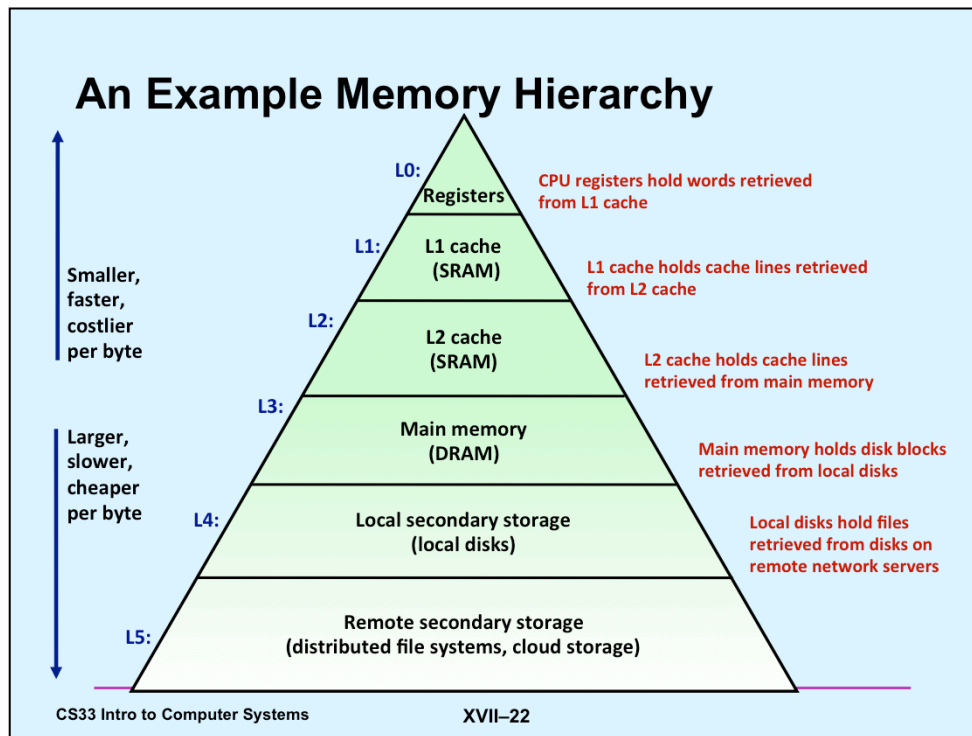
- a) yes
- b) no

```
int sum_array_cols(int a[M][N]) {  
    int i, j, sum = 0;  
  
    for (j = 0; j < N; j++)  
        for (i = 0; i < M; i++)  
            sum += a[i][j];  
    return sum;  
}
```

Memory Hierarchies

- **Some fundamental and enduring properties of hardware and software:**
 - fast storage technologies cost more per byte, have less capacity, and require more power (heat!)
 - the gap between CPU and main memory speed is widening
 - well written programs tend to exhibit good locality
- **These fundamental properties complement each other beautifully**
- **They suggest an approach for organizing memory and storage systems known as a **memory hierarchy****

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Putting Things Into Perspective ...

- **Reading from:**
 - ... the L1 cache is like grabbing a piece of paper from your desk (3 seconds)
 - ... the L2 cache is picking up a book from a nearby shelf (14 seconds)
 - ... main system memory is taking a 4-minute walk down the hall to talk to a friend
 - ... a hard drive is like leaving the building to roam the earth for one year and three months

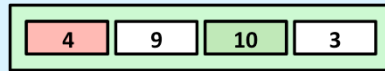
This analogy is from <http://duartes.org/gustavo/blog/post/what-your-computer-does-while-you-wait> (definitely worth reading!).

Caches

- **Cache:** A smaller, faster storage device that acts as a staging area for a subset of the data in a larger, slower device
- Fundamental idea of a memory hierarchy:
 - for each k , the faster, smaller device at level k serves as a cache for the larger, slower device at level $k+1$
- Why do memory hierarchies work?
 - because of locality, programs tend to access the data at level k more often than they access the data at level $k+1$.
 - thus, the storage at level $k+1$ can be slower, and thus larger and cheaper per bit
- **Big Idea:** the memory hierarchy creates a large pool of storage that costs as much as the cheap storage near the bottom, but that serves data to programs at the rate of the fast storage near the top

General Cache Concepts

Cache

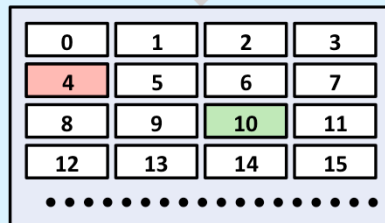


Smaller, faster, more expensive memory caches a subset of the blocks

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Data is copied in block-sized transfer units

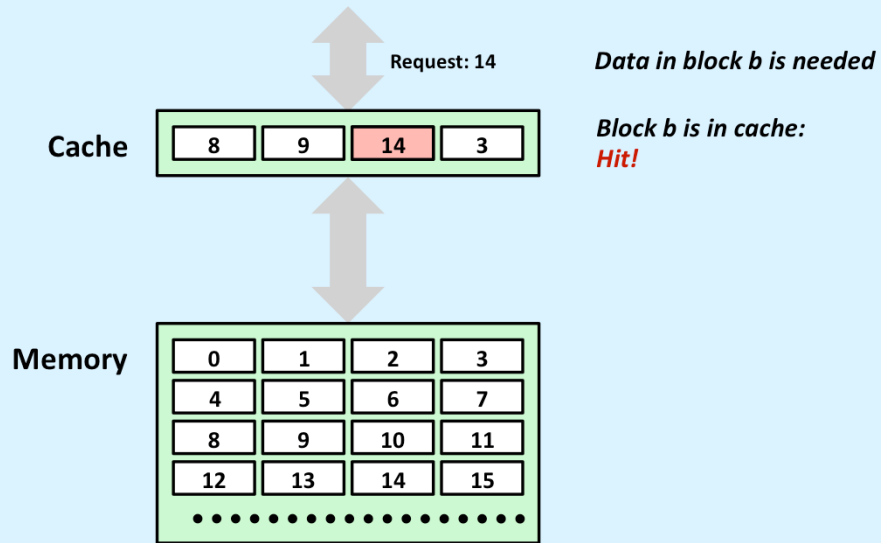
Memory



Larger, slower, cheaper memory viewed as partitioned into "blocks"

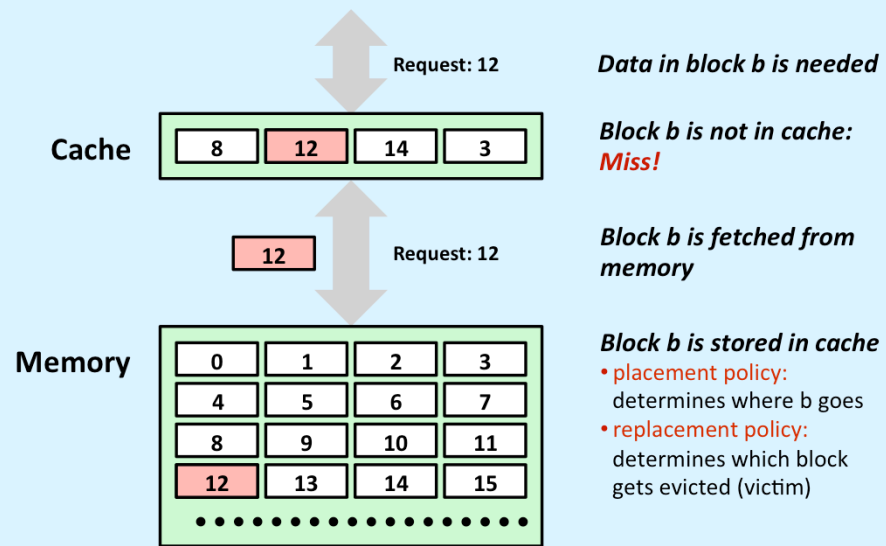
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General Cache Concepts: Hit



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General Cache Concepts: Miss



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General Caching Concepts: Types of Cache Misses

- **Cold (compulsory) miss**
 - cold misses occur because the cache is empty
- **Conflict miss**
 - most caches limit blocks at level $k+1$ to a small subset (sometimes a singleton) of the block positions at level k
 - » e.g., block i at level $k+1$ must be placed in block $(i \bmod 4)$ at level k
 - conflict misses occur when the level k cache is large enough, but multiple data objects all map to the same level k block
 - » e.g., referencing blocks 0, 8, 0, 8, 0, 8, ... would miss every time
- **Capacity miss**
 - occurs when the set of active cache blocks (**working set**) is larger than the cache

Examples of Caching in the Hierarchy

Cache Type	What is Cached?	Where is it Cached?	Latency (cycles)	Managed By
Registers	4-8 bytes words	CPU core	0	Compiler
TLB	Address translations	On-Chip TLB	0	Hardware
L1 cache	64-bytes block	On-Chip L1	1	Hardware
L2 cache	64-bytes block	On/Off-Chip L2	10	Hardware
Virtual Memory	4-KB page	Main memory	100	Hardware + OS
Buffer cache	Parts of files	Main memory	100	OS
Disk cache	Disk sectors	Disk controller	100,000	Disk firmware
Network buffer cache	Parts of files	Local disk	10,000,000	CIFS/NFS client
Browser cache	Web pages	Local disk	10,000,000	Web browser
Web cache	Web pages	Remote server disks	1,000,000,000	Web proxy server

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Summary

- **The speed gap between CPU, memory, and mass storage continues to widen**
- **Well written programs exhibit a property called locality**
- **Memory hierarchies based on caching close the gap by exploiting locality**

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