

# 1 Calibration

## 1.1 Ongoing Performance Monitoring

To ensure hardware component issues are detected early the system is supposed to be monitored by small LED's mounted in between the SiPM's. Short bursts of light injected into one side of the scintillator at a time will provide a stable signal source. Changes in the measured amplitude indicates either an efficiency loss in the scintillator or a gain drop of the involved SiPM's. These signals also act as a reference point in order to determine the time resolution of the detector elements while they are deployed.

It is foreseen to have four channels for all the LED's on one Rail-Board. This allows for every other LED on a single side along the board to be illuminated, leaving a dark scintillator between two illuminated scintillators. This ensures the signal is only produced by the internal light with no light bleed from a neighboring tile. By only illuminating one side interfering factors are reduced and a clean time resolution measurement is possible.

This method needs to be improved as tests have shown that the signals measured from both sides of the scintillator tile vary in intensity, although it was assumed that these LEDs would be used for accurate measurements.

## 1.2 Position Calibration

In order to deliver useful position information for the detector hits the exact position of each tile in the context of the detector needs to be determined. The position of the individual scintillator tiles is mainly of interest in the context of the time resolution, signal delay and amplitude drop along the board which are discussed in the following sections.

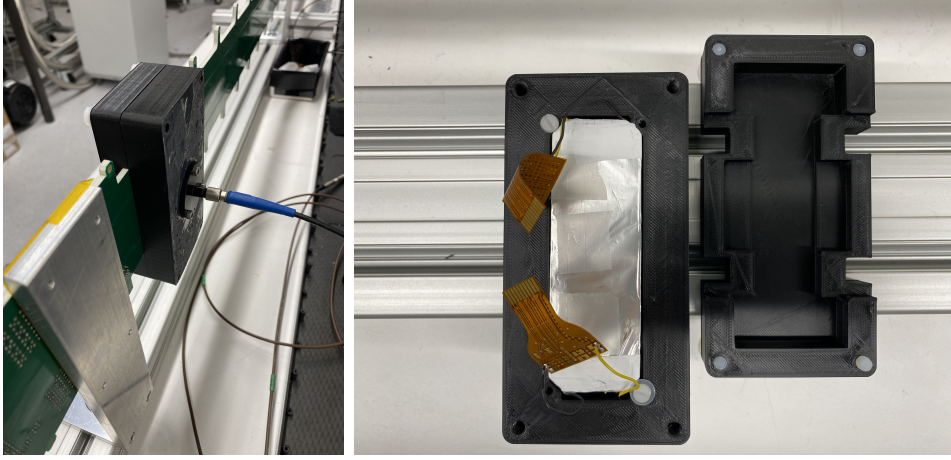
### 1.2.1 Time Resolution Expectancy along the Board

Since the time resolution is affected by signal noise and decreases of the slope of the rising flank it can be expected to receive a worse time resolution for scintillators farther down the Rail-Board with a longer distance between the detector element and the Front End Electronics. In order to create a baseline for the detector performance the time resolution needs to be measured along the length of the Rail-Board. A pulsed signal with a frequency of 50 kHz, 5 V and a duration of 20 ns from a signal generator is used to power the laser diode. The light signal is transmitted through an optical fiber to the middle of the scintillator plate, which is located inside the plastic box (see Fig. 1). The box protects SciTil from outside light and moves very neatly across the Rail-Board. Measuring the time of flight variation, which is expressed by the standard deviation, at each slot along the entire Rail-Board gives fairly similar good results in the 90 to 160 ps range, as shown in Fig. 2, which is twice the event time resolution.

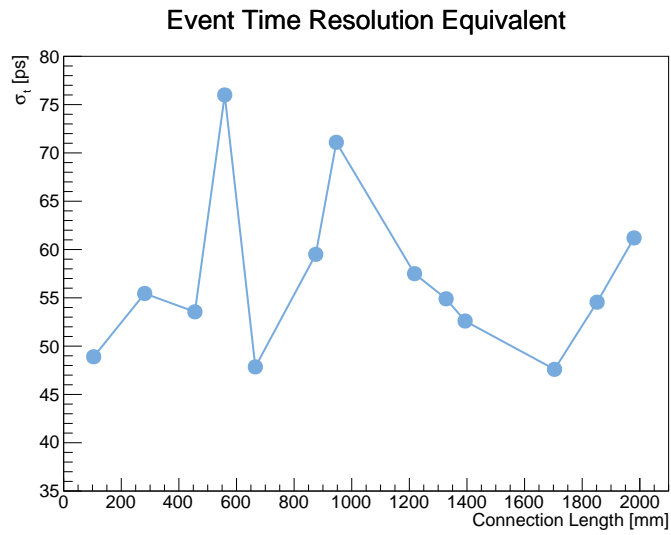
### 1.2.2 Signal Delay along the Board

In order to provide an accurate time stamp for hits in the B-ToF detector the time a signal needs to travel from the SiPM's to the FEE has to be taken into account. The longer the electrical connection line is the larger the time delay between detector hit and time stamp in the electronics.

The speed a signal travels through a copper connection is significantly slower than the speed of light.

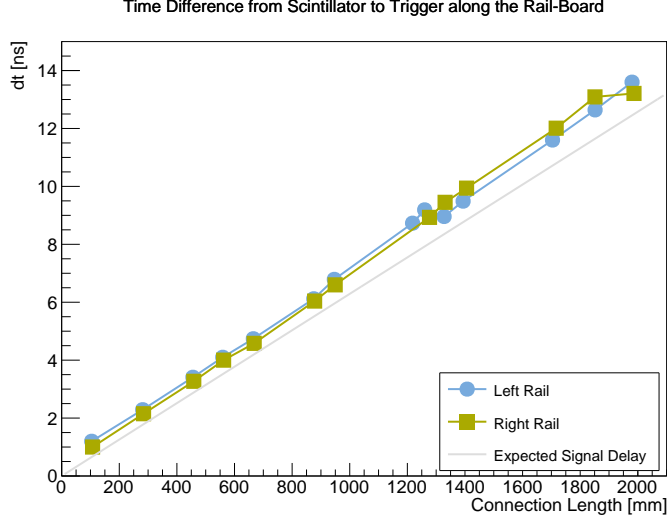


**Figure 1:** *Experimental setup: a black plastic box is attached to the Rail-Board. The light signal is transmitted through an optical fiber. The scintillator plate is located inside the plastic box, the flexible Sensor-Board is soldered with short wires to the photodetectors.*



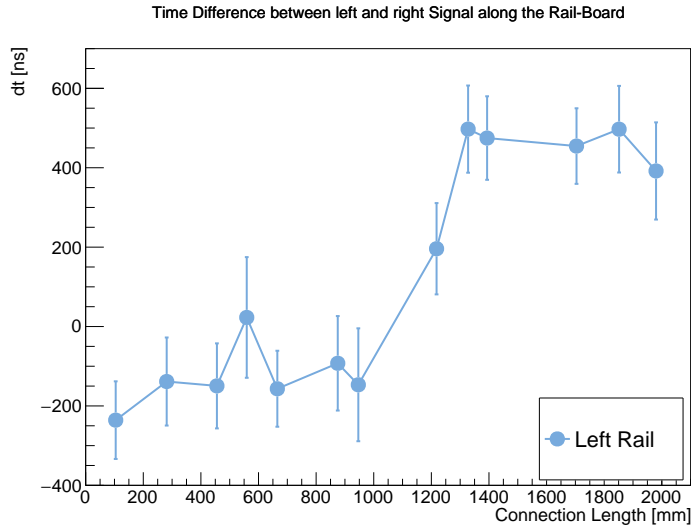
**Figure 2:** *The measured resolution equivalent to the event time resolution.*

Comparing the accumulated signal latency over the entire length of the board (between slots 1 and 60) with what we should expect from theory, that is, the signal velocity is usually about 16.3 cm per nanosecond [1, 2], which shows a good match (see Fig. 3).



**Figure 3:** Time difference between the signals from the left (blue) SiPM arrays and the right SiPM arrays (green) and the reference signal (laser trigger), measured in the middle of the scintillation plate along the Rail-Board.

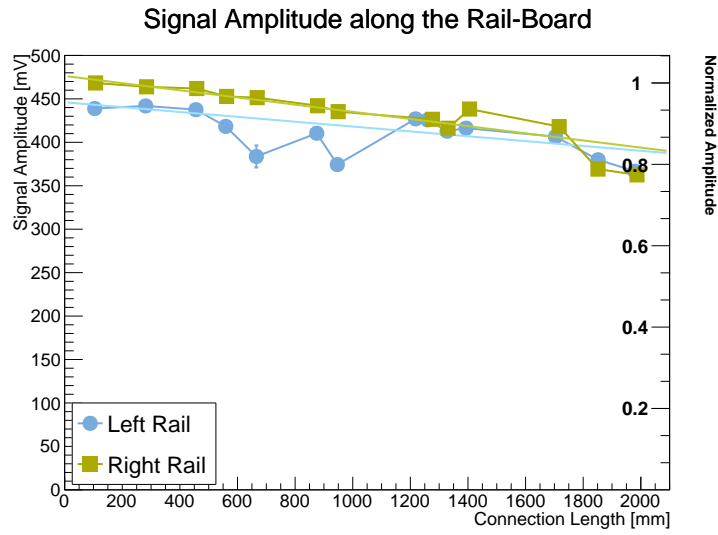
The time difference between the two signals, seen in Fig. 4 increases on the second part of the Rail-Board due to waveform distortion (reflections, different signal attenuation on two sides of one slot).



**Figure 4:** Time difference between the left and right SiPM arrays signals, measured in the middle of the scintillation plate.

### 1.2.3 Amplitude Drop along the Board

Signal attenuation measurements have shown that a drop of up to 23% is expected for an internal connection of 2m length, which means a fairly strong amplitude drop, as shown in Fig. 5.



**Figure 5:** *Signal amplitude drop measured along the staff: a drop of up to 23% is expected for an internal connection of 2 m length. Two strong drops with amplitude measured at 650 mm (slot 20) and 950 mm (slot 30) on the left side are due to mechanical squeezing the flexible Sensor-Board.*

## References

- [1] Brillouin, Léon. *Wave propagation and group velocity*. Academic Press Inc., New York, 1960.
- [2] Clayton R. Paul. *Analysis of Multiconductor Transmission Lines*. John Wiley & Sons., New York, 1994.