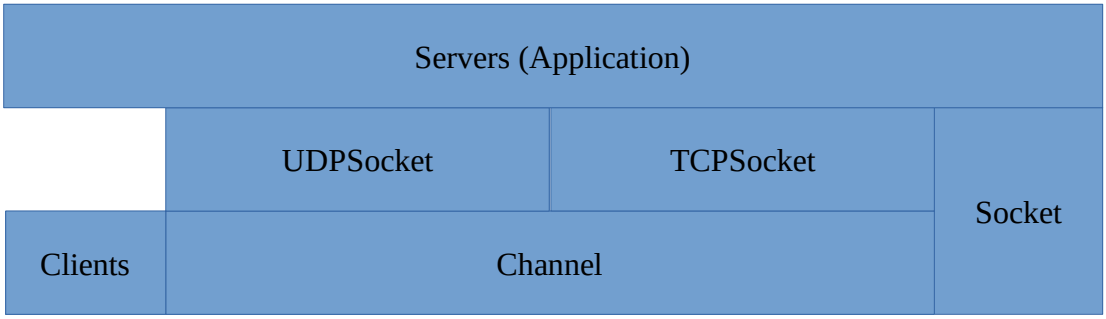


Class structure and design decisions:

The Channel folder in Drivers folder contains the channel.hpp that have abstract class **Channel** that handle socket interactions through its Socket member (which can be TCP or UDP). He have a pointer to a Socket object (Socket* channelSocket) -> (either TCPSocket or UDPSocket). Also have pure virtual functions:
▪ virtual void start() = 0;
▪ virtual void stop() = 0;
▪ virtual void send(const std::string& message) = 0;
▪ virtual void receive() = 0;
These functions MUST be implemented in derived classes: **serverChannel** and **clientChannel**.

The channel.cpp contains only **serverChannel** functions with the pointer that points to the virtual functions of **Socket**.

The Socket folder in Drivers folder conatins socket.hpp that have abstract class **Socket** that define common socket behaviors (send, receive, connect, shutdown) with pure virtual functions:
▪ virtual void connect() = 0;
▪ virtual void send(const std::string& message) = 0;
▪ virtual void receive() = 0;
▪ virtual void shutdown() = 0;
These functions MUST be implemented in derived classes: **TCPSocket** and **UDPSocket**.

tcpsocket.cpp and udpsocket.cpp contains the socket behaviour.

UNICAST_TCPSocket:
the client.cpp contains the clientChannel functions with the client behaviour.

MULTICAST_UDPSocket:
the client.cpp contains the clientChannel functions with the client behaviour.

The Server contains the application behaviour: I made a Time class with a += operator overloading so I can increment the time by 1 and wait 1sec and send the time to clients each 1sec.

Note: To run the application, navigate to either the UNICAST_TCPSocket or MULTICAST_UDPSocket folders and execute the make command in the terminal. This will create an out directory containing the server and client executables, which you can easily run.

Step-by-step guide for setting up the development environment (QEMU) with Yocto:

I made an image with tcp-client and udp-server to try each server and client on Qemu.

For the tcp-client:
Going to: **~/yocto/poky/meta/recipes-example/tcp-client** with this tree:

```
├── files
│   ├── CMakeLists.txt
│   ├── Drivers
│   │   ├── Channel
│   │   │   ├── channel.cpp
│   │   │   └── channel.hpp
│   │   └── Socket
│   │       ├── socket.hpp
│   │       ├── tcpsocket.cpp
│   │       └── udpsocket.cpp
│   ├── include
│   │   └── client.hpp
│   └── src
│       ├── client.cpp
│       └── main.cpp
└── tcp-client_0.1.bb
```

For the udp-server:
Going to: **~/yocto/poky/meta/recipes-example/udp-server** with this tree:

```
├── files
│   ├── CMakeLists.txt
│   ├── Drivers
│   │   ├── Channel
│   │   │   ├── channel.cpp
│   │   │   └── channel.hpp
│   │   └── Socket
│   │       ├── socket.hpp
│   │       ├── tcpsocket.cpp
│   │       └── udpsocket.cpp
│   ├── include
│   │   └── server.hpp
│   └── src
│       ├── main.cpp
│       └── server.cpp
└── udp-server_0.1.bb
```

- you will find the recipes and CmakeLists uploaded, take a look on them.

Then going to: **~/yocto/poky/build/conf** and open **local.conf** and add this line:

IMAGE_INSTALL:append = " tcp-client udp-server"

Select:

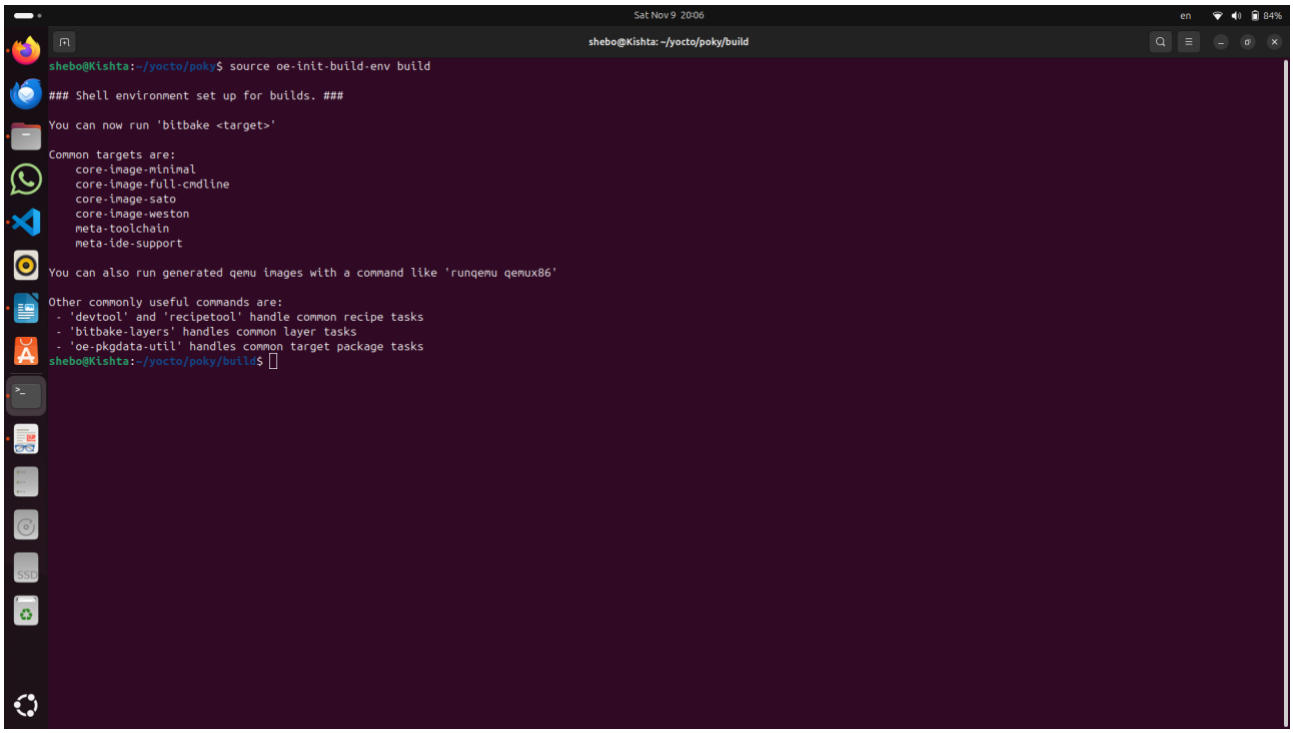
MACHINE ?= "qemuarm64"

to create an image with this applications by yocto, write these commands:

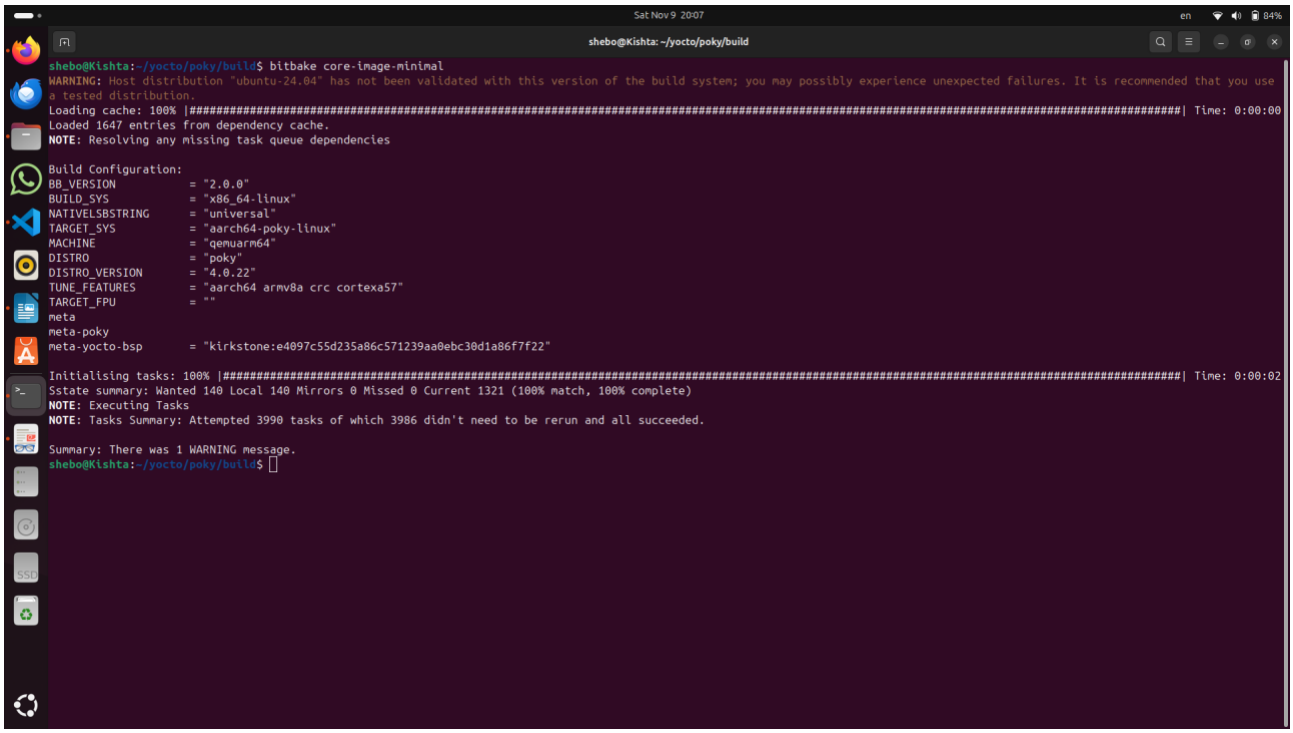
Note:
*-Take the **recipes-example** folder that I uploaded and place it on **~/yocto/poky/meta***

go to: **~/yocto/poky/**

source oe-init-build-env build



bitbake core-image-minimal

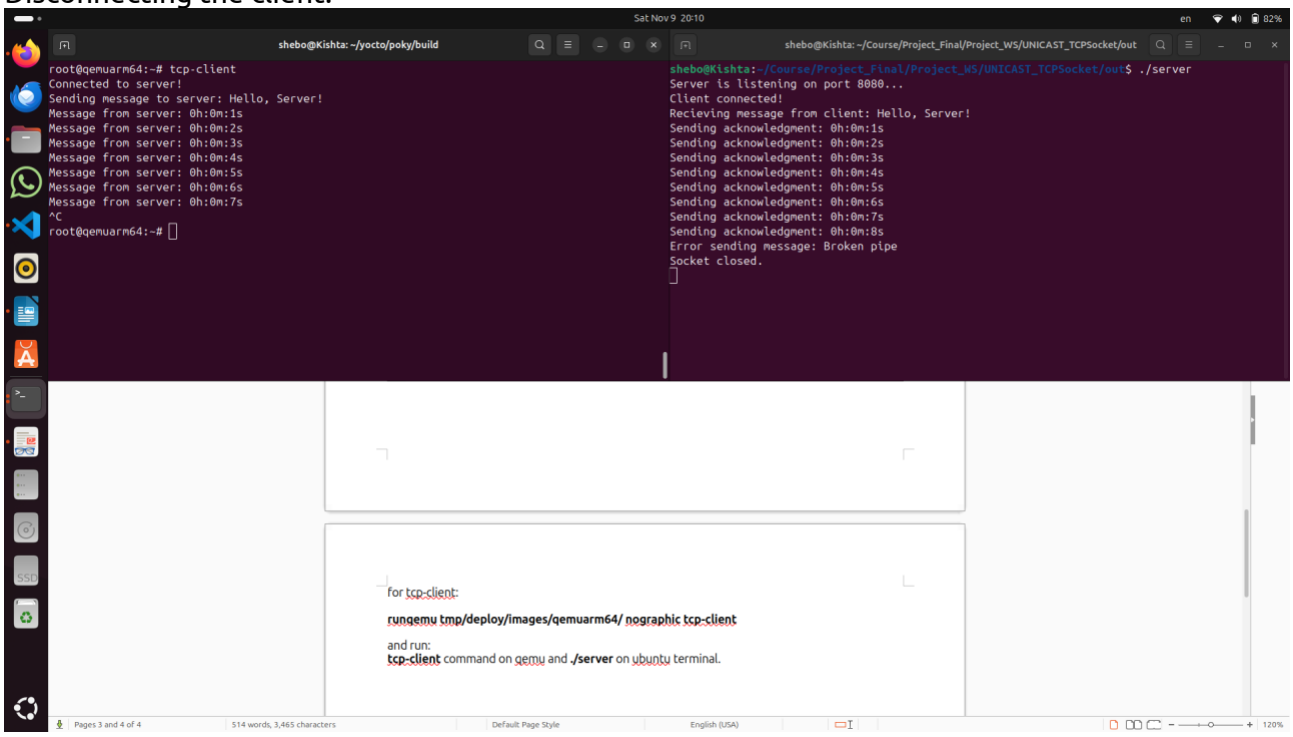


for tcp-client:

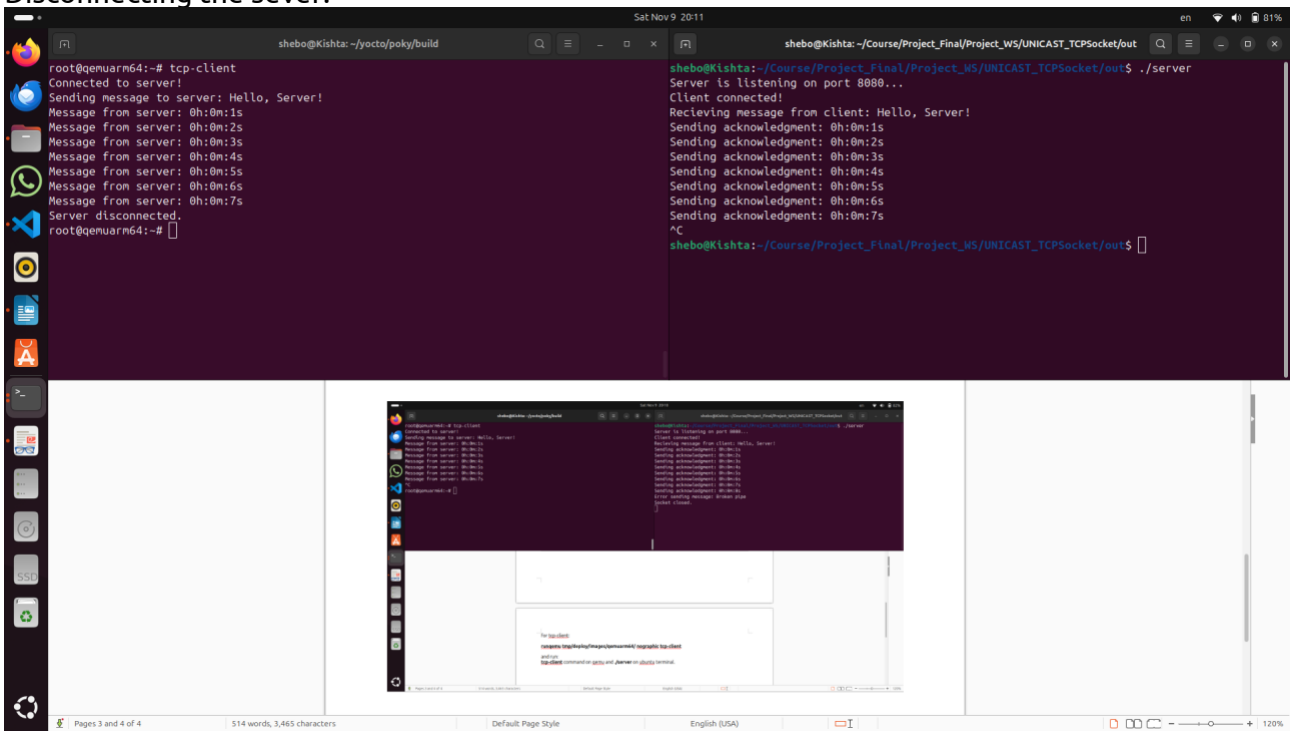
runqemu tmp/deploy/images/qemuarm64/ nographic tcp-client

and run:
tcp-client command on qemu and **./server** on ubuntu terminal.

Disconnecting the client:



Disconnecting the sever:



for udp-server:

runqemu tmp/deploy/images/qemuarm64/ nographic udp-server

and run:

udp-server command on qemu and **./client_1** and **./client_2** on ubuntu terminal.

No matters I disconnect any client, the server continue sending the time.