Nature Inspired Computing Codes

Simulated Annealing (SA) optimization algorithm

```
from numpy import asarray, exp, randn, rand, seed
from matplotlib import pyplot
# Define the objective function, which is minimized
def objective(step):
    return step[0] ** 2.0
# Define the simulated annealing algorithm
def sa(objective, area, iterations, step size, temperature):
    # Create an initial point within the search space
    start_point = area[:, 0] + rand(len(area)) * (area[:, 1] - area[:,
0])
    # Evaluate the starting point
    start point eval = objective(start point)
    # Initialize best known solution to start point and its evaluation
    mia start point, mia start eval = start point, start point eval
    outputs = []
    # Main loop over the number of iterations
    for i in range(iterations):
        # Generate a candidate solution by adding a random step to
the current point
        mia step = mia start point + randn(len(area)) * step size
        mia step eval = objective(mia step)
        # Check if the candidate solution is better than the best
solution so far
```

```
mia start point, mia start eval = mia step, mia step eval
            outputs.append(mia start eval)
        # Calculate the difference between candidate and best solution
        difference = mia_step_eval - mia_start_eval
        # Update temperature based on the current iteration
        t = temperature / float(i + 1)
        # Calculate Metropolis Acceptance Criterion
        metropolis = exp(-difference / t)
        # Accept the new solution if it meets certain criteria (either
better or random acceptance)
        if difference < 0 or rand() < metropolis:</pre>
            mia_start_point, mia_start_eval = mia_step, mia_step_eval
    return mia_start_point, mia_start_eval, outputs
# Set seed for reproducibility
seed(1)
# Define the search space
area = asarray([[-6.0, 6.0]])
# Set algorithm parameters
temperature = 12
iterations = 1200
step_size = 0.1
# Run simulated annealing
best_point, best_eval, outputs = sa(objective, area, iterations,
step_size, temperature)
# Plotting the objective function evaluations over time
```

if mia_step_eval < mia_start_eval:</pre>

```
pyplot.plot(outputs, 'ro-')
pyplot.xlabel('Iteration')
pyplot.ylabel('Evaluation of Objective Function')
pyplot.show()
```

<u>Simulated Annealing to solve the Traveling Salesman</u> Problem (TSP)

```
import numpy as np
import random
import math
# Distance matrix (in km) for Colombo, Kandy, Nuwara Eliya, Galle,
Jaffna
distances = np.array([
    [0, 115, 180, 120, 396], # Colombo
   [115, 0, 75, 80, 380], # Kandy
    [180, 75, 0, 140, 435], # Nuwara Eliya
    [120, 80, 140, 0, 340], # Galle
    [396, 380, 435, 340, 0] # Jaffna
])
# Function to calculate the total distance of a given path
def total distance(path):
    return sum(distances[path[i], path[i+1]] for i in range(len(path))
- 1)) + distances[path[-1], path[0]]
```

```
# Simulated Annealing algorithm
def simulated annealing():
    num cities = len(distances)
    current path = list(range(num cities))
    random.shuffle(current path)
    current distance = total distance(current path)
    T = 10000 # Initial temperature
    T min = 1 # Minimum temperature
    alpha = 0.995 # Cooling rate
    best path = current path[:]
    best_distance = current_distance
    while T > T_min:
        new_path = current_path[:]
        i, j = random.sample(range(num_cities), 2)
        new_path[i], new_path[j] = new_path[j], new_path[i]
        new distance = total distance(new path)
        if new distance < best distance:</pre>
            best path = new path[:]
            best distance = new distance
        delta_distance = new_distance - current_distance
        if delta_distance < 0 or random.random() < math.exp(-</pre>
delta distance / T):
            current path = new path[:]
            current_distance = new_distance
        T *= alpha
```

```
return best_path, best_distance
```

```
# Run the simulated annealing function to find the best path and
distance
best_path, best_distance = simulated_annealing()

# Mapping city indices to names
city_names = ['Colombo', 'Kandy', 'Nuwara Eliya', 'Galle', 'Jaffna']
best_path_names = [city_names[i] for i in best_path]

# Print the results
print("Optimal path:", " -> ".join(best_path_names))
print("Total distance:", best_distance)
```

Particle Swarm Optimization (PSO) to determine the optimal placement of distribution centers based on minimizing the weighted distance to customer locations

```
(29.7604, -95.3698, 60), # Houston
    (33.7490, -84.3880, 50), # Atlanta
    (39.9526, -75.1652, 40), # Philadelphia
    (42.3601, -71.0589, 30), # Boston
    (47.6062, -122.3321, 20), # Seattle
    (32.7157, -117.1611, 10), # San Diego
])
# Haversine formula to calculate distance between two lat/lon points
def haversine distance(lat1, lon1, lat2, lon2):
   R = 6371 # Earth radius in kilometers
   lat1, lon1, lat2, lon2 = map(np.radians, [lat1, lon1, lat2, lon2])
   dlat = lat2 - lat1
   dlon = lon2 - lon1
   a = np.sin(dlat/2)**2 + np.cos(lat1) * np.cos(lat2) *
np.sin(dlon/2)**2
   c = 2 * np.arcsin(np.sqrt(a))
   return R * c
# Objective function: Total weighted distance from distribution
centers to customers
def objective function(positions):
   total cost = 0
   for customer in customers:
       distances = haversine distance(positions[:, 0], positions[:,
1], customer[0], customer[1])
       nearest_center_distance = np.min(distances)
       total cost += nearest center distance * customer[2]
                                                                  #
distance * demand
   return total cost
# Particle class for PSO
class Particle:
```

```
def init (self, bounds, n centers):
        self.position =
                             np.random.uniform(low=bounds[:,
                                                                 0],
high=bounds[:, 1], size=(n centers, 2))
        self.velocity = np.zeros like(self.position)
        self.best position = np.copy(self.position)
        self.best score = float('inf')
# PSO implementation
def
      particle swarm optimization(objective, bounds,
                                                          n centers,
num particles, num iterations):
                    [Particle(bounds, n centers)
    particles =
                                                      for
                                                                  in
range(num particles)]
   global best position = np.zeros((n centers, 2))
   global best_score = float('inf')
   w = 0.5 # inertia weight
   c1 = 1  # cognitive parameter
   c2 = 2 # social parameter
   for in range(num iterations):
        for particle in particles:
            score = objective(particle.position)
            if score < particle.best score:</pre>
                particle.best score = score
                particle.best position = particle.position
            if score < global_best_score:</pre>
               global_best_score = score
               global best position = particle.position
        for particle in particles:
            r1, r2 = np.random.rand(2)
            particle.velocity = (w * particle.velocity +
```

```
c1 * r1 * (particle.best_position -
particle.position) +
                                c2 * r2 * (global best position -
particle.position))
           particle.position = np.clip(particle.position
                                                                 +
particle.velocity, bounds[:, 0], bounds[:, 1])
   return global best position, global best score
# Set up optimization problem
bounds = np.array([[25, 50], [-125, -65]]) # Latitude and Longitude
bounds for USA
n centers = 3 # Number of distribution centers to optimize
num particles = 50
num iterations = 200
# Run PSO
best positions,
                                   best score
particle swarm optimization(objective function, bounds, n centers,
num particles, num iterations)
# Print results
print(f"Optimal distribution center locations:")
for i, pos in enumerate(best positions):
   print(f"Center
                     {i+1}: Latitude {pos[0]:.4f}, Longitude
{pos[1]:.4f}")
print(f"Total weighted distance cost: {best_score:.2f}")
# Visualize the result
plt.figure(figsize=(12, 8))
                                                  0], c='blue',
plt.scatter(customers[:, 1], customers[:,
s=customers[:, 2], alpha=0.6, label='Customers')
```

```
plt.scatter(best_positions[:, 1], best_positions[:, 0], c='red',
s=100, marker='*', label='Distribution Centers')
plt.title('Optimal Distribution Center Locations')
plt.xlabel('Longitude')
plt.ylabel('Latitude')
plt.legend()
plt.grid(True)
plt.show()
```

Ant Colony Optimization (ACO) for playlist recommendations

```
]
# Define parameters
n_ants = 10
n_iterations = 50
decay_rate = 0.1
pheromone_increase = 1.0
# Initialize pheromone levels between each song pair
pheromone_levels = np.ones((len(songs), len(songs)))
# Calculate song compatibility based on mood and genre
def song_compatibility(song1, song2):
    genre_compatibility = 1 if song1["genre"] == song2["genre"] else
0.5
    mood_compatibility = 1 if song1["mood"] == song2["mood"] else 0.5
    return genre_compatibility * mood_compatibility
# Initialize desirability matrix based on compatibility
desirability = np.zeros((len(songs), len(songs)))
for i in range(len(songs)):
    for j in range(len(songs)):
        if i != j:
            desirability[i][j] = song_compatibility(songs[i],
songs[j])
# Ant function to generate playlist
def generate_playlist(start_song):
    playlist = [start_song]
    for _ in range(len(songs) - 1):
        current_song = playlist[-1]
        probabilities = pheromone_levels[current_song["id"] - 1] *
desirability[current_song["id"] - 1]
```

```
probabilities /= probabilities.sum()
        next song = np.random.choice(songs, p=probabilities)
       playlist.append(next song)
   return playlist
# Update pheromones based on successful playlists
def update_pheromones(playlists):
   global pheromone levels
   pheromone levels *= (1 - decay rate) # Apply decay
   for playlist in playlists:
        for i in range(len(playlist) - 1):
            from idx = playlist[i]["id"] - 1
           to idx = playlist[i + 1]["id"] - 1
            pheromone_levels[from_idx][to_idx] += pheromone_increase
# Main ACO loop
for _ in range(n_iterations):
    ant_playlists = [generate_playlist(random.choice(songs)) for _ in
range(n ants)]
   update pheromones(ant playlists)
# Show final playlist and pheromone levels
print("Final Pheromone Levels:")
print(pheromone levels)
for i, song in enumerate(songs):
   print(f"Song {song['name']} transition
                                                      preferences:",
pheromone_levels[i])
```

Genetic Algorithms (GA) for Feature Selection

```
import numpy as np
import pandas as pd
from sklearn.datasets import load_breast_cancer
from sklearn.model selection import train test split
from sklearn.ensemble import RandomForestClassifier
from sklearn.metrics import accuracy score
# Load Breast Cancer Dataset
data = load_breast_cancer()
X = data.data
y = data.target
# Genetic Algorithm Parameters
population size = 20
generations = 50
mutation rate = 0.1
# Initialize Population - Each chromosome represents a binary feature
selection
def initialize_population(size, n_features):
    return np.random.randint(0, 2, (size, n_features))
# Fitness Function - Evaluates the fitness of each chromosome
def fitness_function(population, X_train, y_train, X_test, y_test):
    fitness scores = []
    for chromosome in population:
        selected features = X train[:, chromosome == 1]
        model = RandomForestClassifier()
        model.fit(selected features, y train)
        y pred = model.predict(X test[:, chromosome == 1])
```

```
fitness scores.append(accuracy_score(y_test, y_pred))
   return np.array(fitness scores)
# Selection Function - Selects top-performing chromosomes
def selection(population, fitness scores, num parents):
    parents_indices = np.argsort(fitness_scores)[-num_parents:]
   return population[parents indices]
# Crossover Function - Combines two parents to produce offspring
def crossover(parents, offspring size):
   offspring = np.empty(offspring_size)
   crossover point = np.uint8(offspring size[1] / 2)
   for k in range(offspring_size[0]):
        parent1_idx = k % parents.shape[0]
       parent2_idx = (k + 1) % parents.shape[0]
        offspring[k, :crossover_point] = parents[parent1_idx,
:crossover_point]
       offspring[k, crossover_point:] = parents[parent2_idx,
crossover point:]
   return offspring
# Mutation Function - Mutates a gene in each offspring
def mutation(offspring, mutation rate):
   for idx in range(offspring.shape[0]):
        if np.random.rand() < mutation rate:</pre>
           gene_idx = np.random.randint(0, offspring.shape[1])
           offspring[idx, gene_idx] = 1 - offspring[idx, gene_idx]
   return offspring
# Genetic Algorithm for Feature Selection
X train,
          X test,
                    y train,
                              y_test = train_test_split(X,
                                                                  у,
test size=0.2, random state=42)
n_features = X.shape[1]
```

```
population = initialize_population(population_size, n_features)
for gen in range(generations):
    fitness scores = fitness function(population, X train, y train,
X_test, y_test)
    parents = selection(population, fitness_scores, num_parents=8)
    offspring = crossover(parents, offspring_size=(population_size -
parents.shape[0], n_features))
    offspring = mutation(offspring, mutation rate)
    population[0:parents.shape[0], :] = parents
    population[parents.shape[0]:, :] = offspring
# Get the best chromosome and evaluate its accuracy
best_chromosome = population[np.argmax(fitness_function(population,
X_train, y_train, X_test, y_test))]
selected_features = X[:, best_chromosome == 1]
model = RandomForestClassifier()
model.fit(selected_features, y)
y pred = model.predict(selected features)
print("Final
                Model
                         Accuracy
                                     with
                                             Selected
                                                         Features:",
accuracy score(y, y pred))
print("Selected Features:", data.feature names[best chromosome == 1])
```

```
# Sample real-world songs with details
songs = {
    1: {'name': 'Blinding Lights', 'artist': 'The Weeknd', 'genre':
'Pop', 'popularity': 95},
    2: {'name': 'Watermelon Sugar', 'artist': 'Harry Styles', 'genre':
'Pop', 'popularity': 88},
    3: {'name': 'Levitating', 'artist': 'Dua Lipa', 'genre': 'Pop',
'popularity': 90},
    4: {'name': 'Peaches', 'artist': 'Justin Bieber', 'genre': 'R&B',
'popularity': 85},
    5: {'name': 'drivers license', 'artist': 'Olivia Rodrigo',
'genre': 'Pop', 'popularity': 92},
    6: {'name': 'Save Your Tears', 'artist': 'The Weeknd', 'genre':
'Pop', 'popularity': 89},
    7: {'name': 'MONTERO (Call Me By Your Name)', 'artist': 'Lil Nas
X', 'genre': 'Hip-Hop', 'popularity': 87},
    8: {'name': 'Good 4 U', 'artist': 'Olivia Rodrigo', 'genre':
'Pop', 'popularity': 91},
    9: {'name': 'Kiss Me More', 'artist': 'Doja Cat', 'genre': 'R&B',
'popularity': 86},
    10: {'name': 'Stay', 'artist': 'The Kid LAROI & Justin Bieber',
'genre': 'Pop', 'popularity': 94},
}
# Initialize pheromone levels between songs
pheromones = \{(i, j): 1.0 \text{ for } i \text{ in songs for } j \text{ in songs if } i != j\}
# Heuristic function based on popularity
def heuristic(song1, song2):
    # Preference given to songs with higher popularity
```

```
return (songs[song2]['popularity'] + 1) / 100 # Heuristic scaled
for popularity
# Ant class to build playlists
class Ant:
   def __init__(self):
        self.playlist = []
   def
          select next song(self, current song, unvisited songs,
pheromones):
       # Calculate probabilities based on pheromone levels and
heuristic
       probabilities = []
        for song in unvisited_songs:
            pheromone_level = pheromones[(current_song, song)]
            heuristic_value = heuristic(current_song, song)
            probabilities.append(pheromone_level * heuristic_value)
       # Normalize probabilities
       total = sum(probabilities)
        probabilities = [p / total for p in probabilities]
       # Choose next song based on probabilities
        next song = random.choices(unvisited songs, probabilities)[0]
        return next song
   def build_playlist(self, start_song, pheromones):
        self.playlist = [start song]
        unvisited songs = set(songs.keys()) - {start song}
       while unvisited_songs:
            current song = self.playlist[-1]
```

```
self.select_next_song(current_song,
            next song
unvisited songs, pheromones)
            self.playlist.append(next song)
            unvisited songs.remove(next song)
# Update pheromones based on ant's playlist
def update_pheromones(pheromones, ants, decay=0.1, contribution=1.0):
    # Evaporate pheromones
    for key in pheromones:
        pheromones[key] *= (1 - decay)
    # Deposit new pheromones based on ant playlists
    for ant in ants:
        for i in range(len(ant.playlist) - 1):
            pheromones[(ant.playlist[i], ant.playlist[i + 1])] +=
contribution / len(ant.playlist)
# Simulate ACO for generating playlists
def run aco(num ants=5, iterations=10):
    best playlist = None
    best score = float('inf')
    for in range(iterations):
        ants = [Ant() for _ in range(num_ants)]
        for ant in ants:
            start_song = random.choice(list(songs.keys()))
            ant.build_playlist(start_song, pheromones)
        # Evaluate playlists (for simplicity, sum of popularity)
        for ant in ants:
            score = sum(songs[song]['popularity'] for song
ant.playlist)
```