

RBE3002 Lab4: Mobile Robot Path Planning

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Lab Sign-offs

TASK	SIGNED BY	DATE/TIME
Display Expand obstacles on your own topic	UG	11/28
Display Optimize map with A* path	UG	11/28
Display re-planning using updated heuristic	UG	11/30
Show obstacle avoidance	UG	11/30

Grading Rubric

[100 points] All pre-lab and in-lab procedures are completed and demonstrated prior to the deadline.
All deliverables and sign-off sheet are submitted on time. The code is well commented and structured.