RBE3002 Lab3: Mobile Robot Path Planning

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Lab Sign-offs

	TASK	SIGNED BY	DATE/TIME
	Prelab		
1	RViz configuration	NG	((/1#
	Loading the map	NG	11/14
,	Coloring the map	MU	4/14
	A*	(55	11/14
	Waypoints	NG	11/15
	Extra Credit		

Grading Rubric

[100 points] All pre-lab and in-lab procedures are completed and demonstrated prior to the deadline. All deliverables and sign-off sheet are submitted on time. The code is well commented and structured.

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