

## Homework 3

**Instructions:**

- You may discuss problems with your study group, but ultimately all your work (mathematical problems, code, experimental details) must be individual.
- Your solutions must be **typed up** and uploaded to Gradescope by 11.59PM on Thursday April 24. No late homeworks will be accepted under any circumstances, so you are encouraged to upload early.
- A subset of the problems will be graded.

**Conceptual and mathematical problems**

1. Find the unit vector in the same direction as  $x = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$ .
2. Find all unit vectors in  $\mathbb{R}^2$  that are orthogonal to  $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .
3. The function  $f(x) = 2x_1 - x_2 + 6x_3$  can be written as  $w \cdot x$  for  $x \in \mathbb{R}^3$ . What is  $w$ ?
4. For a certain pair of matrices  $A, B$ , the product  $AB$  has dimension  $10 \times 20$ . If  $A$  has 30 columns, what are the dimensions of  $A$  and  $B$ ?
5. We have  $n$  data points  $x^{(1)}, \dots, x^{(n)} \in \mathbb{R}^d$  and we store them in a matrix  $X$ , one point per row.
  - (a) What is the dimension of  $X$ ? n\*d
  - (b) What is the dimension of  $XX^T$ ? x\*n
  - (c) What is the  $(i, j)$  entry of  $XX^T$ , simply?
6. For  $x = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$  compute  $x^T x$  and  $xx^T$ .
7. The quadratic function  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  given by
 
$$f(x) = 3x_1^2 + 2x_1x_2 - 4x_1x_3 + 6x_3^2$$
 can be written in the form  $x^T M x$  for some *symmetric* matrix  $M$ . What is  $M$ ?
8. Let  $A = \text{diag}(1, 2, 3, 4, 5, 6, 7, 8)$ .
  - (a) What is  $|A|$ ?
  - (b) What is  $A^{-1}$ ?

9. Vectors  $u_1, \dots, u_d \in \mathbb{R}^d$  all have unit length and are orthogonal to each other. Let  $U$  be the  $d \times d$  matrix whose rows are the  $u_i$ .
- What is  $UU^T$ ? 不一定是单位矩阵
  - What is  $U^{-1}$ ?
10. Matrix  $A = \begin{bmatrix} 1 & 2 \\ 3 & z \end{bmatrix}$  is singular. What is  $z$ ?
11. *Gaussian contours.* Roughly sketch the shapes of the following Gaussians  $N(\mu, \Sigma)$ . You only need to show a representative contour line which is qualitatively accurate (has approximately the right orientation, for instance).
- $\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$  and  $\Sigma = \begin{bmatrix} 9 & 0 \\ 0 & 1 \end{bmatrix}$
  - $\mu = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$  and  $\Sigma = \begin{bmatrix} 1 & -0.75 \\ -0.75 & 1 \end{bmatrix}$
12. *Qualitative appraisal of Gaussian parameters.* A bivariate Gaussian has covariance matrix  $\begin{bmatrix} p & q \\ q & r \end{bmatrix}$ . Give precise characterizations, in terms of  $p, q, r$ , of when the following are true.
- The two variables are negatively correlated.
  - The two variables are uncorrelated.
  - One variable is a linear function of the other.
  - The second variable is a constant (i.e. always takes the same value).
13. Suppose we solve a classification problem with  $k$  classes by using a Gaussian generative model in which the  $j$ th class is specified by parameters  $\pi_j, \mu_j, \Sigma_j$ . In each of the following situations, say whether the decision boundary is **linear**, **spherical**, or **other quadratic**.
- We compute the empirical covariance matrices of each of the  $k$  classes, and then set  $\Sigma_1 = \Sigma_2 = \dots = \Sigma_k$  to the **average** of these matrices.
  - The covariance matrices  $\Sigma_j$  are all **diagonal**, but no two of them are the same.
  - There are two classes (that is,  $k = 2$ ) and the covariance matrices  $\Sigma_1$  and  $\Sigma_2$  are multiples of the identity matrix.

## Programming problems

14. *Classifying MNIST digits using generative modeling.* In class, we have already encountered the MNIST data set of handwritten digits. In this problem, you will build a classifier for this data, by modeling each class as a multivariate (784-dimensional) Gaussian.
- Download the `hw3.zip` file and unzip it. Make sure the Jupyter notebook `generative-mnist.ipynb` and the MNIST data set (consisting of 4 data files) are in the same directory.
    - Look over the notebook to see what it is doing, and then run it, one cell at a time.
    - Make sure you understand the form in which the training and test data are stored.
    - The notebook includes a helper function that displays digits.
    - The notebook also includes code for many of the tasks described below.

- Split the training set into two pieces – a training set of size 50000 (say), and a separate *validation set* of size 10000.
- Now fit a Gaussian generative model to the training data of 50000 points.
  - Determine the class probabilities: what fraction  $\pi_0$  of the training points are digit 0, for instance? Call these values  $\pi_0, \dots, \pi_9$ .
  - Fit a Gaussian to each digit, by finding the mean and the covariance of the corresponding data points. Let the Gaussian for the  $j$ th digit be  $P_j = N(\mu_j, \Sigma_j)$ . Note that  $\mu_j$  will be a 784-dimensional vector, and  $\Sigma_j$  will be a  $784 \times 784$  matrix.

Using these two pieces of information, you can classify new images  $x$  using Bayes' rule: simply pick the digit  $j$  for which  $\pi_j P_j(x)$  is largest.

- One last step is needed: it is important to smooth the covariance matrices, and the usual way to do this is to add in  $cI$ , where  $c$  is some constant and  $I$  is the identity matrix. Use the validation set to help you choose the right value of  $c$ : that is, choose the value of  $c$  for which the resulting classifier makes the fewest mistakes on the validation set.
- There are some important details of *numerical precision* that you will need to attend to. In 784-dimensional space, all probabilities  $P_j(x)$  will likely be miniscule, and this can produce all sorts of trouble due to underflow errors. It is better to work with log-probabilities:  $-1000$  is easier to deal with than  $e^{-1000}$ . This means that you should classify a point  $x$  by picking the  $j$  that maximizes  $\log \pi_j + \log P_j(x)$ . Fortunately, the Python `multivariate_normal` package will directly compute  $\log P_j(x)$  for you.

在高维数据中，有一些像素特征高度相关，容易减少训练数据点的维数；如果矩阵接近singular或者是singular，就可能导致协方差矩阵的逆无法计算；而给协方差矩阵加入一点噪声 $c$ ，就可以使矩阵特征值整体提升，避免变得非奇异。

To turn in:

- Give pseudocode (or code) for the procedure you used to select a value of  $c$ . Make it clear which data you used.
- What value of  $c$  did you get?
- What was the error rate on the MNIST test set?
- Out of the misclassified test digits, pick five at random and display them. For each instance, list the true label and predicted label.