

W = emgr(f,g,s,t,w,pr,nf,ut,us,xs,um,xm,dp)

emgr – EMpirical GRamian Framework (Version 5.8)

Mandatory Arguments

f	System Vector Field	(Handle)	$x = f(x,u,p,t)$	i.e.: $f = @(x,u,p,t) A*x+B*u+F*p$
g	Output Functional	(Handle)	$y = g(x,u,p,t)$	i.e.: $g = @(x,u,p,t) C*x+D*u$
			1	$y = x$
s	System Dimensions	(Vector)	$s = [M,N,Q]$	(Inputs, States, Outputs)
t	Time Discretization	(Vector)	$t = [dt,Tf]$	(Time Step, Time Horizon)
w	Gramian Type	(Char)	Empirical System Gramian Type	
			'c'	Empirical Controllability Gramian (returns W_c)
			'o'	Empirical Observability Gramian (returns W_o)
			'x'	Empirical Cross Gramian (returns W_x)
			'y'	Empirical Linear Cross Gramian (returns W_y)
			's'	Empirical Sensitivity Gramian (returns $\{W_c, W_s\}$)
			'i'	Empirical Identifiability Gramian (returns $\{W_o, W_i\}$)
			'j'	Empirical Joint Gramian (returns $\{W_x, W_j\}$)

Optional Arguments

pr	Parameters	(Vector)	Column vector of parameters (default: $pr = 0$)	
		(Matrix)	Set of parameter columns (W_s, W_i, W_j require min & max)	
nf	Options Flags	(Vector)	Thirteen components (default: $nf = 0$)	
ut	Input Function	(Handle)	Input function $u_t = ut(t)$ or char (default: $ut = 'i'$)	
			'i'	Delta impulse input (default)
			's'	Step input
			'c'	Decaying exponential chirp input
			'a'	Sinc input
			'r'	Pseudo-random binary input
us	Steady-State Input	(Scalar)	Uniform steady-state input (default: $us = 0$)	
		(Vector)	Individual steady-state input ($M \times 1$)	
xs	Steady-State	(Scalar)	Uniform steady-state (default: $xs = 0$)	
		(Vector)	Individual steady-states ($N \times 1$)	
um	Input Scales	(Scalar)	Uniform max input scales (default: $um = 1$)	
		(Vector)	Individual max input scales ($M \times 1$)	
		(Matrix)	Custom input scales ($M \times *$)	
xm	Steady-State Scales	(Scalar)	Uniform max steady-state scales (default: $xm = 1$)	
		(Vector)	Individual max steady-state scales ($N \times 1$)	
		(Matrix)	Custom steady-state scales ($N \times *$)	
dp	Dot Product	(Handle)	Custom Inner product / kernel $xy = dp(x,y)$, (default: $dp = []$)	

Option Flags

nf(1)	Trajectory Centering			
		0	None (default)	
		1	Steady state	
		2	Final state	
		3	Arithmetic average	
		4	Root-mean-squared	
		5	Mid-range	
nf(2)	Input Scale Sequence			
		0	Single (default)	
		1	Linear	
		2	Geometric	
		3	Logarithmic	
		4	Sparse	
nf(3)	State Scale Sequence			
		0	Single (default)	
		1	Linear	
		2	Geometric	
		3	Logarithmic	
		4	Sparse	
nf(4)	Input Transformation			
		0	\pm Unit (default)	
		1	+ Unit	
nf(5)	State Transformation			
		0	\pm Unit (default)	
		1	+ Unit	
nf(6)	Normalizing			
		0	None (default)	
		1	Steady state	
		2	Jacobi	
nf(7)	State Gramian Type			
		0	Regular (default)	
	W_c	1	Output controllability Gramian	
	W_o, W_i	1	Averaged observability Gramian	
	W_x, W_y, W_j	1	Non-symmetric cross Gramian	
nf(8)	Extra Input (W_o, W_x, W_s, W_i, W_j only)			
		0	No (default)	
		1	Yes	
nf(9)	Center Param. Scales (W_s, W_i, W_j only)			
		0	None (default)	
		1	Linear mean centering	
		2	Logarithmic mean centering	
nf(10)	Parameter Gramian Type (W_s, W_i, W_j only)			
	W_s	0	Input-state average (default)	
	W_s	1	Input-output average	
	W_i, W_j	0	Approx. Schur-complement (default)	
	W_i, W_j	1	Coarse Schur-complement	
nf(11)	Partitioned Cross Gramian (W_x, W_j only)			
		0	Full cross Gramian (default)	
		<N	Cross Gramian partition size	
nf(12)	Partitioned Cross Gramian (W_x, W_j only)			
		0	Full cross Gramian (default)	
		>0	Partition running index	
nf(13)	Trajectory Weighting			
		0	None (default)	
		1	Linear time-weighting	
		2	Quadratic time-weighting	
		3	State weighting	
		4	Scale weighting	

Custom Solver

Global variable **ODE** is a handle with signature:
 $y = ODE(f,g,t,x0,u,p)$ (default: RK – SSP32)

About Info: $V = emgr('version')$

More info at: <https://gramian.de>